# Kathmandu University

# Department of Computer Science and Engineering Dhulikhel, Kavre



Lab 5 Report
Computer Graphics (COMP 342)

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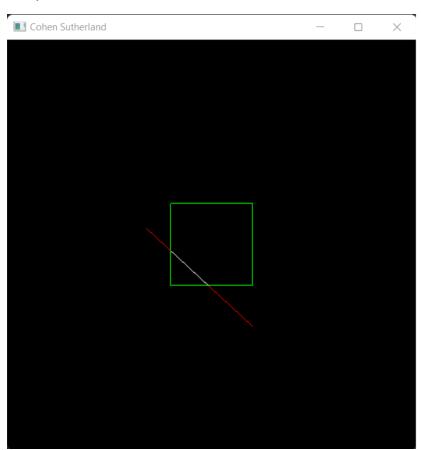
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## Cohen Sutherland Line clipping:

#### Algorithm:

- 1. Assign a region code for each endpoint.
- 2. If both endpoints have a region code 0000 trivially accept this line.
- 3. Else, perform the logical AND operation for both region codes.
  - 3.1 If the result is NOT 0000, trivially reject the line.
  - 3.2 Else (i.e., result = 0000, needs clipping)
    - 3.2.1 Choose an endpoint of the line that is outside the window.
    - 3.2.2 Find the intersection point at the window boundary
    - 3.2.3 Replace endpoint with the intersection point and update the region code.
    - 3.2.4 Repeat step 2 until we find a clipped line either trivially accepted or rejected.

#### Output:

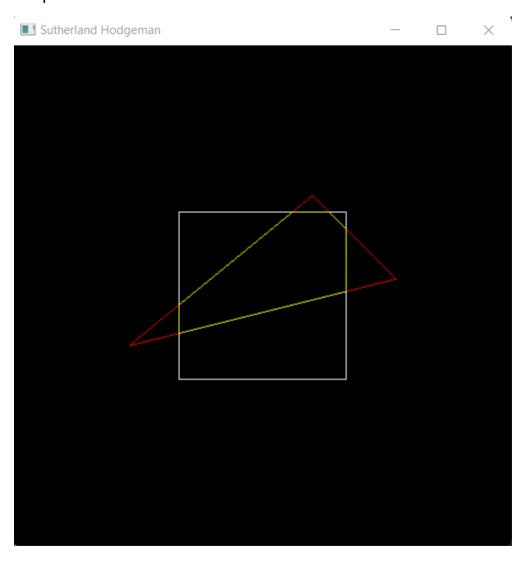


Sutherland Hodgeman Polygon Clipping:

Traverse the edges for four borders (Top, Right, Bottom, Left)

Find the intersection points between clipping window and the edges of the polygon.

## Output:



#### 3D Transformations:

Transformation matrices for the following 3D transformations are:

#### 3D translation:

$$\begin{bmatrix} x' \\ y' \\ z' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & tx \\ 0 & 1 & 0 & ty \\ 0 & 0 & 1 & tz \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

Fixed point 3D Scaling:

$$\begin{bmatrix} x' \\ y' \\ z' \\ 1 \end{bmatrix} = \begin{bmatrix} Sx & 0 & 0 & (1-sx)xf \\ 0 & Sy & 0 & (1-sy)yf \\ 0 & 0 & Sz & (1-sz)zf \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

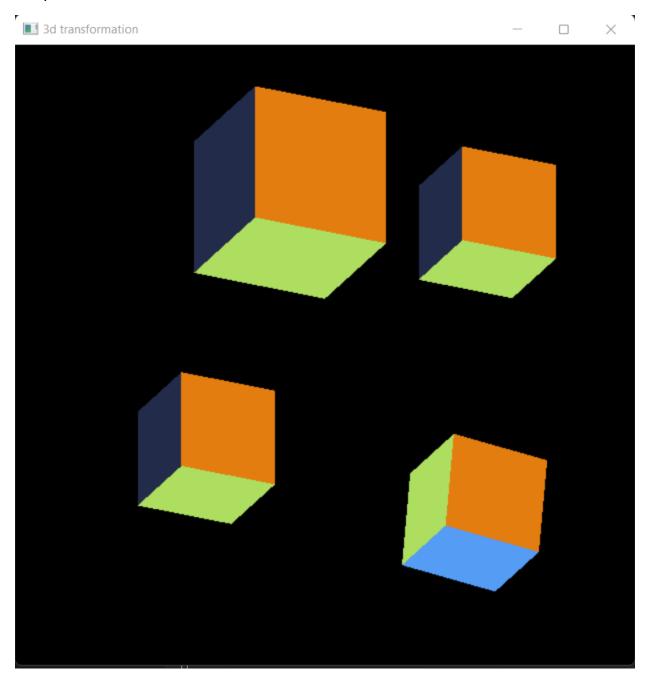
#### 3D Rotation:

x-axis: 
$$\begin{bmatrix} x' \\ y' \\ z' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \Theta & -\sin \Theta & 0 \\ 0 & \sin \Theta & \cos \Theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

y-axis: 
$$\begin{bmatrix} x' \\ y' \\ z' \\ 1 \end{bmatrix} = \begin{bmatrix} \cos \Theta & 0 & \sin \Theta & 0 \\ 0 & 1 & 0 & 0 \\ -\sin \Theta & 0 & \cos \Theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

z-axis: 
$$\begin{bmatrix} x' \\ y' \\ z' \\ 1 \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta & 0 & 0 \\ \sin \theta & \cos \theta & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

# Output:



## Conclusion:

In this way, Cohen Sutherland Line clipping algorithm, Sutherland Hodgeman Polygon Clipping algorithm and various 3D transformations were implemented in PyOpenGL.