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Algorithm 413

ENTCAF and ENTCRE: Evaluation of Normalized Taylor Coefficients of an Analytic Function [C5]

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Key Words and Phrases: Taylor coefficients, Taylor series, Cauchy integral, numerical integration, numerical differentiation, interpolation, complex variable, complex arithmetic, fast Fourier transform

CR Categories: 5.12, 5.13, 5.16

Description

Introduction. Two subroutines, ENTCAF and ENTCRE, coded in ANSI FORTRAN are described here. ENTCAF may be used to calculate approximations $r^2a_s^{(m)}$ to a set of normalized Taylor coefficients

$$r^s a_s = r^s f^{(s)}(\zeta)/s!$$
 $s = 0,1,2,...$ (1.1)

The values of r and ζ , a complex number, are provided by the user together with a function subprogram that represents f(z) as a complex-valued function of a complex variable. The user also provides a value of ϵ_{req} , the required absolute accuracy. The routine returns an accuracy estimate ϵ_{est} together with approximations $r^*a_s^{(m)}$ and a number m. These are supposed to satisfy

$$\begin{vmatrix} r^s a_s^{(m)} - r^s a_s | < \epsilon_{est} & s = 0, 1, 2, \dots, m - 1, \\ r^s a_s | < \epsilon_{est} & s = m, m + 1, \dots$$
 (1.2)

A result status indicator *NCODE* is output. If $\epsilon_{est} > \epsilon_{req}$ this gives a brief indication of why the required accuracy was not achieved.

ENTCRE carries out the same task as ENTCAF in the case that ξ is real and also that f(z) is real when z is real. In this special and common case, ENTCRE is about twice as economic as ENTCAF.

Outline of method. The Taylor coefficients a_s occur in the Taylor series

$$f(z) = \sum_{s=0}^{\infty} a_s (z - \zeta)^s, \quad |z - \zeta| < R_c,$$
 (2.1)

where R_c is the radius of convergence of the Taylor series. Cauchy's theorem provides a set of integral representations. One of these is

$$r^s a_s = \frac{r^s}{2\pi i} \int_{C_x} \frac{f(z)}{(z-\zeta)^{s+1}} dz, \quad r < R_c,$$
 (2.2)

where C_r is the circle $|z - \zeta| = r$. The approximation $r^*a_s^{(m)}$ is obtained by replacing the integral in (2.2) by an approximation based on an m-point trapezoidal rule approximation. Specifically,

$$r^{s}a_{s} \simeq r^{s}a_{s}^{(m)} = m^{-1}\sum_{j=0}^{m-1} \exp(-2\pi i j s/m)f(\xi + r \exp(2\pi i j/m)),$$
 (2.3)
 $s = 0,1,\ldots,m-1.$

tape. The text plus the listing of the algorithm will be printed in the Collected Algorithms from CACM. The charge for the taped algorithm is \$16.00 (U.S. and Canada) or \$18.00 (elsewhere). If the user sends us a small tape (wt. less than 1 lb.) we will copy the algorithm on it and return it to him at a charge of \$10.00 (U.S. only). All orders are to be prepaid with checks payable to "ACM Algorithms." The algorithm is recorded as one file of BCD 80-character card images at 556 B.P.I., even parity, on seven-track tape. If requested, the algorithm is supplied at a density of 800 B.P.I. The cards for the algorithm are sequenced starting at 10 and incremented by 10. The sequence number is right-justified in column 80. Although every attempt is made to insure that the algorithm conforms to the printed description, no guarantee is made, nor is there a guarantee that the algorithm is correct.—L.D.F.

Editor's note: The algorithm described here is available on magnetic

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the ACM

The calculation is in two parts. The first part (stages 1, 2, and 3) is iterative in nature. Using (2.3) the approximations $a_0^{(m)}$ with $m=1,2,4,8,\cdots$ are calculated. The function values are retained. The convergence criterion is based on the circumstance that the true value

$$a_0 = f(\zeta) \tag{2.4}$$

of one of the approximations $a_0^{(m)}$ may be determined by a single function evaluation. A rather involved convergence criterion based on the orderly approach of the sequence $a_0^{(m)}$, $m = 1,2,4,\ldots$, to its limiting value a_0 is used. This is described in some detail by Lyness [8].

When the convergence of $a_0^{(m)}$ to a_0 has been achieved the routine carries out the second part (stage 4). This consists of evaluating $r^*a_s^{(m)}$ from (2.3) for $s=0,1,\cdots,m-1$ using the function values calculated and retained during the first part. A fast Fourier transform technique is used for this calculation. This is particularly appropriate since m is a power of two. The derivation and implementation of this technique is described in Gentleman and Sande [5, pp. 566-7]. The specialized version used in *ENTCRE* is described in Sande [9].

Restrictions: theoretical. There are two restrictions of a theoretical nature.

1. The value of r must be less than the radius of convergence, R_c , of the Taylor series. So long as this condition is satisfied, it can be shown (see [5] and [8]) that

$$|r^{s}a_{s}| < K\rho^{s},$$

 $|r^{s}a_{s}^{(m)} - r^{s}a_{s}| < K\rho^{m+s}/(1-\rho^{m}),$

$$(3.1)$$

where ρ is any number greater than r/R_c and K depends on ρ . Thus the approximations approach their limiting values and there are only a finite number of normalized Taylor coefficients whose magnitude exceeds ϵ_{req} . If this restriction is violated, that is, a value of $r \geq R_c$ is chosen, then in general the sequence $r^s a_s^{(m)}$ converges, but not to $r^s a_s$. Instead it converges to the integral on the right in (2.2), but (2.2) is not generally valid if $r \geq R_c$. Thus the routine itself fails to converge since $a_0^{(m)}$ does not approach $f(\zeta)$ in the limit of increasing m.

