

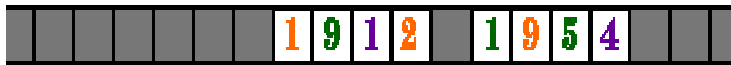
Computing over the **Reals**: Where **Turing** Meets **Newton**



Alan Turing



Sir Isaac Newton (1642-1727)



Lenore Blum

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COMPLEXITY AND REAL COMPUTATION

LENORE BLUM ■ FELIPE CUCKER

MICHAEL SHUB ■ STEVE SMALE

WITH A FOREWORD BY RICHARD M. KARP




Mike Shub, Lenore Blum, Felipe Cucker, Steve Smale

Photo taken by Victor Pan at Dagstuhl, 1995.

Two Traditions of Computation

Numerical Analysis/ Scientific Computation

- Newton's Method Paradigm Example in Most Numerical Analysis Texts
- No Mention of Turing **Machines** 

• Real & Complex #'s
Math is Continuous

• Un**De**veloped
Foundations of **CM**

Logic/Computer Science

- Turing Machine Underlying Model in most CS Texts on Algorithms
- No Mention of Newton's method

• 0's & 1's (bits)
Math is discrete 

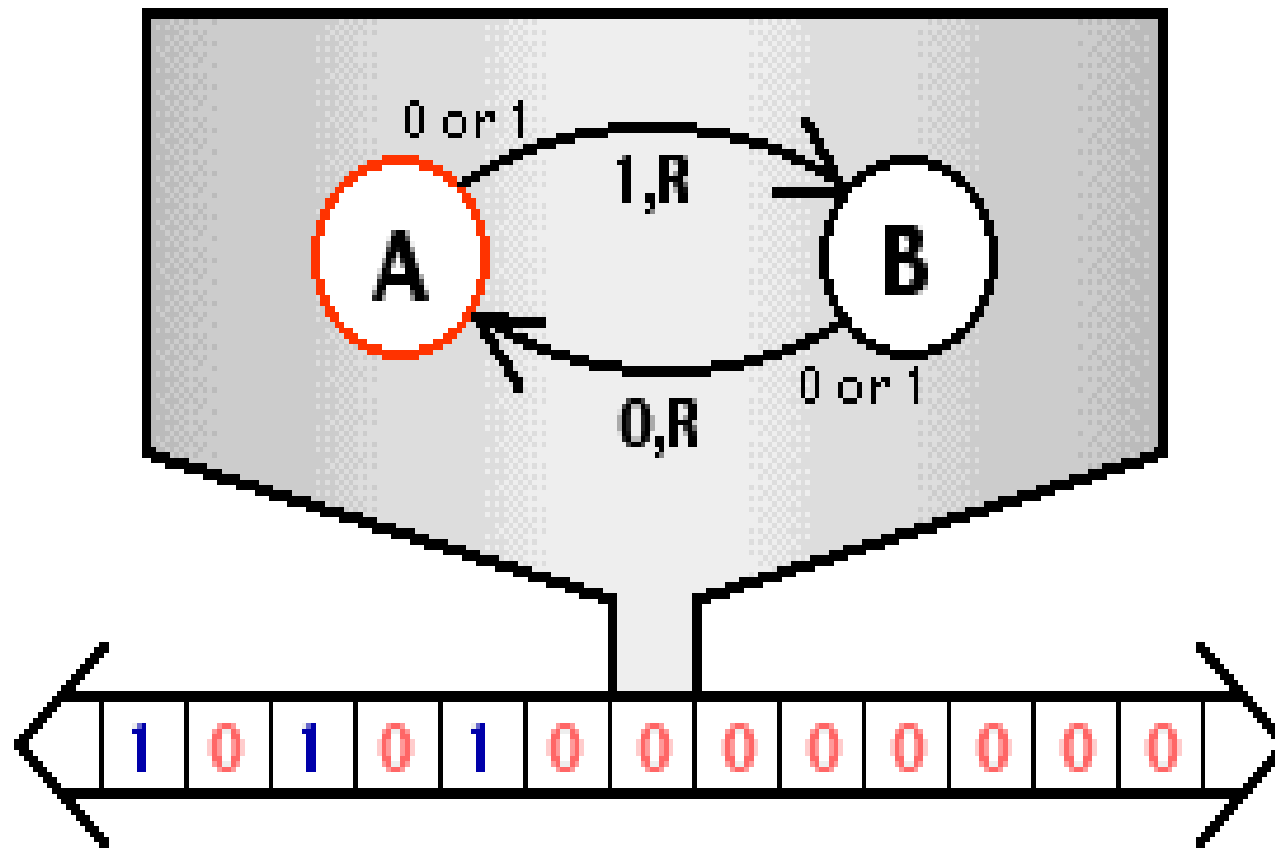
• Highly Developed
Foundations Of **CS**

