Compact binary coalescences: Constraints on waveforms

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Gravitational waveforms for compact binary coalescences (CBCs) have been invaluable for detections by the LIGO-Virgo collaboration. They are obtained by a combination of semi-analytical models and numerical simulations. So far systematic errors arising from these procedures appear to be less than statistical ones. However, the significantly enhanced sensitivity of the new detectors that will become operational in the near future will require waveforms to be much more accurate. This in turn requires reliable procedures to *evaluate* accuracy, particularly in the regions of parameter space where numerical simulations are sparse. Currently errors are estimated by comparing the candidate waveforms with the NR ones, which are taken to be exact. The goal of this paper is to propose a qualitatively different tool. We show that full non-linear general relativity (GR) imposes an infinite number of sharp constraints on the CBC waveforms. These can provide clear-cut measures to evaluate the accuracy of candidate waveforms against exact GR, help find systematic errors, and also provide external checks on NR simulations themselves.

I. INTRODUCTION

Accurate gravitational waveform models for Compact Binary Coalescences (CBCs) are crucial in Gravitational Wave (GW) data analysis. Matched-filtering used for detection, as well as procedures for parameters estimation and tests of General Relativity (GR), all rely on the precise knowledge of GW signals as predicted by GR. Since the exact two-body problem in GR is not solvable analytically, current available waveforms are produced by astute combinations of Numerical Relativity (NR) simulations (see, e.g., [1]) and analytical approximations (see, e.g., [2–13]), or interpolation methods (see, e.g., [14–17]). Thanks to the remarkable accuracy reached, systematic errors are arguably [18, 19] less than statistical ones for current detectors. However, since the sensitivity of current detectors is about to increase [20, 21], and new ground [22–25] and space [26–28] based detectors will soon become operational, the statistical uncertainties will reduce considerably. This in turn requires improvement in waveform models to match this enhanced accuracy [19, 29]. This is particularly important when observations are used as means of test of GR: departure from GR may remain hidden, or may be erroneously claimed due to inaccuracy of waveforms [30]. Considerable ongoing effort is aimed at further reducing systematic errors in the wave-

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form models, for instance by considering higher modes [31–33], by including precession more carefully [34–37], or by improving numerical code efficiency and precision [38].

An important step in this process requires reliable procedures to measure and evaluate the accuracy of the waveforms *relative to the predictions of exact GR*. However, this goal encounters an immediate obstacle: the *exact* waveform is not known! The current extensive and successful work typically estimates errors (see e.g. [18, 19, 39–42]) by considering NR simulations as practical substitutes of the exact waveform. The reliability of such procedures strongly depends on how well one can identify sources of errors in the numerical simulations, and estimate their magnitude. This task is typically carried out using internal checks, comparing different simulations that use, e.g., different grid resolutions and extraction radii for the same physical system. While several modes of NR waveforms have been shown to pass these convergence tests, this is not yet the case for all modes of interest.

In this paper we propose a qualitatively different tool to test the accuracy of semi-analytical models that does not rely on NR, and can therefore be used as an external check on numerical simulations as well. Our strategy is to use asymptotic symmetries –the Bondi, Metzner, Sachs (BMS) group [43–45]– in conjunction with the boundary conditions in the distant past and distant future normally assumed in CBCs. Together, they provide an infinite set of constraints on the CBC waveforms. Violations of these sharp constraints by any proposed waveform provide a measure of its deviation from the exact GR prediction, *without knowing* what that prediction is. Thus, it is a novel approach that can complement the current NR-based procedures.

The paper is organized as follows. In Section II we obtain the infinite number of constraints on the gravitational waveforms. Section III summarizes the main results and presents a few examples of work in progress to illustrate how they could be used to further improve our understanding of waveforms. Important background material is collected in the Appendix, where we explain why 'supertranslations' must be included in the symmetry group of asymptotically Minkowskian spacetimes, leading to balance laws for the related supermomentum [46, 47] from which the proposed constraints arise. This material is also used in the angular momentum considerations, discussed in the companion paper [48], where the BMS symmetries and constraints discussed in this paper play a crucial role.

II.   CONSTRAINTS ON WAVEFORMS

This Section is divided into three parts. In the first we introduce the basic framework that will be used to specify fields at $\mathfrak{I}^+$. In the second, we introduce the notion of the Bondi-Metzner-Sachs (BMS) supermomentum, and the associated balance equations. In the third, we use these balance laws together with the standard asymptotic conditions in the CBC literature to arrive at an infinite family of constraints on waveforms.

A.   Underlying Framework

Our conventions are as follows. We work with $(-, +, +, +)$ signature and define curvature tensors via $2\nabla_{[a}\nabla_{b]}K_c = R_{abc}{}^d K_d$; $R_{ac} = R_{abc}{}^b$ and $R = g^{ab}R_{ab}$. We will assume that the physical spacetime (M, g_{ab}) is asymptotically Minkowskian in the sense spelled out, e.g., in

[49]. [1]

As explained in the Appendix, future null infinity, $\mathfrak{I}^+$, is the natural home for all asymptotic fields. It is a null 3-manifold with topology $\mathbb{S}^2 \times \mathbb{R}$, coordinatized by retarded time u and angular coordinates (θ, φ). One can think of $\mathfrak{I}^+$ either as the future boundary of the conformally completed spacetime $(\hat{M} = M \cup \mathfrak{I}^+, \hat{g}_{ab} = \Omega^2 g_{ab})$ à la Penrose [50], or as the limiting surface '$r = \infty$' obtained by moving away from sources along $u = \text{const}$ null surfaces (of constant retarded time) à la Bondi and Sachs [43–45]. Since waveforms are generally expressed using fields in the physical spacetime without making the conformal completion, in this paper we will do the same.

Since (M, g_{ab}) is asymptotically Minkowskian, following Bondi and Sachs let us introduce a foliation of the asymptotic region of M by outgoing null hypersurfaces $u = \text{const}$ and denote its geodesic null normal by ℓ^a. Introduce an affine parameter r of ℓ^a such that each null surface $u = \text{const}$ is foliated by a family of (space-like) 2-spheres $r = \text{const}$. Denote the intrinsic $(+, +)$ metric of these 2-spheres by q_{ab} and the other null-normal to each of these 2-spheres by n^a, normalized so that $g_{ab}\ell^a n^b = -1$. Finally, introduce a null complex vector field m^a and its complex conjugate $\bar{m}^a$ such that their real and imaginary parts are tangential to these 2-spheres, and they are normalized such that $g_{ab}m^a\bar{m}^b = 1$. Thus, at each point in the asymptotic region we have a null tetrad $\ell^a, n^a, m^a, \bar{m}^a$ for which the only non-zero contractions are $\ell \cdot n = -1$ and $m \cdot \bar{m} = 1$. Finally, asymptotic conditions imply that this structure can be set up in such a way that, as $r \to \infty$, we acquire certain smooth fields on $\mathfrak{I}^+$, denoted here by a over-circle:

(i) $\mathring{q}_{ab} = \lim\limits_{r\to\infty} r^{-2} q_{ab}$ is an unit, round 2-sphere metric (and thus independent of u);

(ii) $\mathring{n}^a = \lim\limits_{r\to\infty} n^a$ coincides with the null normal $\partial/\partial u$ to $\mathfrak{I}^+$;

(iii) $\mathring{\ell}^a = \lim\limits_{r\to\infty} r^2 \ell^a$ is the other null normal to a family of 2-sphere cross-sections $u = \text{const}$ of $\mathfrak{I}^+$, and

(iv) $\mathring{m}^a = \lim\limits_{r\to\infty} r\, m^a$ and $\mathring{\bar{m}}^a = \lim\limits_{r\to\infty} r\, \bar{m}^a$ are tangential to these cross-sections.

In Penrose's conformal completion, one can always make the null normal $\mathring{n}^a$ to $\mathfrak{I}^+$ divergence-free by an appropriate choice of Ω, and for each such choice, we acquire a pair $(\hat{q}_{ab}, \hat{n}^a)$ of fields defined intrinsically on $\mathfrak{I}^+$, with $\hat{q}_{ab}$ the (degenerate) metric of signature $(+, +)$ and $\hat{n}^a$ the null normal to $\mathfrak{I}^+$, both induced by the conformal metric $\hat{g}_{ab}$. However, we can further restrict our conformal factor such that $\hat{q}_{ab}$ is a *unit 2-sphere metric*. The restricted pair $(\hat{q}_{ab}, \hat{n}^a)$ is said to provide a 'Bondi (conformal) frame'. In terms of structures introduced in the last para in physical spacetime, we have $\mathring{q}_{ab} = \hat{q}_{ab}$ and $\mathring{n}^a = \hat{n}^a$ at $\mathfrak{I}^+$. The structure introduced is depicted in Fig. 1.

