Topics of Day-9 hands-on session

Parallel execution on CPUs and GPUs. Covered topics are:

- basic description of GPU acceleration,
- optimise CPU only runs,
- efficiently run on accelerated systems.

Exercise 0: Basic information about GPU acceleration.

cd example0.intro/

 $\textbf{Exercise 1:} \ \, \textbf{Setting up QE on CPU and GPU systems}.$

cd example1.setup/

Exercise 2: Parallel options – improve performance with npool and ndiag

cd example2.CPU/

Exercise 3: Accelerated systems – how to run with NVidia GPUs cd example3.GPU/

(Very) basic concepts about GPUs

This exercise is to provide some basic practical notions about how GPU acceleration works.

The source file code_cpu.f90 is a minimal program to perform a matrix-matrix product on the CPU using the DGEMM subroutine from the BLAS libraries.

In order to compile the code, you first purge all modules with

module purge

and then load the nvfortran compiler with

module load autoload hpc-sdk

link the BLAS libraries. In this case you will be using the BLAS libraries provided with the nvfortran compiler in the hpc-sdk

Then, you can compile the code appending the -lblas flag in order to

package.

nvfortran -o code_cpu.x code_cpu.f90 -lblas

The source file code_gpu.f90 does the same calculation as code_cpu.f90, but on the GPU, using the cuDGEMM subroutine from the cuBLAS libraries. In order to compile the code you load the CUDA module

module load autoload cuda

and then compile the code specifying that you want to use CUDA (-Mcuda) and that you want to link the cuBLAS libraries (-Mcudalib=cublas)

nvfortran -o code_gpu.x code_gpu.f90 -Mcuda -Mcudalib=cublas

- 1. Take a look inside the CPU and GPU code, to have an idea of the CUDA Fortran directives.
- 2. Launch the two executables with varying the SIZE (substitute SIZE with an integer) of the matrices and compare the elapsed time
 - ./code_cpu.x SIZE
 - ./code_gpu.x SIZE

Unfortunately in Quantum ESPRESSO things are a bit more complicated than this, because often the matrices are inizialized on the CPU and then need to be moved to the GPU in order to perfom the computations. Sometimes also the result of the computation needs to be moved back to the CPU memory. This operations are usually referred to as "off-loadings" or "data transfer" between host and device memories. The source code code mix.f90 shows this in

a very simplified manner.

- 1. Have a look at the code_mix.f90 file and find the data transfers between host and device memories.
- 2. Launch code_mix and code_gpu for large matrix sizes, and compare the elapsed times. What can you say?
- ./code_mix.x SIZE

Preparing QE

We will first prepare an HPC ready installation of QE. This exercise will show how to compile QE and check for relevant libraries in the context of standard or accelerated systems.

CPU version

cd qe-cpu

Download the last release, extract it and rename it with the commands below:

For the CPU version we will use hpc-sdk and SpectrumMPI which are a good combination on OpenPower machines. The FFTW library is also required. The environment is setup using the following modules.

Configure QE with

```
./configure CC=pgcc F77=pgf90 FC=pgf90 F90=pgf90 \hookrightarrow MPIF90=mpipgifort
```

The following libraries have been found:

 ... check that relevant libraries have been detected, namely on this system, blas, lapack from hpc-sdk and fftw3:

```
BLAS_LIBS=-lblas

APACK_LIBS=-L/cineca/prod/opt/compilers/hpc-sdk/2020/binary
```

```
→ LAFACK_BIBS--L/CINECA/prod/opt/compilers/npc-sdk/2020/binar

→ -llapack -lblas

FFT_LIBS= -lfftw3
```

Note: we did not enable OpenMP in this case since we will be dealing with small input file. If you plan to run large simulations or you happen to run with accelerators, OpenMP is important and we will indeed enable it in the next section.

We will only need pw.x so we compile it with the command make -j pw
Enjoy some tea or coffe while you wait 3 minutes or so.

