

MGM's College of Engineering and Technology Kamothe Navi Mumbai – 410 209 Department of Computer Engineering

Course Code: CSC304 Course Name: Digital Logic & Computer Organization and Architecture Class: SE AY: 2021-22

Assignment No. 3

Q. N o	Question	Modul e	Bloom's Taxonomy level	Program Indicator	СО
Q1.	Justify Your Answers				
	(a) addressing mode is most suitable to change the normal sequence of execution of instructions.	M3	L2	1.7.1	CO1
	(b)When both inputs of a J-K flip-flop cycle, the output will	M3	L2	1.7.1	CO1
	(c) MAR stand for	M3	L2	1.7.1	CO1
	(d) If the control signals are generated by combinational logic, then they are generated by a type of controlled unit.	M4	L2	1.7.1	CO1
	(e) Individual control word of micro routine are called as	M4	L2	1.7.1	CO1
Q2.	Choose Correct Options				
	(a) Whose operations are more faster among the following? a) Combinational circuits b) Sequential circuits c) Latches d) Flip-flops	M3	L2	1.7.1	CO1
	(b) When both inputs of a J-K flip-flop cycle, the output will a) Be invalid b) Change c) Not change d) Toggle	M3	L2	1.7.1	CO1
	(c) In S-R flip-flop, if Q = 0 the output is said to bea) Set b) Reset c) Previous state d) Current state	M3	L2	1.7.1	CO1
	(d) The addressing mode, where you directly specify the operand value is a) Immediate b) Direct c) Definited) Relative	M3	L2	1.7.1	CO1
	(e) Which is the simplest method of implementing hardwired control unit? a) State Table Method b) Delay Element Method c) Sequence Counter Method d) Using Circuits	M4	L2	1.7.1	CO1
_	State whether the following statements are true or false (Give sons)				
	(a) In auto increment, the operand is retrieved first and then the	M3	L3	1.7.1	CO1

	address altered				
	(b) Micro-program consists of a set of microinstructions which are strings of 0s and 1s.	M4	L3	1.7.1	CO1
	(c) A decoder is required in case of a Vertical Microinstruction.	M4	L3	1.7.1	CO1
Q4	Name the following or define or design the following				
	(a) Design full adder using NAND gate	M3	L2	1.7.1	CO1
	(b) State the instruction format	M4	L3	1.7.1	CO1
	(c) Convert SR flip flops to JK FF and T FF	M3	L3	1.7.1	CO1
Q5.	Answer the following questions in brief (20 to 30 words)				
	(a) Justify how race around condition is overcome in Master Slave JK Flip-flops.	M1	L4	1.7.1	CO1
	(b) Differentiate between Hardwired control unit and micro programmed control unit	M4	L4	1.7.1	CO1
	(c)Explain the Hardwired control unit method in detail and Justify which method of Hardwired control unit is best.	M1	L4	1.7.1	CO1
. Q 6	6. Answer the following questions in brief (50 to 70 words)				
	(a) Explain in detail Addressing modes	M1	L2	1.7.1	CO1
	(b) Draw and explain the Micro Instruction format	M1	L2	1.7.1	CO1
	(c) Write the instruction format and instruction Cycle in register organization	M1	L2	1.7.1	CO1
Q7.	Think and Answer				
	(a) Why Addressing modes is needed?	M1	L4	2.6.1	CO1
	(b) Justify with any the example of micro programs.	M1	L5	2.6.1	CO1
Q8.	My Ideas				
	(a) Design the control unit for one real time application .	M1	L6	5.4.1	CO1

 $\textbf{a. Relative b. not change c.} \ \mathsf{Memory} \ \mathsf{Address} \ \mathsf{Register} \ \mathsf{d.} \ \mathsf{Hardwired} \ \mathsf{e.} \ \mathsf{Micro} \ \mathsf{instruction}$