We will therefore refer to the pair $(\mathring{q}_{ab}, \mathring{n}^a)$ as a *Bondi-frame* at $\mathfrak{I}^+$. A change in the initial set up of the last paragraph can lead to a change in the Bondi frame. Physically, each Bondi-frame selects an *asymptotic Lorentz frame* because the vector field $\mathring{n}^a$ provided

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[1] This notion is weaker than Penrose's original definition of asymptotic simplicity which requires that every null geodesic in M should have endpoints on $\mathfrak{I}^{\pm}$; our conditions refer only to properties of spacetime geometry near infinity.
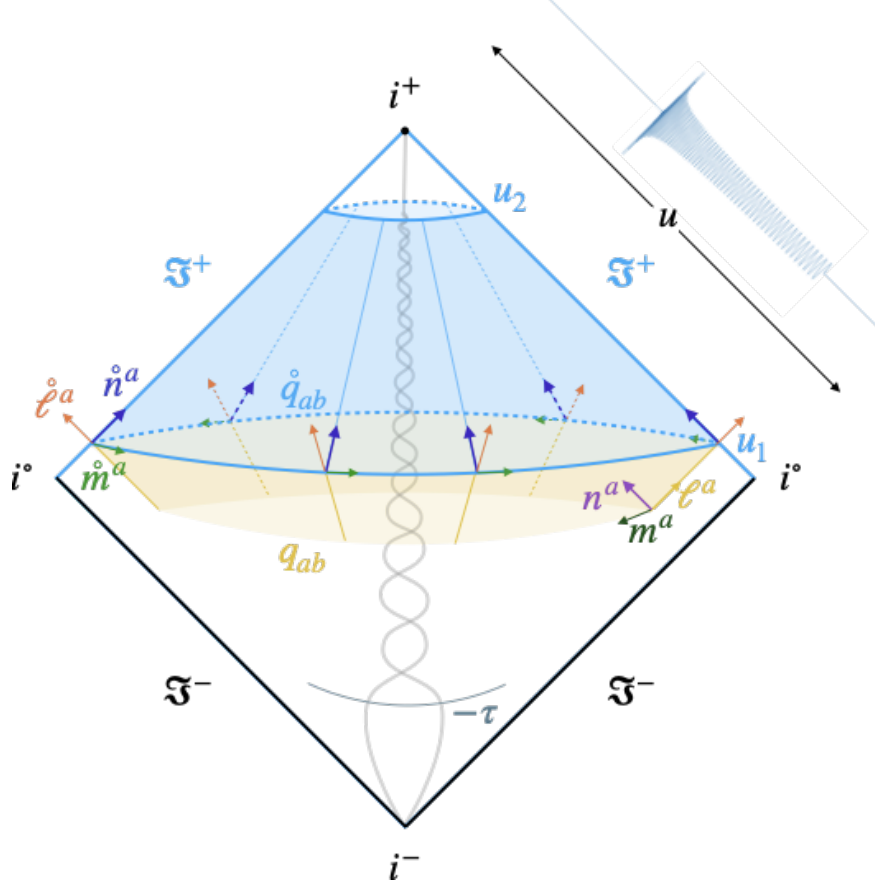
FIG. 1: A depiction of future null infinity, $\mathfrak{I}^+$ (in light blue) that constitutes the future boundary of space-time and has topology $\mathbb{S}^2 \times \mathbb{R}$. The (yellow) outgoing null surface $u = u_1$ in the asymptotic region of space-time intersects $\mathfrak{I}^+$ in a 2-sphere cross-section. The null tetrad $(\ell^a, n^a, m^a, \bar{m}^a)$ and the metric q_{ab} on $r = \text{const}$ 2-spheres in the interior have limits $\mathring{\ell}^a, \mathring{n}^a, \mathring{m}^a, \mathring{\bar{m}}^a$ and $\mathring{q}_{ab}$ respectively on $\mathfrak{I}^+$. The figure also shows an artist's impression of a typical waveform based on [51].

by the Bondi-frame is an asymptotic time translation, i.e., limit to $\mathfrak{I}^+$ of an asymptotic time translation vector field in spacetime. Recall that we have a 3-parameter family of time-translation Killing fields –or Lorentz frames– in Minkowski space. Therefore, one would expect that there would be 3-parameter family of Bondi-frames. This is indeed the case: Bondi-frames are related to one another by (asymptotic) boosts. If we perform a boost by 3-velocity $\vec{v}$, the initial Bondi-frame $(\mathring{q}_{ab}, \mathring{n}^a)$ transforms to $(\mathring{\tilde{q}}_{ab}, \mathring{\tilde{n}}^a)$ given by

$$\mathring{\tilde{q}}_{ab} = \omega^2 \mathring{q}_{ab}, \quad \mathring{\tilde{n}}^a = \omega^{-1} \mathring{n}^a \quad \text{with} \quad \omega = \frac{1}{\gamma\left(1 - \frac{\vec{v}}{c} \cdot \hat{x}\right)}, \tag{2.1}$$

where $\gamma = (1 - (v/c)^2)^{-\frac{1}{2}}$ is the standard Lorentz factor and $\hat{x}$ the unit radial vector with components $(\sin\theta\cos\varphi, \sin\theta\sin\varphi, \cos\theta)$. We will use the terms 'Bondi-frame' and 'asymptotic Lorentz-frame' interchangeably.

Recall from special relativity that the Lorentz frame in which the 4-momentum P_a of the system is purely time-like –i.e., in which the 3-momentum $\vec{P}$ vanishes is referred to as the *rest frame* of the system. In most of this paper we will work with the *past rest frame* at $\mathfrak{I}^+$, i.e., the frame in which the Bondi 3-momentum, defined in Section II B below, vanishes

in the asymptotic past, as $u \to -\infty$. Finally, at one intermediate step we will also have to use the Bondi-frame in which the Bondi 3-momentum vanishes in the distant future –i.e., $u \to \infty$. In a CBC this is the asymptotic Lorentz frame in which the final black hole is at rest, and represents the *future rest frame.*

In terms of the null-tetrads we have: $g_{ab} = -2\ell_{(a}n_{b)} + 2m_{(a}\bar{m}_{b)} = -2\ell_{(a}n_{b)} + q_{ab}$ on the physical spacetime M, and $\mathring{q}_{ab} = 2\mathring{m}_{(a}\mathring{\bar{m}}_{b)}$ on $\mathfrak{I}^+$. Of special interest is the shear $\sigma = -m^a m^b \nabla_a \ell_b$ of ℓ^a because its asymptotic value σ° is directly related to the gravitational waveforms. In Minkowski spacetime we can choose the $u = \text{const}$ surfaces to be the light cones emanating from points of a time-like geodesic. Then ℓ^a is shear-free. In asymptotically Minkowskian spacetimes, shear σ of ℓ^a falls-off as $1/r^2$ and

$$\sigma^\circ(u, \theta, \varphi) := -\lim_{r \to \infty} r^2\big(m^a m^b \nabla_a \ell_b\big) \equiv \frac{1}{2}(h_+^\circ + ih_\times^\circ)(u, \theta, \varphi) \tag{2.2}$$

is well-defined on $\mathfrak{I}^+$, where, in the last step we have expressed σ° in terms of the commonly used waveforms $h_+^\circ \equiv \lim_{r \to \infty} rh_+$ and $h_\times^\circ \equiv \lim_{r \to \infty} rh_\times$. (Because of the '$m^a m^b$' factor, σ° has spin weight $+2$, while the more commonly used combination $h_+^\circ - ih_\times^\circ = 2\bar{\sigma}^\circ$ has spin-weight -2.) The shear tensor σ_{ab}° at $\mathfrak{I}^+$, given by

$$\sigma_{ab}^\circ(u, \theta, \varphi) = -\big(\sigma^\circ \, \mathring{\bar{m}}_a \mathring{\bar{m}}_b + \bar{\sigma}^\circ \, \mathring{m}_a \mathring{m}_b\big)(u, \theta, \varphi), \tag{2.3}$$

is a symmetric, traceless tensor field, transversal to the null normal to $\mathfrak{I}^+$ –i.e. satisfies $\sigma_{ab}^\circ \mathring{n}^a = 0$– and has spin weight zero. It captures the two Transverse-Traceless or radiative modes of the gravitational field in full, non-linear GR. Its time derivative is the Bondi news tensor: [2]

$$N_{ab} := 2\mathcal{L}_{\mathring{n}} \sigma_{ab}^\circ \equiv 2\dot{\sigma}^\circ{}_{ab}. \tag{2.4}$$

One often introduces a 'news function' N via

$$N_{ab} = 2\big(N \mathring{m}_a \mathring{m}_b + \bar{N} \mathring{\bar{m}}_a \mathring{\bar{m}}_b\big), \tag{2.5}$$

so that $N = -\partial_u \bar{\sigma}^\circ \equiv -\dot{\bar{\sigma}}^\circ$ has spin weight -2.

Finally let us introduce the Newman-Penrose components of the Weyl tensor that also feature prominently in the discussion of gravitational waves produced by CBCs. Since the stress energy tensor (if any) of the system is of compact spatial support, curvature in the neighborhood of infinity is fully captured by the Weyl tensor. Because (M, g_{ab}) is asymptotically Minkowskian, components of the Weyl tensor in the null tetrad have a specific fall-off, known as 'peeling properties' [44, 53]. The leading order components of the Weyl tensor in the null tetrad –which carry a superscript $\circ$– can be regarded as fields on $\mathfrak{I}^+$:

$$\Psi_4^\circ(u, \theta, \varphi) = \lim_{r \to \infty} rC_{abcd}n^a\bar{m}^b n^c \bar{m}^d; \qquad \Psi_3^\circ(u, \theta, \varphi) = \lim_{r \to \infty} r^2 C_{abcd}n^a\bar{m}^b n^c \ell^d;$$

$$2\,\mathrm{Re}\,\Psi_2^\circ(u, \theta, \varphi) = \lim_{r \to \infty} r^3 C_{abcd}n^a\ell^b n^c \ell^d; \quad 2\,\mathrm{Im}\,\Psi_2^\circ(u, \theta, \varphi) = -i\lim_{r \to \infty} r^3 C_{abcd}n^a\ell^b m^c \bar{m}^d;$$

$$\Psi_1^\circ(u, \theta, \varphi) = \lim_{r \to \infty} r^4 C_{abcd}\ell^a m^b \ell^c n^d; \qquad \Psi_0^\circ(u, \theta, \varphi) = \lim_{r \to \infty} r^5 C_{abcd}\ell^a m^b \ell^c m^d. \tag{2.6}$$

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[2] It has a clear-cut geometric meaning in the conformally completed spacetime: N_{ab} is the conformally invariant part of the curvature of the intrinsic connection on $\mathfrak{I}^+$ [52].

