

# Algorithmic Differentiation in Python

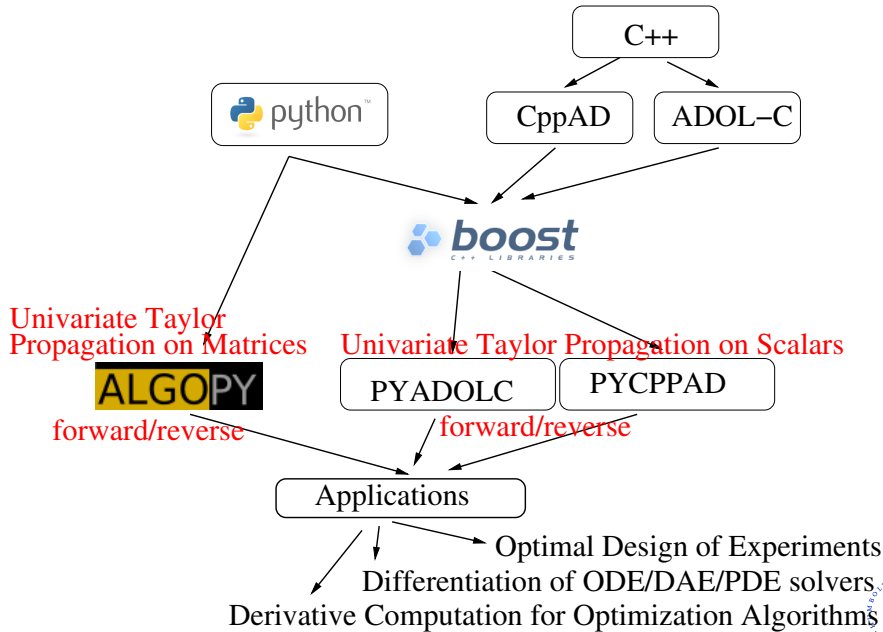
Working with PYADOLC, PYCPPAD and ALGOPY  
from a User's Perspective

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# Available Software for AD in Python to my Knowledge

- Differentiation Module in the ScientificPython package,<sup>1</sup>
  - forward mode, uses lambda functions
- **PYADOLC**, wrapper of ADOL-C <sup>2</sup>
  - arbitrary order vector forward/reverse taylor propagation
  - convenience function for hessian, jacobians, ...
  - sparse Hessian and Jacobian support by matrix compression
  - Very good Numpy support (array operations, slicing, ...)
  - Pythonic feel
- **PYCPPAD**, wrapper of CppAD (collaboration with Brad Bell),<sup>3</sup>
  - second order vector forward/reverse
  - convenience functions for hessian, jacobian, ...
  - AFAIK: same speed as CppAD
- **ALGOPY**<sup>4</sup>
  - pure Python, higher order vector forward/reverse on scalars and matrices

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<sup>1</sup><http://dirac.cnrs-orleans.fr/plone/software/scientificpython>

<sup>2</sup><http://www.github.com/b45ch1/pyadolc>

<sup>3</sup><http://www.github.com/b45ch1/pycppad>

<sup>4</sup><http://www.github.com/b45ch1/algopy>

# Example 1: Gradient of Toy Function with PYADOLC

- if possible: Run Live Example...

- Simple Example: Gradient

```
1 import numpy
  from adolc import *

  def f(x):
      return x[0]*x[1] + x[1]*x[2] + x[2]*x[0]

6
  x = numpy.array([1.*n +1. for n in range(3)])
  ax = adouble(x)

  trace_on(1)
11 independent(ax)
   ay = f(ax)
   dependent(ay)
   trace_off()

16 print gradient(1,x)
```



## Example 2: Toy Problem with PYADOLC and PYCPPAD

*# PYCPPAD*

```
x      = numpy.zeros(N, dtype=float)
ax     = pycppad.independent(x)
4 atmp = []
  for n in range(N):
      atmp.append(numpy.sin( numpy.sum(ax[:n])))
  ay     = numpy.array( [ ax[0] * numpy.sin( numpy.sum(atmp)) ] )
  f      = pycppad.adfun(ax, ay)
9 x      = numpy.random.rand(N)
  w      = numpy.array( [ 1.] )
  H      = f.hessian(x, w)
```

