

# CMO

Sheet 2 — E0230

Assignment (Due: 14 December 2020)

## Instructions

- Answer all questions
- For numerical questions, answer without any leading or trailing spaces
- You can submit MS Teams Form **only once**
- If the value of answer is an **integer**, give answer in box provided as an integer alone **without any decimal point**. For example 0, 10
- Otherwise, if the value of answer is a **decimal number**, give answer in x.yy format **rounded to 2 decimal places**. For example 0.50, 1.50
- Follow this instruction unless otherwise specified in the question
- Late submissions will be penalised

1. *Quadratic minimization.* Consider the following minimization problem

$$5x^2 + 5y^2 - xy - 11x + 11y + 11$$

- (a) Let  $[\hat{x}, \hat{y}]$  be a point satisfying the first order necessary conditions for a solution.
- (i) (1 point)  $\hat{x} =$  \_\_\_\_\_
- (ii) (1 point)  $\hat{y} =$  \_\_\_\_\_
- (b) (1 point) Is this point is a global minimum
- (c) (1 point) What would be the rate of convergence of steepest descent for this problem
- (d) (1 point) Starting at  $x=y=0$ , how many steepest descent iterations would it take (at-most) to reduce the function value to  $10^{-11}$  (in integer format)

2. *Quadratic minimization.* Let  $f : \mathbb{R}^4 \rightarrow \mathbb{R}$  be twice continuously differentiable function. Assume that the hessian of  $f$  is positive definite and the largest absolute eigen value of the Hessian matrix of  $f$  at all points is bounded above by 25. We are given that  $x_0 = [4, 0, -2, 1]^T$ ,  $f(x_0) = 6$ , and  $\nabla f(x_0) = [8, 4, 4, 2]^T$ . Using 2nd order Taylor series, find a quadratic function  $g : \mathbb{R}^4 \rightarrow \mathbb{R}$  such that  $g(x_0) = f(x_0)$  and  $f(x) \leq g(x), \forall x \in \mathbb{R}^4$ . What is the minimum value of  $g$  (rounded to the nearest integer) (5 points)?

3. *Constant step-size.* Consider the function

$$f(x) = 3(x_1^2 + x_2^2) + 4x_1x_2 + 5x_1 + 6x_2 + 7$$

where  $x = [x_1, x_2]^T \in \mathbb{R}^2$ . Suppose we use a fixed step-size gradient descent to find minimizer of  $f$ .

$$x^{k+1} = x^k - \alpha \nabla f(x^{(k)})$$

Let  $a < \alpha < b$  be the largest range of values of  $\alpha$  for which the algorithm is globally convergent. Find a,b rounded to 2 decimal places in x.yy format.

- (a) (2 points) a = \_\_\_\_\_
- (b) (3 points) b = \_\_\_\_\_

4. *Constant step-size.* Consider the function  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  given by

$$f(x) = \frac{3}{2}(x_1^2 + x_2^2) + (1+a)x_1x_2 - (x_1 + x_2) + b$$

where  $a$  and  $b$  are some unknown real valued parameters.

- (a) (2 points) Find the largest value of  $a$  (rounded to the nearest integer) for which unique global minimizer of  $f$  exists.

- (b) (3 points) Consider the following algorithm

$$x^{(k+1)} = x^k - \frac{2}{5} \nabla f(x^{(k)})$$

Find largest value of  $a$  (rounded to the nearest integer) for which the above algorithm converges to the global minimizer of  $f$  for any initial point  $x^{(0)}$ .

5. *Steepest descent.* Write a subroutine (in Python) for implementing steepest descent using exact line search.

- (a) Use the given function `f5.pkl`, its gradient `grad_f5.pkl` and hessian `hess_f5.pkl`. The function in `f5.pkl` takes an argument  $x \in \mathbb{R}^2$  as a python list of size 2 and returns a real number  $f(x)$ . Similarly, the function in `grad_f5.pkl` takes an argument  $x$  as a python list and returns  $\nabla f(x)$  as a python list. The function in `hess_f5.pkl` does not take an argument and returns hessian matrix of  $f(x)$ . The functions can be loaded as `dill.loads(pickle.load(file_pointer))`, where `dill` and `pickle` are python libraries and `file_pointer` points to the pickle file to be read. Now, test your subroutine on  $f(x)$  using initial condition  $[0, 10]^T$ . For the stopping criterion, use  $\|g^{(k)}\|_2 \leq \epsilon$  where  $\epsilon = 10^{-6}$  and  $\|\cdot\|_2$  is 2-norm.

- (i) (2.5 points) Determine number of iterations required to satisfy above stopping condition?

- (ii) (2.5 points) What is value of objective function  $f(x)$  at final point?

- (b) Now, test the subroutine for following quadratic problem  $f(x) = \frac{1}{2}x^T Ax - b^T x$ ,  $x \in \mathbb{R}^4$ . For the stopping criterion, use  $\|g^{(k)}\|_2 \leq \epsilon$  where  $\epsilon = 10^{-6}$  and  $\|\cdot\|_2$  is 2-norm.

$$\text{with } A = \begin{pmatrix} 0.78 & -0.02 & -0.12 & -0.14 \\ -0.02 & 0.86 & -0.04 & 0.06 \\ -0.12 & -0.04 & 0.72 & -0.08 \\ -0.14 & 0.06 & -0.08 & 0.74 \end{pmatrix}, b = \begin{pmatrix} 0.76 \\ 0.08 \\ 1.12 \\ 0.68 \end{pmatrix}, x_0 = 0$$

- (i) (2.5 points) Determine number of iterations required to satisfy above stopping condition?

- (ii) (2.5 points) What is value of objective function  $f(x)$  at final point?

Give answers for (ii) rounded to 2 decimal places in x.yy format.