The spin-weight -2 component Ψ_4° is referred to as the *radiation field* because: (i) it is the leading order coefficient of curvature component with asymptotic fall-off $1/r$; and, (ii) it is directly related to the waveforms, namely $\Psi_4^\circ = -\ddot{\bar{\sigma}}^\circ \equiv -\partial_u^2 \bar{\sigma}^\circ$. By contrast, the real part of the spin-weight zero component Ψ_2° encodes the 'Coulombic' information contained in the Bondi mass. The angular momentum information resides in the spin-weight 1 component Ψ_1° [54, 55]. This may seem surprising at first because one is accustomed to the statement that in Kerr spacetime the only non-zero component of the Weyl tensor is Ψ_2. However, that statement refers to components in principal null directions which do not agree with the pair of null vector fields $(\mathring{n}^a, \mathring{\ell}^a)$ at $\mathfrak{I}^+$. In terms of the null tetrad at $\mathfrak{I}^+$, in a Kerr spacetime with mass M and angular momentum J, Ψ_2° is a real constant with value $-GM$, while $\Psi_1^\circ = (3i/2)\sin\theta \, GJ$. Finally, in this paper we will not need the component Ψ_0°; it was introduced just for completeness.

Remark: The fall-off in $1/r$ of fields constructed from g_{ab} in the physical spacetime translates to degree of differentiability –or smoothness– of the conformally rescaled metric $\hat{g}_{ab}$ in the Penrose completion. There has been considerable debate in the literature on whether these assumptions are physically reasonable (for a summary, see e.g. [56]). Indeed, using the PN perspective it was argued in the early days that they may not be appropriate for CBC [57]. However, as noted in the Appendix, the current consensus in the PN literature is that the asymptotic form of the PN metric is completely consistent with the Bondi-Sachs-Penrose framework [58]. Similarly, the key notions underlying this framework –such as Ψ_4°, N, and σ°– and relations between them are heavily used in NR.

B. The supermomentum balance law

Much of the previous work on supermomentum is carried out in the conformally completed spacetime, without introducing auxiliary structures such as the tetrad vectors $\ell^a, m^a, \bar{m}^a$ that are not canonically defined at $\mathfrak{I}^+$ [46, 47, 59]. Similarly, one does not require that the intrinsic metric $\mathring{q}_{ab}$ on $\mathfrak{I}^+$ is the round, unit 2-sphere metric. This generality made it manifest that the results have all the required invariance and covariance properties. However, since the waveforms community does not use conformal completion, we will now present the material using only those notions that are introduced in Section II A (and in the Appendix). On the other hand, to check transformation properties, e.g., from one Bondi frame to another, it is easiest to use the original invariant framework.

As explained in the Appendix, one of the major surprises to emerge from the Bondi-Sachs work was that, although spacetimes under consideration are asymptotically Minkowskian, the asymptotic symmetry group is not the Poincaré group $\mathcal{P}$, but an infinite dimensional enlargement thereof, the BMS group $\mathfrak{B}$. While $\mathfrak{B}$ does admit a canonical 4-dimensional normal subgroup $\mathcal{T}$ of translations [60], it also contains an infinite dimensional Abelian subgroup $\mathcal{S}$ of *supertranslations*, which can be thought of as 'angle dependent translations'. There is a direct relation between this enlargement and the presence of gravitational waves: In absence of gravitational radiation the group naturally reduces back to the Poincaré group [52, 59, 61]. Intuitively, the enlargement occurs because the ripples of curvature propagate out all the way to infinity, introducing an ambiguity in the choice of the 'background Minkowski metric' that the physical metric g_{ab} is approaching as $1/r$. In any Bondi-frame at $\mathfrak{I}^+$, we have the following properties:

(i) translations are represented by vector fields $\xi^a_{(\alpha)} := \alpha(\theta, \phi)\mathring{n}^a$ at $\mathfrak{I}^+$, where α is a (real-valued) linear combination of the first 4 spherical harmonics:

$$\alpha(\theta, \varphi) = \alpha_o Y_{0,0} + \sum_{m=-1}^{m=1} \alpha_m Y_{1,m}(\theta, \varphi) \tag{2.7}$$

for some constants α_0, α_m;

(ii) the vector field $\xi^a_{(0)} = \mathring{n}^a$ is *the* time-translation in the chosen Bondi frame and the vector fields $\xi^a_{(\vec{\alpha})} = \sum_{m=-1}^{m=1} \alpha_m Y_{1,m}(\theta, \varphi) \, \mathring{n}^a$ are spatial translations in that frame;

(iii) the more general vector-fields $\xi^a_{(f)} = f(\theta, \varphi) \, \mathring{n}^a$ where f is any smooth function on a 2-sphere are called supertranslations; so translations are just special cases of super-translations. If we fix a Bondi-frame –as we will in most of the paper, taking it to be the rest-frame in the asymptotic past– we can speak of 'pure' supertranslations: These correspond to

$$f(\theta, \varphi) = \sum_{\ell=2}^{\infty} \sum_{m=-\ell}^{\ell} f_{\ell,m} Y_{\ell,m}(\theta, \varphi) \,. \tag{2.8}$$

In what follows, we will use the symbol $\alpha(\theta, \varphi)$ to refer to BMS translation and $f(\theta, \varphi)$ to refer to generic BMS supertranslations.[3]

Recall that for fields in Minkowski space, energy-momentum arises as the Hamiltonian generating canonical transformations corresponding to spacetime translations. In the same spirit, in GR one can construct a phase space Γ_{Rad} of radiative modes at $\mathfrak{I}^+$ [62], show that the action of BMS supertranslations $\xi^a_{(f)}$ on $\mathfrak{I}^+$ induces canonical transformations on Γ_{Rad}, and calculate the corresponding Hamiltonians [47]. They are given by integrals over $\mathfrak{I}^+$ which have the interpretation of the *total fluxes* $\mathcal{F}_{(f)}$ across $\mathfrak{I}^+$ of the components of supermomentum defined by $f(\theta, \varphi)$:

$$\begin{aligned} \mathcal{F}_{(f)} &= \frac{1}{32\pi G} \int_{\mathfrak{I}^+} \mathrm{d}u \, \mathrm{d}^2 \mathring{V} \, f(\theta, \varphi) \left[N_{ab} N^{ab} + 2\mathring{D}_a \mathring{D}_b N^{ab} \right](u, \theta, \varphi) \\ &= \frac{1}{4\pi G} \int_{\mathfrak{I}^+} \mathrm{d}u \, \mathrm{d}^2 \mathring{V} \, f(\theta, \varphi) \left[|\dot{\sigma}^\circ|^2 - \text{Re}(\eth^2 \dot{\bar{\sigma}}^\circ) \right](u, \theta, \varphi) \,. \end{aligned} \tag{2.9}$$

Here, in the first step we have raised the indices of N_{ab} using the unit 2-sphere metric $\mathring{q}^{ab}$ on the $u = \text{const}$ 2-spheres, and $\mathring{D}_a$ is the derivative operator compatible with $\mathring{q}_{ab}$. In the second step we have used the Newman-Penrose angular derivative operator $\eth$ whose action on a spin-weight s scalar A, given by

$$\eth A = \frac{1}{\sqrt{2}} (\sin \theta)^s \left(\frac{\partial}{\partial \theta} + \frac{i}{\sin \theta} \frac{\partial}{\partial \varphi} \right) (\sin \theta)^{-s} A \,, \tag{2.10}$$

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[3] If we change the Bondi-frame, the vector field $\mathring{n}^a$ is rescaled as in Eq. (2.1). Since the supertranslation is given by $\xi^a = f\mathring{n}^a = \tilde{f}\tilde{\mathring{n}}^a$, the labels f and $\tilde{f}$ in the two frames are related by $\tilde{f} = \omega f$. In the Penrose conformal picture, f is not a scalar but carries a conformal weight 1. It turns out that the notion of a BMS translation is invariant with respect to this change of the Bondi-frame, but the notion of a 'pure' supertranslation' is not.

yields a scalar with spin-weight $s + 1$. (In our case, $\dot{\bar{\sigma}}^\circ$ has spin-weight -2, whence $\eth^2 \dot{\bar{\sigma}}^\circ$ has spin-weight zero. Please note that in the literature, $\eth$ often carries the opposite sign relative to Eq. (2.10).) The second equality in (2.9) provides us with supermomentum fluxes directly in terms of the waveform $2\sigma^\circ(u, \theta, \varphi) = (h_+^\circ + ih_\times^\circ)(u, \theta, \varphi)$.

