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# Berlekamp–Massey algorithm

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*Not to be confused with [Berlekamp's algorithm](#).*

The **Berlekamp–Massey algorithm** is an [algorithm](#) that will find the shortest [linear feedback shift register](#) (LFSR) for a given binary output sequence. The algorithm will also find the [minimal polynomial](#) of a linearly [recurrent sequence](#) in an arbitrary [field](#). The field requirement means that the Berlekamp–Massey algorithm requires all non-zero elements to have a multiplicative inverse.<sup>[1]</sup> Reeds and Sloane offer an extension to handle a [ring](#).<sup>[2]</sup>

[Elwyn Berlekamp](#) invented an algorithm for decoding [Bose–Chaudhuri–Hocquenghem \(BCH\) codes](#).<sup>[3]</sup><sup>[4]</sup> [James Massey](#) recognized its application to linear feedback shift registers and simplified the algorithm.<sup>[5]</sup><sup>[6]</sup> Massey termed the algorithm the LFSR Synthesis Algorithm (Berlekamp Iterative Algorithm),<sup>[7]</sup> but it is now known as the Berlekamp–Massey algorithm.

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## Description of algorithm [\[edit\]](#)

The Berlekamp–Massey algorithm is an alternate method to solve the set of linear equations described in [Reed–Solomon Peterson decoder](#), which can be summarized as:

$$S_{i+\nu} + \Lambda_1 S_{i+\nu-1} + \cdots + \Lambda_{\nu-1} S_{i+1} + \Lambda_{\nu} S_i = 0.$$

In the code examples below, C(x) is a potential instance of  $\Lambda(x)$ . The error locator polynomial C(x) for *L* errors is defined as:

$$C(x) = C_L x^L + C_{L-1} x^{L-1} + \cdots + C_2 x^2 + C_1 x + 1$$

or reversed:

$$C(x) = 1 + C_1 x + C_2 x^2 + \cdots + C_{L-1} x^{L-1} + C_L x^L.$$

The goal of the algorithm is to determine the minimal degree *L* and C(x) which results in:

$$S_n + C_1 S_{n-1} + \cdots + C_L S_{n-L} = 0$$

for all syndromes, *n* = *L* to (*N*-1).

Algorithm: C(x) is initialized to 1, *L* is the current number of assumed errors, and initialized to zero. *N* is the total number of syndromes. *n* is used as the main iterator and to index the syndromes from 0 to (*N*-1). B(x) is a copy of the last C(x) since *L* was updated and initialized to 1. *b* is a copy of the last discrepancy *d* (explained below) since *L* was updated and initialized to 1. *m* is the number of iterations since *L*, B(x), and *b* were updated and initialized to 1.

Each iteration of the algorithm calculates a discrepancy *d*. At iteration *k* this would be:

$$d = S_k + C_1 S_{k-1} + \cdots + C_L S_{k-L}.$$

If *d* is zero, the algorithm assumes that C(x) and L are correct for the moment, increments *m*, and continues.

If *d* is not zero, the algorithm adjusts C(x) so that a recalculation of *d* would be zero:

$$C(x) = C(x) - (d/b) x^m B(x).$$

The *x<sup>m</sup>* term *shifts* B(x) so it follows the syndromes corresponding to 'b'. If the previous update of L occurred on iteration *j*, then *m* = *k* - *j*, and a recalculated discrepancy would be:

$$d = S_k + C_1 S_{k-1} + \cdots - (d/b)(S_j + B_1 S_{j-1} + \cdots).$$

This would change a recalculated discrepancy to:

$$d = d - (d/b)b = d - d = 0.$$

The algorithm also needs to increase  $L$  (number of errors) as needed. If  $L$  equals the actual number of errors, then during the iteration process, the discrepancies will become zero before  $n$  becomes greater than or equal to  $(2L)$ . Otherwise  $L$  is updated and algorithm will update  $B(x)$ ,  $b$ , increase  $L$ , and reset  $m = 1$ . The formula  $L = (n + 1 - L)$  limits  $L$  to the number of available syndromes used to calculate discrepancies, and also handles the case where  $L$  increases by more than 1.

