

Computational Methods in Physics (PHY 365)

FA23

Dr. Muhammad Kamran

Department of Physics

COMSATS University Islamabad

Lab 17

Differential equations

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- The **order** of a DE is the order of the **highest derivative** of the unknown function that appears in the equation.
- A **homogeneous*** DE is one in which the source function is **zero**.

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- A DE does not, **in general**, determine a unique solution function.
- A DE is usually accompanied by **auxiliary conditions**.
- These conditions, together with the DE, specify the unknown function precisely.

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- An ODE is called **implicit** when the derivative of the dependent variable can not be isolated and moved to the other side of the equal sign.

$$y^{(1)}(x) = f\left(x, y(x), y^{(1)}(x)\right).$$

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- We often want a numerical solution to a differential equation because
 - the closed form solution may be very complicated and difficult to evaluate, or
 - no closed-form solution can be found.

Euler's method

- This numerical method does not have the utmost generality, but it is natural and capable of high precision.
- Its principle is to represent the solution of a differential equation locally by a few terms of its Taylor series.

$$x(t+h) = x(t) + hx'(t) + \frac{h^2}{2!}x''(t) + \dots + \frac{h^m}{m!}x^{(m)}(t) + \dots \quad (1)$$

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- For numerical purposes, the Taylor series truncated after $m+1$ terms enables us to compute $x(t+h)$ rather accurately
 - if h is small, and
 - if the m derivatives are known.

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- To find approximate values of the solutions to the initial-value problem

$$\begin{cases} x' = f(t, x(t)) \\ x(a) = x_a \end{cases} \quad (2)$$

over the interval $[a, b]$, the first two terms in the Taylor series (1) are used.

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over the interval $[a, b]$, the first **two** terms in the Taylor series (1) are used.

$$x(t+h) \approx x(t) + hx'(t). \quad (3)$$

Euler's method

- Hence, the formula

$$x(t+h) = x(t) + hf(t, x(t)). \quad (4)$$

can be used to step from $t = a$ to $t = b$ with n steps of size $h = (b - a) / n$.

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- Since only two terms of the Taylor series are used in Euler's method, it is not very accurate.
- In solving an IVP, it is useful to distinguish two types of errors
 - ◇ local truncation error
 - ◇ global truncation error

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- For Euler's method, the local error is simply the remainder of Taylor's approximation, i.e., $O(h^2)$.
- Since at each step of Euler's method an additional truncation error is introduced, the accumulation of these errors is called the global truncation error.

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- The interval, step size, and initial condition

$a = 0;$

$b = 1;$

$\text{no_steps} = 1;$

$\text{step_size} = (b - a) / \text{no_steps};$

$x_0 = 1;$

Euler's method

- The function

$$f = f(t, x);$$

Euler's method

- The function

```
f = @(t , x) x;
```

- Applying Euler's method

```
for n = 1 : no_steps  
    x = x_0 + step_size * f(a , x_0);  
    x_0 = x;  
    a = a + step_size;  
end
```

Euler's method

- Displaying the result

```
disp ( [ 'The approximate value is ', num2str(x) ] )
```

References

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- <https://tutorial.math.lamar.edu/classes/de/de.aspx>
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