- Want to reconcile dissonance
- Build bridges
- Unify
- Traditions/tools of each should inform the other*

*Examples

FOCS → FoCM: Complexity Theory

FoCM → FOCS: Condition



The **Turing Machine** provides the Mathematical Foundation for the **Classical Theories** of **Computation** and **Complexity**

Logicians in the 1930's-40's (Godel, Church, Kleene, ...) **Computer Scientists** in the 60's-70's (Rabin, M. Blum, Cook, Karp, Levin...)

*TM courtesy of Bryan Clair

Since the 1930's, many seemingly different models have been proposed for a general theory of (discrete) computing. What has been striking is that all such models have given rise to the *exact same class* of “computable” functions: the class of input-output maps of Turing machines are exactly the computable functions derived from Post production systems, as from flow-chart machines, as from random access machines, as from axiomatic descriptions of *recursive functions*, etc...

The has been essentially true wrt the accompanying complexity theories (up to polynomial time): poly-time and intractability are essentially invariant across platforms. Thus logicians and computer scientists have confidence they are working with a very natural class of functions and justifies the use of their favorite model. Even more, this naturalness/invariance underlie the impact theory has had on technological developments, be it in programming, the design of computers or cryptography.

The **classical** Turing tradition yields:

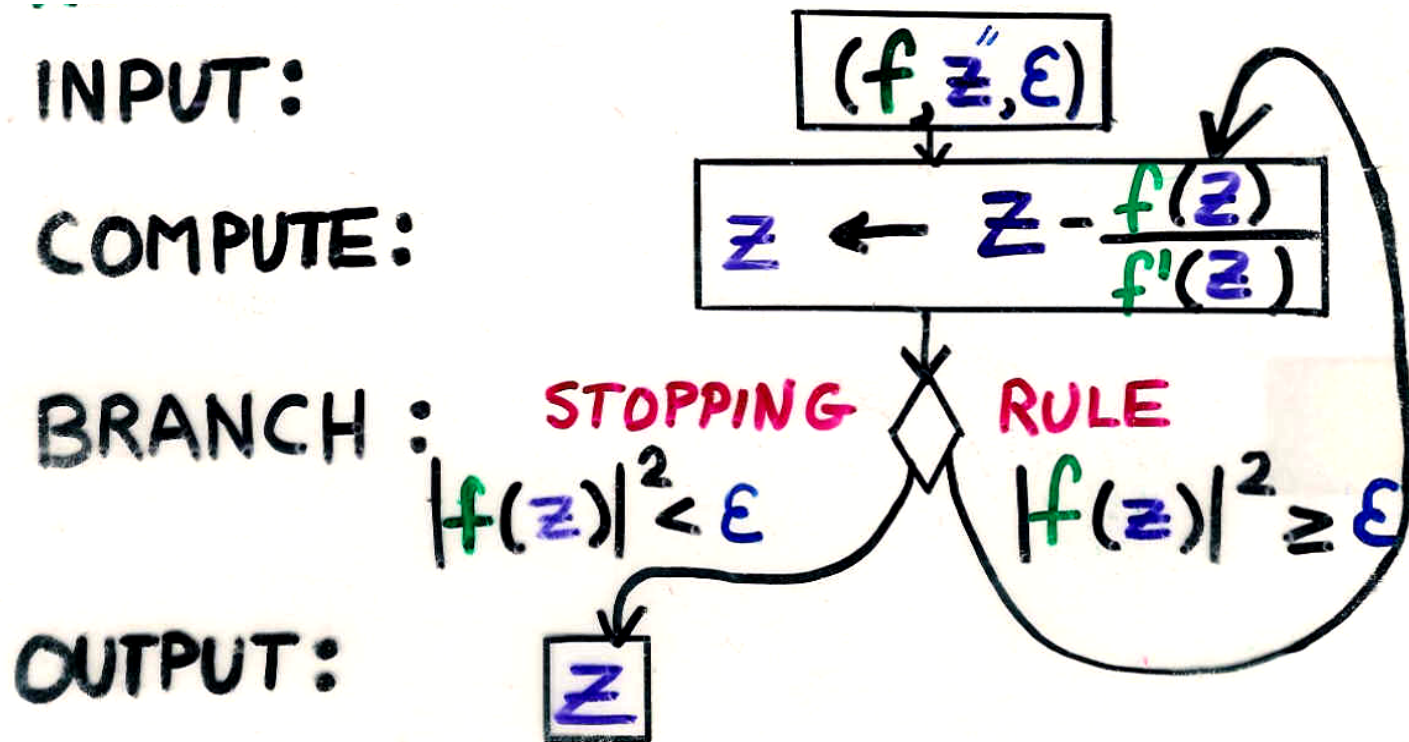
- A highly developed and *rich* (**invariant**) *theory of computation and complexity*
- With *important applications* to computation, cryptography, security, etc
- And, *deep interesting problems*.

