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 - $ightharpoonup \mathcal{F} \subset 2^{\Omega}$ set of events; each event is a subset of Ω
 - ▶ $P: \mathcal{F} \rightarrow [0,1]$ is a probability (measure) that satisfies the three axioms:

A1
$$P(A) \ge 0$$
, $\forall A \in \mathcal{F}$
A2 $P(\Omega) = 1$
A3 If $A_i \cap A_j = \phi, \forall i \ne j$ then $P(\bigcup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} P(A_i)$

• When $\Omega = \{\omega_1, \omega_2, \cdots\}$ (is countable), then probability is generally assigned by

$$P(\{\omega_i\})=q_i,\;i=1,2,\cdots,\; ext{with}\;q_i\geq 0,\;\sum_iq_i=1$$

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► When Ω is finite with *n* elements, a special case is $q_i = \frac{1}{n}$, $\forall i$. (All outcomes equally likely)

► Conditional probability of *A* given (or conditioned on) *B* is

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- This holds for multiple event, e.g., P(ABC) = P(A|BC)P(B|C)P(C)
- Given a partition, $\Omega = B_1 + B_2 + \cdots + B_m$, for any event, A,

$$P(A) = \sum_{i=1}^{m} P(A|B_i)P(B_i)$$
 (Total Probability rule)

► Bayes Rule

$$P(D|T) = \frac{P(T|D)P(D)}{P(T|D)P(D) + P(T|D^{c})P(D^{c})}$$

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Bayes rule can be viewed as transforming a prior probability into a posterior probability.

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▶ If A, B are independent then so are $A\&B^c$, $A^c\&B$ and $A^c\&B^c$.

▶ Events A_1, A_2, \dots, A_n are said to be (totally) independent if for any k, $1 \le k \le n$, and any indices i_1, \dots, i_k , we have

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- Events may be conditionally independent but not independent. (e.g., 'independent' multiple tests for confirming a disease)
- ▶ It is also possible that *A*, *B* are independent but are not conditionally independent given some other event *C*.

$$P(A|BC) = \frac{P(BC|A)P(A)}{P(BC|A)P(A) + P(BC|A^c)P(A^c)}$$

We can write Bayes rule with multiple conditioning events.

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- Assuming conditional independence we can calculate the new posterior probability using the same information we had about true positive and false positive rate.

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$$= \frac{0.99 * 0.99 * 0.1}{0.99 * 0.99 * 0.1 + 0.05 * 0.05 * 0.9} = 0.97$$

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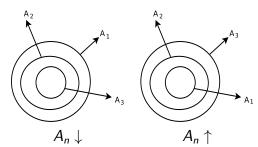
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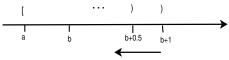
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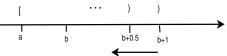
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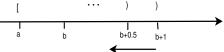
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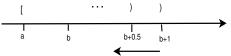
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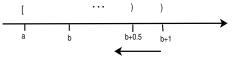
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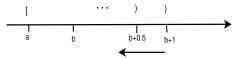
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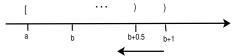
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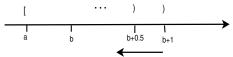
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 - ▶ $\forall \epsilon > 0, \ b + \epsilon \notin A_n$ after some $n \Rightarrow b + \epsilon \notin \cap_i A_i$.

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- Consider a sequence of intervals:

$$A_n = [a, b + \frac{1}{n}), n = 1, 2, \cdots \text{ with } a, b \in \Re, a < b.$$



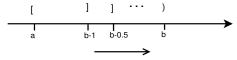
- ▶ We have $A_n \downarrow$ and $\lim A_n = \bigcap_i A_i = [a, b]$
- ▶ Why? because
 - \blacktriangleright $b \in A_n, \forall n \Rightarrow b \in \cap_i A_i$, and
 - ▶ $\forall \epsilon > 0, \ b + \epsilon \notin A_n \text{ after some } n \Rightarrow b + \epsilon \notin \cap_i A_i.$ For example, $b + 0.01 \notin A_{101} = [a, b + \frac{1}{101}).$

▶ We have shown that $\bigcap_n [a, b + \frac{1}{n}) = [a, b]$

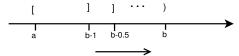
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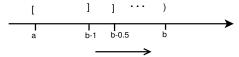


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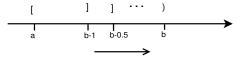
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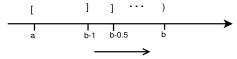
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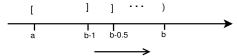
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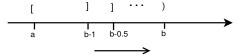
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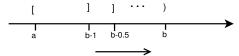
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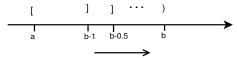
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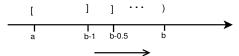
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- ► These examples also show how using countable unions or intersections we can convert one end of an interval from 'open' to 'closed' or vice versa.

➤ To summarize, limits of monotone sequences of events are defined as follows

$$A_n \downarrow \lim_{n\to\infty} A_n = \bigcap_{k=1}^{\infty} A_k$$

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Having defined the limits, we now ask the question

$$P\left(\lim_{n\to\infty}A_n\right)\stackrel{?}{=}\lim_{n\to\infty}P(A_n)$$

where we assume the sequence is monotone.

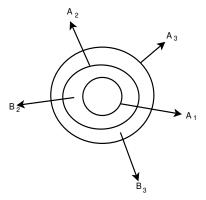
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PS Sastry, IISc, Bangalore, 2020 19/34

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- ▶ But for our problem, we can not put any fixed limit on the number of tosses and hence our sample space should be for infinite tosses of a coin.

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- ► Thus "no head in the first *n* tosses" would be an event.

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- \triangleright So, uncountable Ω arise naturally if we want to consider infinite repetitions of a random experiment

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- ► As we already saw, the probability of this event is (0.5)² which is the length of this interval

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- ► That means 'almost all' numbers in [0,1] when expanded as infinite binary fractions, satisfy this property.
- ► This is called Borel's normal number theorem and is an interesting result about real numbers.

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- The theory allows one to derive consequences or properties of the model.

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001	1/8
0 1 0	1/8
0 1 1	1/8
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101	1/8
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- Now probability theory can derive many consequences:
 - ► The tosses are independent
 - Probability of 0 or 3 heads is 1/8 while that of 1 or 2 heads is 3/8

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- ► The consequences now change
 - ► The probability that number of heads is 0 or 1 or 2 or 3 are all same and all equal 1/4.
 - ► The tosses are not independent

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- ▶ One chooses a model based on application.
- ▶ If we think tosses are independent then we choose P_1 . But if we need to model some dependence among tosses, we choose a model like P_2 .

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▶ It is also a useful model.

We next consider the concept of random variables. These allow one to specify and analyze different probability models.

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This entire course can be considered as studying different random variables.

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- lackbox We can effectively work with \Re as sample space in all probability models