CS 563: Software Maintenance And Evolution

Software Defect Localization



Oregon State University, Spring 2024

What have we learnt so far?

What, Why, When, and how?

- Software maintenance (4 types)
- Software change management (SCM coordinator, VCSs)
- Software design patterns (GangsOfFour, SOLID, MVC)
- Evolution of Software Evolution (Lehman laws's)
- Software defect prediction
 - Code complexity metrics (Control Flow Graphs)
 - ML based prediction techniques

Today's plan

- Software Fault Localization
- In-class exercise: Advanced uses of Git (graded exercise, team of 2, due Sunday, April 21, 11:59 PM)

Software Debugging

What are software *faults* and how do they differ from software *defects*?

Software Debugging

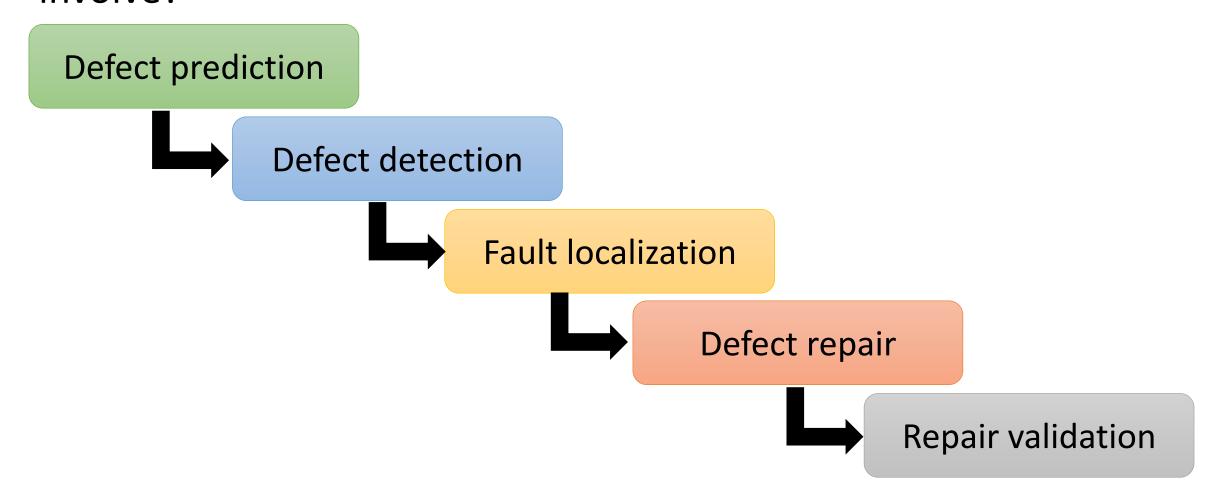
What are software *faults* and how do they differ from software *defects*?

- **Defect:** Bugs or errors in the code, documentation, requirements, etc. where the actual behavior or software differs from its expected behavior.
- Fault: A static issue in the source code that can potentially cause failure (e.g., syntax errors, logical errors, incorrect algorithm).

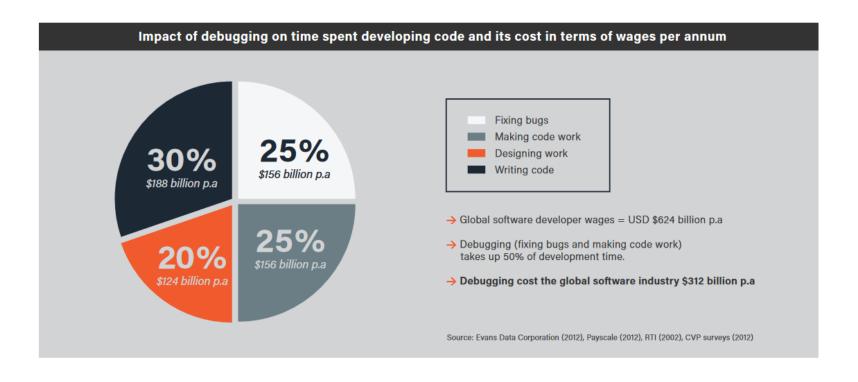
Software defect is the actual manifestation of a **fault** that leads to observable incorrect behavior in the software

Software Debugging Process

What is software debugging and what all activities does it involve?