Why do we want a new model of computation?

Motivation 1 for New Model

Want model of computation which is more natural for algorithms of numerical analysis, such as Newton's Method.

"Newton Machine"



Paradigm method of numerical analysis.

Translating to 'bit' operations would wipe out the natural structure of Newton's algorithm.

Motivation 2 for New Model

Want model* of computation where it is more natural to pose and answer questions of decidability and complexity about problems and sets over the real and complex numbers.

*uniform model

NATIONAL BESTSELLER

THE EMPEROR'S NEW MIND

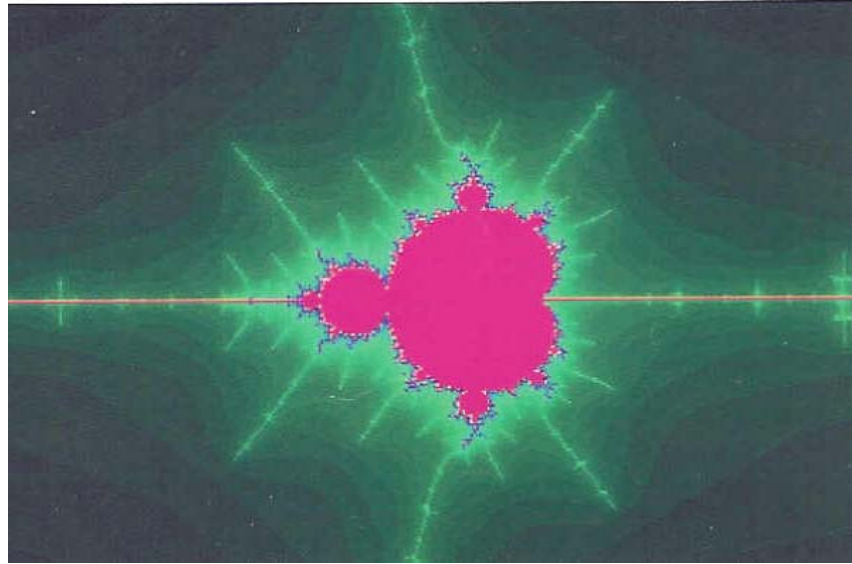
Concerning Computers, Minds, and the Laws of Physics



Roger Penrose

Roger Penrose (1989).

Is the **Mandelbrot set** decidable?

