IOT_PHASE 4: Development Part 2

SMART PUBLIC RESTROOM

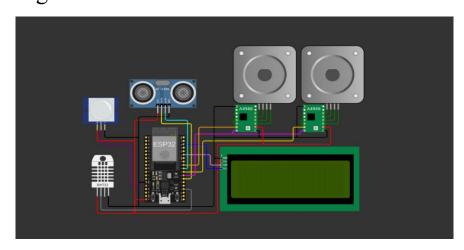
Hardware Components:

- ESP32 processor
- DHT22 temperature and humidity sensor
- Ultrasonic distance sensor
- Stepper motors (2)
- Liquid Crystal Display (LCD)
- Capacitive Sensor

Project Requirements:

- Monitor temperature and humidity in the restroom.
- Detect water levels in the restroom water tank.
- Automatically fill the water tank when it's low.
- Lower the room temperature if it exceeds a threshold.
- These requirements are essential for maintaining a comfortable and hygienic public restroom.
- To Detect Water Leakage in restroom.

Circuit diagram:



Program:

```
#include <Wire.h>
#include <Adafruit Sensor.h>
#include <DHT.h>
#include <AccelStepper.h>
#include <NewPing.h>
#include <LiquidCrystal I2C.h>
#include <WiFi.h>
#include <HTTPClient.h>
#define DHT PIN 15 // GPIO connected to DHT22
#define DHT_TYPE DHT22
#define ULTRASONIC TRIGGER 4 // GPIO connected to ultrasonic sensor trigger
#define ULTRASONIC ECHO 5 // GPIO connected to ultrasonic sensor echo
#define MOTOR1 STEP 18
#define MOTOR1 DIR 16
#define MOTOR1 ENABLE 1
#define MOTOR2 STEP 17
#define MOTOR2 DIR 16
#define MOTOR2 ENABLE 2
#define IR_SENSOR_PIN 13 // GPIO connected to IR sensor
#define CAPACITIVE SENSOR PIN 14 // GPIO connected to the capacitive sensor
#define LCD_ADDRESS 39 // I2C address of the LCD
#define LCD COLS 20
#define LCD ROWS 6
DHT dht(DHT PIN, DHT TYPE);
AccelStepper stepper1(10000, MOTOR1 STEP, MOTOR1 DIR);
AccelStepper stepper2(1, MOTOR2 STEP, MOTOR2 DIR);
NewPing sonar(ULTRASONIC TRIGGER, ULTRASONIC ECHO);
```

```
LiquidCrystal I2C lcd(LCD ADDRESS, LCD COLS, LCD ROWS);
int count = 0;
int waterLeakage = 0; // Initialize the water leakage variable
const char* ssid = "Wokwi-GUEST";
const char* password = "";
const char* thingSpeakUrl = "https://api.thingspeak.com/update";
const String apiKey = "F9IE7GGUTH545VG5"; // Replace with your ThingSpeak API Key
void setup() {
 Serial.begin(9600);
 Serial.print("Connecting to WiFi");
 WiFi.begin(ssid, password);
 while (WiFi.status() != WL CONNECTED) {
  delay(100);
  Serial.print(".");
 }
 Serial.println(" Connected!");
 Serial.begin(115200);
 lcd.init();
 lcd.backlight();
 dht.begin();
 pinMode(MOTOR1 ENABLE, OUTPUT);
 pinMode(MOTOR2 ENABLE, OUTPUT);
 pinMode(IR SENSOR PIN, INPUT); // IR sensor as input
 pinMode(CAPACITIVE SENSOR PIN, INPUT); // Capacitive sensor as input
 digitalWrite(MOTOR1 ENABLE, LOW);
 digitalWrite(MOTOR2 ENABLE, LOW);
```

```
stepper1.setMaxSpeed(10000);
 stepper1.setSpeed(2000);
 stepper2.setMaxSpeed(1000);
 stepper2.setSpeed(200);
}
void loop() {
 float temperature = dht.readTemperature();
 float humidity = dht.readHumidity();
 unsigned int cm = sonar.ping cm();
 if (cm < 170) {
  // Rotate motor 1 clockwise by a certain number of steps
  digitalWrite(MOTOR1 ENABLE, HIGH); // Enable the motor
  digitalWrite(MOTOR1 DIR, HIGH); // Set direction
  for (int i = 0; i \le 170; i++) {