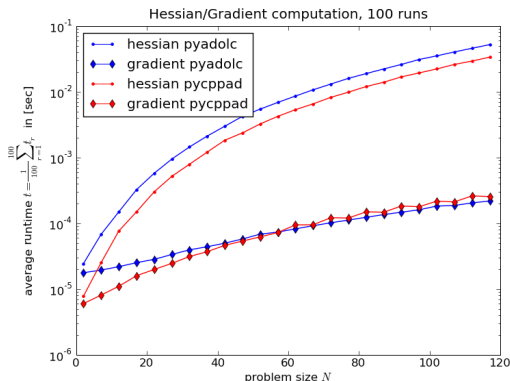
*# PYADOLC*

```
14 x      = numpy.zeros(N, dtype=float)
  adolc.trace_on(0)
  ax = adolc.adouble(x)
  adolc.independent(ax)
  atmp = []
19 for n in range(N):
      atmp.append(numpy.sin( numpy.sum(ax[:n])))
  ay     = numpy.array( [ ax[0] * numpy.sin( numpy.sum(atmp)) ] )
  adolc.dependent(ay)
  adolc.trace_off()
24 H = adolc.hessian(0,x)
```



# Example 2: Performance, PYCPPAD vs PYADOLC

code at `./pyadolg/tests/comparison_pycppad_pyadolg/compare_pycppad_pyadolg.py`



- factor two in Hessian computation: 1) ADOLC can't do vector forward followed by a reverse run 2) more cache misses because of nonlocality
- PYADOLC better for implementing univariate Taylor propagation forward/reverse and more Pythonic User Interface



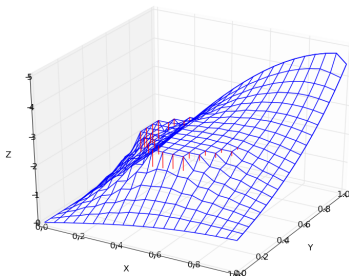
# Example 3: Minimal Surface Problem with PYADOLC

- Minimal Surface Problem:

$$u : S \subset [0, 1] \times [0, 1] \rightarrow \mathbb{R} \quad u \in C^1(S)$$

$$\begin{aligned} O(u) &= \int_0^1 \int_0^1 \sqrt{1 + \left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial y}\right)^2} \, dx dy \\ &\approx \sum_{i=0}^{m-1} \sum_{j=0}^{m-1} O_{ij}(u) \end{aligned}$$

$$O_{ij}(u) := h^2 \left[ 1 + \frac{(u_{i+1,j+1} - u_{i,j})^2 + (u_{i,j+1} - u_{i+1,j})^2}{4} \right]$$



Nonlinear Program with Inequality Box Constraints:

$$\begin{aligned} \mathbb{R}^{m \times m} \ni u_* &= \operatorname{argmin}_u O(u) \\ \text{s.t. } 0 &\leq u_{ij} \quad \forall (i,j) \in \text{Cylinder set} \end{aligned}$$



# Example 3: Code, Numpy Slicing and Broadcasting works

```
1 import numpy
  from adolc import *
  def O_tilde(u):
      M = numpy.shape(u)[0]
      h = 1./(M-1)
6      return M**2*h**2 +
          numpy.sum(0.25*( (u[1:,1:] - u[0:-1,0:-1])**2
              + (u[1:,0:-1] - u[0:-1, 1:])**2))

M = 5
h = 1./M
11 u = numpy.zeros((M,M), dtype=float)
    u[0,:]= [ numpy.sin(numpy.pi*j*h/2.) for j in range(M)]
    u[-1,:]= [ numpy.exp(numpy.pi/2) * numpy.sin(numpy.pi * j * h / 2.)
    u[:,0]= 0
    u[:, -1]= [ numpy.exp(i*h*numpy.pi/2.) for i in range(M)]
16 trace_on(1)
    au = adouble(u)
    independent(au)
    ay = O_tilde(au)
    dependent(ay)
21 trace_off()
    ru = numpy.ravel(u)
    rg = gradient(1, ru)
    g = numpy.reshape(rg, numpy.shape(u))
```





