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# Tree sort

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A **tree sort** is a [sort algorithm](#) that builds a [binary search tree](#) from the keys to be sorted, and then traverses the tree ([in-order](#)) so that the keys come out in sorted order. Its typical use is sorting elements [adaptively](#): after each insertion, the set of elements seen so far is available in sorted order.

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## Efficiency [\[edit\]](#)

Adding one item to a binary search tree is on average an  $O(\log n)$  process (in [big O notation](#)), so adding  $n$  items is an  $O(n \log n)$  process, making tree sort a 'fast sort'. But adding an item to an unbalanced binary tree needs  $O(n)$  time in the worst-case, when the tree resembles a [linked list \(degenerate tree\)](#), causing a worst case of  $O(n^2)$  for this sorting algorithm. This worst case occurs when the algorithm operates on an already sorted set, or one that is nearly sorted. Expected  $O(\log n)$  time can however be achieved in this case by shuffling the array.

The worst-case behaviour can be improved upon by using a [self-balancing binary search tree](#). Using such a tree, the algorithm has an  $O(n \log n)$  worst-case performance, thus being degree-optimal for a [comparison sort](#). When using a [splay tree](#) as the binary search tree, the resulting algorithm (called [splaysort](#)) has the additional property that it is an [adaptive sort](#), meaning that its running time is faster than  $O(n \log n)$  for inputs that are nearly sorted.

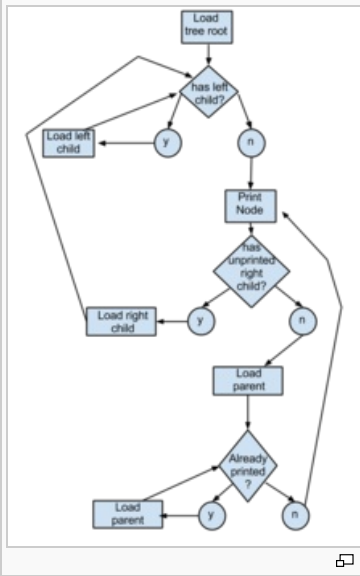
## Example [\[edit\]](#)

The following tree sort algorithm in pseudocode accepts an [array of comparable items](#) and outputs the items in ascending order:

```
STRUCTURE BinaryTree
    BinaryTree:LeftSubTree
    Object:Node
    BinaryTree:RightSubTree

PROCEDURE Insert (BinaryTree:searchTree, Object:item)
    IF searchTree.Node IS NULL THEN
        SET searchTree.Node TO item
    ELSE
        IF item IS LESS THAN searchTree.Node THEN
            Insert (searchTree.LeftSubTree, item)
        ELSE
            Insert (searchTree.RightSubTree, item)
```

### Tree sort



<b>Class</b>	<a href="#">Sorting algorithm</a>
<b>Data structure</b>	<a href="#">Array</a>
<b>Worst case performance</b>	$O(n^2)$ (unbalanced) $O(n \log n)$ (balanced)
<b>Best case performance</b>	$O(n \log n)$ <sup><a href="#">[citation needed]</a></sup>
<b>Average case performance</b>	$O(n \log n)$
<b>Worst case space complexity</b>	$\Theta(n)$

```
PROCEDURE InOrder (BinaryTree:searchTree)
  IF searchTree.Node IS NULL THEN
    EXIT PROCEDURE
  ELSE
    InOrder (searchTree.LeftSubTree)
    EMIT searchTree.Node
    InOrder (searchTree.RightSubTree)

PROCEDURE TreeSort (Array:items)
  BinaryTree:searchTree

  FOR EACH individualItem IN items
    Insert (searchTree, individualItem)

  InOrder (searchTree)
```

In a simple **functional programming** form, the algorithm (in **Haskell**) would look something like this:

```
data Tree a = Leaf | Node (Tree a) a (Tree a)

insert :: Ord a => a -> Tree a -> Tree a
insert x Leaf = Node Leaf x Leaf
insert x (Node t y s)
  | x <= y = Node (insert x t) y s
  | x > y  = Node t y (insert x s)

flatten :: Tree a -> [a]
flatten Leaf = []
flatten (Node t x s) = flatten t ++ [x] ++ flatten s

treesort :: Ord a => [a] -> [a]
treesort = flatten . foldr insert Leaf
```

In the above implementation, both the insertion algorithm and the retrieval algorithm have  $O(n^2)$  worst-case scenarios.

See also [\[edit\]](#)

- **Heapsort**: builds a **binary heap** out of its input instead of a binary search tree, and can be used to sort in-place (but not adaptively).

External links [\[edit\]](#)

- [Binary Tree Java Applet and Explanation](#)
- [Tree Sort of a Linked List](#)
- [Tree Sort in C++](#)

The Wikibook *Algorithm Implementation* has a page on the topic of: **Binary Tree Sort**

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