Computer Architecture

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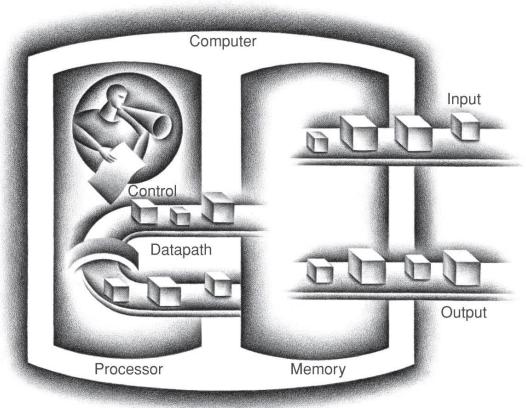
Chapter 2: Computer Functions and Interconnection

- Computer Components
- 2. Computer Functions
- 3. Inter-connection Structures

[with materials from Computer Organization and Architecture, 10th Edition, William Stallings, ©2016, Pearson]

Computer Organization

From Chap.1: classic components of a computer

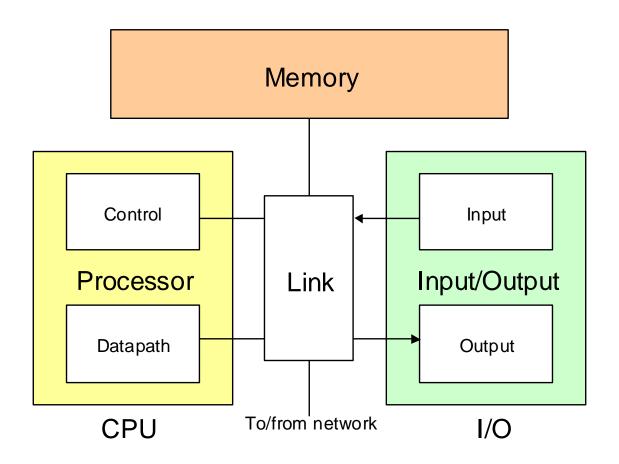


Computer

- Input data
- Execute stored programs
- Output result

1. Computer Components

More detailed computer organization



Computer organization with system link

CPU (Central Processing Unit)

- Control Unit
 - Fetch instruction from memory.
 - Interpret instruction.
 - Control other components to execute instruction.
- Datapath: performs arithmetic operations to process data.
- Register file (chapter 3): small and fast data storage for instruction execution.
- Some other dedicated components

CPU

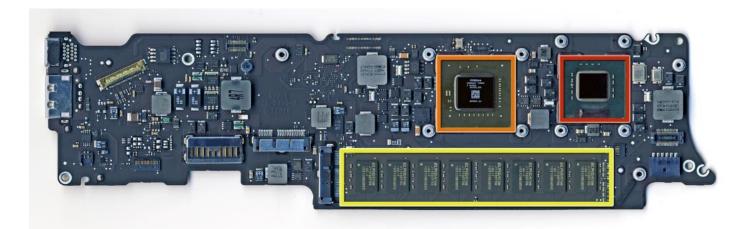
Example: Apple A5



Memory

- □ Store instructions of the running programs.
- Store data that are currently in use.

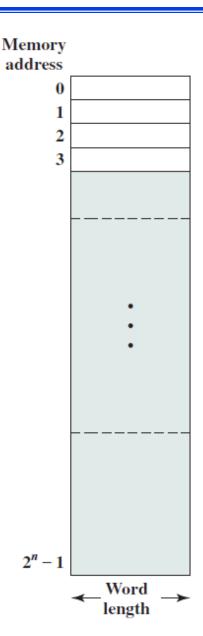




Futher reading: memory technologies

Memory

- Logical organization
 - Array of memory cells
 - Each cell holds one byte of data
 - Each cell is assigned an unique adress
 - Data value can be changed, address is fixed
- Data are stored on memory cells
 - 8-bit integer requires 1 cell
 - 32-bit integer requires 4 cells
 - Array requires consecutive cells according to its size.