# Differences Between ADOL-C and PYADOLC

- Python: **can't** overload the = operator
- Python: **garbage collector**
- ADOL-C differentiates between unnamed variables (adub) and named variables (adouble)
- **Test Function:**

```
1 for n in range(N):  
    ay = ay * ay
```
- in C++: `ay * ay` does create adub object, assign to adouble, go out of scope. Thus, memory address may be reused

- PYADOLC

register	0	1	2	3	4	5	6
operation							
assign \$0 → \$1	1.	0.	0.	0.	0.	0.	0.
mul \$1 \$1 → \$2	1.	1.	0.	0.	0.	0.	0.
mul \$2 \$2 → \$3	1.	1.	1.	1.	0.	0.	0.
mul \$3 \$3 → \$4	1.	1.	1.	1.	1.	0.	0.

- ADOL-C

register	0	1	2	3	4	5	6
operation							
assign \$0 → \$1	1.	0.	0.	0.	0.	0.	0.
mul \$1 \$1 → \$1	1.	1.	0.	0.	0.	0.	0.
mul \$1 \$1 → \$1	1.	1.	0.	0.	0.	0.	0.
mul \$1 \$1 → \$1	1.	1.	0.	0.	0.	0.	0.

## Tape of ADOL-C: tape\_11.tex

generated by pyadolc/tests/tape\_equivalence\_PyADOLC\_ADOLC/adolc.exe

Only two named variables using: loc 0 and loc 1

code	op	loc	loc	loc	loc	double	double	value	value
33	start of tape								
39	take stock op			2	0		6.908924e - 310		
1	assign ind				0		1.000000e + 00		
3	assign a			0	1				1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
15	mult a a		1	1	1			1.000000e + 00	1.000000
2	assign dep				1				1.000000
0	death not			0	2				1.000000
32	end of tape								

# Tape Generated by PYADOLC, tape\_9.tex

generated by pyadolg/tests/tape\_equivalence\_PyADOLC\_ADOLC/pyadolg.py

## 21 named variables

code	op	loc	loc	loc	loc	double	double	value	value
33	start of tape								
39	take stock op			2	0		0.000000e + 00		
1	assign ind				1		1.000000e + 00		
15	mult a a		1	1	2			1.000000e + 00	1.000000e
15	mult a a		2	2	3			1.000000e + 00	1.000000e
15	mult a a		3	3	4			1.000000e + 00	1.000000e
15	mult a a		4	4	5			1.000000e + 00	1.000000e
15	mult a a		5	5	6			1.000000e + 00	1.000000e
15	mult a a		6	6	7			1.000000e + 00	1.000000e
15	mult a a		7	7	8			1.000000e + 00	1.000000e
15	mult a a		8	8	9			1.000000e + 00	1.000000e
15	mult a a		9	9	10			1.000000e + 00	1.000000e
15	mult a a		10	10	11			1.000000e + 00	1.000000e
15	mult a a		11	11	12			1.000000e + 00	1.000000e
15	mult a a		12	12	13			1.000000e + 00	1.000000e
15	mult a a		13	13	14			1.000000e + 00	1.000000e
15	mult a a		14	14	15			1.000000e + 00	1.000000e
15	mult a a		15	15	16			1.000000e + 00	1.000000e
15	mult a a		16	16	17			1.000000e + 00	1.000000e
15	mult a a		17	17	18			1.000000e + 00	1.000000e
15	mult a a		18	18	19			1.000000e + 00	1.000000e
15	mult a a		19	19	20			1.000000e + 00	1.000000e
15	mult a a		20	20	21			1.000000e + 00	1.000000e
2	assign dep				21				
0	death not			0	21				
32	end of tape								

# Workaround for PYADOLC: use $\ll=$ operator instead of $=$

```
from adolc import *
import numpy as npy
3 trace_on(10)
  ax = adouble(1.)
  independent(ax)
  ay = ax
  for i in range(N):
8     ay  $\ll=$  ay * ay

  dependent(ay)
  trace_off()

13 tape_to_latex(10, npy.array([x]), npy.array([0]))
```

- $\ll=$  in Python calls `operator_eq_adub` in C++:

```
badouble& (badouble::operator_eq_adub) ( const adub& ) = &badouble::operator=
```