One can show that the $\mathcal{F}_{(f)}$ is in fact an integral of an exact 3-form, whence the integral on $\mathfrak{I}^+$ can be expressed as the difference between two 2-sphere integrals, performed at i° (i.e. on the '$u = -\infty$' 2-sphere) and i^+ (i.e. on the '$u = \infty$' 2-sphere) [47]:

$$\mathcal{F}_{(f)} = \lim_{u_o \to -\infty} P_{(f)}|_{u=u_o} - \lim_{u_o \to \infty} P_{(f)}|_{u=u_o} \tag{2.11}$$

where

$$P_{(f)}\big|_{u=u_o} := -\frac{1}{4\pi G} \oint_{u=u_o} \mathrm{d}^2\mathring{V}\, f(\theta, \varphi) \, \mathrm{Re}\big[\Psi_2^\circ + \bar{\sigma}^\circ \dot{\sigma}^\circ\big](\theta, \varphi) \tag{2.12}$$

is the f-component of the supermomentum of the system at the retarded time $u = u_o$. Eq. (2.11) constitutes an infinite family of *balance laws* –one for each choice of a supertranslation, i.e., of smooth $f(\theta, \varphi)$ on a 2-sphere. These laws will provide us with an infinite family of constraints on waveforms. Finally, Refs. [46, 47] provide more general expression of supermomentum that hold on *any* 2-sphere cross-section of $\mathfrak{I}^+$ (not necessarily $u = $ const) and formula of supermomentum flux through *any* patch $\Delta\mathfrak{I}^+$ of $\mathfrak{I}^+$. Eqs (2.9) and (2.12) are just special cases of those expressions adapted to the setup introduced in Section II A.

Since the balance law holds for any supertranslation $f(\theta, \varphi)\mathring{n}^a$, it holds in particular for translations $\alpha(\theta, \varphi)\mathring{n}^a$. In this case $P_{(\alpha)}$ is simply the Bondi-Sachs energy-momentum of the system at the retarded time $u = u_o$. Since the functions $\alpha(\theta, \varphi)$ are linear combinations of the first four spherical harmonics, the flux formula simplifies. For, $\mathring{q}^{ab}\mathring{D}_b\alpha$ is a conformal Killing field of the 2-sphere metric $\mathring{q}_{ab}$, whence $\mathring{D}_a\mathring{D}_b\alpha \propto \mathring{q}_{ab}$. Therefore, integrating the first equation in (2.9) by parts and using the fact that N_{ab} is trace-free, one obtains:

$$\mathcal{F}_{(\alpha)} = \frac{1}{4\pi G} \int_{\mathfrak{I}^+} \mathrm{d}u\, \mathrm{d}^2\mathring{V}\, \alpha(\theta, \varphi)\, |\dot{\sigma}^\circ|^2(u, \theta, \varphi) \,. \tag{2.13}$$

In particular, for any *time*-translation, $\alpha(\theta, \varphi)$ is positive, whence the flux of energy is necessarily positive. This is the celebrated Bondi-Sachs result. To calculate the final black hole kick, one computes the 3-momentum flux $\mathcal{F}_{(\vec{\alpha})}$, where the function $\vec{\alpha}$ is a general linear combination of the three $Y_{1,m}$.

Remark: In the literature between 1960s and early 1980s there was considerable confusion about supermomentum because the flux expressions were not obtained from a physically well-motivated procedure. For example, expressions of supermomentum given in [63–66] lead to a non-zero flux between general cross-sections of $\mathfrak{I}^+$ *in Minkowski space* [67–69]! The expression (2.9) by contrast vanishes anytime the news tensor vanishes, in particular in any stationary spacetime (relation between these flux expressions is discussed in [68]). Even when Hamiltonian considerations were used to provide a physical basis for the derivation, the flux expression in the early literature was incorrect (see, e.g. second article in [45] and [70]) because of a subtle fact that the radiative phase space is an affine space, rather than a vector space (for details, see [47]). These examples serve to bring out the fact that considerable care is needed to arrive at viable balance laws.

C. Implications for waveforms

We can now apply the balance laws to isolated systems undergoing CBC. Since the balance laws refer to exact GR, we will not need to make any approximations. However, we need to incorporate the fact that we are now restricting ourselves to CBC. We will do so through two physically motivated assumptions in Section II C 1. The resulting constraints and their possible applications on the global waveforms are discussed in Section II C 2, while Section II C 3 discusses the constraints on restrictions of waveforms to finite u intervals.

1. Assumptions

(1) We assume that the Bondi news tensor N_{ab} on $\mathfrak{I}^+$ goes to zero as $u \to \pm\infty$ as $1/u^{1+\epsilon}$ for some $\epsilon > 0$. [4]

This condition is necessary and sufficient to ensure that the flux of the BMS angular momentum across $\mathfrak{I}^+$ is finite [47, 48]. For vacuum solutions, the Christodoulou-Klainnerman results, for example, ensure that this condition holds with $\epsilon = 1/2$. Waveforms constructed so far satisfy this assumption because the Bondi news goes to zero rapidly at early and late times; within the approximations made and accuracy achieved, N_{ab} is in fact indistinguishable from zero outside some finite u-interval. In terms of the waveform $\sigma^\circ = h^\circ_+ + ih^\circ_\times$, our assumption reads:

$$\sigma^\circ(u, \theta, \varphi) = \sigma_\pm(\theta, \varphi) + |u|^{-\epsilon}\, \sigma^{(1)}_\pm(\theta, \varphi) + O(|u|^{-\epsilon-1}) \quad \text{as } u \to \pm\infty\,, \qquad (2.14)$$

so that $\sigma_\pm(\theta, \varphi)$ are the limits of $\sigma^\circ(u, \theta, \varphi)$, and $\pm\epsilon\sigma^{(1)}_\pm(\theta, \varphi)$ are the limits of $|u|^{1+\epsilon}\, \bar{N}(u, \theta, \varphi)$ as $u \to \pm\infty$.

Next, it is expected that the system would settle down to a stationary state after coalescence. Indeed, in the case of binary black holes, numerical simulations show that at late times the spacetime metric approaches the Kerr solution. In addition, the PN calculations assume that the system is stationary in the past, i.e., for times $t < -\tau$ [58]. We will need a much weaker assumption to capture the physical behavior of the compact binary in the asymptotic future and past.

Let us first note a consequence of assumption *(1)*. Since $N_{ab} = O(1/|u|^{1+\epsilon})$ as $u \to \pm\infty$, Einstein's equations together with Bianchi identities imply that $\partial_u\Psi^\circ_4$, $\partial_u\Psi^\circ_3$ and $\partial_u\Psi^\circ_2$ go to zero as $u^{-(3+\epsilon)}$, $u^{-(2+\epsilon)}$ and $u^{-(1+\epsilon)}$ respectively. In this precise sense these three complex components of the asymptotic curvature become 'time-independent' or 'stationary' *in the limit $u \to \pm\infty$*. Because N_{ab} is invariant under the change of Bondi-frame, this fall-off behavior holds in *any* Bondi-frame. Furthermore, Ψ°_4 and Ψ°_3 themselves vanish in these limits, and for Ψ°_2 we have

$$\Psi^\circ_2(u, \theta, \varphi) = \psi_\pm(\theta, \varphi) + |u|^{-\epsilon}\psi^{(1)}_\pm(\theta, \varphi) + O(|u|^{-\epsilon-1}) \quad \text{as } u \to \pm\infty\,, \qquad (2.15)$$

again in any Bondi-frame, although the limiting values $\psi_\pm(\theta, \varphi)$ and $\psi^{(1)}_\pm(\theta, \varphi)$ depend on the choice of the frame. Note, however, that assumption *(1)* does *not* imply that Ψ°_1 (or Ψ°_0)

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[4] Throughout, we assume that if a field $F(u, \theta, \phi) = O(1/|u|^\alpha)$ –i.e., if $|u|^\alpha F(u, \theta, \varphi)$ admits smooth limits $F_\pm(\theta, \varphi)$ as $u \to \pm\infty$– then its mth u-derivative, $\partial^m_u F(u, \theta, \varphi)$ is $O(1/|u|^{m+\alpha})$.

become stationary as $u \to \pm\infty$. Furthermore, the limiting values of $\partial_u \Psi_1^\circ$ depend on the choice of the Bondi-frame and in general the rest-frame of the final black hole is different from that of the system in the distant past because of black hole kicks [71, 72]. We will now make our second assumption:

(2) $\partial_u \Psi_1^\circ \to 0$ in the past Bondi-frame as $u \to -\infty$, and in the future Bondi-frame as $u \to \infty$.

Recall that the past Bondi-frame is the one in which the Bondi 3-momentum vanishes in the distant past (i.e., as $u \to -\infty$), and the future Bondi-frame is the one in which the Bondi 3-momentum vanishes in the distant future (i.e., as $u \to \infty$). Thus, we are *not* requiring that the system should become stationary in the past and the future in the same rest-frame. As we discuss below, that requirement would have been too restrictive. Ours is quite weak: in the distant past it is *much weaker* than what is assumed in PN waveforms, and it is found to hold in the NR simulations in the distant future, since the solution quickly relaxes to a stationary spacetime [1].

