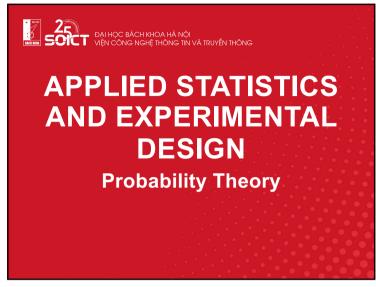


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Applied Statistics and Experimental Design

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II. Basics of Probability theory

- 2.1. Probability.
- 2.2. Random variables.
- 2.3. Law of large number
- 2.4. Normal probability distribution (Gaussian distribution).



}

- Probability
 - · Laplace classic definition of probability:

 $P(A) = \frac{\text{Number of outcomes favorable to } A}{A}$ Total number of possible outcomes

Relative frequency definition of probability:

$$P(A) = \lim_{n \to \infty} \frac{n_A}{n}$$



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2.1. Probability

- · Events: A and B
 - Mutualy exclusive events: A ∩ B = Ø
 - Partition of Ω :



 $A_i \cap A_j = \phi$, and $\bigcup A_i = \Omega$



 ${\cal A} \cap {\cal B} = \phi$ • Example: experiment of tossing two coins simultaneously · Elementary events:

$$\xi_1 = (H, H), \quad \xi_2 = (H, T), \quad \xi_3 = (T, H), \quad \xi_4 = (T, T)$$

• The subset $A = \{ \xi_1, \xi_2, \xi_3 \}$



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2.1. Probability

- · Kolmogorov axiomatic formulation
 - Ω : sample space: set of all experimental outcomes

$$\Omega = \{ \, \xi_1, \, \xi_2, \, \dots \, \xi_k, \, \dots, \, \xi_n, \, \dots \, \}$$

- Event any subset of Ω . Number of subset of sample space : 2^n if $n < \infty$.
- σ -field F of subsets of Ω
- P: a probability measure on the sets in F
 - A any event
 - · 3 axiom of probability
 - (i) $P(A) \ge 0$ (Probability is a nonnegative number)
 - (ii) $P(\Omega) = 1$ (Probability of the whole set is unity)
 - (iii) If $A \cap B = \emptyset$, then $P(A \cup B) = P(A) + P(B)$.
- $<\Omega$, F, P >: probability model



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Probability

- Counting the sample points
 - Evaluate is the element of chance associated with the occurrence of certain events when an experiment is performed.
 - · To solve a probability problem by counting the number of points in the sample space without actually listing each element.
 - The fundamental principle of counting multiplication rule:
 - If an operation can be performed in n_1 ways, and if for each of these a second operation can be performed in n_2 ways, and for each of the first two a third operation can be performed in n_3 ways, and so forth, then the sequence of koperations can be performed in $n_1n_2 \cdots n_k$ ways.



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- Conditional probability and independence
 - N independent trials,
 - N_A , N_B , N_{AB} : the number of times events A, B and AB
 - For large N $P(A) \approx \frac{N_A}{N}$, $P(B) \approx \frac{N_B}{N}$, $P(AB) \approx \frac{N_{AB}}{N}$.
 - Conditional probability: P(A|B)

$$P(A | B) = \frac{N_{AB}}{N_B} = \frac{N_{AB} / N}{N_B / N} = \frac{P(AB)}{P(B)}$$



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2.1. Probability

- If B ⊂ A then P(A|B) = 1
- If A ⊂ B then P(A|B) > P(A)
- Let, $A_1, A_2, \, ..., \, A_n$ are pair wise disjoint and their union is

$$A_i \cap A_j = \emptyset, \qquad \bigcup_{i=1}^n A_i = \Omega.$$

· B is an event

$$P(B) = \sum_{i=1}^{n} P(BA_i) = \sum_{i=1}^{n} P(B \mid A_i) P(A_i).$$



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2.1. Probability

- Properties of conditional probability
 - P(A|B) is nonnegative:

$$P(A | B) = \frac{P(AB) \ge 0}{P(B) > 0} \ge 0,$$

P(Ω|B) = 1

$$P(\Omega \mid B) = \frac{P(\Omega B)}{P(B)} = \frac{P(B)}{P(B)} = 1,$$

• If $A \cap C = \emptyset$,

$$P(A \cup C \mid B) = P(A \mid B) + P(C \mid B),$$



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2.1. Probability

• Independence: A and B events

P(AB) = P(A) P(B)