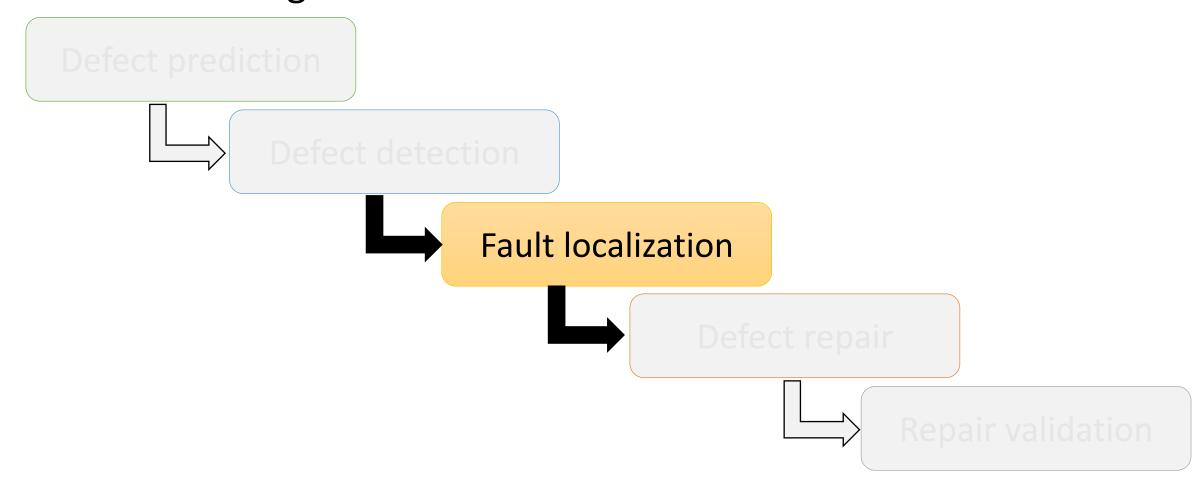
Software Debugging Is Expensive



"Software developers spend 35-50% of their time validating and debugging software. The cost of debugging, testing, and verification is estimated to account for 50-75% of the total budget of software development projects, amounting to more than \$100 billion annually."

Software Fault Localization

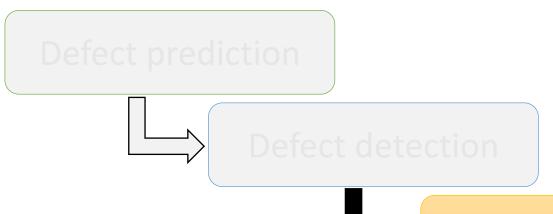
What is software fault localization and why should we care about localizing software faults?



Software Fault Localization

What is software fault localization and why should we care

about localizing software faults?



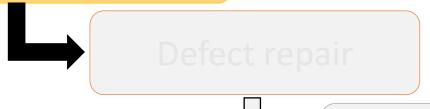
What?

The process of identifying faults in the source code of the software that can potentially cause software defects or failures when the software is used.

Fault localization

Why?

- Software quality
- Developer productivity
- Reduce debugging cost





Repair validation

Software Fault Localization

How to know which software code elements are buggy?

Program Elements

What is a software program composed of?

- Files (or classes in OOP)
- Functions (or methods)
- Statements (remember they are different from lines!)

A bug can be localized to any of the above listed granularities. Therefore, these are called *program elements*.

Perfect Bug Detection

A bug in an element will be detected by a programmer if that element is manually examined

- A correct element will not be mistakenly identified as a faulty element
- If the assumption does not hold, a programmer may need to examine more code than necessary to find a faulty element

Commonly used traditional techniques

Commonly used traditional techniques

- Insert *print* statements
- Add assertions or set breakpoints
- Examine core dump or stack trace

Rely on programmers' intuition and domain expert knowledge

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- Insert *print* statements
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Rely on programmers' intuition and domain expert knowledge

How to automate it?