2. Constraints on global waveforms

The two assumptions lead to a key simplification in the surface terms representing asymptotic values of supermomentum (2.12) used in the balance laws (2.11). First, in any Bondi-frame, Einstein's equations and Bianchi identities imply that the following relations hold on all of $\mathfrak{I}^+$ (see, e.g., [53]):

$$\partial_u \Psi_1^\circ \;=\; m^a \mathring{D}_a \Psi_2^\circ + 2\sigma^\circ \, \Psi_3^\circ \;\equiv\; \eth \Psi_2^\circ - 2\sigma^\circ \eth \dot{\bar\sigma}^\circ, \quad \text{and,} \tag{2.16}$$
$$\mathrm{Im}\,\Psi_2^\circ \;=\; \mathrm{Im}\left(\bar\eth^2 \, \sigma^\circ + \sigma^\circ \, N\right). \tag{2.17}$$

They have two important consequences. Let us first consider the *past* Bondi-frame. Then,

(i) in the limit $u \to -\infty$ the left side of (2.16) vanishes by assumption *(2)*, while the second term on the right hand side vanishes by assumption *(1)*. Therefore $m^a \mathring{D}_a \Psi_2^\circ$ vanishes –i.e., Ψ_2° *becomes spherically symmetric*– in the limit $u \to -\infty$.

(ii) Next, thanks to assumption *(1)*, Eq. (2.17) implies $\lim_{u \to -\infty} \mathrm{Im}\,\Psi_2^\circ = \bar\eth^2 \, \mathrm{Im}\,\sigma_-$. Integrating both sides over a 2-sphere, and using spherical symmetry of $\mathrm{Im}\,\Psi_2^\circ$ we conclude that $\mathrm{Im}\,\Psi_2^\circ = 0$ in the limit.

To evaluate the limit of $\mathrm{Re}\,\Psi_2^\circ$, we will use the expression (2.12) to calculate the past limit of the Bondi 4-momentum. This limit is purely time-like in the rest-frame at i°, and the limiting Bondi energy is precisely the initial (or the total) mass M_{i°. Therefore, setting $f = 1$ in Eq. (2.12), and taking the limit $u_o \to -\infty$ we obtain:

(iii) $\lim_{u \to -\infty} \mathrm{Re}\,\Psi_2^\circ = -GM_{i^\circ}$.

Thus, we conclude:

$$\lim_{u \to -\infty} \mathrm{Re}\,\Psi_2^\circ(u, \theta, \varphi) = -GM_{i^\circ}, \quad \text{and} \quad \lim_{u \to -\infty} \mathrm{Im}\,\Psi_2^\circ(u, \theta, \varphi) = 0. \tag{2.18}$$

Now, the asymptotic rest frame of the system at $u = \infty$ is generically different from that in the past. To work out the implication of condition *(2)* on the behavior of Ψ_2° in the distant future, let us for a moment switch to the future Bondi-frame –in which the *final* black hole is at rest– and denote fields in that frame with a prime. Then the reasoning we used also implies that

$$\lim_{u \to \infty} \Psi_2^{\circ\prime} = -GM_{i^+}. \tag{2.19}$$

Since the balance law is formulated in a general but *fixed* Bondi-frame, and we have chosen to work in the past Bondi-frame, we need to transform $\Psi_2^{\circ\prime}$ to that frame. The two frames are related to each other by a boost defined by the velocity $\vec{v}$ of the final black hole (in the past rest-frame), commonly referred to as the *kick* velocity. To calculate the components $v_i = (v_x, v_y, v_z)$ of $\vec{v}$ in the past rest frame, we first note that since initially the Bondi 3-momentum is zero, the 3-momentum $P_{(\alpha_i)}$ of the final black hole in the past rest-frame is just the negative of the Bondi 3-momentum flux $\mathcal{F}_{(\alpha_i)}$ carried by gravitational waves, and hence completely determined by the waveform. From Eq. (2.13) we obtain

$$\gamma \, M_{i^+} \, v_i \equiv P_{(\alpha_i)} = -\frac{1}{4\pi G} \int \mathrm{d}u \, \mathrm{d}^2 \mathring{V} \, \alpha_i(\theta, \varphi) \, |\dot{\sigma}^\circ(u, \theta, \varphi)|^2 \,, \tag{2.20}$$

where, again $\gamma = (1 - v^2/c^2)^{-\frac{1}{2}}$ is the standard Lorentz factor and $\alpha_i(\theta, \varphi) = (\sin\theta\cos\varphi, \sin\theta\sin\varphi, \cos\theta) \equiv \hat{x}$. In terms of this velocity $\vec{v}$, the transformation property of Ψ_2° under the change of Bondi-frames implies that the future limit of Ψ_2° in the past Bondi-frame is given by [5]

$$\Psi_2^\circ\big|_{u=\infty} = \frac{\Psi_2^{\circ\prime}}{\gamma^3 \left(1 - \frac{\vec{v}}{c} \cdot \hat{x}\right)^3} = -\frac{GM_{i^+}}{\gamma^3 \left(1 - \frac{\vec{v}}{c} \cdot \hat{x}\right)^3} \,. \tag{2.21}$$

Thus, using assumptions *(1)* and *(2)* we have now expressed Ψ_2° in both asymptotic limits $u \to \pm\infty$ using the the past Bondi-frame through Eqs. (2.18) and (2.21).

We can now use the balance law (2.11) for a general supertranslation $f(\theta, \varphi)$, in conjunction with with the forms (2.19) and (2.21) of Ψ_2° in the asymptotic past and future, to conclude that the waveform $\sigma^\circ = (h_+^\circ + ih_\times^\circ)/2$ must satisfy

$$\oint \mathrm{d}^2 \mathring{V} \, f(\theta, \varphi) \left(GM_{i^\circ} - \frac{GM_{i^+}}{\gamma^3 \left(1 - \frac{\vec{v}}{c} \cdot \hat{x}\right)^3} \right) = \oint \mathrm{d}^2 \mathring{V} \, f(\theta, \varphi) \int_{-\infty}^{\infty} \mathrm{d}u \left[|\dot{\sigma}^\circ|^2 - \mathrm{Re}(\eth^2 \dot{\bar{\sigma}}^\circ) \right](u, \theta, \varphi) \,. \tag{2.22}$$

Since $f(\theta, \varphi)$ is an arbitrary smooth function, we can peel-off the 2-sphere integral to obtain

$$GM_{i^\circ} - \frac{GM_{i^+}}{\gamma^3 \left(1 - \frac{\vec{v}}{c} \cdot \hat{x}\right)^3} = \int_{-\infty}^{\infty} \mathrm{d}u \left[|\dot{\sigma}^\circ|^2 - \mathrm{Re}(\eth^2 \dot{\bar{\sigma}}^\circ) \right](u, \theta, \varphi) =: \mathcal{F}(\theta, \varphi). \tag{2.23}$$

$\mathcal{F}(\theta, \varphi)$ can be thought of as the 'total flux of supermomentum in the (θ, φ) direction'. Since, Eq.(2.23) holds for each (θ, φ) *we have an infinite set of conditions.*

Now, every waveform used for data analysis provides us with:

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[5] This transformation property follows from the conformal rescaling of $\mathring{n}^a$ given in Eq. (2.1), the normalization condition $g_{ab}\ell^a n^b = -1$ in physical spacetime, the definition of $\Psi_2^\circ(u, \theta, \phi)$ given in Eq. (2.6) and the fact that the radial coordinate changes via $r' = \gamma\left(1 - \frac{\vec{v}}{c} \cdot \hat{x}\right) r + O(1)$ under a boost.

(i) the waveform $\sigma^\circ(u,\theta,\varphi) = \frac{1}{2}(h^\circ_+ + ih^\circ_\times)$ that completely determines the right side of (2.23), as well as the kick velocity v through Eq. (2.13);

(ii) the total initial mass of the system M_{i°;

(iii) the mass M_{i^+} of the final black hole.

If the global procedure used to create the waveform is to be consistent with exact GR, then the outcome must satisfy the infinite set of constraints (2.23). This is our principal observation.

To get an intuitive feel for these constraints, let us first consider the special case where there is no kick, i.e., where the velocity v of the final black hole is zero. Then the left side of (2.23) is a constant, while the right side $\mathcal{F}(\theta,\varphi)$, constructed from the waveform, is a function of (θ,φ). The infinite set of constraints now imply that $\mathcal{F}(\theta,\varphi)$ must be a constant. However, zero kick represents a very special CBC. Let us now consider the general case. Numerical simulations show that typical kick velocities are a few hundred km/s. For definiteness, let us take it be ~ 300 km/s, so $v/c \sim 10^{-2}$. One can then Taylor expand the second term in the left side of (2.23) in v/c,

$$GM_{i^\circ} - \frac{GM_{i^+}}{\gamma^3\left(1 - \frac{\vec{v}}{c}\cdot\hat{x}\right)^3} = GM_{i^\circ} - GM_{i^+}\left(1 + \left(3\,\hat{v}\cdot\hat{x}\right)\frac{v}{c} - \left(\frac{3}{2} - 6(\hat{v}\cdot\hat{x})^2\right)\frac{v^2}{c^2} + \dots\right) \quad (2.24)$$

and keep terms to the desired accuracy (here $\hat{v}$ is the unit vector in the $\vec{v}$ direction). Within this scheme, to test if a given waveform is accurate to $\sim 0.3\%$ we only need to retain the first order term in v/c, namely, $(-3\,GM_{i^+}\,\hat{v}\cdot\hat{x})\,v/c$. Then the right side has only linear combinations of $\ell = 0,1$ spherical harmonics, whence, in the expansion of $\mathcal{F}(\theta,\varphi)$ in terms of spherical harmonics, *all coefficients of the flux must vanish for $\ell \geq 2$.* This means that the waveform must be such that the total flux of the infinitely many components of *pure* supermomentum across $\mathfrak{I}^+$ must vanish to $\sim 0.3\%$ accuracy. If we are interested in 0.01% accuracy, we would keep terms up to $O(v^2/c^2)$ and should then find that the coefficients of the total flux must vanish for $\ell > 2$, and so on. *To summarize, (2.24) provides an infinite number of conditions that any proposed waveform must satisfy if it is to approximate the outcome of the exact GR calculation to a given desired accuracy.* The resulting error-bars are relative to exact GR rather than NR simulations (which come with their own error bars).