2. The function f(z) must not be an odd function of $(z - \zeta)$. While the convergence criterion based on (2.4) has much to recommend it, it does have one serious drawback. If it happens (as it does in the case $f(z) = \sin(z)$; $\zeta = 0$) that

$$f(z - \zeta) = -f(\zeta - z), \tag{3.2}$$

then every approximation $a_0^{(m)}$ is zero, as is the true value a_0 . The routine then finds that it converges immediately. In this case the problem should be reformulated. One defines $g(z) = f(z)/(z-\zeta)$ or $g(z) = (z-\zeta)f(z)$. The Taylor coefficients A_s of $g(z) = \zeta$ are then calculated using *ENTCAF*. A_s is the same as a_{s+1} or a_{s-1} as the case may be.

Restrictions: practical. There are two principal practical restrictions. These arise because (1) the computer uses finite length floating-point arithmetic; (2) execution cannot be allowed to continue indefinitely; at some stage it has to terminate whether or not the calculation is complete.

An output status parameter *NCODE* indicates to the user whether the results have been significantly affected by either of these restrictions.

1. Roundoff error. The routine requires as an input parameter the machine accuracy parameter ϵ_M . The approximations $r^*a_s^{(m)}$ given by (2.3) are of such a form that an estimate of the roundoff error level is

$$\epsilon_{r,o}^{(m)} = \epsilon_M \max_{j=0, \dots, m-1} |f(\zeta + r \exp(2\pi i j/m))|.$$
 (3.3)

If, at any stage it appears that

$$\epsilon_{reg} < 10 \ \epsilon_{r,o}^{(m)}$$
, (3.4)

the routine internally replaces $\epsilon_{r,eq}$ by 10 $\epsilon_{r,o}^{(m)}$ and either terminates

(input NCODE negative) or continues with the calculation (input NCODE nonnegative).

2. Physical upper limit. This is defined by an input parameter NMAX. Iterations in the first part to calculate $a_0^{(m)}$, $m = 1,2,4,8,\ldots$, with m < NMAX are possible. If convergence has not been achieved by this stage, the calculation is completed.

The output status parameter NCODE is +1 if all went well. In general NCODE = 0 if the calculation was terminated; is positive if it converged and negative if it did not converge; has magnitude 1 if roundoff error was not observed; and has magnitude 2 if roundoff error was observed.

If $NCODE \neq 0$, the returned value ϵ_{est} corresponds to the estimated accuracy of TCOF(J) whether or not convergence or roundoff error occurred. If NCODE = 0, the quantity $10 \epsilon_{r,o}^{(m)}$ is returned in place of ϵ_{est} .

Comments. The algorithms described here deliver approximations to a set of normalized Taylor coefficients r^*a_s . It is natural to ask why this choice of output was made, rather than perhaps a set of Taylor coefficients a_s or a set of derivatives $f^{(s)}(\zeta)$. The most immediate reason is that the algorithm naturally provides a set or normalized Taylor coefficients to a uniform absolute accuracy. The user specifies r and ϵ_{req} only. If, for example, one is interested in a set of derivatives, the specification of the accuracy requirements becomes very much more complicated. However, if one looks ahead to the use to which the Taylor coefficients are to be put, one finds in many cases that uniform accuracy in normalized Taylor coefficients corresponds to the sort of accuracy requirement which is most convenient.

As an illustration we consider a very trivial problem. We wish to represent f''(x) as a polynomial in the interval (-l,l) to an accuracy E. Clearly

$$f''(x) = \sum_{s=2}^{\infty} s(s-1)a_s x^{s-2} = \frac{1}{r^2} \sum_{s=2}^{\infty} s(s-1)a_s r^s \left(\frac{x}{r}\right)^{s-2}. \quad (4.1)$$

A very crude approach might be to take r = l and $\epsilon = r^2 E/6$. In this case the error in the sth term is less than $s(s-1)E(x/l)^{s-2}/6$. One cannot be assured that for $x \simeq l$ these errors may not cooperate in such a way as to lose the required accuracy. However, if r is chosen to be greater than l and $\epsilon = r^2(1 - l/r)^3E/2$ then it follows at once that if the allowed error in a_s , r^s is less than ϵ , the error in f''(x) is less than E. These two approaches represent extremes. Neither take into account that the sequence $a_s r^s$ itself approaches zero and for high values of s it is unnecessary to bound the error in omitting such a term by ϵ . A more complicated formula based on (3.1) is derived by Lyness and Delves [5], eq. (2.9). But the underlying feature of any of these approaches to approximating (4.1) is that a uniform absolute accuracy for $a_s r^s$, s = 0,1,2,..., is very convenient for this problem. If the algorithm instead calculated $f^{(s)}(0)$ to a specified relative accuracy, the determination of the accuracy to use in this problem would be very much more involved.

Possible modifications. The general approach to a numerical calculation by means of the numerical evaluation of contour integrals is at present an open field for investigation. The algorithms described here may be used in several problems known to the authors. These are: (a) determination of zeros of analytic function [7, 1, and 5]; (b) numerical differentiation [7, 6]; (c) numerical quadrature [8].

