```
close all;
beta =0.92;
varpi = 1/3;
al = 1;
ah = 1.1;
sigma = 2;
delta = 0.03;
save parameterfile beta varpi al ah sigma delta
pi_p0=1.76;
pi_g0=1.47;
pi_pF_obser=1.4;
pi qF obser=0.7;
pi pF simul=0.8;
pi_gF_simul=0.8;
dynare model_observed
load('model_observed_results.mat')
y_obser = y;
i_obser = i;
k \text{ obser} = k;
c obser = c;
Configuring Dynare ...
[mex] Generalized QZ.
[mex] Sylvester equation solution.
[mex] Kronecker products.
[mex] Sparse kronecker products.
[mex] Local state space iteration (second order).
[mex] Bytecode evaluation.
[mex] k-order perturbation solver.
[mex] k-order solution simulation.
[mex] Quasi Monte-Carlo sequence (Sobol).
[mex] Markov Switching SBVAR.
Using 64-bit preprocessor
Starting Dynare (version 4.5.7).
Starting preprocessing of the model file ...
Found 6 equation(s).
Evaluating expressions...done
Computing static model derivatives:
 - order 1
Computing dynamic model derivatives:
 - order 1
Processing outputs ...
done
Preprocessing completed.
```

EIGENVALUES:

Imaginary	Real	Modulus
0	0.9589	0.9589
0	1.134	1.134

There are 1 eigenvalue(s) larger than 1 in modulus for 1 forward-looking variable(s)

The rank condition is verified.

MODEL SIMULATION:

```
Iter: 1, err. = 7.1408, time = 0.018
Iter: 2, err. = 0.14094, time = 0.003
Iter: 3, err. = 0.00038816, time = 0.003
Iter: 4, err. = 1.2529e-06, time = 0.003
```

Total time of simulation: 0.031

Perfect foresight solution found.

MODEL SIMULATION:

```
Iter: 1, err. = 7.1408, time = 0.004
Iter: 2, err. = 0.14094, time = 0.004
Iter: 3, err. = 0.00038816, time = 0.004
Iter: 4, err. = 1.2529e-06, time = 0.004
```

Total time of simulation: 0.019

Perfect foresight solution found.

Residuals of the static equations:

```
Equation number 1 : 0 : Aggregate Output Equation number 2 : 0 : Euler Equation Equation number 3 : 0 : Budget Constrain Equation number 4 : 0 : low-tech capital Equation number 5 : 0 : total capital Equation number 6 : 0 : investment
```

```
load('model_simul_results.mat')
y_simul = y;
i simul = i;
k simul = k;
c_simul = c;
Configuring Dynare ...
[mex] Generalized QZ.
[mex] Sylvester equation solution.
[mex] Kronecker products.
[mex] Sparse kronecker products.
[mex] Local state space iteration (second order).
[mex] Bytecode evaluation.
[mex] k-order perturbation solver.
[mex] k-order solution simulation.
[mex] Quasi Monte-Carlo sequence (Sobol).
[mex] Markov Switching SBVAR.
Using 64-bit preprocessor
Starting Dynare (version 4.5.7).
Starting preprocessing of the model file ...
Found 6 equation(s).
Evaluating expressions...done
Computing static model derivatives:
 - order 1
Computing dynamic model derivatives:
 - order 1
Processing outputs ...
done
Preprocessing completed.
EIGENVALUES:
                                          Imaginary
         Modulus
                             Real
          0.9589
                           0.9589
                                                  0
           1.134
                            1.134
There are 1 eigenvalue(s) larger than 1 in modulus
for 1 forward-looking variable(s)
The rank condition is verified.
```

Total computing time : 0h00m00s

dynare model_simul

MODEL SIMULATION:

```
Iter: 1, err. = 11.1429, time = 0.017
       Iter: 2, err. = 0.39697, time = 0.004
       Iter: 3, err. = 0.013091, time = 0.004
       Iter: 4, err. = 0.00051815, time = 0.004
       Iter: 5, err. = 1.831e-07, time = 0.003
       Total time of simulation: 0.034
       Perfect foresight solution found.
       MODEL SIMULATION:
       Iter: 1, err. = 11.1429, time = 0.004
       Iter: 2, err. = 0.39697, time = 0.004
       Iter: 3, err. = 0.013091, time = 0.004
       Iter: 4, err. = 0.00051815, time = 0.004
       Iter: 5, err. = 1.831e-07, time = 0.004
       Total time of simulation: 0.024
       Perfect foresight solution found.
       Residuals of the static equations:
       Equation number 1 : 0 : Aggregate Output
       Equation number 2 : 0 : Euler Equation
       Equation number 3 : 0 : Budget Constrain
       Equation number 4 : 0 : low-tech capital
       Equation number 5 : 0 : total capital
       Equation number 6 : 0 : investment
       Total computing time : 0h00m00s
Graphs
       figure;
       set(gcf, 'Color', [1,1,1]);
       subplot(2,2,1);
       plot(c_obser,'r-','LineWidth',1);
       hold on
```

plot(c simul, 'b-', 'LineWidth',1);

set(gca,'Fontsize',8);
%xlim([2003 2017]);

```
title(['Consumption'],'FontSize',8,'FontWeight','bold');
legend('observed', 'alternative', 'Location', 'Best')
subplot(2,2,2);
plot(i_obser,'r-','LineWidth',1);
hold on
plot(i simul, 'b-', 'LineWidth',1);
set(gca,'Fontsize',8);
%xlim([2003 2017]);
title(['Investment'], 'FontSize', 8, 'FontWeight', 'bold');
legend('observed', 'alternative', 'Location', 'Best')
subplot(2,2,3);
plot(k_obser,'r-','LineWidth',1);
hold on
plot(k_simul, 'b-', 'LineWidth',1);
set(gca,'Fontsize',8);
%xlim([2003 2017]);
title(['Capital'],'FontSize',8,'FontWeight','bold');
legend('observed', 'alternative', 'Location', 'Best')
subplot(2,2,4);
plot(y_obser,'r-','LineWidth',1);
hold on
plot(y_simul, 'b-', 'LineWidth', 1);
set(gca,'Fontsize',8);
%xlim([2003 2017]);
title(['Output'], 'FontSize', 8, 'FontWeight', 'bold');
legend('observed', 'alternative', 'Location', 'Best')
snapnow
% capital-output ratio
figure;
plot(k_obser./y_obser,'r-','LineWidth',1);
hold on
plot(k_simul./y_simul, 'b-', 'LineWidth',1);
set(gca,'Fontsize',8);
%xlim([2003 2017]);
title(['Capital Output Ratio
 (observed)'],'FontSize',8,'FontWeight','bold');
legend('observed', 'alternative', 'Location', 'Best')
snapnow
```





