Command Name: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

(Example: FireCatapult)

What Subsystems does it use?

(Example: Catapult)

What does it do? (From the perspective of the driver)

(Example: Launch the catapult)

What does it do? (What happens to the hardware?)

(Example: Fire a solenoid)

What buttons does the driver use to control it?

(Example: Press the A button on controller 2)

How is it tested? Include the necessary tests to ensure all functionality detailed above is correct:

(Example: When the forward button is pressed, verify the robot moves forward 10 centimeters.)