# Resulting Tape: tape\_10.tex

generated by pyadolc/tests/tape\_equivalence\_PyADOLC\_ADOLC/pyadolc.py

code	op	loc	loc	loc	loc	double	double	value	value	
33	start of tape									
39	take stock op			1	0		0.000000e + 00			
40	assign d one				1					
1	assign ind				1		1.000000e + 00			
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
15	mult a a		1	1	1			1.000000e + 00	1.000000e	
2	assign dep				1					
0	death not			0	21					
32	end of tape									



# Quick Performance Comparison:

- **ADOL-C**

speelpenning:

Adolc function taping: ..... elapsed time: 0.000058

Adolc function evaluation: 0.000000 elapsed time: 0.000013

gradient evaluation: ..... elapsed time: 0.000028

matrix vector multiplication:

Adolc function taping: ..... elapsed time: 0.001564

Adolc function evaluation: 1.051874 elapsed time: 0.000209

jacobian evaluation: ..... elapsed time: 0.009419

- **PYADOLC**

speelpenning:

PyADOLC function taping: ..... elapsed time: 0.000535

Adolc function evaluation: 0.000000 elapsed time: 0.000031

gradient evaluation: ..... elapsed time: 0.000035

matrix vector multiplication:

PyADOLC function taping: ..... elapsed time: 0.036444

Adolc function evaluation: 1.051874 elapsed time: 0.000294

jacobian evaluation: ..... elapsed time: 0.015260

- Approximately:  $1 \leq \frac{\text{Runtime(PYADOLC)}}{\text{Runtime(ADOL-C)}} \leq 2$



# Univariate Taylor Propagation on Matrix Valued Functions

## Univariate Taylor Propagation on Matrices UTPM

Differentiate obj. fun. operating on matrices by forward/reverse UTP:

$$q_* = \operatorname{argmin}_q \Phi(C(q))$$

$$C = \begin{pmatrix} I & 0 \end{pmatrix} \begin{pmatrix} J_1^T J_1 & J_2^T \\ J_2 & 0 \end{pmatrix}^{-1} \begin{pmatrix} J_1^T J_1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} J_1^T J_1 & J_2^T \\ J_2 & 0 \end{pmatrix}^{-T} \begin{pmatrix} I \\ 0 \end{pmatrix}$$

Regard matrices  $\mathbb{M}$  as **elementary datatypes**.

$$F : \mathbf{R}^{N_X \times M_X} \rightarrow \mathbf{R}^{N_Y \times M_Y} \implies F : \mathbb{M}_{N_X, M_X} \rightarrow \mathbb{M}_{N_Y, M_Y}$$

Transformation: UTPS  $\Leftrightarrow$  UTPM

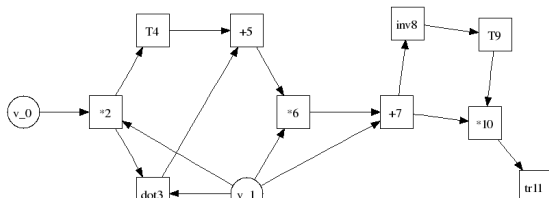
$$\begin{pmatrix} \sum_{d=0}^D X_d^{11} t^d & \dots & \sum_{d=0}^D X_d^{1M} t^d \\ \vdots & \ddots & \vdots \\ \sum_{d=0}^D X_d^{N1} t^d & \dots & \sum_{d=0}^D X_d^{NM} t^d \end{pmatrix} = \sum_{d=0}^D \begin{pmatrix} X_d^{11} & \dots & X_d^{1M} \\ \vdots & \ddots & \vdots \\ X_d^{N1} & \dots & X_d^{NM} \end{pmatrix} t^d$$



```

X = 2 * numpy.random.rand(2,2,2,2); Y = 2 * numpy.random.rand(2,2,2,2)
2 AX = Mtc(X)
  AY = Mtc(Y)
  cg = CGraph()
  FX = Function(AX)
  FY = Function(AY)
7 FX = FX*FY
  FX = FX.dot(FY) + FX.transpose()
  FX = FY + FX * FY
  FY = FX.inv()
  FY = FY.transpose()
12 FZ = FX * FY
  FTR = FZ.trace()
  cg.independentFunctionList = [FX, FY]
  cg.dependentFunctionList = [FTR]
  cg.plot(filename = 'trash/computational_graph_circo.png', method = 'c

