



WIKIPEDIA  
The Free Encyclopedia

Main page  
Contents  
Featured content  
Current events  
Random article  
Donate to Wikipedia  
Wikipedia store

Interaction  
Help  
About Wikipedia  
Community portal  
Recent changes  
Contact page

Tools  
What links here  
Related changes  
Upload file  
Special pages  
Permanent link  
Page information  
Wikidata item  
Cite this page


Print/export  
Create a book  
Download as PDF  
Printable version

Languages   
العربية  
Deutsch  
Español  
Français  
Українська  Edit links

Create account Log in

Article [Talk](#)

[Read](#) [Edit](#) [More](#) ▾

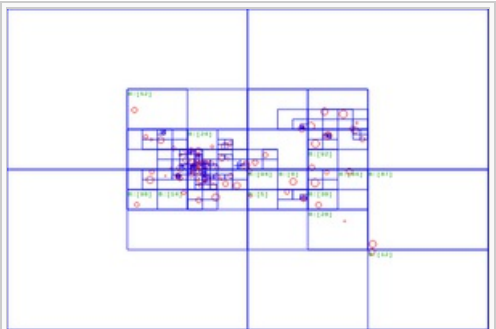


# Barnes–Hut simulation

From Wikipedia, the free encyclopedia

The **Barnes–Hut simulation** ([Josh Barnes](#) and [Piet Hut](#)) is an [approximation algorithm](#) for performing an *n*-body [simulation](#). It is notable for having [order](#)  $O(n \log n)$  compared to a direct-sum algorithm which would be  $O(n^2)$ <sup>[*citation needed*]</sup>.

The simulation volume is usually divided up into cubic cells via an [octree](#) (in a three-dimensional space), so that only [particles](#) from nearby cells need to be treated individually, and particles in distant cells can be treated as a single large particle centered at the cell's [center of mass](#) (or as a low-order [multipole expansion](#)). This can dramatically reduce the number of particle pair interactions that must be computed.



A 100-body simulation with the Barnes-Hut tree visually as blue boxes.

## Contents

[\[hide\]](#)

- 1 Algorithm
  - 1.1 The Barnes-Hut tree
  - 1.2 Calculating the force acting on a body
- 2 See also
- 3 References
- 4 External links

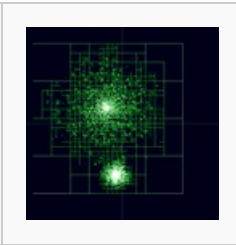
## Algorithm [\[edit\]](#)

### The Barnes-Hut tree [\[edit\]](#)

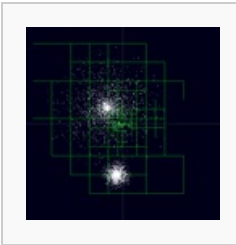
In a three-dimensional *n*-body [simulation](#), the Barnes-Hut algorithm [recursively](#) divides the *n* bodies into groups by storing them in a [octree](#) (or a [quad-tree](#) in a 2D simulation). Each [node](#) in this tree represents a region of the three-dimensional space. The topmost node represents the whole space, and its eight children represent the eight [octants](#) of the space. The space is recursively subdivided into octants until each subdivision contains 0 or 1 bodies (some regions do not have bodies in all of their octants). There are two types of nodes in the octree: internal and external nodes. An external node has no children and is either empty or represents a single body. Each internal node represents the group of bodies beneath it, and stores the [center of mass](#) and the total mass of all its children bodies.



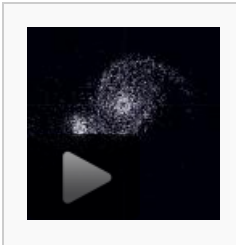
Particle distribution resembling two neighboring galaxies.



Complete Barnes-Hut tree. (Nodes that do not contain particles are not drawn)



Nodes of the Barnes-Hut tree used for calculating the force acting on a particle at the point of origin.



*n*-Body simulation based on the Barnes-Hut algorithm.

### Calculating the force acting on a body [\[edit\]](#)

To calculate the [net force](#) on a particular body, the nodes of the tree are traversed, starting from the root. If the center of mass of an internal node is sufficiently far from the body, the bodies contained in that part of the tree are treated as a single particle whose position and mass is respectively the center of mass and total mass of

Whether a node is or isn't sufficiently far away from a body, depends on the quotient  $\mathbf{s}/d$ , where  $s$  is the width of the region represented by the internal node, and  $d$  is the distance between the body and the node's center of mass. The node is sufficiently far away when this ratio is smaller than a threshold value  $\theta$ . The parameter  $\theta$  determines the accuracy of the simulation; larger values of  $\theta$  increase the speed of the simulation but decreases its accuracy. If  $\theta = 0$ , no internal node is treated as a single body and the algorithm degenerates to a direct-sum algorithm.

- $n$ -body simulation
- Multipole methods
- NEMO (Stellar Dynamics Toolbox)



- J. Barnes and P. Hut (December 1986). "A hierarchical  $O(N \log N)$  force-calculation algorithm". *Nature* **324** (4): 446–449. [Bibcode:1986Natur.324..446B](#) [↗](#). doi:[10.1038/324446a0](#) [↗](#).
- J. Dubinski (October 1996). "A Parallel Tree Code". *New Astronomy* **1** (2): 133–147. [arXiv:astro-ph/9603097v1](#) [↗](#). [Bibcode:1996NewA....1..133D](#) [↗](#). doi:[10.1016/S1384-1076\(96\)00009-7](#) [↗](#).
- U. Becciani, R. Ansaloni, V. Antonuccio-Delouga, G. Erbaccic, M. Gamberaa, and A. Pagliarod (October 1997). "A parallel tree code for large  $N$ -body simulation: dynamic load balance and data distribution on a CRAY T3D system". *Computer Physics Communications* **106** (1–2): 105–113. [arXiv:physics/9709003](#) [↗](#). [Bibcode:1997CoPhC.106..105B](#) [↗](#). doi:[10.1016/S0010-4655\(97\)00102-1](#) [↗](#).
- T. Ventimiglia, and K. Wayne. "[The Barnes-Hut Algorithm](#)" [↗](#). Retrieved 30 March 2012.

- [Treecodes, J. Barnes](#)
- [Parallel TreeCode](#)
- [HTML5/JavaScript Example Graphical Barnes-Hut Simulation](#)
- [PEPC - The Pretty Efficient Parallel Coulomb solver](#), an open-source parallel Barnes-Hut tree code with exchangeable interaction kernel for a multitude of applications

This page was last modified on 7 July 2015, at 21:12.

[Privacy policy](#) [About Wikipedia](#) [Disclaimers](#) [Contact Wikipedia](#) [Developers](#) [Mobile view](#)

