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# De Casteljau's algorithm

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In the [mathematical](#) field of [numerical analysis](#), **De Casteljau's algorithm** is a [recursive](#) method to evaluate polynomials in [Bernstein form](#) or [Bézier curves](#), named after its inventor [Paul de Casteljau](#). **De Casteljau's algorithm** can also be used to split a single Bézier curve into two Bézier curves at an arbitrary parameter value.

Although the algorithm is slower for most architectures when compared with the direct approach, it is more [numerically stable](#).

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## Definition

A Bézier curve  $B$  (of degree  $n$ , with control points  $\beta_0, \dots, \beta_n$ ) can be written in Bernstein form as follows

$$B(t) = \sum_{i=0}^n \beta_i b_{i,n}(t).$$

where  $b$  is a [Bernstein basis polynomial](#)

$$b_{i,n}(t) = \binom{n}{i} (1-t)^{n-i} t^i.$$

The curve at point  $t_0$  can be evaluated with the [recurrence relation](#)

$$\begin{aligned} \beta_i^{(0)} &:= \beta_i, \quad i = 0, \dots, n \\ \beta_i^{(j)} &:= \beta_i^{(j-1)} (1-t_0) + \beta_{i+1}^{(j-1)} t_0, \quad i = 0, \dots, n-j, \quad j = 1, \dots, n \end{aligned}$$

Then, the evaluation of  $B$  at point  $t_0$  can be evaluated in  $n$  steps of the algorithm. The result  $B(t_0)$  is given by :

$$B(t_0) = \beta_0^{(n)}.$$

Moreover, the Bézier curve  $B$  can be split at point  $t_0$  into two curves with respective control points :

$$\begin{aligned} &\beta_0^{(0)}, \beta_0^{(1)}, \dots, \beta_0^{(n)} \\ &\beta_0^{(n)}, \beta_1^{(n-1)}, \dots, \beta_n^{(0)} \end{aligned}$$

## Example implementation

Here is an example implementation of De Casteljau's algorithm in [Haskell](#):

```
deCasteljau :: Double -> [(Double, Double)] -> (Double, Double)
deCasteljau t [b] = b
deCasteljau t coefs = deCasteljau t reduced
  where
    reduced = zipWith (lerpP t) coefs (tail coefs)
    lerpP t (x0, y0) (x1, y1) = (lerp t x0 x1, lerp t y0 y1)
    lerp t a b = t * b + (1 - t) * a
```

## Notes [\[edit\]](#)

When doing the calculation by hand it is useful to write down the coefficients in a triangle scheme as

$$\begin{array}{ccccccc} \beta_0 & & & & & & \\ & \beta_0^{(1)} & & & & & \\ & & \beta_1^{(0)} & & & & \\ & & & \ddots & & & \\ & & & & \beta_0^{(n)} & & \\ & & & & & & \\ & \beta_{n-1}^{(0)} & & & & & \\ & & \beta_{n-1}^{(1)} & & & & \\ & & & & & & \\ & \beta_n^{(0)} & & & & & \end{array}$$

When choosing a point  $t_0$  to evaluate a Bernstein polynomial we can use the two diagonals of the triangle scheme to construct a division of the polynomial

$$B(t) = \sum_{i=0}^n \beta_i^{(0)} b_{i,n}(t) , \quad t \in [0, 1]$$

into

$$B_1(t) = \sum_{i=0}^n \beta_0^{(i)} b_{i,n} \left( \frac{t}{t_0} \right) , \quad t \in [0, t_0]$$

and

$$B_2(t) = \sum_{i=0}^n \beta_i^{(n-i)} b_{i,n} \left( \frac{t-t_0}{1-t_0} \right) , \quad t \in [t_0, 1]$$

## Example [\[edit\]](#)

We want to evaluate the Bernstein polynomial of degree 2 with the Bernstein coefficients

$$\begin{aligned} \beta_0^{(0)} &= \beta_0 \\ \beta_1^{(0)} &= \beta_1 \\ \beta_2^{(0)} &= \beta_2 \end{aligned}$$

at the point  $t_0$ .