   digitalWrite(MOTOR1 STEP, HIGH);
   delayMicroseconds(50);
   digitalWrite(MOTOR1 STEP, LOW);
   delayMicroseconds(50);
  }
  digitalWrite(MOTOR1_ENABLE, LOW); // Disable the motor
 } else {
  digitalWrite(MOTOR1 ENABLE, LOW); // Disable the motor
 }
 if (temperature > 25.0) {
  // Rotate motor 2 clockwise by a certain number of steps
  digitalWrite(MOTOR2 ENABLE, HIGH); // Enable the motor
```

```
digitalWrite(MOTOR2 DIR, HIGH); // Set direction
 for (int i = 0; i < 200; i++) {
  digitalWrite(MOTOR2_STEP, HIGH);
  delayMicroseconds(50);
  digitalWrite(MOTOR2 STEP, LOW);
  delayMicroseconds(50);
 digitalWrite(MOTOR2 ENABLE, LOW); // Disable the motor
} else {
 digitalWrite(MOTOR2 ENABLE, LOW); // Disable the motor
}
// IR sensor count detection
if (digitalRead(IR SENSOR PIN) == HIGH) {
 // Increment the count when IR sensor detects an object
 count++;
}
// Read the capacitive sensor value
waterLeakage = digitalRead(CAPACITIVE SENSOR PIN);
// Create a query string with all the data you want to send
String queryString = "api key=" + apiKey +
           "&field1=" + String(temperature) +
           "&field2=" + String(humidity) +
           "&field3=" + String(count) +
           "&field4=" + String(waterLeakage) +
           "&field5=" + String(cm); // Add ultrasonic distance as field5
// Send the data to ThingSpeak
```

```
HTTPClient http;
http.begin(thingSpeakUrl);
http.addHeader("Content-Type", "application/x-www-form-urlencoded");
int httpResponseCode = http.POST(queryString);
if (httpResponseCode == 200) {
 Serial.println("Data sent to ThingSpeak successfully");
} else {
 Serial.println("Failed to send data to ThingSpeak");
}
http.end();
// Delay before the next iteration
delay(1000);
lcd.clear();
lcd.setCursor(0, 0);
lcd.print("Temp: " + String(temperature) + "C");
lcd.setCursor(0, 1);
lcd.print("Humidity: " + String(humidity) + "%");
lcd.setCursor(0, 2);
lcd.print("Count: " + String(count));
lcd.setCursor(0, 3);
lcd.print("Leakage: " + String(waterLeakage));
lcd.setCursor(0, 4);
lcd.print("Dis: " + String(cm) + "cm"); // Display ultrasonic distance
delay(1000);
```

}

Website:

https://sites.google.com/view/smartrestrooms/home

1.Include Libraries:

• Several libraries are included at the beginning of the code to use specific sensors and components, as well as to enable WiFi and make HTTP requests.

2. Global Variables:

• The program defines various global constants and variables to store sensor pin configurations, sensor data, and WiFi credentials.

3. Setup Function:

- The setup function initializes the program. It performs the following tasks.
- Connects to a WiFi network using the specified SSID and password.
- Initializes the LCD display and DHT sensor.
- Sets up pins for motor control, IR sensor, and capacitive sensor.
- Configures and sets the maximum speed and speed for two stepper motors.
- **Note:** The code should have only one Serial.begin statement at a single baud rate, so it's recommended to remove the redundant Serial.begin(9600).