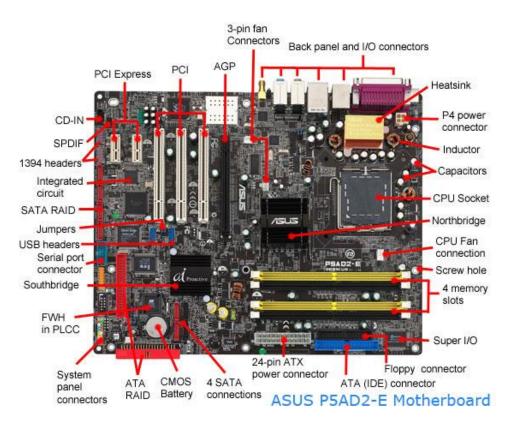


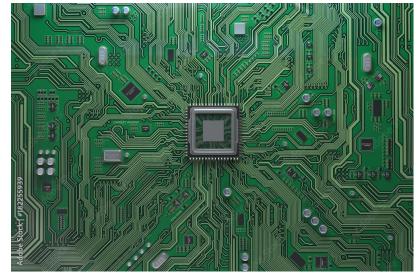
Input/output

- □ Interfacing computer with physical world/environment.
- Types of I/O device
 - Input: mouse, keyboard, webcam...
 - Output: display, printer, speaker...
 - Storage: HDD, SSD, optical, USB drives...
 - Communication: WiFi, Ethernet, Bluetooth modules...

Link: System interconnection

- The fabric to connect all components
- Huge number of connection, requires very good design so that all components function properly





2. Computer functions

- Executing program
- Interrupt
- Input/Output

2.1 Executing program

- □ → the most basic function of computers.
- Program: a set of instructions.
- Computers execute instructions sequentially.
- Instruction cycle:
 - Instruction fetch: control unit fetches an instruction from memory
 - Instruction execution:
 - control unit decodes instruction,
 - then "tells" datapath and other components to perform the required action.

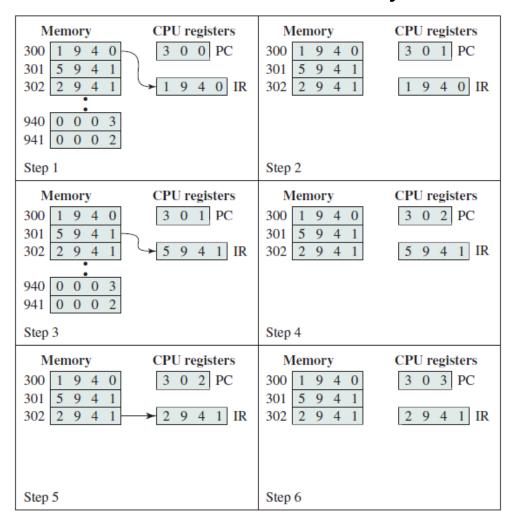
More details in Chapter 5.

Instruction fetch

- Importance
 - To get the correct instruction.
 - To execute all instructions in a program sequentially.
- At the beginning of each instruction cycle the processor fetches an instruction from memory.
- □ The program counter (PC) holds the address of the instruction to be fetched.
- □ The processor increases PC after each instruction fetch so that PC points to the next instruction in sequence.
- The fetched instruction is loaded into the instruction register (IR).