- · If A and B are independent events:
- Bayes theorem $P(A \mid B) = P(A)$

$$P(A \mid B) = \frac{P(B \mid A)}{P(B)} \cdot P(A)$$

· Generalized Bayes theorem:

$$P(A_i \mid B) = \frac{P(B \mid A_i)P(A_i)}{P(B)} = \frac{P(B \mid A_i)P(A_i)}{\sum_{i=1}^{n} P(B \mid A_i)P(A_i)},$$



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- Bayes' theorem interpretation:
 - *P*(*A*) represents the a-priori probability of the event *A*.
 - The event B is new knowledge obtained from an experiment.
 - Conditional probability P(A|B) of A given B –
 - a-posteriori probability
 - The new information should be used to improve knowledge of A.



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2.1. Probability

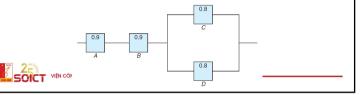
- Example:
 - In a box: 6 white and 4 black balls.
 - Remove two balls randomly without replacement.
 - P{the first one is white and the second one is black} = ?
 - Question: are events W₁ and B₂ independent?
 - W1 = "first ball removed is white"
 - B2 = "second ball removed is black"



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Probability

- Examples
 - An electrical system consists of four components. The system works if components A and B work and either of the components C or D works. The reliability (probability of working) of each component is also shown in the Figure. Find the probability that:
 - (a) the entire system works and
 - (b) the component C does not work, given that the entire system works. Assume that the four components work independently.



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2.1. Probability

• If, in an experiment, the events A_1, A_2, \ldots, A_k can occur,

 $P(A_1 \cap A_2 \cap \ldots \cap A_k) = P(A1)P(A2|A1)P(A3|A1 \cap A2) \ldots P(A_k|A_1 \cap A_2 \cap \ldots \cap A_{k-1}).$

• If the events A_1, A_2, \ldots, A_k are independent, then $P(A_1 \cap A_2 \cap ... \cap A_k) = P(A_1)P(A_2) ... P(A_k).$

- Example
 - · Three cards are drawn in succession, without replacement, from an ordinary deck of playing cards. Find the probability that the event A1 \cap A2 \cap A3 occurs, where A1 is the event that the first card is a red ace, A2 is the event that the second card is a 10 or a jack, and A3 is the event that the third card is greater than 3 but less than 7.



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- Example: Two boxes B1 and B2 contain 100 and 200 light bulbs respectively. The first box (B1) has 15 defective bulbs and the second -5. Suppose a box is selected at random and one bulb is picked out.
 - (a) What is the probability that it is defective?
 - (b) Suppose we test the bulb and it is found to be defective. What is the probability that it came from box 1?



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2.1. Probability

• An event A has probability p of occurring in a single trial. Find the probability that A occurs exactly k times in determined location, k $\leq n$ in *n* trials.

$$P_{0}(\omega) = P(\{\xi_{i_{1}}, \xi_{i_{2}}, \dots, \xi_{i_{k}}, \dots, \xi_{i_{n}}\}) =$$

$$= P(\{\xi_{i_{1}}\})P(\{\xi_{i_{2}}\})\dots P(\{\xi_{i_{k}}\})\dots P(\{\xi_{i_{n}}\}) =$$

$$= \underbrace{P(A)P(A)\dots P(A)}_{k} \underbrace{P(\overline{A})P(\overline{A})\dots P(\overline{A})}_{n-k} = p^{k}q^{n-k}.$$

- P{ A occurs exactly k time in n trials } = $C_{np}^{k}q^{n-k}$
 - Bernoulli formula