In particular applications, modifications of *ENTCAF* or *ENTCRE* can lead to more efficient calculations. Possible modifications include: (a) Provision for calculation of only some of the Taylor coefficients, for example, s even or $s \leq 12$; (b) Provision for a "subsequent return option" which allows the same calculation to be taken up at a later stage if it is found subsequently that higher accuracy is required; (c) Provision for an "early exit." Used in conjunction with (b) this would enable the program to consider intermediate results to determine whether to continue with the current values of r and ϵ , before a high investment of computer time has been made.

In fact, *ENTCRE* is a special modification of *ENTCAF* designed for a particular application, ζ real, f(x) real. The output

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October 1971 Volume 14 Number10 status parameter NCODE is of particular use in these applications since it allows appropriate remedial action to be taken under program control.

Algorithms which include modifications (b) and (c) above have been used by the first author. However, these involve complicated logic and are strongly connected with the particular application. The algorithms listed here may be modified by the user in particular applications for any large scale use. However, in pilot runs or small scale calculations they are adequate as they stand.

Comparisons and examples. In [6] and [8], several numerical examples are given, and comparisons with other methods are made. So far as the determination of zeros of an analytic function is concerned, the method described in [6] has some advantages in a global situation, but should not be used locally. For numerical quadrature, the method described [8] is definitely superior to standard methods if there is a nearby pole or singularity of a special type. In these cases a proper evaluation depends on the details of the problem under consideration.

It is in problems involving numerical differentiation that the method on which these algorithms are based show up to great advantage. This is simply because, once the use of complex function values is allowed, the numerical instability associated with numerical differentiation may be avoided.

In [6], a different but related method for numerical differentiation is described. The remarks about the roundoff error given there apply to these routines also. There as an example, the calculation of $f^{(5)}(0)$ was considered for

$$f(x) = e^x/(\sin^3(x) + \cos^3(x)).$$

The actual value of this derivative is an integer, namely

$$f^{(5)}(0) = -164.$$

In order to provide some sort of comparison, a special algorithm for numerical differentiation based on polynomial interpolation was written using only function values at real abscissas. A set of several dozen numerical experiments were carried out on a machine for which $\epsilon_M = 3 \times 10^{-11}$. The closest result was in error by 10^{-2} ; the worst result had the wrong sign.

ENTCRE was then used for the same problem in an attempt to obtain seven-digit accuracy, i.e. an absolute accuracy of $E=10^{-4}$. A sequence of values of r was used, with in each case $\epsilon_{req}=r^5\times 10^{-4}/5!$ and input parameter NCODE=-1 to secure immediate termination if roundoff error prevented a sufficiently accurate result from being attained. With r=0.1 and r=0.2, execution terminated using in each case one complex and three real function values. With r=0.4, the result

$$f^{(5)}(0) = -164.00000013$$

was obtained at a cost of 15 complex and three real function values (m = 32); the accuracy estimate given by the algorithm was

$$E_{est} = \epsilon_{est} 5!/r^s = 6 \times 10^{-6}.$$

Incidentally, an absolute accuracy of less than 10^{-4} was estimated and a better accuracy obtained for r=0.3, 0.4, 0.5, 0.6, 0.7 with m=32, 32, 64, 64, 128, respectively. For r=0.8 and r=0.9 the routine failed to converge with m=128 giving absurd results and estimates. These latter values of r are greater than the radius of convergence $R_c=\pi/4$.

The role played by the output status parameter NCODE is illustrated in this example. With r=0.1 and r=0.2, the value of NCODE indicated immediately that the results were not to be taken seriously because of roundoff error. With r=0.8 and r=0.9, the value of NCODE indicated that the results were not to be taken seriously because of lack of convergence. Thus the calculation could have been carried out completely under program control, with a driver program finding for itself an appropriate value of r. An efficient program for this application would require modifications (a), (b), and (c) of the previous section.

The testing of the algorithm included the calculation of high-

order derivatives. In general, it frequently happens that even when analytic closed expressions are known for such derivatives, these expressions are difficult to evaluate because of excessive subtraction error. Cases in point include the functions e^x/x and sin(x)/x. Programs were written to evaluate the first 80 derivatives of these functions at x=5, 10, 20, 40, and 80. It turned out that meaningful results could be obtained. For example, for $f(x)=e^x/x$, using r=32 and $\epsilon_{req}=10^{-10}$, ENTCRE gives

$$f^{(25)}(40) = 3.6560469 \times 10^{16}$$

with an estimated relative accuracy of 2.5×10^{-9} . These results were compared with those obtained using an algorithm due to Gautschi and Klein [2, 3]. In all cases examined corresponding results agreed to within the calculated error estimate.

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Algorithm

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C OUTPUT PARAMETERS (12) AND (13) AND NOTE(2) BELOW)
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AVAILABLE ARE -

SINTAR(J+1) = SIN(PI*JZ/*NTAR) , J = 0*1*2*...NTAH-1.

WE PROUTRE THE SEQUENCE SIN(PI*JZ/*(NTCOF/4)).

JF (NTCOF/4-1).

IF (NTCOF/L).**(NTCOF/4-1).

IF (NTCOF/L).**(A*NTAR) THESE NUMBERS ARE ALREADY AVAILABLE IN

HF SINTAR LIBBLE SPACED AT AN INTERVAL 2*NSPACE = RENIABZ/NICOF.

OTHERWISE.** NICOF = RENIAB AND THE SINTAB TABLE IS UPDATED.