4.Loop Function:

- The loop function runs repeatedly and performs the following tasks:
- Reads temperature and humidity data from the DHT22 sensor.
- Measures the distance in centimeters using an ultrasonic sensor.
- Controls the rotation of two stepper motors based on the sensor values (distance and temperature).
- Detects objects using an IR sensor and increments the count.
- Reads a capacitive sensor to check for water leakage.
- Creates a query string with the sensor data and sends it to ThingSpeak.
- Displays sensor data, including temperature, humidity, count, and leakage, on an LCD screen.
- Displays the ultrasonic sensor's distance on the LCD.
- Waits for a delay of 1 second before the next iteration.

5. Sending Data to ThingSpeak:

• The program constructs a query string with the data in the format required by ThingSpeak, including the API key and individual field values. It then sends an HTTP POST request to the ThingSpeak server to update the data fields.

6.LCD Display:

• The LiquidCrystal_I2C library is used to control the LCD display. The sensor data (temperature, humidity, count, leakage, and distance) is displayed on the LCD screen for monitoring.

7.Retrieve Data from ThingSpeak:

• Use the ThingSpeak API to retrieve data from your channel.

8. Host Your Webpage:

• Upload your HTML webpage to a web server or use a hosting service that supports HTML, CSS, and JavaScript files.

9. Access Your Webpage:

• Open a web browser and navigate to the URL of your hosted webpage to view the ThingSpeak data displayed.

Mobile application development:



Codeblock for mobile application:

```
on UNAVMOTTED ConnectionStateChang
                                                           NewState StateString
                                                             C UsA2MQTT1 - bConnected -
     UniAI2MQTT1 - . IsCome
                                                                  Maria . (Till b | "decred" .
         CHITOMERAL IN
                                                                   and United Section 10 ( press disconnect to disconnect of United Section 1)
                                                                                         Topic (imposión)
                                                                   Buton1 * . Sed * to consed *

Libbs * . Sed * to * press consed to consed *
    (Image 1 * ) City

(Unada NOTIT * ) . (a) Connected *
           cal UniAZMOTTE Publish
                                                            on (UniAQMOTTTE) Published
                               par management
                                                           Topic Psyload Message Reteining Dupring
                                                            D f | pat Message * * * herpote's
                                                             thin and Message 1 to Spit 1 left | put Message 1
                                                                  mit Labai2 m . Not m to (0
     | Image2 = .Oct | Una42MQTT1 = . biConnected =
         CAT (UNAZWOTTE PARK)
                                                                   mi (1812 a . Not a la ( 0 pm)
                               lopic | *(commercen) *
                                                             clos of put Message 1 *1 Country *
                                                             then and Message to spile their put Message to
                                                                  and Entroline . Recting to 1 (a) join 1 select that them that 1 get (Moosepare)
    UsAl2MQTT1 * . IsCornected *
        OR CHITCHARD IN
                                                              alon f get Message * - * | * testage *
                           Kepic | "Wildrichterp"
                                                             then and Message to split to led out Message to
        oil (InAZXIIIII) Decoraed
nitistra global mama to 🚺
divide grade link to 1 Hips/lep.throppesk.com/charme/s/259599/ce...
               when (Wib11) GotText
               url responseCode responseType responseContent
               to 0 f pal suppriseCode 1 = 1 (20)
                  than (0) initiative boost part to ( call Which is also
                                                                         gal responseContent *
                        in 😕 gobel name " lo (
                    wil (Wilder) . (Here to post gettel ink .)
```

Future Enhancements:

- Adding remote monitoring and control capabilities.
- Implementing water quality monitoring.
- Enhancing energy efficiency.

Conclusion:

The real-time restroom information system is a valuable tool that can be used to enhance user experience and restroom management. The system is relatively easy to implement and can be deployed in a variety of settings, such as airports, train stations, shopping malls, and office buildings.