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2.1. Probability

- Repeated trials, Bernoulli trials
 - Consider *n* independent experiments with models (Ω_1 , F_1 , P_1). $(\Omega_2, F_2, P_2), ..., (\Omega_n, F_n, P_n).$
 - Let $\xi_1 \in \Omega_1$, $\xi_2 \in \Omega_2$,..., $\xi_n \in \Omega_2$: elementary events.
 - A joint performance of the *n* experiments produces an elementary events $\omega = (\xi_1, \, \xi_2, \, ..., \, \xi_n)$.
 - Consider space $\Omega = \Omega_1 \times \Omega_2 \times ... \times \Omega_n : \xi_1 \in \Omega_1, ..., \xi_n \in \Omega_n$
 - Events in combined space Ω are of the form $A_1 \times A_2 \times ... \times A_n$.
 - If *n* experiments are independent, then $P(A_1 \times A_2 \times ... \times A_n) = P(A_1) \times ... \times P(A_n)$



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2.1. Probability

- De Moivre Laplace Theorem
 - Guess that: $n \rightarrow \infty$ with fixed p.
 - k is in the neighborhood

 \sqrt{npq} of np.

• Bernoulli probability estimation:

$$C_n^k p^k q^{n-k} \approx \frac{1}{\sqrt{2\pi npq}} e^{-(k-np)^2/2npq}.$$

• Stirling formula for n! approximation:

$$n! \sim \sqrt{2\pi} n^{n+\frac{1}{2}} e^{-n}$$



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· Estimation of Bernoulli formula

$$\binom{n}{k} p^{k} q^{n-k} = \frac{n!}{(n-k)!k!} p^{k} q^{n-k},$$

$$\binom{n}{k} p^{k} q^{n-k} > c_{1} \sqrt{\frac{n}{2\pi(n-k)k}} \left(\frac{np}{k}\right)^{k} \left(\frac{nq}{n-k}\right)^{n-k}$$

$$\binom{n}{k} p^{k} q^{n-k} < c_{2} \sqrt{\frac{n}{2\pi(n-k)k}} \left(\frac{np}{k}\right)^{k} \left(\frac{nq}{n-k}\right)^{n-k}$$

• Các hằng số c_1 và c_2 khá gần nhau.

ác hằng số c₁ và c₂ khá gần nhau.
$$c_1 = e^{\left\{\frac{1}{12n+1} - \frac{1}{12(n-k)} - \frac{1}{12k}\right\}} \qquad c_2 = e^{\left\{\frac{1}{12n} - \frac{1}{12(n-k)+1} - \frac{1}{12k+1}\right\}}.$$



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2.2. Random variables

- Definition
 - (Ω, F, P) probability model for an experiment,
 - X a function that maps every $\xi \in \Omega$ to a unique point $x \in R$
 - Random Variable (r.v): a finite single valued function that maps the set of all experimental outcomes Ω into the set of real numbers R is said to be a r.v, if the set $A = \{\xi | X(\xi) \le x\}$ is an event $A \subset F$ for every x in R.



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2.1. Probability

- Example:
 - Toss a coin *n* times. Probability of getting *k* heads in *n* trials =
 - · Consider rolling a fair dice eight times. Find the probability that either 3 or 4 shows up five times.
 - Suppose 5.000 components are ordered. The probability that a part is defective equals 0.1. What is the probability that the total number of defective parts does not exceed 400?

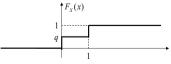


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2.2. Random variables

- Probability distribution function
 - Probability distribution function of random variable X: (pdf)
 - $F_X(x)=P\{\xi|X(\xi)\leq x\}\geq 0$
 - Examples
 - $X r.v: X(\xi) = c, \xi \in \Omega, F_X(x) = ?$
 - X r.v. coin tossing, $\Omega = \{H, T\}$. X(T) = 0, X(H) = 1. $F_X(x) = ?$