- Key insight: Faults reside in the execution slice of a test that fails on execution
 - An *execution slice* is the set of a program's code (blocks, statements, decisions, c-uses, or p-uses) executed by a test

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 - Too much code in the slice!
- Another Key insight: Narrow the search domain by execution dices
 - An execution dice is obtained by subtracting successful execution slices from failed execution slices

Dice = Execution slices of failed tests — Execution slices of successful tests

```
read (a, b, c);
class = scalene;
if a = b \parallel b = a
   class = isosceles;
if a^*a = b^*b + c^*c
  class = right;
                                            a≥b≥c
if a = b & b = c
   class = equilateral;
case class of
   right : area = b*c / 2;
   equilateral : area = a*a * sqrt(3)/4;
   otherwise : s = (a+b+c)/2;
                 area = sqrt(s*(s-a)*(s-b)*(s-c));
end;
write(class, area);
```

Test case	Input			Output	
	a	b	С	class	area
Т1	2	2	2	equilateral	1.73
T_2	4	4	3	isosceles	5.56
T_3	5	4	3	right	6.00
T_4	6	5	4	scalene	9.92
T ₅	3	3	3	equilateral	3.90

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T_5	3	3	3	equilateral	3.90
T_6	4	3	3	scalene	4.47

Failure!

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read (a, b, c);
                      4, 3, 3
class = scalene;
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Failure!

Can you identify the bug?

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Failure!

Too much code needs to be examined!

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Т ₁	2	2	2	equilateral	1.73
T_2	4	4	3	isosceles	5.56
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A Passed Test T₂ and a Failed Test T₆

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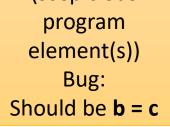
Failure!

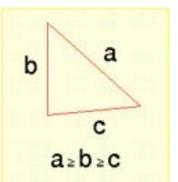
A Passed Test T₂ and a Failed Test T₆

Execution slices for Passed Test T₂ and a Failed Test T₆

Execution dice

(suspicious program element(s)) Bug:





С	lass =	iso	scele
if a*	$a = b^*l$	+ 0	c*c
С	lass =	righ	nt;

if a = b & b = cclass = equilateral;

case class of

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: area = b*c / 2; right

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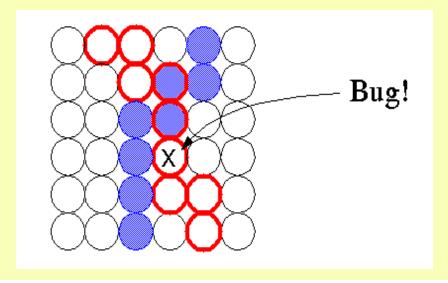
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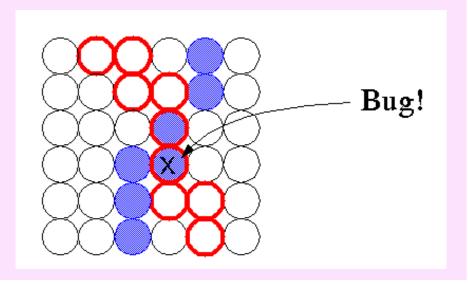
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Execution Slice & Dice Limitations

- Buggy code is in the execution dice (top priority)
- A bug is in the failed execution slice (the red path) but not in the successful execution slice (the blue path)