GPU version

Now go back to the folder of example1 and download the last release of the GPU accelerated version of QE

```
wget
```

cd qe-gpu

```
https://gitlab.com/QEF/q-e-gpu/-/archive/qe-gpu-6.7/q-e-gpu-qe-gpu-tar xjf q-e-gpu-qe-gpu-6.7.tar.bz2
mv q-e-gpu-qe-gpu-6.7 qe-gpu
```

For the GPU version you *must* use the HPC-SDK which provides a CUDA Fortran compiler. The other libraries remain the same, except for cuda

```
module purge
module load    hpc-sdk/2020--binary

→ spectrum_mpi/10.3.1--binary

→ fftw/3.3.8--spectrum_mpi--10.3.1--binary cuda/11.0
```

Configure with

```
./configure CC=pgcc F77=pgf90 FC=pgf90 F90=pgf90

MPIF90=mpipgifort --enable-openmp --with-cuda=$CUDA_HOME

--with-cuda-runtime=11.0 --with-cuda-cc=70
```

 ... check that relevant libraries have been detected, DFLAGS show that CUDA, CUSOLVER and MPI will be activated:

You'll notice that the code is using the internal version of FFTW (-D__FFTW instead of -D__FFTW3). This is not an issue in this case since 99% of the FFTs will be performed on the GPU with optimized CUDA libraries.

Compile again the code

Congratulations, now you have both a "standard" and an

"accelerated" version of pw.x to be used in the following exercises.

make -j pw

Optimize CPU execution

In this section we only make use of CPUs and try to optimize the time to solution keeping the amount of compute power fixed.

1. Pool parallelism

Optimize the number of kpoint pools, starting with 1 up to 8 (what are the admissible values for this option?). The jobscript file to be used on Marconi100 is already available in this folder and is also reported below for your convenience.

```
#!/bin/bash
\#SBATCH --nodes=1
                 # number of nodes
#SBATCH --ntasks-per-node=16 # number of MPI per node
#SBATCH --cpus-per-task=4 # number of HW threads per task
#SBATCH --mem=230000MB
#SBATCH -p m100 usr prod
#SBATCH -J qeschool
module load hpc-sdk/2020--binary

    spectrum_mpi/10.3.1--binary

    fftw/3.3.8--spectrum mpi--10.3.1--binary

export QE_ROOT=../example1.setup/qe-cpu/
export PW=$QE_ROOT/bin/pw.x
# This sets OpenMP parallelism, in this case we do a pure MPI
export OMP NUM THREADS=1
# Run pw.x with default options for npool and ndiag
mpirun ${PW} -npool 1 -ndiag 1 -inp pw.CuO.scf.in | tee

→ no_options
```

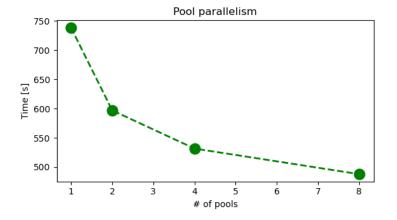
- 1. First, submit the job as is, with npool set to 1.
- 2. Second, open the job-script file (job.sh) and change the number of pools to be used -npool X, with X={2,4,8}. Don't forget to rename the output file as well.
 - 3. **Collect the time** taken by the code as a function of the number of k point pools.

The execution time can be obtained by looking at one of the last lines of the output, that reads for example

PWSCF : 5m53.84s CPU 5m58.18s WALL

the WALL time is the value you want to note down (if you wonder what CPU time is, check wikipedia).

You should be able to produce a plot similar to this one:



Congrats! With the same computational resources, the time to solution is almost halved!

our MPI processes reside on a single node and inter-process

Pool parallelism can be actually much better than what you

parallelization on plane waves is good enough, especially because all

obtained in this example. Indeed for this small input file the

communication is fast.

2. Parallel diagonalization

In this second part we want to speedup the code by solving the dense eigenvalue problem using more than one core.

- 1. Set -npool to 4 and activate parallel diagonalization by changing -ndiag 4 to improve the performance.
- 2. Inspect the beginning of the output file and look for this message
 - Subspace diagonalization in iterative solution of the eigenvalue problem: one sub-group per band group will be used custom distributed-memory algorithm (size of sub-group: 2* 2 procs)
- 3. Check the time to solution. Did you manage to reduce the WALL time?

Unfortunately you'll notice that the simulation is actually **taking longer**.