```

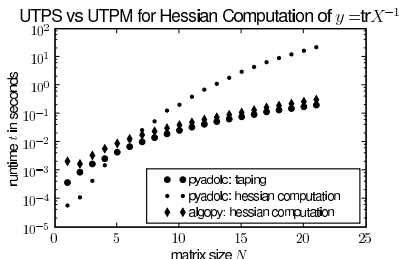
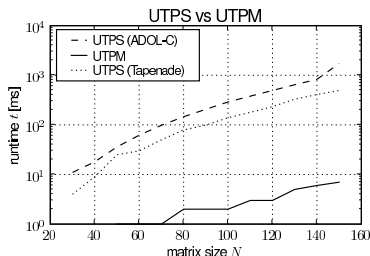




# AD on Matrix Valued Functions: UTPM vs UTPS

source available at [http://github.com/b45ch1/hpsc\\_hanoi\\_2009\\_walter](http://github.com/b45ch1/hpsc_hanoi_2009_walter)

- As far as I know: ADMC++ also uses UTPM (operator overloading in Matlab/ execution in C++).<sup>5</sup>
- Comparison: UTPS vs UTPM



Test Function:  $f : \mathbf{R}^{N \times N} \rightarrow \mathbf{R}, \quad X \mapsto \text{tr}(X^{-1})$

<sup>5</sup><http://sourceforge.net/projects/admcpp>



# Implementation 1: Operator Overloading in Python

Code snippet from `algopy/algopy.py`

```
class Mtc:
    def __init__(self, X):
        """ INPUT:  shape(X) = (D,P,N,M)
            D: Degree of the Matrix Polynomial
            P: Number of Forward Directions
            N: Number of rows of the matrix
            M: Number of cols of the matrix """
        if ndim(X) == 4: self.TC = asarray(X)
        else: raise NotImplementedError

    def __mul__(self, rhs):
        retval = Mtc(zeros(shape(self.TC)))
        (D,P,N,M) = shape(retval.TC)
        for d in range(D):
            retval.TC[d,:,:,:] = sum(
                self.TC[:d+1,:,:,:] * rhs.TC[d::-1,:,:,:], axis=0)
        return retval

X = Mtc( zeros((D,P,M,N))
Y = Mtc( zeros((D,P,N,M))
Z = X * Y
Z = X.__mul__(Y) # equivalent
```



# Implementation 2: Using Boost:Python

```
adub *adub_add_badouble_badouble(const badouble &lhs, const badouble &rhs)
void hov_forward(short tape_tag, int M, int N, int D, int P,
                 bpn::array &bpn_x, bpn::array &bpn_V, bpn::array &bpn_W,
                 double* x = (double*) nu::data(bpn_x);
    ...
    hov_forward(tape_tag, M, N, D, P, x, V, y, W);
}
8 BOOST_PYTHON_MODULE(_adalc){
    import_array();
    bpn::array::set_module_and_type("numpy", "ndarray");
    def("trace_on", trace_on_default_argument);
    def("trace_off", trace_off_default_argument);
13 def("gradient", &c_wrapped_gradient);
    def("hessian", &c_wrapped_hessian);
    def("jacobian", &c_wrapped_jacobian);
    def("hov_forward", &hov_forward);
    class_<badouble>("badouble", init<const badouble &>())
18     .def("__add__", adub_add_badouble_badouble, return_value_policy<reference>)
     .def("__mul__", adub_mul_badouble_badouble, return_value_policy<reference>)
}
```



## Summary: The current state

- All examples here are part of the examples resp. unit test of PYADOLC and ALGOPY
- AD tools in Python are sufficiently mature to do serious prototyping
  - ① PYADOLC and PYCPPAD transform code to low level register machine language (without jump statements)
  - ② ALGOPY high level description of algorithms
- Execution speed is comparative to pure C++ ADOL-C or CppAD

## Outlook: Where to go from here

- wrap the Checkpointing functionality of ADOL-C
- Fix the problem of ADOL-C calling `exit()` on errors (this quits python too...)
- improve memory management of ALGOPY
- add missing linear algebra routines (LU, QR, LDU,  $\text{eig}(A)$ )
- add sparse matrix support in ALGOPY