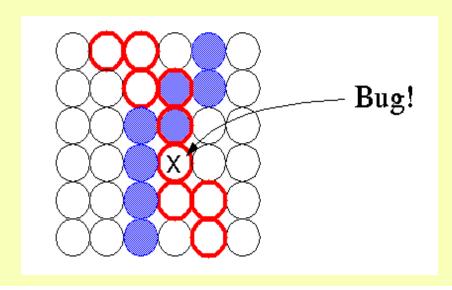
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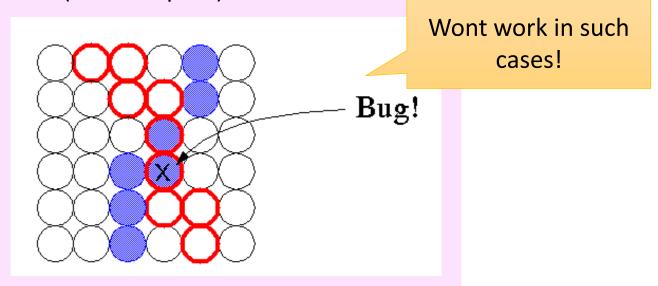
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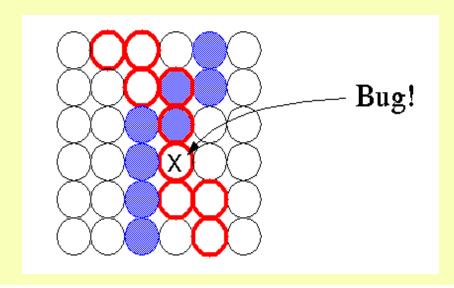


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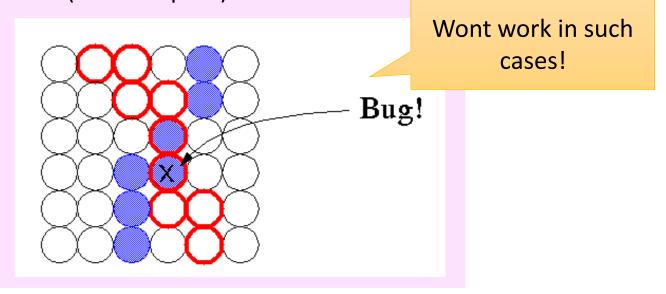
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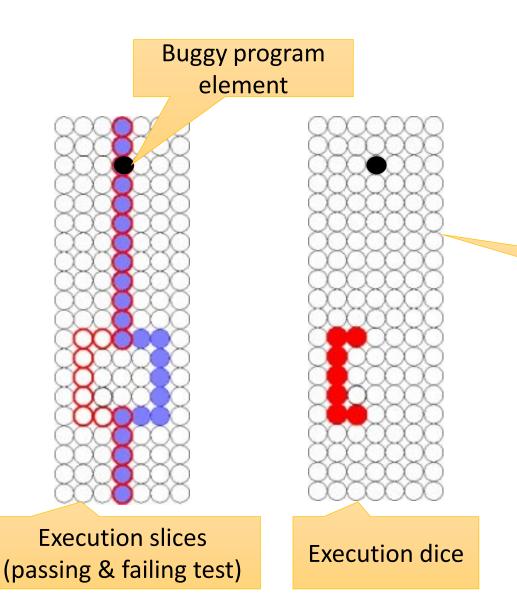


