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Evolution strategy

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In computer science, an **evolution strategy (ES)** is an [optimization](#) technique based on ideas of adaptation and evolution. It belongs to the general class of [evolutionary computation](#) or [artificial evolution](#) methodologies.

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History

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The 'evolution strategy' optimization technique was created in the early 1960s and developed further in the 1970s and later by [Ingo Rechenberg](#), [Hans-Paul Schwefel](#) and their co-workers.

Methods

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Evolution strategies use natural problem-dependent representations, and primarily mutation and [selection](#), as search operators. In common with [evolutionary algorithms](#), the operators are applied in a loop. An iteration of the loop is called a generation. The sequence of generations is continued until a termination criterion is met.

As far as real-valued search spaces are concerned, mutation is normally performed by adding a [normally distributed](#) random value to each vector component. The step size or mutation strength (i.e. the standard deviation of the normal distribution) is often governed by self-adaptation (see [evolution window](#)). Individual step sizes for each coordinate or correlations between coordinates are either governed by self-adaptation or by covariance matrix adaptation ([CMA-ES](#)).

The (environmental) selection in evolution strategies is deterministic and only based on the fitness rankings, not on the actual fitness values. The resulting algorithm is therefore invariant with respect to monotonic transformations of the objective function. The simplest evolution strategy operates on a population of size two: the current point (parent) and the result of its mutation. Only if the mutant's fitness is at least as good as the parent one, it becomes the parent of the next generation. Otherwise the mutant is disregarded. This is a $(1 + 1)$ -ES. More generally, λ mutants can be generated and compete with the parent, called $(1 + \lambda)$ -ES. In $(1, \lambda)$ -ES the best mutant becomes the parent of the next generation while the current parent is always disregarded. For some of these variants, proofs of [linear convergence](#) (in a [stochastic](#) sense) have been derived on unimodal objective functions.^{[[1](#)][[2](#)]}

Contemporary derivatives of evolution strategy often use a population of μ parents and also recombination as an additional operator, called $(\mu/\rho +, \lambda)$ -ES. This makes them less prone to get stuck in local optima.^{[[3](#)]}

See also

[\[edit\]](#)

- [Genetic algorithm](#)
- [Evolutionary computation](#)
- [Covariance matrix adaptation evolution strategy \(CMA-ES\)](#)
- [Natural evolution strategy](#)

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Research centers [\[edit\]](#)

- [Bionics & Evolutionstechnik at the Technical University Berlin](#)
- [Chair of Algorithm Engineering \(Ls11\) – University of Dortmund](#)
- [Collaborative Research Center 531 – University of Dortmund](#)

v · t · e Evolutionary computation [hide]	
Main Topics	Convergence (evolutionary computing) · Evolutionary algorithm · Evolutionary data mining · Evolutionary multimodal optimization · Human-based evolutionary computation · Interactive evolutionary computation
Algorithms	Cellular evolutionary algorithm · Covariance Matrix Adaptation Evolution Strategy (CMA-ES) · Differential evolution · Evolutionary programming · Genetic algorithm · Genetic programming · Gene expression programming · Evolution strategy · Natural evolution strategy · Neuroevolution · Learning classifier system
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