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2.2. Random variables

- Properties of probability distribution function
 - $F_x(x)$ is a distribution function:
 - $F_X(-\infty) = 0$; $F_X(+\infty) = 1$
 - Pdf is nondecreasing function:

if $x_1 \le x_2$ then $F_X(x_1) \le F_X(x_2)$

• Pdf is right continuous: $F_X(x^+) = F_X(x) \forall x$



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2.2. Random variables

- Continuous and discrete random variables
 - X continuous r.v if $F_X(x)$ is continuous
 - For continuous r.v, $F_X(x) = F_X(x)$ and $P\{X=x\} = 0$
 - If F_X(x) = const, except for a finite number of jump discontinuities, then X is said to be a discrete-type r.v.
 - If x_i is such a discontinuity point, then

$$p_i = P\{ X = x_i \} = F_X(x) - F_X(x-)$$



2.2. Random variables

• If $F_X(x_0) = 0$ for some x_0 , then $F_X(x) = 0 \ \forall x \le x_0$

• P{ $X(\xi) > x$ } = 1 - $F_X(x)$

• If $x_2 > x_1$, then

$$P\{ x_1 < X(\xi) \le x_2 \} = F_X(x_2) - F_X(x_1)$$

• $P\{X(\xi) = x\} = F_X(x) - F_X(x)$

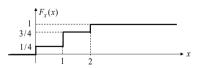


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2.2. Random variables

- Examples
 - A fair coin is tossed twice, and let the r.v X represent the number of heads. Find $F_X(x)$





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2.2. Random variables

- Distribution density function
 - Derivative of distribution function $F_x(x)$ is density function $f_X(x)$ of the r.v.

 $f_X(x) = \frac{dF_X(x)}{dx}$.

• $F_X(x)$ is monoton nondecreasing function, so that

 $f_X(x) = \frac{dF_X(x)}{dx} = \lim_{\Delta x \to 0} \frac{F_X(x + \Delta x) - F_X(x)}{\Delta x} \ge 0,$



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2.2. Random variables

 $P\{x_1 < X(\xi) \le x_2\} = F_X(x_2) - F_X(x_1) = \int_{x_1}^{x_2} f_X(x) dx.$



2.2. Random variables

- If r.v is continuous then f_X(x) is continuous.
- For discrete r.v

$$f_X(x) = \sum_i p_i \delta(x - x_i), \qquad \uparrow^{f_X(x)} p_i$$
• x_i is jump-discontinuity point function in $F_X(x)$

 $F_X(x) = \int_{-\infty}^{x} f_x(u) du$. $F_X(+\infty) = 1, \quad \int_{-\infty}^{+\infty} f_X(x) dx = 1,$

 $P\{x_1 < X(\xi) \le x_2\} = F_X(x_2) - F_X(x_1) = \int_{x_1}^{x_2} f_X(x) dx.$

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2.2. Random variables

- Some continuous random variables
 - Normal (Gaussian) random variables $X \sim N(\mu, \sigma^2)$
 - · Density function

$$f_X(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-(x-\mu)^2/2\sigma^2}.$$
• Bell shape curve

- · Distribution function

$$F_{X}(x) = \int_{-\infty}^{x} \frac{1}{\sqrt{2\pi\sigma^{2}}} e^{-(y-\mu)^{2}/2\sigma^{2}} dy = G\left(\frac{x-\mu}{\sigma}\right),$$

 $G(x) = \int_{-\infty}^{x} \frac{1}{\sqrt{2\pi}} e^{-y^{2}/2} dy$

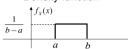


2.2. Random variables

· Uniform random variables:

$$X \sim U(a,b), \ a < b,$$

Density function



 $f_X(x) = \begin{cases} \frac{1}{b-a}, & a \le x \le b, \\ 0, & \text{otherwise.} \end{cases}$

Exponential random variables

$$X \sim \varepsilon(\lambda)$$

· Density function

$$f_X(x) = \begin{cases} \frac{1}{\lambda} e^{-x/\lambda}, & x \ge 0, \\ 0, & \text{otherwise.} \end{cases}$$

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Random variables

Poisson r.v

$$X \sim P(\lambda)$$
,

$$P(X = k) = e^{-\lambda} \frac{\lambda^k}{k!}, k = 0, 1, \dots, \infty.$$

$$P(X = k)$$



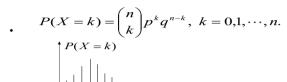
2.2. Random variables

· Some important discrete random variables

• Bernoulli r.v: X takes values 0, 1

$$P(X = 0) = q$$
, $P(X = 1) = p$.

