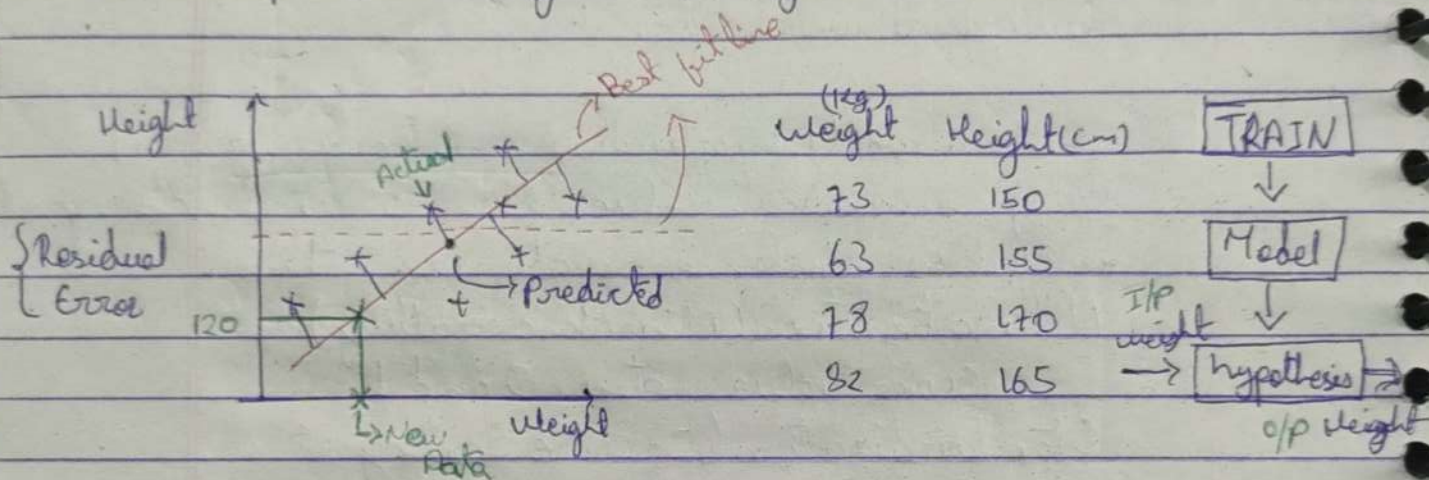


Linear Regression Algorithm

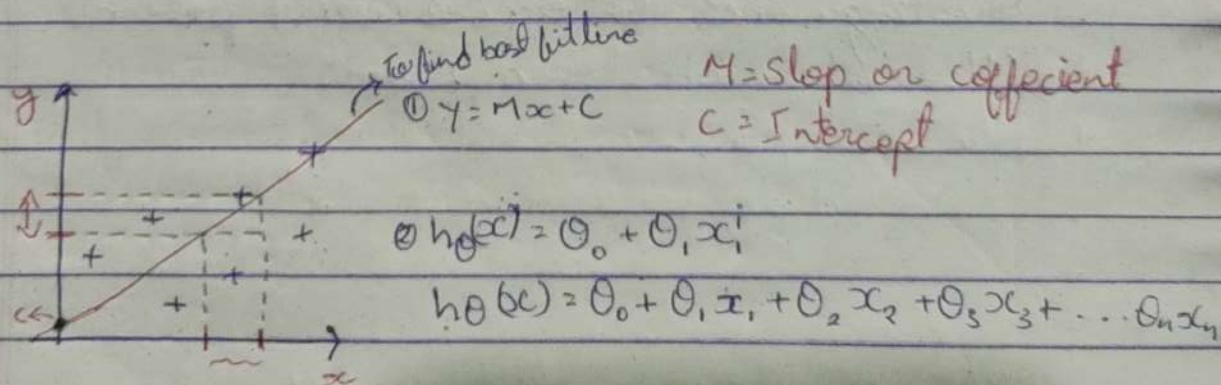
Linear regression is a way to predict a number by drawing the best straight line through data points.

It learns the relationship between input (X) and output (Y) using a straight line.



Residual Error is difference between the actual value and the predicted value.

Aim: To find best fit line with minimal error.