Instruction fetch

Automatic increment of PC in fetch cycle

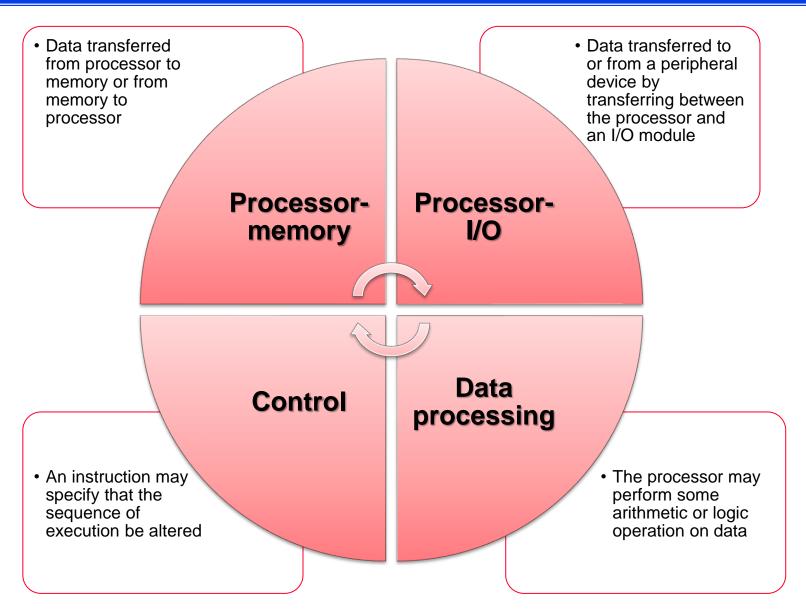


Elaboration: How to support branching?

Instruction execution

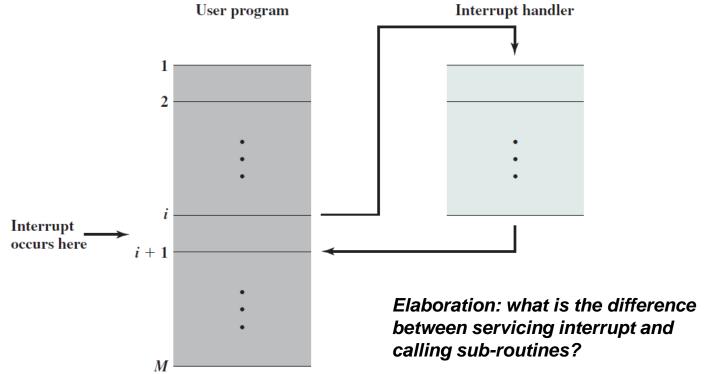
- Instruction (fetched and stored in IR) is decoded to get
 - The operation that the processor needs to do
 - The location to get input data (source operands)
 - The location to store output data (destination operand)
- Operand address calculation: calculate the address of operands
- Operand fetch: fetch source operands
- Data operation: perform the action on source operands and get result
- Operand store: store result into destination operand

Types of operation



2.2 Interrupt

- □ The mechanism to allow other components (memory, I/O) interrupt the normal processing of processor.
- Servicing interrupt: processor temporarily switch from the current program to execute a different (rather short) program, before continuing the original program.



Sources of interrupt

- Typical sources of interrupt:
 - Software/program: occurs during instruction execution upon some special condition such as division by 0, arithmetic overflow... Can also be called exception.
 - Timer: generated by system timer inside processor, to provide timing service, such as for operating system task scheduler service.
 - I/O: generated by I/O modules, to request service from processor or acknowledge the completion of an operation.
 - Hardware failure: generated when error happens with hardware.
- Example: detecting keyboard events (key up/key down)
 - Method 1: CPU checks keyboard status frequently
 - Method 2: keyboard issue interrupt to notify CPU upon key up/down

Which is better regarding CPU usage?

Interrupt handler/Interrupt service routine (ISR)

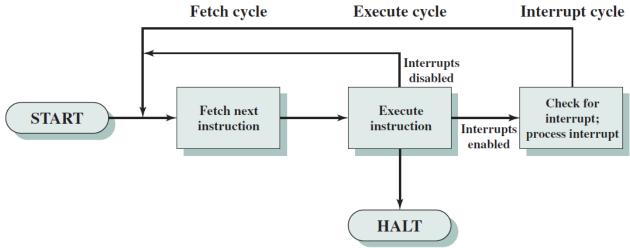
- Special programs to be executed to service interrupts.
- Usually a part of operating system or system software.
- Typical operation:
 - Determine the nature of interrupt: source and reason of interrupt.
 - Perform corresponding operation.
 - Return control to the interrupted program.

Structure:

Interrupt handler ends with a special instruction, to restore context and value of PC, so that CPU can continue the interrupted program properly.