3. Constraints on waveforms over finite time intervals

So far we have focused on the 'global balance law' (2.11) that refers to all of $\mathfrak{I}^+$. However, we also have a 'quasi-local' balance law for any portion $\Delta\mathfrak{I}^+$ that is bounded by two cross-sections C_1 and C_2 [46, 47]. For waveform considerations it suffices to take C_1 and C_2 to be $u = u_1(\theta,\varphi)$ and $u = u_2(\theta,\varphi)$ cross-sections in any given Bondi-frame. Then we have:

$$P_{(f)}|_{u=u_1} - P_{(f)}|_{u=u_2} = \mathcal{F}_{(f)}\Big|_{u_1}^{u_2} \quad (2.25)$$

where the supermomenta $P_{(f)}|_{u_i}$ (with $i = 1,2$) on the left hand side are again given by (2.12),

$$P_{(f)}\big|_{u=u_i} := -\frac{1}{4\pi G}\oint_{u=u_i} \mathrm{d}^2\mathring{V}\, f(\theta,\varphi)\,\mathrm{Re}\big[\Psi_2^\circ + \bar{\sigma}^\circ\dot{\sigma}^\circ\big](\theta,\varphi) \quad (2.26)$$

and the flux on the right side is given by

$$\mathcal{F}_{(f)}\big|_{u_1}^{u_2} = \frac{1}{4\pi G} \oint d^2\mathring{V}\, f(\theta,\varphi) \int_{u_1}^{u_2} du\, \big[|\dot{\sigma}^\circ|^2 - \mathrm{Re}(\eth^2\dot{\bar{\sigma}}^\circ)\big](u,\theta,\varphi). \qquad (2.27)$$

One can again 'peel off' the 2-sphere integral using the fact that $f(\theta,\varphi)$ is arbitrary and arrive at the local analog of (2.23):

$$\mathrm{Re}\big[\Psi_2^\circ + \bar{\sigma}^\circ\dot{\sigma}^\circ\big](u_1,\theta,\varphi) - \mathrm{Re}\big[\Psi_2^\circ + \bar{\sigma}^\circ\dot{\sigma}^\circ\big](u_2,\theta,\varphi) = -\int_{u_1}^{u_2} du\, \big[|\dot{\sigma}^\circ|^2 - \mathrm{Re}(\eth^2\dot{\bar{\sigma}}^\circ)\big](u,\theta,\varphi)$$
$$(2.28)$$

The quasi-local constraint (2.28) has richer content than the the global constraints (2.23): since u_1 and u_2 are arbitrary, it provides dynamical checks on the waveform [73]. However, in order to verify whether it is satisfied, one needs to know Ψ_2°. The SXS collaboration is expected to release simulations that extract Ψ_2° in the NR regime in the very near future [74, 75], making (2.28) a potentially powerful tool to estimate errors in the simulations vis a vis exact GR.

We will conclude with a few remarks on Section II as a whole.

1. Had spacetime been exactly stationary for $t < -\tau$, as is generally assumed in the PN literature [57, 58, 76, 77], then we could have used the multipolar expansion of the metric that is shown to hold rigorously for stationary spacetimes outside some spatially compact region [78]. Using this expansion, one can calculate the asymptotic Weyl tensor and show that Ψ_2° is real and spherically symmetric on $\mathfrak{I}^+$ in the past Bondi-frame on *an infinite* interval $u < -u_o$ for some u_o. (In this case, the past Bondi-frame is the one in which $\mathring{n}^a$ is the limit to $\mathfrak{I}^+$ of the stationary Killing field.) Since our notion of asymptotic stationary in the past is extremely weak in comparison, we can only conclude that Ψ_2° becomes spherically symmetric in the limit $u \to -\infty$.

2. All analytical approximations used to construct waveforms –such as EOB– agree with the PN one in the distant past. Since our weak assumption *(2)* is inspired by the PN stationarity condition, it holds in these approaches as well.

3. Since the Lorentz transformation of energy only involves the first power of $\gamma(\vec{v}\cdot\hat{x}/c)$ in the denominator, the appearance of the cube of this factor in (2.23) may seem surprising. The additional factor of $(\gamma(\vec{v}\cdot\hat{x}/c))^{-2}$ comes from the transformation property of the 2-sphere area-element: We have 'peeled-off' a 2-sphere integral in the passage from (2.11) to (2.23).

4. If there is no kick, i.e., if $v = 0$ identically, then the past and future Bondi frames coincide. This is of course a *very special case* realized, e.g., in an equal mass head-on collision. In this case, Eq. (2.21) simplifies to $\Psi_2^\circ|_{u=\infty} = -GM_{i^+}$. Thus Ψ_2° becomes spherically symmetric *in the same Bondi-frame* in both asymptotic limits, $u \to \pm\infty$. Therefore, in the terminology used in the literature, the *linear (or, ordinary) memory vanishes.* Recently, this implication of asymptotic stationarity of the system in the *same Bondi frame,* as $u \to \pm\infty$, was arrived at using detailed calculations using the physical spacetime metric [79]. Analysis at $\mathfrak{I}^+$ summarized above brings out the minimal setup needed to obtain this result:

(i) One only needs that the past and future rest frames are the same, and $\partial_u \Psi_1^\circ \to 0$ as $u \to \pm\infty$ along $\mathfrak{I}^+$ in this Bondi frame. There is no explicit assumption on the underlying metric and, at the level of curvature, Ψ_0° does not have to become stationary;

(ii) In full GR, the result follows in a couple of steps if one uses Eqs. (2.16) and (2.17) at $\mathfrak{I}^+$, which are immediate consequences of Bianchi identities and Einstein's equations at $\mathfrak{I}^+$ [53].

Finally, note that we do allow kicks in our main analysis; our assumption *(2)* does *not* require that the past and the future rest frame is the same and the ordinary memory does not vanish.

5. The assumption of 'past stationarity' [57, 58] –i.e., that the system is stationary before some time $(t = -\tau)$– is extremely strong. Sometimes one models the behavior of the system in distant past by assuming that it is represented by a binary in a quasi-circular orbit, rather than by a stationary system. In this case, velocities of the individual bodies would go to zero asymptotically and our two assumptions would still be satisfied. In practice, one may want to avoid the limit $u \to -\infty$ altogether and simply start at some finite time $u = u_1$ sufficiently in the past when the binary is well within the PN regime, and use (2.28) in place of (2.23) with $u_2 = \infty$.

III. DISCUSSION

Thanks to the combined technical expertise of the waveform community, the matched filtering procedure based on currently available waveforms has led to the dramatic discovery of several CBCs [80]. The pace of detection has gone up considerably already during the current LIGO-Virgo observation run and, with a global network of gravitational wave observatories, the detection rate could be as high as 1000 binary black holes coalescences a year, with masses below $100 M_\odot$. The 3G observatories and LISA will further increase the total rate, have a higher sensitivity and widen the parameter range significantly. These discoveries will enable us to better understand the astrophysics of sources assuming GR, and also to carry out more stringent tests of GR itself. Furthermore, some experts emphasize that even with the current LIGO-Virgo detectors, more accurate waveforms could lead to the discovery of near or (sub-)threshold events and/or events in regions of the parameter space where NR simulations are sparse [29]. Therefore, it would be extremely useful to have *external* criteria to ensure that the waveforms used in the analysis *do* represent predictions of GR to a very high degree of accuracy. As we remarked in the Introduction, the conceptual difficulty is that we do not have waveforms from *exact* GR with which to compare the candidates! Therefore errors are generally estimated by comparing various analytic waveforms with the NR ones, which are taken to be the 'practical substitutes' for the exact waveforms (see e.g.[18, 19, 39–42]). In Section II we showed that the supermomentum balance laws provide an alternate avenue: One can test the accuracy of a proposed waveform *vis a vis exact GR* using Eqs. (2.23) and (2.28). These equations imposes an infinite number of constraints on the waveform that must be satisfied in full, non-linear GR. Since they refer only to the asymptotic structure of space-time, they hold not only for the BH-BH binaries, but also for NS-NS and NS-BH binaries. Violations of these constraints can provide sharp error-bars on

any waveform candidate for all CBCs. Work is in progress to use the constraints to gain further insights in several directions.