THIS INVOLVES ARE PARAMSING THE NITAB VALUES AND UPDATING

NTAB TO 2*NTAB.
                  **O QUANTITIES CALCULATED IN STAGE THREE(B) **

ITERATIONS ARE NUMBERED 8.16.32....AT THE END OF ITERATION
NICOF. THE NICOF/Z + 1 COMPLEX FUNCTION VALUES AT
ABSCISSAS PEGULARLY SPACED ON UPPER HALF OF CIRCLE ARE
STOPED IN THE ICOF VECTOR AS FOLLOWS.
ICOF(J+1) = PRAL PART OF CEUN(/J) J=0.11.2....NICOF/Z.
ICOF(NICOF-J+1) = 1 MAGINAPY PART OF CFUN(Z(J))

J=1.2....(NICOF/Z-1).

WHEDE
                WHEPE

Z(J) = ZETA + RCIRCOCEAP(ZOPIOSE SPINTCOF)

THIS INVOLVES A REARRANGEMENT OF THE NITCOFZOP THIS INVOLVES A REARRANGEMENT OF THE NITCOFZOP THE STAND AND THE CALCULATION OF A FURTHER NITCOFZOP FUNCTION VALUES OF AR FMAX MAXIMUM MODULIS OF THE FUNCTION VALUES SO FAR ENCOUNTERED.

APPROX AN APPROXIMATION TO TOOF (1)

BASED ON THESE FUNCTION VALUES.
                         BASED ON THESE FUNCTION VALUES.

BY QUANTITIES CALCULATED AT STAGE THMEE(C) **

ERRORS CURRENT VALUE OF THE FRHOR = AMS(APPROX-EXACT).

EPRORS-ERRORS VALUES OF ERROR AT END OF THREE PREVIOUS ITERATIONS.

EPMENT ON ITERATIONS.

EPMENT ON THE ACCURACY PARAMETER. (INPUT) PARAMETER)

EPPRO HIGHEST ACCURACY (INPUT PARAMETER)

THE STACE OF THE FUNCTION VALUES SO FAR ENCOUNTERED.

(=10.00 PMACH*FMAX)

EPCOF CURRENTLY REGULTER ACCURACY (=AMAXI (EPREO.EPRO)).

EPFST STIMATE OF CURRENT ACCURACY (THE MAXIMIM OF EPRO AND A FUNCTION OF EPPORS 1.23 AND 4) (UUTPUT PARAMETER)
                       ** CONVERGENCE AND TERMINATION CHECKS IN STAGE THREE(C) **
(1) USES FMAX TO RAISE EPOOF ABOVE ROUND OFF LEVEL. IF
THIS IS NECESSARY AND THE INPUT VALUE OF NCODE IS NEGATIVE.
IT TFOMINATES SETTING NCODE = 0.
(2) USES APPROX TO EVALUATE CONVERGENCE OF TCOF(1) TOWARDS
EXACT. IT MAY ASSIGN CONVERGENCE AND GO TO STAGE FOUR(A)
SETTING NCODE = 1 OR *2.
```

```
FVALIM = AIMAG(FVAL)

SUPPER = SUPPER-FVALRE
FMAX = AMAX1(FMAX+CABS(FVAL))

TCOF(J-1) = FVALE

TCOF(J-1) = FVALE

TCOF(J-1) = FVALIM

JREFL = NPHEV-J

JRCONJ = NTCOF-JRFFL

VAL = CMPLX/ZETA-RCOS+RSIN)
FVAL = CFINI(ZVAL)

FVALRE = HEAL (FVAL)

FVALIM = AIMAG(FVAL)

SUPPER = SUPPER-FVALRE

FMAX = AMAX1(FMAX-CABS(FVAL))

TCOF(JRFFL+1) = FVALRE

TCOF(JRCONJ+1) = FVALIM
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                ## OUTPUT PARAMETERS ##
(4) WORK (REAL) OUTPUT ARRAY.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         ** INDEXING OF ARRAYS **
THE TWO POINT FOURIER TRANSFORM IS APPLIED TO THE POINTS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       THE IND POINT FOURTEM TRANSFORM IS APPLIED TO THE POINTS
OF TOOF WITH INDICES
JOISPONDERV-JREPL AND JDISPONDERV-JREPL-NHALF
HE RESULTS ARE MODIFIED BY THE APPROPRIATE TWINDLE FACTOR
AND STORED IN WORK WITH INDICES
JOISPONNEXT-JREPL AND JDISPONNEXT-JREPL-NPREV
WHERE
WHERE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            C OF
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 PRODUCT OF HEMAINING FACTORS.
PRODUCT OF PREVIOUS FACTORS.
PRODUCT OF PREVIOUS AND CURRENT FACTORS.
PRODUCT OF PREVIOUS AND REMAINING FACTORS.
REPLICATION INDEX = 122...NPKEV.
HEWAITIAN SYMMETRY IN THIS INDEX RESULTS IN
THEEF CACES.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        NOTSP
NOTSP
NOPEV
NNFXT
 NHALE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             JREPL
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 HERMITIAN SYMMETRY IN THIS INDEX RESULTS IN THYEE CASES.

1) INITIAL POINT - JDISP=0. INPUT POINTS ARE PURELY REAL AND OUTPUT POINTS ARE PURELY REAL.

2) MIDDLE POINT - JDISP=NDISP/2 - NOT ALWAYS PRESENT. INPUT POINTS AME COMPLEX AND OUTPUT POINTS ARE PURELY REAL.