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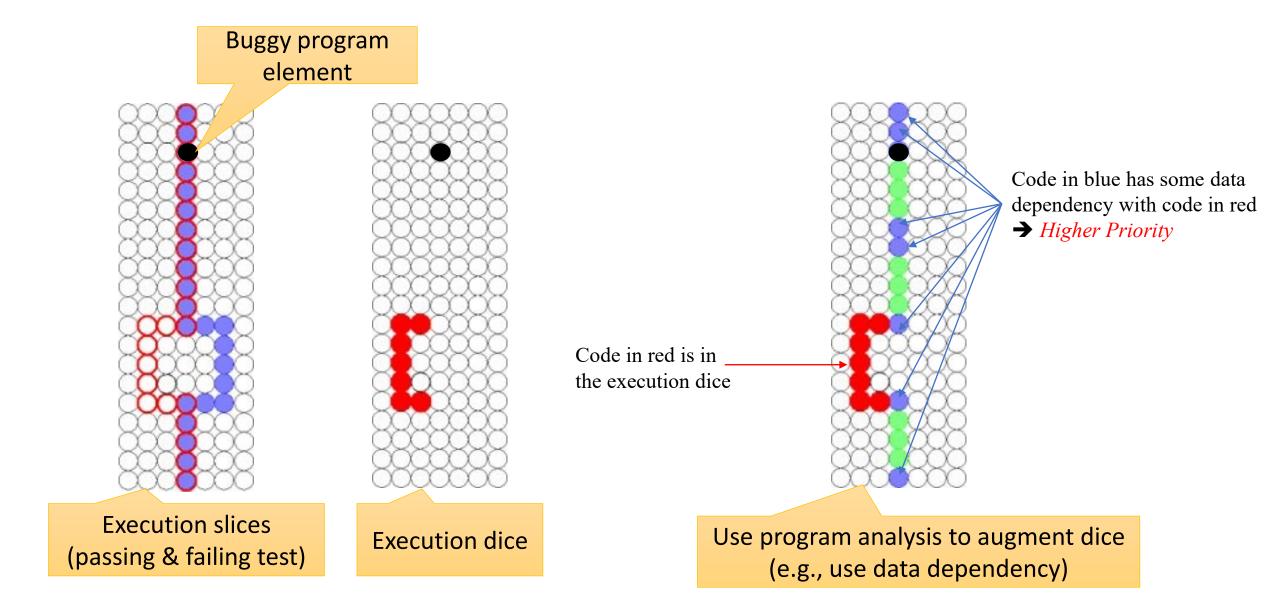
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Execution Slice & Dice Limitations

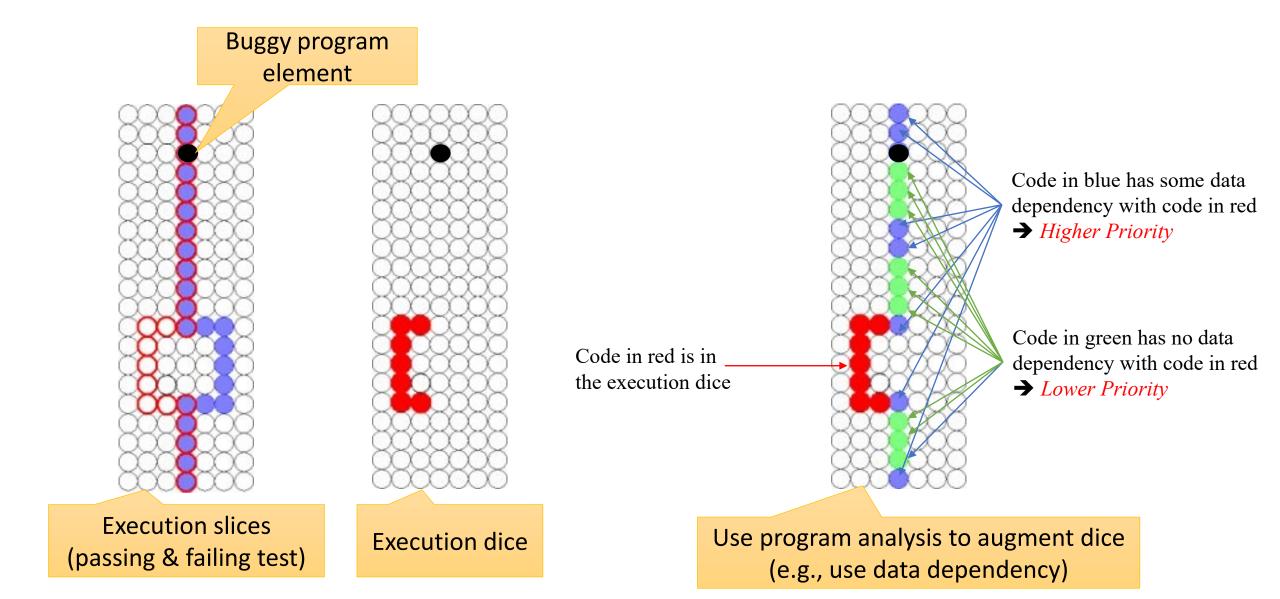


How do we narrow the search space of program elements to be analyzed for locating the bug? Ideas?