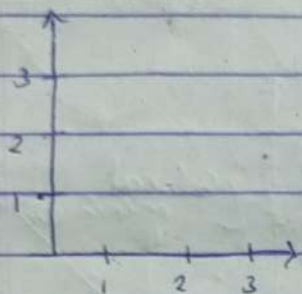


Hypothesis

{y is a linear function of x}

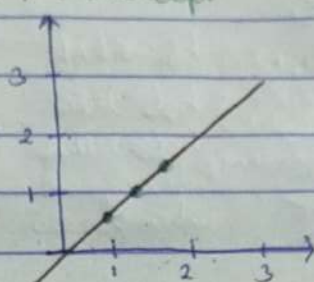
$$h_0(x) = \theta_0 + \theta_1 x$$

↗ coefficient
↘ intercept



$$\theta_0 = 1.5$$

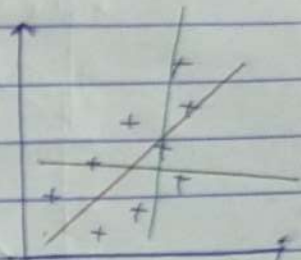
$$\theta_1 = 0$$



$$\theta_0 > 0 \rightarrow \theta_0(0.5) = 0.5$$

$$\theta_1 = 0.5 \rightarrow 0 + (0.5)2 = 1$$

= 1



Solve { Cost function }

minimize θ_0, θ_1

$$\sum_{i=1}^m \frac{1}{2m} (h_0(x^{(i)}) - y^{(i)})^2$$

$$\frac{d(x^2)}{dx} = 2x^{2-1}$$

$$= 2x //$$

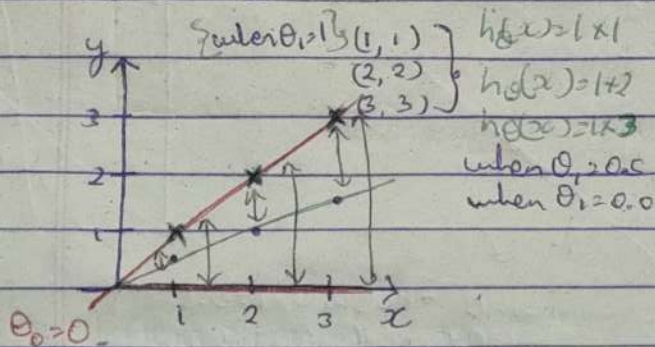
$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^m (h_0(x^{(i)}) - y^{(i)})^2$$

(also called)
→ Squared Error Function

Hypothesis

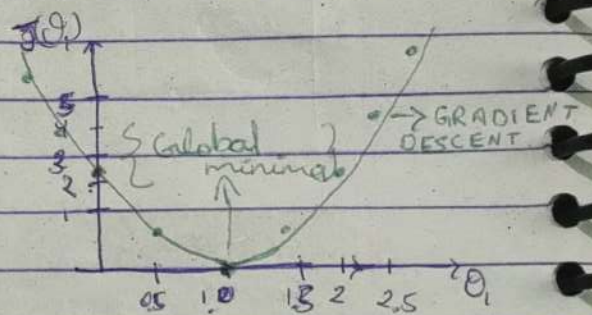
lets $\theta_0 = 0$

$$h_\theta(x) = \theta_0 + \theta_1 x$$



Cost function

$$J(\theta_0, \theta_1) = \frac{1}{2} \sum_{i=1}^n (h_\theta(x^{(i)}) - y^{(i)})^2$$



$$J(\theta_1) = \frac{1}{2n} \sum_{i=1}^n (h_\theta(x^{(i)}) - y^{(i)})^2$$

when $\theta_1 = 1$

$$= \frac{1}{6} [(0)^2 + (0)^2 + (0)^2]$$

$$= 0$$

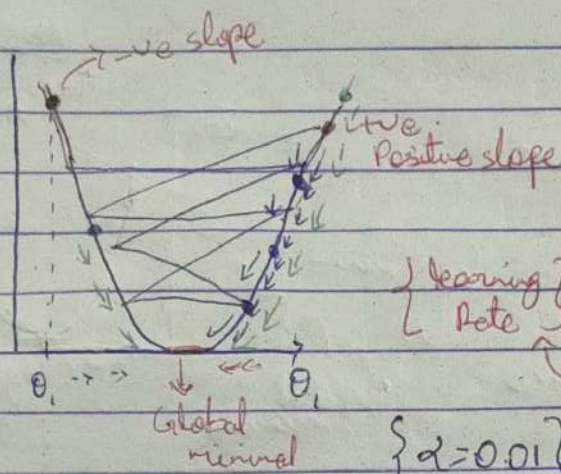
$$J(\theta_1) = \frac{1}{6} [(0.5-1)^2 + (-2)^2 + (1.5-3)^2]$$

when $\theta_1 = 0.5$

$$= \frac{1}{6} (3.5) \approx 0.58$$

$$J(\theta_1) = \frac{1}{6} [(0-1)^2 + (0-2)^2 + (0-3)^2]$$

$$= \frac{14}{6} \approx 2.3$$



{ learning rate }

{ $\alpha = 0.01$ }

Repeat convergence theorem

$$\theta_j = \theta_j - \alpha \frac{\partial}{\partial \theta_j} (J(\theta_0, \theta_1))$$

$$\begin{aligned} \theta_0 &= \theta_0 - \alpha (+ve) && \text{decreased} \\ \theta_1 &= \theta_1 - \alpha (-ve) && \text{increased} \end{aligned}$$

Outline

- 1 Start with θ_0 & θ_1
- 2 keep changing θ_0, θ_1 + reduce $J(\theta_0, \theta_1)$ until we reach near global minimum.
- 3 Convergence theorem

$$\theta_j = \theta_j - \alpha \frac{\partial}{\partial \theta_j} (J(\theta_0, \theta_1))$$