LIMO robot:

<https://docs.trossenrobotics.com/agilex_limo_docs/getting_started.html>

ROS2 Humble

<https://github.com/agilexrobotics/limo_ros2>

<https://github.com/agilexrobotics/limo_ros2_doc/>

ROS1-Noetic

<https://github.com/agilexrobotics/limo_ros/>

<https://github.com/agilexrobotics/limo-doc/>

<https://limo-agx.github.io/index.html>