We start the recursion with

$$\begin{aligned} \beta_0^{(1)} &= \beta_0^{(0)} (1 - t_0) + \beta_1^{(0)} t_0 = \beta_0 (1 - t_0) + \beta_1 t_0 \\ \beta_1^{(1)} &= \beta_1^{(0)} (1 - t_0) + \beta_2^{(0)} t_0 = \beta_1 (1 - t_0) + \beta_2 t_0 \end{aligned}$$

and with the second iteration the recursion stops with

$$\begin{aligned} \beta_0^{(2)} &= \beta_0^{(1)} (1 - t_0) + \beta_1^{(1)} t_0 \\ &= \beta_0 (1 - t_0) (1 - t_0) + \beta_1 t_0 (1 - t_0) + \beta_1 (1 - t_0) t_0 + \beta_2 t_0 t_0 \\ &= \beta_0 (1 - t_0)^2 + \beta_1 2t_0 (1 - t_0) + \beta_2 t_0^2 \end{aligned}$$

which is the expected Bernstein polynomial of degree 2.

## Bézier curve [\[edit\]](#)

When evaluating a Bézier curve of degree  $n$  in 3-dimensional space with  $n+1$  control points  $\mathbf{P}_i$

$$\mathbf{B}(t) = \sum_{i=0}^n \mathbf{P}_i b_{i,n}(t) , \quad t \in [0, 1]$$

with

$$\mathbf{P}_i := \begin{pmatrix} x_i \\ y_i \\ z_i \end{pmatrix}.$$

we split the Bézier curve into three separate equations

$$B_1(t) = \sum_{i=0}^n x_i b_{i,n}(t), \quad t \in [0, 1]$$

$$B_2(t) = \sum_{i=0}^n y_i b_{i,n}(t), \quad t \in [0, 1]$$

$$B_3(t) = \sum_{i=0}^n z_i b_{i,n}(t), \quad t \in [0, 1]$$

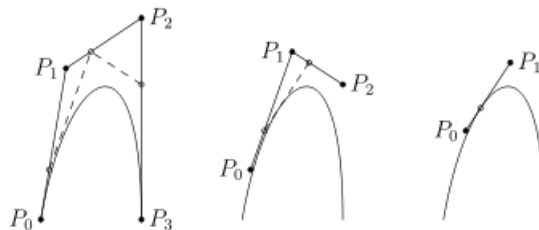
which we evaluate individually using De Casteljau's algorithm.

## Geometric interpretation [\[edit\]](#)

The geometric interpretation of De Casteljau's algorithm is straightforward.

- Consider a Bézier curve with control points  $P_0, \dots, P_n$ . Connecting the consecutive points we create the control polygon of the curve.
- Subdivide now each line segment of this polygon with the ratio  $t:(1-t)$  and connect the points you get. This way you arrive at the new polygon having one fewer segment.
- Repeat the process until you arrive at the single point - this is the point of the curve corresponding to the parameter  $t$ .

The following picture shows this process for a cubic Bézier curve:



Note that the intermediate points that were constructed are in fact the control points for two new Bézier curves, both exactly coincident with the old one. This algorithm not only evaluates the curve at  $t$ , but splits the curve into two pieces at  $t$ , and provides the equations of the two sub-curves in Bézier form.

The interpretation given above is valid for a nonrational Bézier curve. To evaluate a rational Bézier curve in  $\mathbf{R}^n$ , we may project the point into  $\mathbf{R}^{n+1}$ ; for example, a curve in three dimensions may have its control points  $\{(x_i, y_i, z_i)\}$  and weights  $\{w_i\}$  projected to the weighted control points  $\{(w_i x_i, w_i y_i, w_i z_i, w_i)\}$ . The algorithm then proceeds as usual, interpolating in  $\mathbf{R}^4$ . The resulting four-dimensional points may be projected back into three-space with a [perspective divide](#).

In general, operations on a rational curve (or surface) are equivalent to operations on a nonrational curve in a [projective space](#). This representation as the "weighted control points" and weights is often convenient when evaluating rational curves.

## See also [\[edit\]](#)

- [Bézier curves](#)
- [De Boor's algorithm](#)
- [Horner scheme](#) to evaluate polynomials in [monomial form](#)
- [Clenshaw algorithm](#) to evaluate polynomials in [Chebyshev form](#)

## References [\[edit\]](#)

- Farin, Gerald & Hansford, Dianne (2000). *The Essentials of CAGD*. Natic, MA: A K Peters, Ltd. [ISBN 1-56881-123-3](#)

## External links [\[edit\]](#)

- [Piecewise linear approximation of Bézier curves](#)  – description of De Casteljau's algorithm, including a criterion to determine when to stop the recursion
- [Bezier Curves and Picasso](#)  — Description and illustration of De Casteljau's algorithm applied to cubic Bézier curves.

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