 Binomial r.v $X \sim B(n, p)$,





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2.3 Some characteristics of random variables

Mean value

$$\eta_X = \overline{X} = E(X) = \int_{-\infty}^{+\infty} x f_X(x) dx.$$

· For discrete random variable

$$\eta_X = \overline{X} = E(X) = \int x \sum_i p_i \delta(x - x_i) dx = \sum_i x_i p_i \underbrace{\int \delta(x - x_i) dx}_{i}$$
$$= \sum_i x_i p_i = \sum_i x_i P(X = x_i).$$



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Mean and Variance

• Example: uniform random variable

$$E(X) = \int_{a}^{b} \frac{x}{b-a} dx = \frac{1}{b-a} \frac{x^{2}}{2} \bigg|_{a}^{b} = \frac{b^{2}-a^{2}}{2(b-a)} = \frac{a+b}{2}$$

• Example: exponential random variable

$$E(X) = \int_0^\infty \frac{x}{\lambda} e^{-x/\lambda} dx = \lambda \int_0^\infty y e^{-y} dy = \lambda,$$

• Example: Poisson random variable

$$E(X) = \sum_{k=0}^{\infty} kP(X=k) = \sum_{k=0}^{\infty} ke^{-\lambda} \frac{\lambda^k}{k!} = e^{-\lambda} \sum_{k=1}^{\infty} k \frac{\lambda^k}{k!}$$
$$= e^{-\lambda} \sum_{k=1}^{\infty} \frac{\lambda^k}{(k-1)!} = \lambda e^{-\lambda} \sum_{i=0}^{\infty} \frac{\lambda^i}{i!} = \lambda e^{-\lambda} e^{\lambda} = \lambda.$$



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2.3 Some characteristics of random variables

- Example:
- Example: variance of Poisson r.v.

$$\sigma_{x}^{2} = \overline{X^{2}} - \overline{X}^{2} = (\lambda^{2} + \lambda) - \lambda^{2} = \lambda.$$

· Example: variance of Gaussian r.v.

$$Var(X) = E[(X - \mu)^{2}] = \int_{-\infty}^{+\infty} (x - \mu)^{2} \frac{1}{\sqrt{2\pi\sigma^{2}}} e^{-(x - \mu)^{2}/2\sigma^{2}} dx.$$

$$Var(X) = \sigma^2$$



2.3 Some characteristics of random variables

- Variance

 - For r.v X with mean μ Variance $\sigma_{_{_{v}}}^{^{2}}=E[\left(X-\mu\right)^{2}]>0.$

• Or
$$\sigma_x^2 = \int_{-\infty}^{+\infty} (x - \mu)^2 f_X(x) dx > 0.$$

- · Standard deviation
- $\sigma_{X} = \sqrt{E(X-\mu)^2}$
- · Variance anf means $Var(X) = \sigma_X^2 = E[(X - \mu)^2] = E[X^2 - 2X\mu + \mu^2] =$ $E[X^2] - E[2X\mu] + E[\mu^2] = E[X^2] - 2E[X]\mu + \mu^2$



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2.3 Some characteristics of random variables

- Moments
 - X random variables

$$m_n = X^n = E(X^n), \quad n \ge 1$$

· Central moments

$$\mu_n = E[(X - \mu)^n]$$

· Relation between moments and central moments

$$\mu_n = E[(X - \mu)^n] = \sum_{k=0}^n C_n^k m_k (-\mu)^{n-k}.$$

· Mean and variance:

$$\mu = m_1, \qquad \sigma^2 = \mu_2.$$



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2.3 Some characteristics of random variables

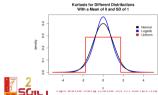
· Generalized moments of X about a

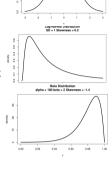
$$E[(X-a)^n]$$

· Absolute moments of X

$$E[|X|^n]$$

- Measure of skewness is $E[(X \mu_X)^3]/\sigma^3_X$
- Measure of kurtosis is EI(X μ_X)⁴]/ σ^4_X .