3) INTERMEDIATE POINTS - JDISP=1.2,..(NDISP/2-1) - NOT ALWAYS PRESENT. INPUT POINTS AME COMPLEX AND OUTPUT POINTS AME COMPLEX.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    ON INPUT. THE HERMITIAN SYMMETRY IS IN A BLOCK OF LENGTH 2°NDISP-I.E. THE POINT CONJUGATE TO JOISP IS 2°NDISP-JDISP. ON DITPUT. THE HERMITIAN SYMMETRY IS IN A BLOCK OF LENGTH MOISP. I.E. THE POINT CONJUGATE TO JOISP IS NOISP-JDISP. A HERMITIAN SYMMETRIC HLOCK PAS REAL PARTS AT THE FRONT IMAGINARY PARTS (WHEN THEY EXIST) AT THE CONJUGATE POSITIONS AT THE MACK.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       THE THIDDLE FACTOR CEXP(-PI®FYE®J/NDISP). J=1.2...(NDISP/2-1) IS OBTAINED AS SEPARATE REAL AND IMAGINARY PARTS FROM THE SINTAB IAND. THE IMAGINARY PART SINTER JAMES. IS FOUND AT A SPACING OF MSPACEZEWNTAR/NDISP IN SINTAB. THE REAL PART IS FOUND AT A CONJUGATE POSITION IN THE TABLE.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          C IS ONTAINED AS SEPARATE REAL AND IMAGINARY PARTS FROM
C THE SINTAB SAME, THE IMAGINARY PART SINTETS FROM
C THE SINTAB SAME, THE IMAGINARY PART SINTETS IN SINTAM,
C THE BRAIL PART IS FOUND AT A CONJUGATE POSITION IN THE TABLE.

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C CALCULATION OF FIRST NICOF TAYLOR COEFFICIENTS USING F.F.T.

400 CONTINUE

NOISE = NCONVENROUND

NOISE = NCONVENROUND

NOISE = NOISE/C

CALL HEOF (NICOF.NDISP.TCOF.WORK.NIAB.SINIAB)

IF (NOISP.GI.) GO TO 430

DO 420 J = 1.NICOF

TCOF(J) = WORK(J)

420 CONTINUE

GO TO 440

430 CONTINUE

SOLE = 1.0/FLOAT(NICOF.NDISP.WORK.TCOF.NIAB.SINIAB)

IF (NOISP.GI.) GO TO 410

440 CONTINUE

SOLE = 1.0/FLOAT(NICOF.)

DO 450 J = 1.NICOF.

TCOF(J) = TCOF(J).SCALE

WORK(J) = TCOF(J).SCALE

WORK(J) = TCOF(J).SCALE

WORK(J) = TCOF(J).SCALE

WORK(J) = NOISP.WORK.TCOF.NOISP.WORK.TCOF.NIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.SINIAB.
         C ** HERMITIAN FOURTER COEFFICIENTS **
                       ** GENERAL PURPOSE ***
THIS POUTINE DOES ONE PASS OF A FAST FOURIER TRANSFORM.
THE INDEXING IS ARRANGED SO THAT THE COEFFICIENTS ARE IN
OPDER AT THE END OF THE LAST PASS. THIS INDEXING REGULRES
THE USE OF SEPARATE ARRAYS FOR INPUT AND OUTPUT OF THE
PARTIAL RESULTS. THIS **OUTINE IS CALLED ONCE FOR FACH PASS.
                                                                                       INPUT PARAMETERS **
ITCUF NUMBER OF COEFFICIENTS TO BE PROCESSED.
DISP MAXIMUM VALUE OF DISPLACEMENT INDEX.
COF (REAL) IMPUT ARRAY.
IAB NUMBER OF ENTRIES IN SINIAB.
(NTAH (H-AL) IABLE OF VALUES OF SINE.
SINTAH(J+1)=SIN(PI*J/2*NTAB). J=0.1.2...NTAH-1
                                ** INPU
(1) MICOF
(2) MOISP
(3) ICOF
(5) MIAB
(6) SINIAH
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 FIND
SUBROUTINE ENTERF ( CHUN, 7ETA, RETRE, EPREG, FPMACH, NMAX, NCQUE,
FPEST, NICUF, ICOF, WORK, NIAB, EXPIAB)
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```
** QUANTITIES CALCULATED IN STAGE THREE(A) **

THIS IS THE FIRST PART OF ITERATION NUMBER NTCOF, PRESENTLY

AVAILABLE ARE EXPTABLS-1) = CEXP(PI*EYE*J/NTAB).

J = 0.1.2...NTAB-1.

WE REFOURE THE SEQUENCE CEXP(PI*EYE*J/NTCOF/2)).

JE (NTCOF.LE.2*NTAB) THESE NUMBERS ARE ALREADY AVAILABLE
IN THE EXPTAB TABLE SPACED AT AN INTERVAL 2*NSPACE = 4*NTAB/NTCOF.

OTHERWISE. NTCOF = 4*NTAB AND THE EXPTAB TABLE IS UPDATED.

THIS INVOLVES PEARRANGING THE NTAB VALUES AVAILABLE.

CALCULATING AND STORING NTAB NEW VALUES AND UPDATING

NTAB TO 2*NTAB.
                                     ** EVALUATION OF NORMALIZED TAYLOR COEFFICIENTS **
OF AN ANALYTIC FUNCTION **
                             ** GENERAL PURPOSE **

THIS ROUTINE EVALUATES A SET OF NORMALIZED TAYLOR COEFFICIENTS

TCOF(J+1) = (RCIRC***) * (J-TH DERIVATIVE OF CFUN(7) AT Z=ZETA)

DIVIDED BY FACTORIAL(J) ... J = 0.1.2.3...NMAX-1.