6. *In-exact line search.* Backtracking is a form of inexact line search in which a step size is determined at each step which satisfies the Armijo-Goldstein condition. Given constants  $\alpha, \beta \in (0, 1)$ , at each step of the algorithm, if the current point is  $x \in \mathbb{R}^d$ , the direction of line search is chosen as  $u = -\nabla f(x)$ , and for determining the step size, an initial step size  $t = 1$  is chosen and is repeatedly updated as  $t \leftarrow \beta t$  until  $f(x + tu) \leq f(x) + \alpha t \nabla f(x)^T u$  and then  $x$  is updated as  $x \leftarrow x + tu$ . Once the update distance  $\|tu\|_2$  for the point  $x$

becomes less than  $\epsilon$  during any epoch, the algorithm is stopped.

Use the given function `f6.pkl` and its gradient `grad_f6.pkl`. The function in `f6.pkl` takes an argument  $x \in \mathbb{R}^4$  as a python list of size 4 and returns a real number  $f(x)$ .

Similarly, the function in `grad_f6.pkl` takes an argument  $x$  as a python list and returns  $\nabla f(x)$  as a python list. The functions can be loaded as

`dill.loads(pickle.load(file_pointer))`, where `dill` and `pickle` are python libraries and `file_pointer` points to the pickle file to be read.

Apply backtracking line search algorithm with initial point  $[10, 100, 100, 10]$ ,  $\alpha = 0.5$ ,  $\beta = 0.5$  and  $\epsilon = 10^{-7}$ .

- (a) Let  $[x_1, x_2, x_3, x_4]$  the solution vector with each element rounded to 2 decimal places in x.yy format.
  - (i) (1 point)  $x_1 =$  \_\_\_\_\_
  - (ii) (1 point)  $x_2 =$  \_\_\_\_\_
  - (iii) (1 point)  $x_3 =$  \_\_\_\_\_
  - (iv) (1 point)  $x_4 =$  \_\_\_\_\_
- (b) (3 points) Give the number of iterations it took to obtain the result.
- (c) (i) (1.5 points) Give the least number of function calls to `f6` to obtain the result.  
 (ii) (1.5 points) Give the least number of function calls to `grad_f6` used to obtain the result.

7. *One-dimensional search methods.* Consider the one-dimensional minimization problem

$$\min_{x \in [a, b]} f(x) \quad (1)$$

We are given  $a, b$  and a subroutine 'foo'. The subroutine 'foo' returns the value function  $f(x)$  for any  $x \in [a, b]$ . Let  $x^*$  be the unique minimizer for this problem. Given a tolerance value  $\epsilon > 0$ , we are interested in finding  $\hat{x} \in [a, b]$  such that  $|\hat{x} - x^*| \leq \epsilon$ . Here is a pseudo-code to find  $\hat{x}$ .

- Initialize:  $x_l = a, x_u = b$
- In loop:
  - $d = (x_u - x_l) * \rho, 0 < \rho < 1$
  - $x_- = x_u - d, x_+ = x_l + d$
  - if  $f(x_-) < f(x_+)$  then  $x_u = x_+$  otherwise  $x_l = x_-$
- Output:  $0.5(x_l + x_u)$ , tolerance =  $0.5(x_u - x_l)$ ,  $NSC$  = number of times the subroutine 'foo' was called.

Using the generic pseudo-code described above, we want you to implement two line search techniques for uni-modal functions. First is Golden section search (GS) where  $\rho = \frac{\lambda}{(1+\lambda)}$  where  $\lambda = 0.5(1 + \sqrt{5})$ . Now implement Golden section search as a function (in Python). Note that the loop part of GS continues until  $tolerance \leq \epsilon$  is satisfied.

Second is Fibonacci search. In FS,  $k^{th}$  iteration uses  $\rho = \frac{F_{N-k}}{F_{N-k+1}}$ , where  $F_0 = 1$ ,  $F_1 = 1$ ,  $F_n = F_{n-1} + F_{n-2} \geq 2$  is the Fibonacci sequence. Note that in FS, the loop will be executed  $N - 1$  times.

Implement the 'foo' subroutine such that 'foo(x)' returns  $e^{-x} - \cos(x)$  for  $x \in [0, 1]$ . First call FS subroutine for  $N = 20$ ,  $N = 10$ . Then call GS subroutine with  $\epsilon$  returned by tolerance value of FS. Give answers for  $\hat{x}$  and tolerance rounded to 3 decimal places in the form **x.yyy**.

- (a) Run FS subroutine for  $N = 20$  and report the following values
  - (i) (1 point)  $\hat{x} =$  \_\_\_\_\_
  - (ii) (1 point)  $tolerance =$  \_\_\_\_\_
  - (iii) (0.5 points)  $NSC =$  \_\_\_\_\_
- (b) Run GS subroutine using  $\epsilon$  calculated in (a) and report the following values
  - (i) (1 point)  $\hat{x} =$  \_\_\_\_\_
  - (ii) (1 point)  $N =$  \_\_\_\_\_
  - (iii) (0.5 points)  $NSC =$  \_\_\_\_\_
- (c) Run FS subroutine for  $N = 10$  and report the following values
  - (i) (1 point)  $\hat{x} =$  \_\_\_\_\_
  - (ii) (1 point)  $tolerance =$  \_\_\_\_\_
  - (iii) (0.5 points)  $NSC =$  \_\_\_\_\_
- (d) Run GS subroutine using  $\epsilon$  calculated in (c) and report the following values
  - (i) (1 point)  $\hat{x} =$  \_\_\_\_\_
  - (ii) (1 point)  $N =$  \_\_\_\_\_
  - (iii) (0.5 points)  $NSC =$  \_\_\_\_\_