Execution Slice & Dice Extension

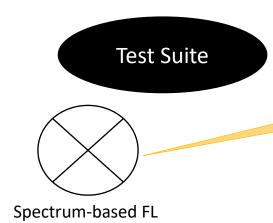


Execution Slice & Dice Extension



Suspicious Ranking Based FL

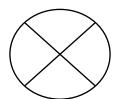
- Compute the suspiciousness (likelihood of containing bug) of each program element
- Rank all the executable program elements in descending order of their suspiciousness
- Examine the elements one-by-one from the top of the ranking until the first faulty element is located
- Elements with higher suspiciousness should be examined before elements with lower suspiciousness as the former are more likely to contain bugs than the latter



Effect of passing and failing tests on *program element*

Test Suite

Effect of passing and failing tests on *program element*

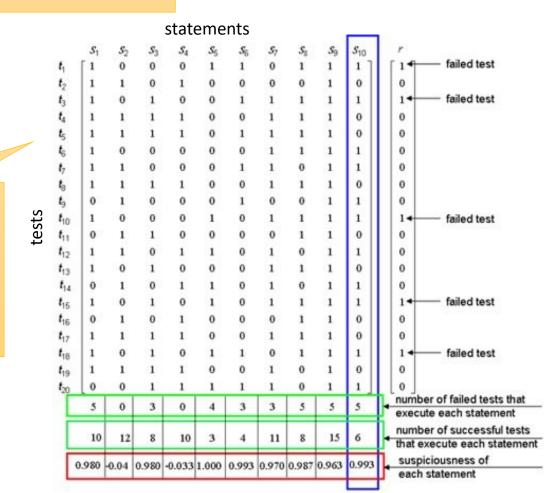


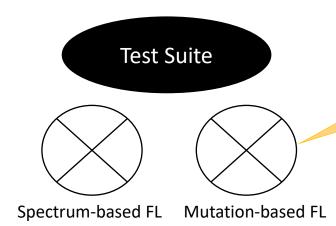
Spectrum-based FL

- The number of failing tests that **do** (e_f) and **do not** (n_f) execute the element
- The number of passing tests that do (e_p) and do not (n_p) execute the element.
- Ochiai

$$score = \frac{e_f}{\sqrt{(e_f + n_f)(e_f + e_p)}}$$

Example of program spectra (coverage matrix)





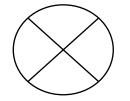
Effect of mutating program element on passing and failing tests

Test Suite

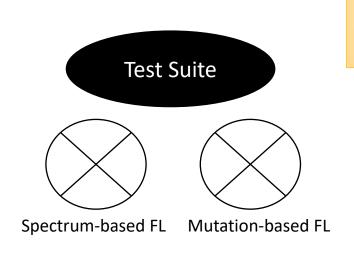
Spectrum-based FL Mutation-based F/

Reduce program to a minimal form while still maintaining a given behavior

Program Slicing

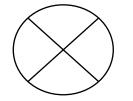


Program Slicing FL



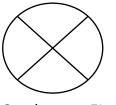
Use the list of active stack frames during execution of a program

Program Slicing



Program Slicing FL

Stack Trace



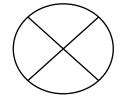
Stack trace FL

Test Suite

Spectrum-based FL Mutation-based FL

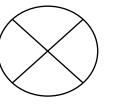
Effect of predicate (conditional expression) on failing tests