TO A UNIFORM ABSOLUTE ACCURACY **EPEST** USING FUNCTION

VALUES OF CFUN(2) AT POINTS IN THE COMPLEX PLANE LYING ON

THE CIPCLE OF RADIUS **RCIFC** WITH CENTER AT Z = ZETA.
                           ** THEORETICAL RESTRICTIONS **

RCTRC MUST BE SMALLER THAN THE RADIUS OF CUNVERGENCE OF THE TAYLOR SEPIES. THE PROBLEM HAS TO BE REFORMULATED SHOULD CFUN(2) HAPPEN TO BE AN ODD FUNCTION OF (Z - ZETA). THAT IS IF THE RELATION **-CFUN(-(Z-ZETA))=CFUN(Z-ZETA)**

IS AN IDENTITY.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              ** REQUIREMENTS FOR CALLING PROGRAM **
CALLING PROGRAM MUST CONTAIN CONTROL STATEMENTS DESCRIBED
IN NOTES (3) AND (4) HELOW. IT MUST ALSO ASSIGN VALUES TO
INPUT PARAMETERS. THE ROUTINE REQUIRES TWO SUBPROGRAMS.
CFCOF (LISTED AFTER ENTCAF) AND CFUN (SEE NOTE(4) BELOW).
                                                                          ** INPUT PARAMETERS **
                                                                                                                                                            NAME OF COMPLEX FUNCTION SUBPROGRAM.
COMPLEX POINT ABOUT WHICH TAYLOR EXPANSION
PADIUS (REAL)
                                13 REDUTAED.
14) FREQ THE ABSOLUTE ACCURACY (REAL) TO WHICH THE NORMALIZED TAYLOR COEFFICIENTS. TCOF(J). ARE REQUIRED COMMENTATION THE MACHINE ACCURACY PARAMETER (REAL) (OR AN UPPER BOUND ON THE RELATIVE ACCURACY OF OHIGH TITES LIKELY TO HE ENCOUNTERED).

(6) NMAX PHYSICAL UPPER LIMIT ON THE SIZE AND LENGTH OF THE CALCULATION. THE MAKINUM NUMBER OF COEFFICIENTS CALCULATED WILL BE THAT POWER OF TWO LESS 1-AAN OR FOUAL TO MAMAX. MAMAX IS ASSUMED TO HE AT LEAST 4. (SEE NOTE(3) RELOW.)

(7) NCODF. GEAT THE MOUTINE WILL DO AS WELL AS IT CAN.

LI.D THE MOUTINE WILL ABORT AT AN EARLY STAGE IF THE REQUIRED ACCURACY CANNOT HE ATTAINED HECAUSE OF ROUND OFF ERROR.

IN NORMAL PUNNING, NTAH SHOULD BE SET TO ZERO BEFORK THE FIRST CALL TO ENTOCAF, BUT LEFT ALONE AFTER THAT. (FOR MORE SOPHISTICATED USF, SEE OUTPUT PARAMETERS (12) AND (13) AND NOTE(2) HELDW.)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 *** ON ON THE STAGE THREE(C) ***

FRROR1 CURRENT VALUE OF THE ERROR = CABS(APPROX-EXACT).

ERROR2. ERROR3. ERRORA VALUES OF FRROR AT END OF THREE

PREVIOUS ITERATIONS.

EPHACH MACHINE ACCURACY PARAMETER. (INPUT PARAMETER)

EPRED REQUIRED ACCURACY (INPUT PARAMETER)

HIGHEST ACCURACY REASONABLY ATTAINABLE IN VIEW OF

THE SIZE OF THE FUNCTION VALUES SO FAR ENCOUNTERED.

(=10.09EPHACH=FMAX)

EPCOF CURRENTLY PEQUIRED ACCURACY (=AMAXI (EPREQ-EPRO)).

EPEST ESTIMATE OF CURRENT ACCURACY. (THE MAXIMUM OF EPRO ATA FUNCTION OF ENHORS 1-2-3 AND 4. (OUTPUT PARAMETER)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               A FUNCTION OF ERRORS 1.2.3 AND 4. (OUTPUT PARAMETER)

** CONVERGENCE AND TERMINATION CHECKS IN STAGE THREE(C) **

(1) USES FMAX TO MAISE EPCOF ABOVE HOUND OF LEVEL.

IT THIS NECESSARY AND THE INPUT VALUE OF NCODE IS NEGATIVE,

IT TERMINATES SETTING MCODE=0.

(2) USES APPROX TO EVALUATE CONVERGENCE OF ICOF(I) TOWARDS
EXACT. IT MAY ASSIGN CONVERGENCE AND GO TO STAGE FOUR(A)

SETTING NCODE=+1 OR +2. (CONVERGENCE IS NOT CHECKED FOR
FOUR OR FEMER POINTS).

(3) USES NMAX TO CHECK PHYSICAL LIMIT. IF THIS HAS BEEN
REACHED. IT GOES TO STAGE FOUR(A) SETTING NCODE=-1 OR -2.