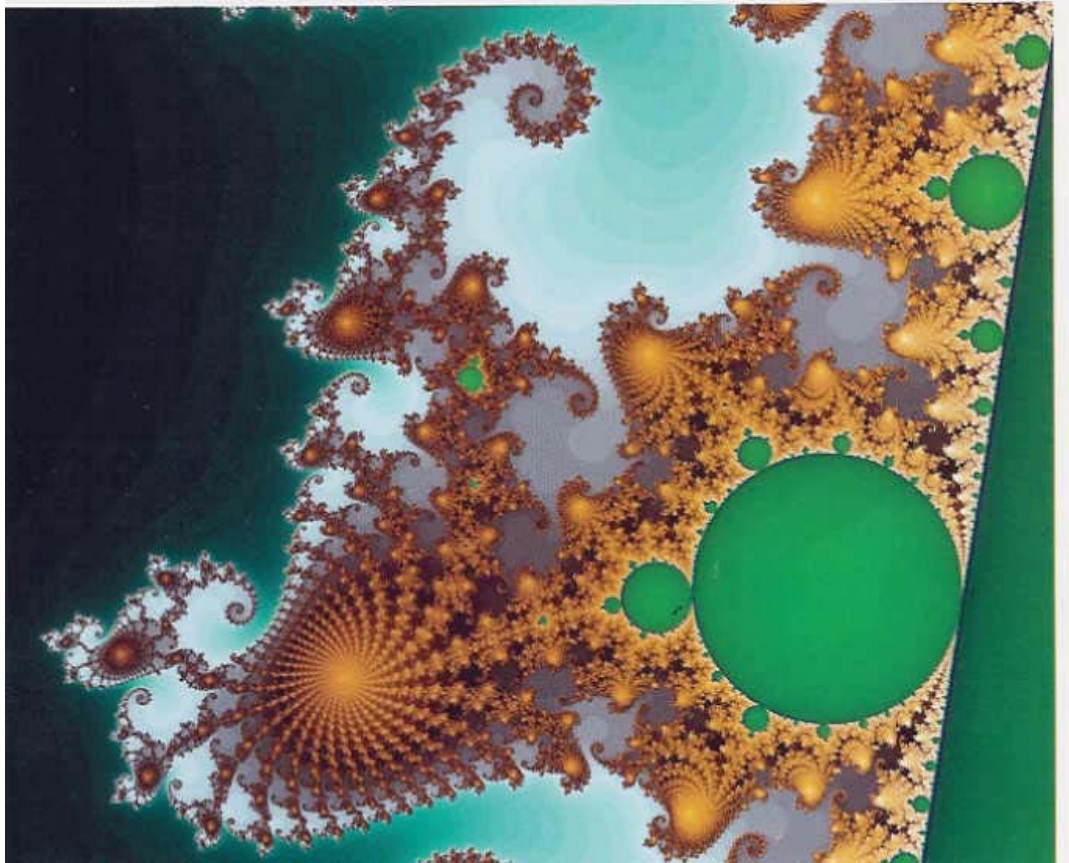


$$\mathbf{M} = \{c \mid p_c^n(0) \not\rightarrow \infty\}, \quad p_c(z) = z^2 + c, \quad c \in \mathbf{C}, \quad \mathbf{M} \subset \mathbf{C} = \mathbf{R}^2$$

“Now we witnessed, ..., a certain extraordinarily complicated-looking set, namely the **Mandelbrot set**. Although the rules which provide its definition are surprisingly simple, the set itself exhibits an endless variety of highly elaborate structure.

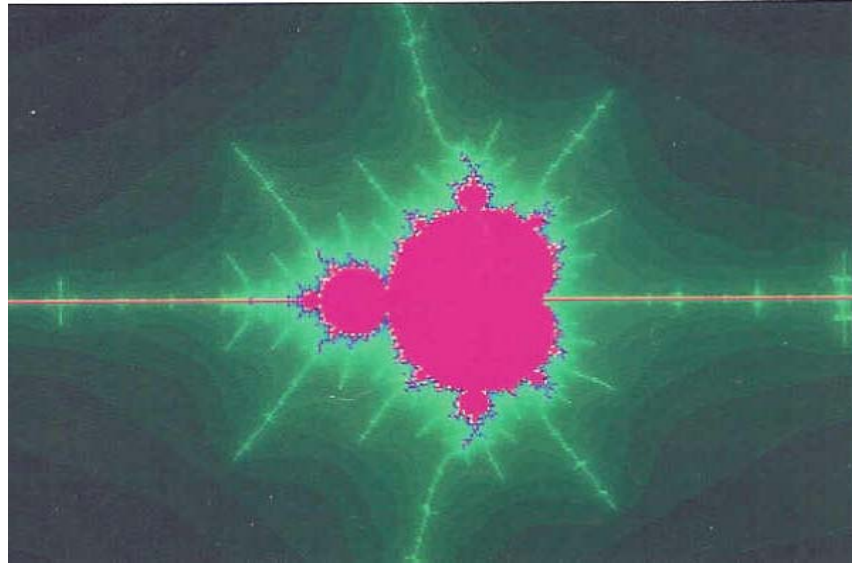
Could this be an example of an **undecidable** set, truly exhibited before our mortal eyes?”

Complexity on the boundary in Seahorse Valley



Roger Penrose (1989).

Is the **Mandelbrot set** decidable?



$$\mathbf{M} = \{c \mid p_c^n(0) \not\rightarrow \infty\}, \quad p_c(z) = z^2 + c, \quad c \in \mathbf{C}, \quad \mathbf{M} \subset \mathbf{C} = \mathbf{R}^2$$

After considering possible interpretations via the classical theory of computation, Penrose concludes:

“... one is left with the strong feeling that the correct viewpoint has not yet been arrived at.”