The first concerns sub-dominant modes in the (spin-weighted) spherical harmonic decomposition of the waveform. Different models already provide us with several modes beyond the leading (2,2) mode. For example, in the spinning, non-precessing case, there are EOB waveforms that include the (2,2), (2,1), (3,3), (4,4), and (5,5) modes [32] while in phenom models precessing waveforms that include all $\ell \leq 4$ modes are available (PhenomPv3HM [33]). It is natural to ask for the errors one makes in ignoring other modes [81–84]. Since the equality (2.22) assumes that σ° on the right side is the exact GR waveform –which include all modes– it is can be used to evaluate these errors. Significant violations of this equality could also be used as signals that certain waveforms need further scrutiny.

In practice it useful to carry out a spherical harmonic decomposition, using $Y_{\ell,m}(\theta, \varphi)$ (for various ℓ, m) for $f(\theta, \varphi)$ in (2.22):

$$\oint \mathrm{d}^2 \mathring{V}\, Y_{\ell,m}\Big(GM_{i^\circ} - \frac{GM_{i^+}}{\gamma^3\big(1 - \frac{\vec{v}}{c}\cdot\hat{x}\big)^3}\Big) = \oint \mathrm{d}^2 \mathring{V}\, Y_{\ell,m}(\theta, \varphi)\int_{-\infty}^{\infty}\mathrm{d}u\, \big[|\dot{\sigma}^\circ|^2 - \mathrm{Re}(\eth^2\dot{\bar{\sigma}}^\circ)\big](u, \theta, \varphi)\,. \tag{3.1}$$

One can use the candidate waveform $\frac{1}{2}\big(h^\circ_+ + ih^\circ_\times\big)$ for σ° on the right side of this equation, and also in the calculation of the velocity $\vec{v}$ on the left side. Generically, there will be a mismatch between the right and left sides of (3.1) which will provide an estimate of the error in the candidate waveform for each choice of ℓ, m. For instance, the $m = 0$ modes are usually set to zero in non-precessing models, and they arise in precessing waveforms solely from the time-dependent rotation that takes into account precession. For non-precessing systems, therefore, the $Y_{\ell,0}$ components of the constraint (3.1) are violated, primarily because the second term on the right side is vanishing by construction. Work in progress shows that for the IMRPhenomD [5] and SEOBNRv4 [51] models the violation is most significant for $Y_{2,0}$, as one might expect. Errors in different models are essentially the same because their $|\dot{\sigma}^\circ|^2$ is essentially indistinguishable and the left hand side negligible, being of order $(v/c)^2$.

However, for other modes the magnitude of the violation of (3.1) can differ markedly from one class of models to another. This is in particular the case for precessing systems. As a specific example, let us compare SEOBNRv3 [11, 85] and IMRPhenomPv2 [6] (whose waveforms includes all $\ell = 2$ modes). Consider then a precessing binary system of equal mass black holes, each with spin 0.4 in the positive x-direction (measured at a reference time corresponding to a GW frequency of 0.01 in units of the total mass). Since these models do not include the (3,2) mode, by fiat the second term on the right hand side of Eq. (3.1) is set to zero in the (3,2) part of this constraint. Therefore again the constraint is violated. However, in this case the orders of magnitude of the violation are *very* different: while it is 4×10^{-4} for SEOBNRv3, it is of order 10^{-14} for IMRPhenomPv2, both in units of GM_{i°. Therefore –unlike in the case of the (2,0) mode discussed above– the discrepancy cannot come solely because the (3,2) mode is ignored; there is another source of systematic error involved. Of course to determine whether these inaccuracies are significant in practice, one would have to take into account the precise sensitivity of the next generation detectors.

Work is also in progress [86] on using these constraints to calculate the probability distribution functions (PDFs) for the total gravitational memory in various LIGO events. Recall that the the mass and spin of the final black hole serve as inferred observables for LIGO events to date, and comparisons of the posterior PDFs of these observables, obtained from EOB and Phenom waveforms, have generally added to confidence that the accuracy of these

waveforms is adequate. The total memory is another inferred observable associated with CBCs. It can also be used to probe systematic errors in given waveforms. The strategy can be summarized as follows. Let us set $\ell \geq 2$ and re-express (3.1) by: (i) carrying out the u integral in the term that is linear in $\dot{\sigma}^\circ$ on the right hand side; (ii) using the fact that $\mathrm{Im}\,\eth^2\bar{\sigma}^\circ$ vanishes at $u = \pm\infty$ because $\mathrm{Im}\Psi_2^\circ$ vanishes there; (iii) integrating $\eth^2$ by parts and using the identity $\eth^2 Y_{\ell,m} = \frac{1}{2}\sqrt{(l-1)l(l+1)(l+2)}\ _2Y_{\ell m}$; and, (iv) moving the result to the left side. We obtain [6]

$$
\begin{aligned}
\frac{1}{2}\sqrt{(l-1)l(l+1)(l+2)} & \left[\lim_{u_\circ \to \infty} - \lim_{u_\circ \to -\infty} \right] \oint_{u=u_\circ} \mathrm{d}^2\mathring{V}\ _2Y_{\ell,m}\,\mathrm{Re}(\bar{\sigma}^\circ) \\
&= GM_{i^+} \oint \mathrm{d}^2\mathring{V}\,\frac{Y_{\ell,m}}{\gamma^3\left(1 - \frac{\vec{v}}{c}\cdot\hat{x}\right)^3} \;+\; \oint \mathrm{d}^2\mathring{V}\,Y_{\ell,m}\int_{-\infty}^{\infty}\mathrm{d}u\,|\dot{\sigma}^\circ|^2(u,\theta,\varphi)\,.
\end{aligned}
\tag{3.2}
$$

The left hand side of (3.2) provides the (ℓ, m) component of the total gravitational memory. This term vanishes for all (ℓ, m) in the currently available Phenom and EOB waveforms. However, physical considerations imply that the total memory is generically non-zero (see, e.g., [49, 52, 61, 79]). The idea is to *use* our constraint to extract the correct total memory by evaluating the right hand side [86, 88]. Detailed examination shows that for CBCs that have been observed so far, the first term on the right side (called the linear (or ordinary) memory) is dominated by the second term on right hand side (called the non-linear (or null) memory). The second term, in turn, is dominated by modes (particularly (2,2)) that are expected to be correctly captured in the available waveforms. Therefore, in various LIGO events one can use the currently available posterior PDFs from EOB and Phenom models to construct the PDFs for total memory. Comparison between these pairs of PDFs for various (ℓ, m) components of the total memory –i.e., for these new inferred observables– can provide additional support for their viability, or signal a new source of systematic error that was not revealed by the PDFs of currently used inferred observables –the mass and spin of the final black hole.

While the total gravitational memory can be evaluated using the above procedure, the calculation of the full (2,0) mode of the waveform *as a function of time* is more challenging. In the NR regime, accurate results have been obtained [89] using Cauchy-Characteristic Extraction (CCE). It can be seen that (2,0) mode has a monotonic behavior, superimposed by some oscillations. This form can be understood conceptually using our constraints: The monotonic part can be directly traced to the (finite time version of the) non-linear memory term, and the oscillatory, to the (finite time version of the) linear memory term in (2.28).[7] However, CCE is numerically expensive, and the (2,0) mode provided by the SxS

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[6] In the framework developed in Section II, $\sigma^\circ = 0$ at i°, so the left hand side receives contributions only from $u \to +\infty$, which is generically non-zero because the past and future Bondi-frames are related by a *supertranslation*. This subtlety is important for hybrid waveforms where it is natural to work in the past Bondi frame in the PN regime, thereby setting $\sigma^\circ = 0$ at i°, and it is also natural to work with the future Bondi frame in the NR regime, where $\sigma^\circ = 0$ at i^+. To obtain a consistent waveform, one then has to incorporate the supertranslation relating the two frames [48, 87].

[7] More precisely, we need to work with a finite time analog of (3.2), obtained by integrating (2.28) against $Y_{2,0}(\theta,\varphi)$ and setting $u_1 = -\infty$. In our setup σ^o vanishes at $u = -\infty$. Therefore, this procedure expresses $\oint \mathrm{d}^2\mathring{V}\,Y_{2,0}(\theta,\varphi)\,\sigma^\circ(u_2,\theta,\varphi)$ as a sum of the (finite-time) non-linear memory that is monotonic, and a (finite-time) linear memory term which turns out to be oscillatory.

collaboration is generically unreliable since it does not converge with increasing precision [1]. Work in progress [75] is likely to provide the full (2,0) mode by combining the SxS simulations with analytic considerations suggested by the constraints presented in this paper.

