Name of Subsystem:\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

(Example: DriveTrain)

What does it do?

(Example: Drive the robot)

What hardware does it use? (Speed controllers, Servos, Solenoids)

(Example: 4 Speed controllers)

What is the default command? (What does it do when no buttons are pressed?)

(Example: Drive the robot based off joystick input)

How is it tested? Include the necessary tests to ensure all functionality detailed above is correct:

(Example: When the robot is enabled and no button are pressed, verify it remains still.)