There are two reasons for this:

- 1. the eigenvalue is too small to take advantage of parallel diagonalization,
- 2. we didn't use optimized libraries for this task. The code is using a suboptimal parallel eigensolver. Two common options to improve in this case are linking Scalapack or ELPA libraries.

Running with GPUs

To run the accelerated version you are supposed to couple **each MPI** with a single GPU. Therefore this time your jobscript is setup to request **two MPI** processes and 2 GPUs with your submission script.

The jobscript file to be used on Marconi100 is already available in this folder and is also reported below for your convenience.

```
#!/bin/bash
#SBATCH --ntasks-per-node=2 # number of MPI per node
#SBATCH --ntasks-per-socket=2 # number of MPI per socket
#SBATCH --cpus-per-task=8 # number of HW threads
#SBATCH -- gres=gpu:2
                              # number of gpus per node
#SBATCH --mem=230000MB
#SBATCH --time 00:10:00
                              # format: HH:MM:SS
#SBATCH -A cin QEdevel1 4
#SBATCH -p m100 usr prod
#SBATCH -J qeschool
module load hpc-sdk/2020--binary spectrum_mpi/10.3.1--binary

    fftw/3.3.8--spectrum mpi--10.3.1--binary

export QE_ROOT=../example1.setup/qe-gpu/
export PW=$QE_ROOT/bin/pw.x
export OMP_NUM_THREADS=1 # This sets OpenMP parallelism
# Run pw.x with default options for npool and ndiag
mpirun ${PW} -npool 1 -ndiag 1 -inp pw.CuO.scf.in | tee
```

 \hookrightarrow no_options

- 1. Analyze the difference with the previous jobscript and,
- 2. **submit this jobscript** that will run the same input without any parallel optimization.
- 3. Once the simulation is complete, **check the output file**.

At the beginning of the output file you will spot	
GPU acceleration is ACTIVE.	

CPU tests, taking slightly less than 2 minutes.

Moreover, this run should be much faster than any of the previous

4. Now try to exploit the entire CPU with OpenMP.

Change the environment variable set by the following command ${\tt export\ OMP_NUM_THREADS=X}$

with X=2,4,8.

5. You'll notice a small improvement and, eventually a satu	uration.

Once again, OpenMP is effective only for large simulation, but in

this case it is used to take advantage of idle CPU cores as much as

possible.

Pool parallelism

You can improve the previous result with pool parallelism. This time you will be limited by the total number of MPI processes, namely 2.

- 1. **Modify the original jobscript**, set -npool 2, submit the job.
- 2. Check the time to solution.

You should observe a substantial **reduction of the time to solution** which is now about **3/4 of your previous test**. This improvement is actually due to FFTs that are now performed without communications on a single GPU.

Oversubscription

For small inputs, one can possibly obtain some additional performance by oversubscribing the $\ensuremath{\mathsf{GPU}}.$

Try to increase the number of MPI processes used to run this job by changing the jobscript as shown below:

```
#!/bin/bash
#SBATCH --ntasks-per-node=4 # number of MPI per node
#SBATCH --ntasks-per-socket=4 # number of MPI per socket
#SBATCH --cpus-per-task=4 # number of HW threads per

    t.a.sk

#SBATCH --qres=qpu:2 # number of qpus per node
#SBATCH --mem=230000MB
#SBATCH -A cin_QEdevel1_4
#SBATCH -p m100 usr prod
#SBATCH -J geschool
module load hpc-sdk/2020--binary

    spectrum_mpi/10.3.1--binary

    fftw/3.3.8--spectrum_mpi--10.3.1--binary

export QE_ROOT=../example1.setup/qe-gpu/
export PW=$QE_ROOT/bin/pw.x
export OMP_NUM_THREADS=1
mpirun ${PW} -npool 4 -ndiag 1 -inp pw.CuO.scf.in |
\hookrightarrow oversubscription
```

Compare with theoretical performance

The ratio between the peak performance of the GPU and the CPU is about a factor 10.

1. Evaluate the ratio between the best time to solution of your CPU and GPU tests. Do your results reproduce the ideal ratio? Why not?