Program Slicing



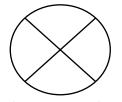
Program Slicing FL

Stack Trace

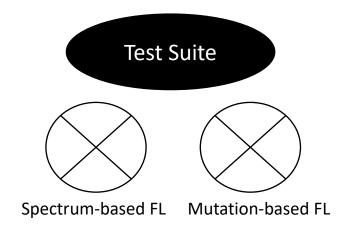


Stack trace FL

Control Flow



Predicate Switching FL



Rank program elements using bug report as query

Bug report

IR-based FL

Program
Slicing

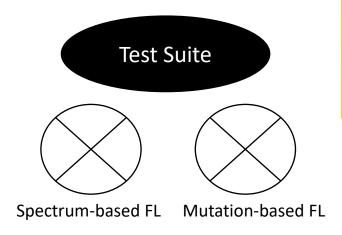
Program Slicing FL

Stack Trace

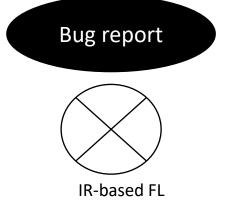
Stack trace FL

Control Flow

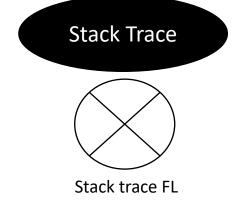
Predicate Switching FL

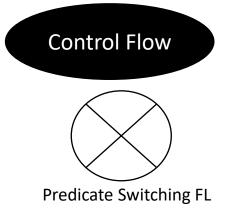


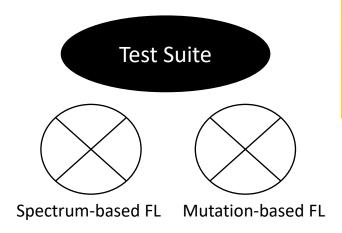
Problem: Recent research shows that none of these techniques is the best technique!





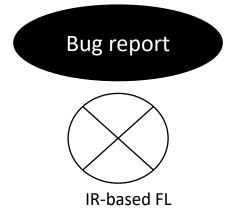




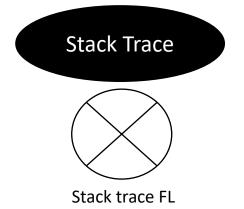


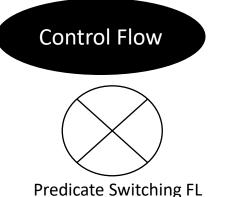
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Solution: Use ML^{1,2,3,4} to combine these techniques!









Evaluation Metrics for FL techniques

- **Precision**: proportion of reported faulty statements that are actually faulty
- Recall (or Sensitivity): proportion of actually faulty statements that are identified
- **F-measure:** harmonic mean of precision and recall $((2 \times P \times R)/(P + R))$ to evaluate overall effectiveness. Higher F-measure means better balance between precision and recall
- Area Under the Curve (AUC): area under the precision recall (or ROC) curve
- Top-k accuracy: proportion of actually faulty statements that are ranked within the top-k positions
- Reciprocal Rank: 1/rank of the first faulty statement found in the ranked list
- Mean Average Precision (MAP): Average Precision across all faults in a dataset
- Mean Reciprocal Rank (MRR): Average Reciprocal Rank across all faults in a dataset
- **EXAM:** fraction of ranked statements one needs to inspect before finding a faulty statement
- Time Complexity: How efficiently can a technique be applied to large codebases
- Space Complexity: Memory required to execute the technique (think about the size of coverage matrix for MLOC applications!)

Announcements

- Paper selection due tonight!
- Project idea proposal due next Monday
 - Try to prepare a rough sketch of the project idea to brainstorm and get feedback during the next in-class exercise on Wednesday

In-class exercise: Advanced uses of Git

- Form a team of 2, go to Canvas Assignments and work on:
- Due at the end of this week on Sunday, April 21, 2024, at 11:59 PM

In-class Exercise #1: Advanced Uses of Git A

Due: Sunday, April 21, 2024, 11:59 PM PT

This in-class exercise is a group submission. This means that each group only needs to submit their solution once and also that every student in a group will get the same grade.

Overview and goal

The high-level goal of this exercise is to gain more experience with Git, in particular working with branches, cherry-picking commits, and understanding the difference between *reset*, *rebase*, and *revert*.