Next, recall that the mathematical GR literature generally assumes that σ° can be freely specified on $\mathfrak{I}^+$. On the other hand we found that it is subject to an infinite number of constraints stemming from the balance laws. How did this come about? The constraints arose because (i) we are considering gravitational waves emitted in CBCs, rather than source-free solutions; and, (ii) we assumed that the CBCs become stationary in a weak sense both in the distant past and future, in the respective asymptotic rest frames. Let us therefore reexamine the boundary conditions we imposed in the limits $u \to \pm\infty$ in Section II C 1. The first has direct physical motivation: We assume that the Bondi news –the time derivative of the waveform– decays sufficiently rapidly so that the total flux of supermomentum across $\mathfrak{I}^+$ is well defined. (This is also the necessary and sufficient condition for the flux of Bondi angular momentum across $\mathfrak{I}^+$ to be finite. The condition is satisfied in, e.g., the analysis of non-linear stability of Minkowski space given, e.g., in [90].) This condition guarantees that the system becomes asymptotically stationary in the weak sense that time derivatives of the components Ψ_4°, Ψ_3° and Ψ_2° of the asymptotic Weyl curvature go to zero in any Bondi frame as $u \to \pm\infty$ (if these conditions hold in one Bondi frame, they hold in all). The second condition we imposed is a strengthening of this notion of asymptotic stationarity: We require that the time derivative of Ψ_1° also goes to zero as $u \to \pm\infty$. But now the limits depend on the choice of the Bondi-frame, whence the requirement in the past is imposed *only* in the Bondi frame in which the system is at rest in distant past, and similarly the requirement in the future is imposed *only* in the Bondi frame in which the system is at rest in distant future. We saw that, had we demanded the time derivative of Ψ_1° vanishes as $u \to \pm\infty$ in the *same* Bondi-frame, the condition would have been physically too restrictive –in particular it would have ruled out black hole kicks [71, 72]! By contrast, our condition requires asymptotic stationarity in a weak sense. In particular, in NR simulations space-time geometry approaches the Kerr solution in the distant future and PN analysis used in the early phase of coalescence assumes a *much* stronger notion of stationarity in the distant past.

Finally we would like to clarify a potential confusion about the field Ψ_1° on $\mathfrak{I}^+$. Global results by Christodoulou and Klainnermann [90] on non-linear stability of Minkowski space showed that Ψ_4, Ψ_3 and Ψ_2 'peel' as $1/r$, $1/r^2$ and $1/r^3$ respectively, as implied by the Newman-Penrose asymptotic conditions [53]. However, in that analysis, Ψ_1 is guaranteed to fall-off only as $1/r^{7/2}$, rather than as $1/r^4$. Therefore, it follows from Eq. (2.6) that Ψ_1° need not exist on $\mathfrak{I}^+$ for the class of initial data considered in Ref. [90]. Note that this is not a statement about limits $u \to \pm\infty$ along $\mathfrak{I}^+$ considered in this paper; rather, Ψ_1° need not exist *anywhere* on $\mathfrak{I}^+$. In particular, this means that the angular momentum of the system would be ill-defined at *any* retarded time $u = u_o$ [54, 55]. From a physical viewpoint, therefore, this analysis caters to too broad a class of systems. In CBC, in particular, angular momentum *is* well-defined and constitutes an important parameter in the system characterization. Indeed, even in the vacuum case to which Ref. [90] restricts itself to, Chrusciel and Delay [91] have shown that there is a non-linear neighborhood of Minkowski initial data that evolves to a unique global solution in which the Newman-Penrose peeling holds, i.e. Ψ_1° has a well-defined C^k limit to $\mathfrak{I}^+$. Finally, note that all these global results refer to vacuum (or electrovac) situations in which there is outgoing *as well as incoming* gravitational radiation. Physically we are much more interested in gravitational waves produced by sources –such as compact

binaries– with no incoming radiation on $\mathfrak{I}^-$. Among solutions covered by the currently available global existence theorems, the only one with no incoming radiation is Minkowski space! Therefore, these theorems do not offer direct guidance for what the appropriate fall-off conditions would be for systems undergoing compact binary coalescence.

Acknowledgments

Appendix A: Null infinity and emergence of supertranslations

In Section II we used several known facts about the structure of null infinity and properties of fields thereon. Since some in the PN and NR communities may not be familiar with them, in this Appendix we present a brief summary, focusing only on those features that we need.

Eventhough Einstein, Eddington and others explored the properties of gravitational waves in the weak field approximation around Minkowski space soon after the discovery of general relativity, there was considerable confusion about the reality of gravitational waves in *full, nonlinear* GR for several subsequent decades largely because of the coordinate freedom: What appeared to be a wave-like behavior in one coordinate system could appear stationary in another. This confusion was resolved only in the 1960s when Bondi, Sachs and others showed that one can unambiguously disentangle gravitational waves by moving away from isolated sources in retarded *null directions*, i.e., in the usual terminology, by taking the limit $r \to \infty$ keeping the retarded time constant $u = $ const. The asymptotic boundary conditions introduced by Bondi and Sachs [43, 44] were geometrized by Penrose [50] through the notion of a conformal completion of spacetime, i.e., by attaching to spacetime a 3-dimensional boundary $\mathfrak{I}^+$, representing *'future null infinity'*.

These frameworks provided a definitive, coordinate invariant characterization of gravitational radiation in asymptotically flat spacetimes and introduced techniques to analyze its properties in exact, non-linear general relativity. However, initially there were concerns as to whether the underlying assumptions are too strong to be satisfied by realistic isolated systems such as compact binaries (see, e.g., [57]). The current consensus is that they are not too strong. In particular, the asymptotic form of the PN metric is completely consistent with the Bondi-Sachs-Penrose framework, as shown for instance by Theorem 4 in [58]. Similarly, the key notions of this framework –such as the radiation field Ψ_4°, the Bondi news N, and the asymptotic shear σ°– and their properties are heavily used in numerical simulations of waveforms and calculations of energy and momentum flux in NR. These notions and properties are summarized in Section II.

The detailed analysis of gravitational radiation at null infinity brought to forefront an

unforeseen result that plays a key role in Section II: Even though spacetimes representing isolated gravitating systems are asymptotically Minkowskian, the asymptotic symmetry group is *not* the Poincaré group $\mathcal{P}$, but rather an infinite dimensional generalization thereof, the BMS group $\mathfrak{B}$. This is a consequence of the fact that gravitational radiation is on a genuinely different footing –from, say, the electromagnetic one– in one important respect. It introduces ripples in spacetime curvature that extend all the way to infinity, i.e., to $\mathfrak{I}^+$, making it impossible to single out a *preferred* Poincaré group $\mathcal{P}$ using asymptotic Killing vectors. This difficulty can be seen in concrete terms as follows. Suppose we have a metric g_{ab} that is asymptotically flat in the sense of Bondi and Sachs; so it approaches a Minkowski metric η_{ab}, with $g_{ab} = \eta_{ab} + \mathcal{O}(1/r)$, as $r \to \infty$ keeping $u = t - r$ constant. Therefore, Poincaré transformations of η_{ab} provide us with asymptotic Killing fields for g_{ab}. Now consider a diffeomorphism $t \to t' = t + f(\theta, \varphi)$, $\vec{x} \to \vec{x}' = \vec{x}$ where $t, \vec{x}$ are Cartesian coordinates of η_{ab}. This is an *angle dependent translation*, whence the metric η_{ab} is sent to a *distinct* flat metric η'_{ab}.[8] One can verify that since g_{ab} approaches η_{ab} as $1/r$ à la Bondi-Sachs, it also approaches η'_{ab} as $1/r'$ à la Bondi-Sachs! Therefore, the Poincaré transformations of η'_{ab} are also asymptotic Killing fields of our physical g_{ab}. But since the two Minkowski metrics are distinct, their isometry groups $\mathcal{P}$ and $\mathcal{P}'$ are also distinct. The BMS group can be interpreted as a 'consistent union' of Poincaré groups associated with all these Minkowski metrics, related to one another by 'angle dependent translations.' These are known as *supertranslations*. Detailed examination brought out another subtlety: All these Poincaré groups define the same translation subgroup asymptotically, whence the BMS group does admit a canonical, 4-dimensional translation subgroup $\mathcal{T}$ [60]. However, the Lorentz subgroups $\mathfrak{L}$ of various Poincaré groups are different even asymptotically. Recall that the Poincaré group $\mathcal{P}$ admits a 4-parameter family of Lorentz subgroups –each of which defines rotations and boosts about one specific origin in Minkowski space– related to one another by a translation. By contrast, the BMS group $\mathfrak{B}$ admits an infinite parameter family of Lorenz subgroups that are related to one another by supertranslations. This gives rise to the well-known 'supertranslation ambiguity' in the notion of angular momentum at null infinity. We discuss this issue in detail in [48], again in the context of CBC.

In this paper we focused on supertranslations. Just as the translational symmetries of the Minkowski metric lead to the notion of energy-momentum for fields in Minkowskian physics, supertranslation symmetries on $\mathfrak{I}^+$ lead to the notion of *supermomenta*. In the case of energy-momentum, we have two different quantities available at $\mathfrak{I}^+$. The first is the Bondi 4-momentum –a 2-sphere integral on a cross-section C at $\mathfrak{I}^+$, representing the energy momentum of the system, left over at the retarded instant of time $u = u_0$ defined by C. The second is the notion of flux of energy-momentum carried away by gravitational waves through a 'patch' $\Delta \mathfrak{I}^+$ of $\mathfrak{I}^+$. As a consequence we have a balance law: The difference between the Bondi 4-momentum evaluated on two different cross-sections C_1 and C_2 of $\mathfrak{I}^+$ is the flux of energy-momentum across the patch $\Delta \mathfrak{I}^+$ bounded by them. It turns out that the same is true for supermomentum. Thus we have an infinite number of balance laws –Eqs. (2.25) (or (2.28)) in the main text– each characterized by a function on a 2-sphere defining the supertranslation. As we discussed in Section II, these lead to an infinite set of

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[8] We chose a time-translation just for definiteness: the argument continues to hold if the 'angle dependent translation' is generic.

constraints –imposed by full, non-linear GR– that any waveform must satisfy in a CBC.

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