(4) OTHERWISE CONTINUES NEXT ITERATION BY GOING TO STAGE
THAFF.
                        (12) NTAB
                           **GELOW**)

***OUTPUT APAGETERS ***
(1)*(2)*(3)*(4)*(5)*(6)**IDENTICAL WITH INPUT VALUES.*

(7) NCODE

**RESULT STATUS INDICATOR** TAKES ONE OF FIVE VALUES AS FOLLOWS**.

**=*1**CONVERGED** NORMALLY**

**=*1***OUTO CONVERGE**, NO ROUND OFF ERROR TROUBLE **2***CONVERGE*** NIT WITH A HIGHER TOLERANCE SET BY THE ROUND OFF LEVEL.*

**EPECTOR OFF THE STATE OF THE STATE OF THE STATE OF THE STATE OF ACTUAL UNIFORM ABSOLUTE ACCURACY IN ALL TOOP***, **EXCEPT IF NCODE***EQ***, **O ESTIMATE OF ACTUAL UNIFORM ABSOLUTE ACCURACY IN ALL TOOP***, **EXCEPT IF NCODE***EQ***, **O ESTIMATE OF ROUND OFF LEVEL.**

(9) NTCOF***

NUMBER OF NONTHIVIAL VALUES OF TOOP ACTUALLY OFF CEPTA.**

**CALCULATED**** THEY ARE BASED ON NICOF*** CALLS OF CFIN***

**COMPLEX INTERESTEDATION OFF ALL ADDRIVENTIONS TO
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 **CALCHLATION OF FIRST NICOF TAYLOR COEFFICIENTS IN STAGE FOUR(A)
A VENSION OF THE FAST FORMER TRANSFORM USING A WORK ARRAY
IS USED. THE ARRAY ***MOR*** IS USED ONLY DURING THIS STAGE.
THE WORK ARRAY ALLOWS THE PERMUTING OF INDICES ASSOCIATED
WITH IN-PLACE FFIS TO BE SUPPRESSED. THE FFT CALCHLATES
THE NECCESSARY SUMMATIONS EXCEPT FOR DIVIDING BY NICOF.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      C THE NECCESSARY SUMMATIONS EXCEPT FOR DIVIDING BY NICOF.

C SETTING OF PEMAINING TAYLOR COEFFICIENTS IN STAGE FOUR(B)
C THE CONVERGENCE CHIEFION ALLOWS US TO INFER IMAT THE
C NORMALIZED LAYLOR COEFFICIENTS OF ORDER GREATER THAN NICOF
C ARE ZERO TO ACCURACY FPEST.
C THEY ARE EVALUATION AS BEING EXACTLY ZERO.
COMPLEX CFIN
COMPLEX ZITA
RFAL RCIRC.FPHED.FPMACH-FPEST
INTEGEP NAWAN-NCODE.NICOF.NITAB
COMPLEX TOUF (1). WORK (1). EXPITAB (1)
INTEGEP NAWAN-NCODE.NICOF.NIDAB.
OMPLEX CONDIF.LEPOF.CEMIN-FPMO.FPJ2.FP42.ERROR1.FRNOR2
REAL FRORS-ENHOWA.FMAX-SAFEIY-SCALE.TWOPI
INTEGEP J.JCONJ.JFRNM.JTAH.JTO
COMPLEX CONDIF.CEMIN.FPMO.TAH.JTO
COMPLEX CONDIF.CEMIN.FRNM.JTAH.JTO
CONDIT.CEMIN.JTAH.JTO
CONDIT.CEMIN.J
            CALCULATED. THEY ARE BASED ON NICOF-1 CALLS
OF CFIN.

(10) TCOF

COMPLEX DIMENSION (DIM). APPROXIMATIONS ID
THE NORMALIZED LAYLOR COEFFICIENTS. EXCEPT WHEN
OUTPUT NCOUE = 0. (SEE NOTE-3) HELOW.)

(11) NORK

INTERNAL WORKING AREA OF COMPLEX DIMENSION (DIM).
(SEE NOTE(3) HELOW). CONTENTS IS IDENTICAL
(12) FXPTAB COMPLEX DIMENSION (DIM/2). (SEE NOTES (2) AND
(3) HELOW.) FXPTAB(J=1) = CEXP(PIEXYF=JNTAS)
J = 0.12.....AIAB-1. (A HALF CYCLE)
OTHEP LOCATIONS ARE EMPTY.
C (11) WORK
         NITIALISE BUOKKEEPING PAPAMETE
NADONDO = 1
NAHORT = 0
IF (NCOUE.LI.O) NAHORT = 1
FPCOF = EPREU
SAFETY = 10.0
7VAL = ZEIA
FVAL = CFUN(ZVAL)
FXACT = FVAL

= CTAGE TWO

TOTALE TOTALE TOTALE TOTALE

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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            FXACI = FVAL

C *** STAGET TWO ****

C *** STAGET TWO ****

C FIRST TWO TIEBATIONS ( THOSE WITH NICOF = 1.2 ).

FWADR3 = 0.0

FVAL = ZETA+CMPLX (PCIRC+0.0)

FVAL = ZETA+CMPLX (PCIRC+0.0)

FVAL = ZETA+CMPLX (PCIRC+0.0)

FVAL = ZENS (FVAL)

TCGF(1) = FVAL

FWADP2 = CAHS (APPDOX-EXACT)

TVAL = ZETA-CMPLX (RCIRC+0.0)

FVAL = CFONIC (VAL)

APPROX = 0.5* (APPDOX-FVAL)

FWAX = AMAXI (FMAX-CAHS (FVAL))

TCGF(2) = FVAL

FRADRI = CAHS (APPROX-EXACT)

*** NICOF = 2

C *** STAGE THREE ***

C *** STAGE THREE ***

C *** STAGE THREE ***

C *** STAGE THREE(A) ***

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C *** STAGE THREE(A) ***

C *** STAGE THREE(A) ***

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STAGE THREE(A) **

STAGE THREE(A
              COMPLEX CFIN.

*** HOOKKEFPING PARAMETERS FOR STAGE ONE ***

***NCONV 1 CONVERGENCE ACHIEVED.

-1 NO CONVERGENCE ACHIEVED.

