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Doubly connected edge list

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The **doubly connected edge list** (**DCEL**), also known as **half-edge data structure**, is a [data structure](#) to represent an [embedding](#) of a [planar graph](#) in the [plane](#) and [polytopes](#) in [3D](#). This data structure provides efficient manipulation of the topological information associated with the objects in question (vertices, edges, faces). It is used in many [algorithms](#) of [computational geometry](#) to handle polygonal subdivisions of the plane, commonly called [planar straight-line graphs](#) (PSLG).^[1] For example, a [Voronoi diagram](#) is commonly represented by a DCEL inside a bounding box.

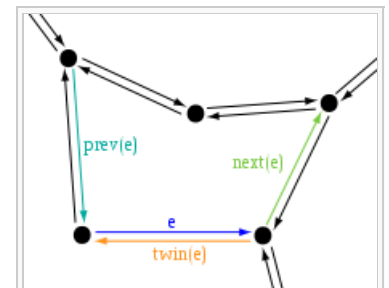
This data structure was originally suggested by Muller and Preparata^[2] for representations of 3D [convex polyhedra](#).

Later a somewhat different data structuring was suggested, but the name "DCEL" was retained.

For simplicity, only [connected graphs](#) are considered, however the DCEL structure may be extended to handle disconnected graphs as well.

Data structure [\[edit\]](#)

DCEL is more than just a [doubly linked list](#) of edges. In the general case, a DCEL contains a record for each edge, [vertex](#) and [face](#) of the subdivision. Each record may contain additional information, for example, a face may contain the name of the area. Each edge usually bounds two faces and it is therefore convenient to regard each edge as two half-edges. Each half-edge bounds a single face and thus has a pointer to that face. A half-edge has a pointer to the next half-edge and previous half-edge of the same face. To reach the other face, we can go to the twin of the half-edge and then traverse the other face. Each half-edge also has a pointer to its origin vertex (the destination vertex can be obtained by querying the origin of its twin, or of the next half-edge).



Each half-edge has exactly one previous half-edge, next half-edge and twin.

Each vertex contains the coordinates of the vertex and also stores a pointer to an arbitrary edge that has the vertex as its origin. Each face stores a pointer to some half-edge of its outer boundary (if the face is unbounded then pointer is null). It also has a list of half-edges, one for each hole that may be incident within the face. If the vertices or faces do not hold any interesting information, there is no need to store them, thus saving space and reducing the data structure's complexity.

See also [\[edit\]](#)

- [Quad-edge data structure](#)
- [Doubly linked face list](#)
- [Winged edge](#)

References [\[edit\]](#)

- ↑ The definition of a DCEL may be found in all major [books in computational geometry](#).
- ↑ Muller, D. E. ; Preparata, F. P. "Finding the Intersection of Two Convex Polyhedra", Tech. Rept. [UIUC](#), 1977, 38pp, also *Theoretical Computer Science*, Vol. 7, 1978, 217–236

Categories: [Graph data structures](#) | [Geometric graph theory](#) | [Geometric data structures](#)

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