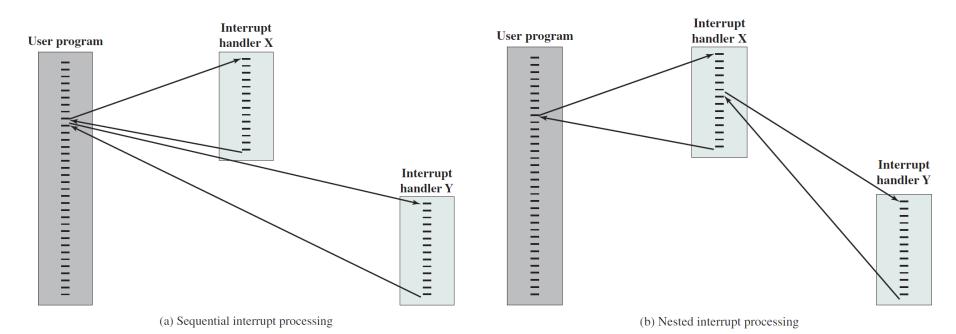
Servicing interrupts: instruction and interrupt cycle

- Interrupt is checked at the end of each instruction cycle
- □ Interrupt cycle if interrupt occurred:
 - CPU saves context of current program (current value of PC).
 - Address of interrupt handler is loaded to PC.
 - CPU continues with new instruction cycles, with new PC. Interrupt handler will be executed instead of original program.
 - At the end of interrupt handler, context will be restored including PC value. CPU return to the interrupted program.



Multiple interrupt procesing

- Number of interrupt sources is (always) high.
- Interrupts can occur at the same time or overlap.
- Sequential vs nested interrupt processing
 - Usually priority-based.
 - More details in chapter 7.

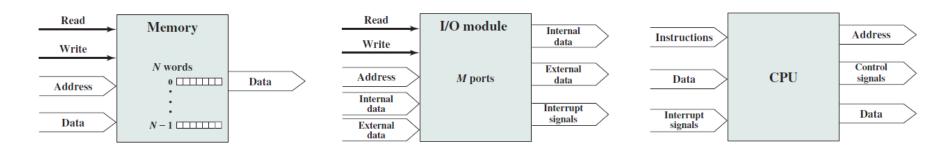


2.3 Input/output

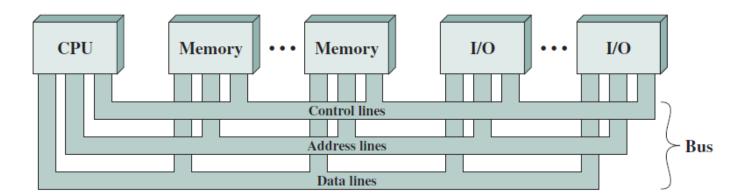
- The operation when data is transferred between I/O modules and CPU/memory.
- CPU-controlled data transfer: data is transferred between CPU and I/O, under the control of CPU.
- Direct memory access: data is transferred between memory and I/O, under the control of special controllers called DMAC.

3. System interconnection

- Interconnection model of each component
 - → Need to connect these components

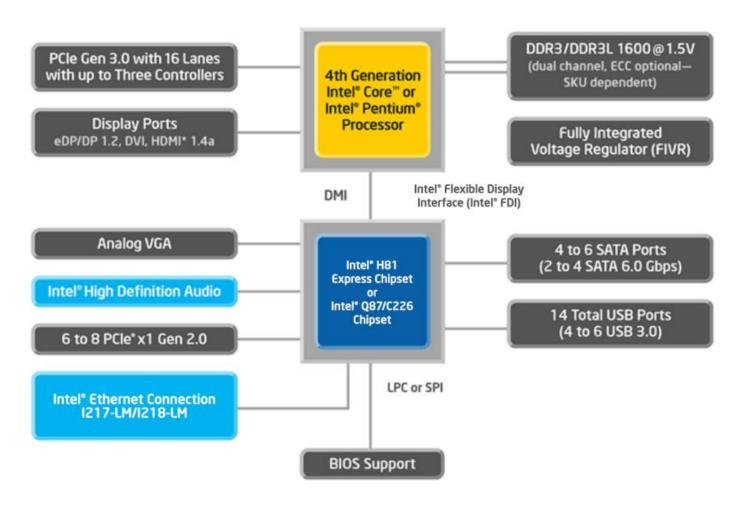


Theoretical bus interconnection scheme



System interconnection

Interconnection system for high performance computers: hierarchical bus



End of chapter 2