Motivation 3 for New Model

New perspectives for

$$P = NP?$$

The Model

(BSS, '89)

Inspired by *both* computer science and
numerical analysis

From
Numerical
Analysis...

CCT

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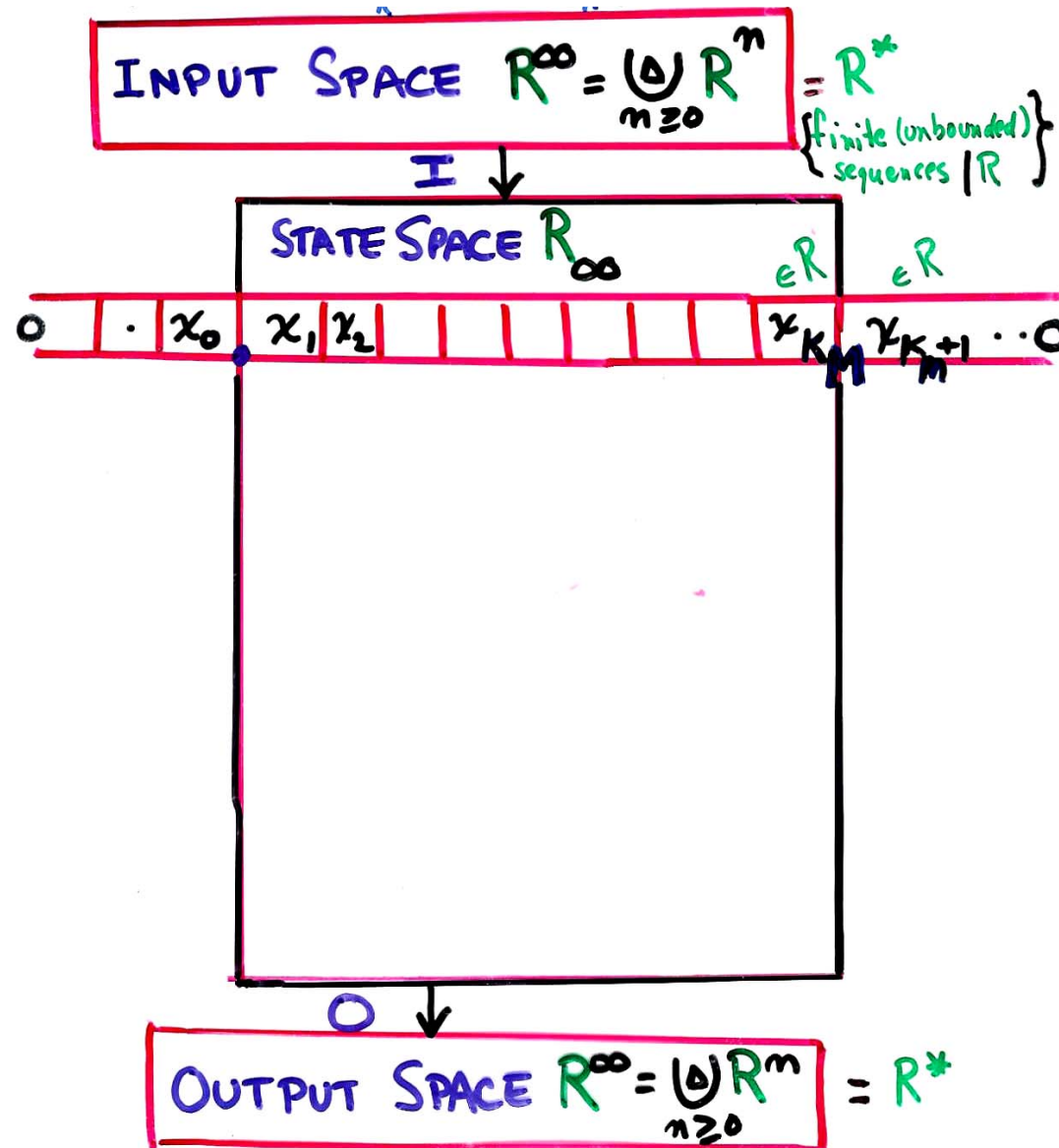
“Rounding-off Errors In Matrix Processes”

The Quarterly Journal of Mechanics and Applied Mathematics, vol. I, 1948, pp. 287-308.