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2.4 Chebychev Inequality and Law of Large numbers

- Chebychev Inequality
 - Consider an interval of width 2ε symmetrically centered around its mean μ



Chebychev Inequality

$$P(|X-\mu|\geq \varepsilon)\leq \frac{\sigma^2}{\varepsilon^2},$$



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2.3 Some characteristics of random variables

- · Characteristic function
 - Continuous r.v X

$$\Phi_X(\omega) \stackrel{\Delta}{=} E(e^{jX\omega}) = \int_{-\infty}^{+\infty} e^{jx\omega} f_X(x) dx.$$

We have:

$$\Phi_{V}(0) = 1,$$

• And • Discrete r.v $|\Phi_X(\omega)| \le 1 \quad \forall \omega$

$$\Phi_X(\omega) = \sum_k e^{jk\omega} P(X = k).$$



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2.4 Chebychev Inequality and Law of Large numbers

- · Weak law and strong law of large numbers
 - X_i independent, identically distributed Bernoulli random

$$P(X_i) = p,$$
 $P(X_i = 0) = 1 - p = q,$

- $k = X_1 + X_2 + ... + X_n$ number of successes in *n* trials
- Weak law of large numbers:

$$P\{\left|\frac{k}{n}-p\right|>\varepsilon\}\leq \frac{pq}{n\varepsilon^2}$$

- - The ratio k/n tends to p not only in probability, but with probability 1



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2.5. Gaussian distribution

- Gaussian distribution
 - One dimentional normal distribution

$$p(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2\right]$$

$$\mu \equiv E(x) = \int_{-\infty}^{\infty} xp(x)dx$$

$$\sigma^2 \equiv E((x-\mu)^2) = \int_{-\infty}^{\infty} (x-\mu)^2 p(x)dx$$

$$\sum_{n=0}^{\infty} \sum_{n=0}^{\infty} (x-\mu)^2 p(x)dx$$

$$\lim_{n\to\infty} \sum_{n=0}^{\infty} \sum_{n=0}^{\infty} (x-\mu)^2 p(x)dx$$

$$\lim_{n\to\infty} \sum_{n=0}^{\infty} \sum_{n=0}^{\infty} (x-\mu)^2 p(x)dx$$

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2.5. Gaussian distribution

Covariance matrix



2.5. Gaussian distribution

• Multidimentional Gaussian distribution (d dimentional)

$$p(\mathbf{x}) = \frac{1}{(2\pi)^{d/2} \left| \sum^{1/2} \right|} \exp \left[-\frac{1}{2} (\mathbf{x} - \mathbf{\mu})^T \sum^{-1} (\mathbf{x} - \mathbf{\mu}) \right]$$
$$\mathbf{\mu} = E(\mathbf{x}) = \int \mathbf{x} p(\mathbf{x}) d\mathbf{x}$$

$$\Sigma = E((\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^{T}) = \int (\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^{T} p(\mathbf{x}) d\mathbf{x}$$

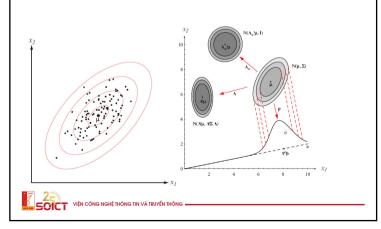
- Where, **x**, **μ** are *d*-dimentional vector
- Σ covariance matrix symmetric and semi-positive defined matrix.
- Consider cases, when Σ positive defined.

$$\mu_i = E(x_i) \qquad \qquad \sigma_{ij} = E((x_i - \mu_i)(x_j - \mu_j))$$

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2.5. Gaussian distribution



2.5. Gaussian distribution

- Multidimentional Gaussian distribution is fully defined by d+d(d+1)/2 parameters of mean vector $\boldsymbol{\mu}$ and covariance matrix $\boldsymbol{\Sigma}$.
- Mahalanobis distance:

$$r = (\mathbf{x} - \mathbf{\mu})^T \mathbf{\Sigma}^{-1} (\mathbf{x} - \mathbf{\mu})$$