## Code sample [\[edit\]](#)

The algorithm from [Massey \(1969, p. 124\)](#).

```

polynomial(field K) s(x) = ... /* coeffs are s_j; output sequence as N-1 degree
polynomial) */
/* connection polynomial */
polynomial(field K) C(x) = 1; /* coeffs are c_j */
polynomial(field K) B(x) = 1;
int L = 0;
int m = 1;
field K b = 1;
int n;
for (n = 0; n < N; n++)
{
    /* calculate discrepancy */
    field K d = s_n + \Sigma_{i=1}^L c_i * s_{n-i};
    if (d == 0)
    {
        /* annihilation continues */
        m = m + 1;
    }
    else if (2 * L <= n)
    {
        /* temporary copy of C(x) */
        polynomial(field K) T(x) = C(x);
        C(x) = C(x) - d b^{-1} x^m B(x);
        L = n + 1 - L;
        B(x) = T(x);
        b = d;
        m = 1;
    }
    else
    {
        C(x) = C(x) - d b^{-1} x^m B(x);
        m = m + 1;
    }
}
return L;

```

## The algorithm for the binary field [\[edit\]](#)

The following is the Berlekamp–Massey algorithm specialized for the typical binary [finite field](#)  $F_2$  and  $GF(2)$ . The field elements are 0 and 1. The field operations  $+$  and  $-$  are identical and become the exclusive or operation, XOR. The multiplication operator  $*$  becomes the logical AND operation. The division operator reduces to the identity operation (i.e., field division is only defined for dividing by 1, and  $x/1 = x$ ).

1. Let  $s_0, s_1, s_2 \cdots s_{n-1}$  be the [bits](#) of the stream.
2. Initialise two arrays  $b$  and  $c$  each of length  $n$  to be zeroes, except  $b_0 \leftarrow 1, c_0 \leftarrow 1$
3. assign  $L \leftarrow 0, m \leftarrow -1$ .
4. For  $N = 0$  step 1 while  $N < n$ :
  - Let  $d$  be  $s_N + c_1 s_{N-1} + c_2 s_{N-2} + \cdots + c_L s_{N-L}$ .
  - if  $d = 0$ , then  $c$  is already a polynomial which annihilates the portion of the stream from  $N - L$  to  $N$ .
  - else:

- Let  $t$  be a copy of  $c$ .
- Set  $c_{N-m} \leftarrow c_{N-m} \oplus b_0$ ,  $c_{N-m+1} \leftarrow c_{N-m+1} \oplus b_1, \dots$  up to  $c_{n-1} \leftarrow c_{n-1} \oplus b_{n-N+m-1}$  (where  $\oplus$  is the [Exclusive or](#) operator).
- If  $L \leq \frac{N}{2}$ , set  $L \leftarrow N + 1 - L$ , set  $m \leftarrow N$ , and let  $b \leftarrow t$ ; otherwise leave  $L$ ,  $m$  and  $b$  alone.

At the end of the algorithm,  $L$  is the length of the minimal LFSR for the stream, and we have  $c_L s_a + c_{L-1} s_{a+1} + c_{L-2} s_{a+2} + \dots = 0$  for all  $a$ .

## Code sample for the binary field in Java [\[edit\]](#)

The following code sample is for a binary field.

```
public static int runTest(int[] array) {
    final int N = array.length;
    int[] b = new int[N];
    int[] c = new int[N];
    int[] t = new int[N];
    b[0] = 1;
    c[0] = 1;
    int l = 0;
    int m = -1;
    for (int n = 0; n < N; n++) {
        int d = 0;
        for (int i = 0; i <= l; i++) {
            d ^= c[i] * array[n - i];
        }
        if (d == 1) {
            System.arraycopy(c, 0, t, 0, N);
            int N_M = n - m;
            for (int j = 0; j < N - N_M; j++) {
                c[N_M + j] ^= b[j];
            }
            if (l <= n / 2) {
                l = n + 1 - l;
                m = n;
                System.arraycopy(t, 0, b, 0, N);
            }
        }
    }
    return l;
}
```

## See also [\[edit\]](#)

- [Reeds–Sloane algorithm](#), an extension for sequences over integers mod  $n$
- [Berlekamp–Welch algorithm](#)
- [NLFSR](#), Non-Linear Feedback Shift Register

## References [\[edit\]](#)

- ↑ [Reeds & Sloane 1985](#), p. 2
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- ↑ [Massey 1969](#), p. 124

## External links [\[edit\]](#)

- Hazewinkel, Michiel, ed. (2001), "Berlekamp-Massey algorithm" [↗](#), *Encyclopedia of Mathematics*, Springer, ISBN 978-1-55608-010-4
- Berlekamp–Massey algorithm [↗](#)<sup>[*dead link*]</sup> at PlanetMath.
- Weisstein, Eric W., "Berlekamp–Massey Algorithm" [↗](#), *MathWorld*.
- GF(2) implementation in Mathematica [↗](#)
- **(German)** Applet Berlekamp–Massey algorithm [↗](#)
- Online GF(2) Berlekamp-Massey calculator [↗](#)

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