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We have the following relations among different modes of convergence

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- All the implications are one-way and we have seen counter examples
- ▶ In general, almost sure convergence does not imply convergence in r^{th} mean and vice versa

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- ▶ Central Limit Theorem: $\frac{S_n n\mu}{\sigma\sqrt{n}} \stackrel{d}{\to} \mathcal{N}(0,1)$

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$$\phi_X(u) = E\left[e^{iuX}\right] = \int e^{iux} dF_X(x) \quad (i = \sqrt{-1})$$

▶ Given rv X, its characteristic function, ϕ_X , is defined by

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 - If $E|X|^r < \infty$, ϕ would be differentiable r times and

$$\phi^{(r)}(u) = E[(iX)^r e^{iuX}]$$

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- Let ϕ be the characteristic function of X_i . Then

$$\phi_{S_n}(t) = (\phi(t))^n$$
 and $\phi_{\tilde{S}_n}(t) = \left(\phi\left(\frac{t}{\sigma\sqrt{n}}\right)\right)^n$

 \blacktriangleright Recall that we can expand ϕ in a Taylor series

$$\phi(u) = \sum_{s=0}^{r-1} \mu_s \frac{(iu)^s}{s!} + \rho(u) \mu_r \frac{(iu)^r}{r!}, \quad \rho(u) \to 1, \text{ as } u \to 0$$

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▶ By Continuity theorem, distribution function of \tilde{S}_n converges to that of standard Normal rv

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► Thus, S_n is well approximated by a normal rv with mean $n\mu$ and variance $n\sigma^2$, if n is large

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$$\begin{split} P[|Z| \leq 3] &= P[-3 \leq Z \leq 3] \\ &= P\left[\frac{-3}{\sqrt{\frac{5}{3}}} \leq \frac{Z - EZ}{\sqrt{\mathsf{Var}(Z)}} \leq \frac{3}{\sqrt{\frac{5}{3}}}\right] \\ &\approx \Phi\left(\frac{3}{\sqrt{\frac{5}{3}}}\right) - \Phi\left(\frac{-3}{\sqrt{\frac{5}{3}}}\right) \\ &\approx \Phi(2.3) - \Phi(-2.3) \\ &= 0.9893 - 0.0107 \approx 0.98 \end{split}$$

► Hence probability that the sum differs from true sum by more than 3 is 0.02

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- ▶ To get a good approximation, to calculate $P[S_n \le m]$ one uses $P[S_n \le m + 0.5]$ in the above approximation formula

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- \blacktriangleright Here, the 0.34 would be the sample mean. The other two numbers can be fixed using CLT

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- ► In analyzing any experimental data the confidence intervals or the variance term is important

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- We need the joint distribution of every finite subcollection of them.

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We can write it as

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- ► This is a useful model for many dynamic systems or processes

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- ► We are considering the case where states as well as time are discrete.
- ▶ It can be more general and we discuss some of them

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- ▶ P is called the state transition probability function. It satisfies
 - $P(x,y) > 0, \ \forall x,y \in S$
 - $\sum_{y \in S} P(x, y) = 1, \forall x \in S$
- ▶ If S is finite then P can be represented as a matrix

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In this course we will consider only homogeneous chains

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- ▶ The joint distribution of $X_{i_1}, \dots X_{i_k}$ is now calculated as a marginal distribution from the joint distribution of X_0, \dots, X_m