**NO CONVERGENCE ACHIEVED.

***NORDING 1 NO ROBING OFF THOURLE OBSERVED.

**PORIND OFF PROBLEME OBSERVED.

**ORDING OFF PROBLEME.

1 TEPMINATE WHEN ROUND OFF TROUBLE OBSERVED.

FXACT THE EXACT VALUE OF TCOF(1) WHICH IS CFUN(ZETA).

SAFELY THIS IS A SAFELY FACTOR BY WHICH THE ROUTINE AVOIDS THE ROUND OFF LEVEL. IT IS SET TO 16-0 AND APPEARS ONLY IN THE COMPLIANTION (SAFELYSEPMACH). TO ALTER THIS FACTOR, OF TO REMUVE THE MOUND OFF ERROR GUARD.

COMPLETELY. THE USER NEFD ONLY ADJUST THE INPUT PARAMETER EPMACH APPROPRIATELY.
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310 CONTINUE
NOCLIM = NTAB-1
NOCLIM = NTAB-1
NOCLIM = NTAB-1
NOCLIM = NTAB-1
JTO = 2 * JFROM
FXPTAB(JTO+1) = FXPTAB(JFROM+1)

320 CONTINUE
NTAB = 2 * NTAB
TYOP1 = K.0 * ATAN(1.0)
CONDIF = COS(TWOP1/FLOAT(2 * NTAB))
NINGLIM = NTAB-3
NOCLIM = NTAB-3
PO 330 J = 1 * NUOLIM * 2
FXPTAM(J+1) = (0.5 * EXPTAB(J) * 0.5 * EXPTAB(J+2))/COSDIF

330 CONTINUE
                  330 CONTINUE
FXPTAH(NTAH) = (0.59EXPTAR(NTAH-1)-(0.5.0.0))/COSOIF
      330 CONTINUE
FXPTAH(NIAB) = (0.5°EXPTAH(NIAH-1)-(
340 CONTINUE
C *** STAGE THHEE(H) ***

C UPPATE LIST OF FUNCTION VALUES IN TCOF.

C CALCHIATE FMAX AND APPROX.

NIDOLIM = NPREV-1

DO 350 J = 1.NIDOLIM

JEROM = NPREV-1

JTO = 2**JFROM

COFIJIO+1) = TCOF(JFROM+1)

350 CONTINUE
SUM = (0.0.0.0)

NSPACE = (2**NTAH)/NTCOF

DO 360 J = 1.NNDLIM-2

JTAH = J**NSPACE

PEXP = RCIRCE*XPFAH(JTAH+1)

/VAL = ZETA**PEXP

FVAL = CFUN(YVAL)

SUM = SUM**FVAL

JCONJ = NTCOF**J

JVAL = 7E | A**CONJG(REXP)

FVAL = CFUN(ZYAL)

SUM = SIM**FVAL

JCONJ = NTCOF**J

JVAL = TE | A**CONJG(REXP)

FVAL = CFUN(ZYAL)

SUM = SIM**FVAL

JCONJ = NTCOF**J

JVAL = TE | A**CONJG(REXP)

FVAL = CFUN(ZYAL)

SUM = SIM**FVAL

FMAX = AMAXI(FMAX**CABS(FVAL))

TCOF**JONJOH**J

SUM = SIM**FVAL

FMAX = AMAXI(FMAX**CABS(FVAL))

TCOF**JONJOH**J

APPROX = 0.5**APPMOX**SUM/*FLOAT(NTCOF)
SUPROUTINE CECOF ( NTCOF+ NDISP+ TCOF+ WORK+ NTAB+ EXPTAB )
    SUPROJUTE GLOW CASES

C SO COMPLEX FOURIER COEFFICIENTS SO C

SO GENERAL PURPOSE SO C

C HIS SHUTINE DOES ONE PASS OF A FAST FOURIER TRANSFORM.

C THE INVEXING IS ARRANGED SO THAT THE COFFFICIENTS APE IN CORDER AT THE END OF THE LAST PASS. INTO INDEXING REQUIRES

C THE USE OF SEPAPATE ARRAYS FOR INPUT AND OUTPUT OF THE

C PARTIAL RESULTS. THIS ROUTINE IS CALLED ONCE FOR

C EACH PASS.
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C : INPUT PARAMETERS **
C (1) MICOF NUMBER OF COEFFICIFNTS TO HE PROCESSED.
C (2) MOTSP MAXIMUM VALUE OF DISPLACEMENT INDEX.
C (3) TOOF (COMPLEX) INPUT ARXAY.
C (5) NIAB MUMBER OF CENTRIES IN EXPTAB.
C (6) FAPTAH (COMPLEX) TABLE OF VALUES OF COMPLEX EXPONENTIAL.
C (6) FAPTAH (COMPLEX) TABLE OF VALUES OF COMPLEX EXPONENTIAL.
C (7) WORK (COMPLEX) OUTPUT ARXAY.
C ** OUTPUT PARAMETERS **
C (4) WORK (COMPLEX) OUTPUT APRAY.
C ** OUTPUT PARAMETERS O**
C (6) WORK (COMPLEX) OUTPUT APRAY.
C ** INDEXIMO OF ARMAYS O**
C THE TWO POINT FOURTER (MANSFORM IS APPLIED TO THE POINTS OF THE TWO POINT FOURTER (MANSFORM IS APPLIED TO THE POINTS OF THE TWO POINTS OF WITH INDICES OF TOOR OF THE PROPOSED OF THE TWO POINTS OF THE TWO
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