1. Measures of work in a process

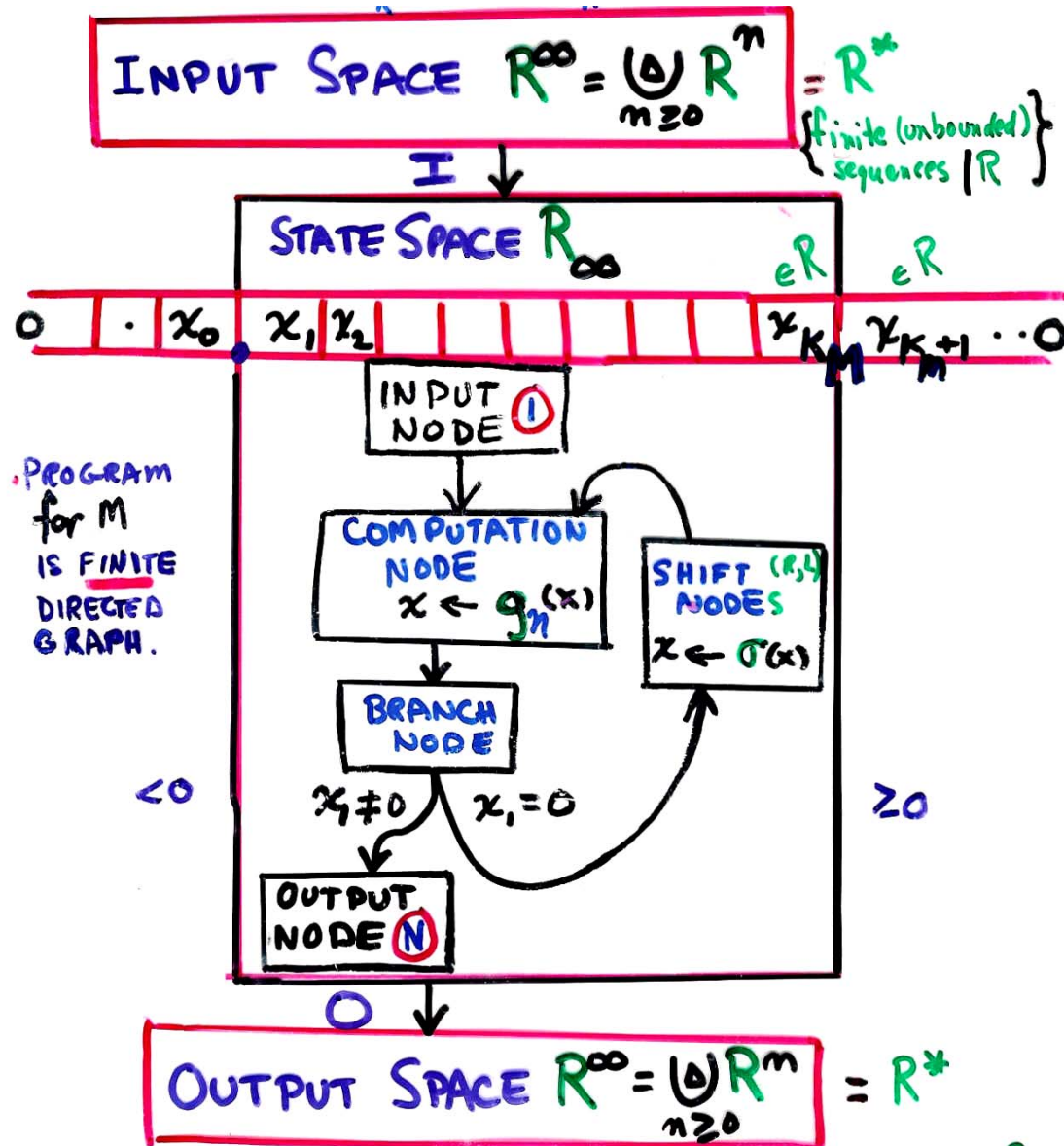
It is convenient to have a *measure of the amount of work involved in a computing process*, even though it be a very crude one...We might, for instance, *count the number of additions, subtractions, multiplications, divisions, recordings of numbers, ...*

Machine M over a Ring R ($+.x$) (BSS '89)



R is commutative with unit. M looks like a Turing Machine, but inside ...

Machine M over Ring R ($+.x$) (BSS '89)



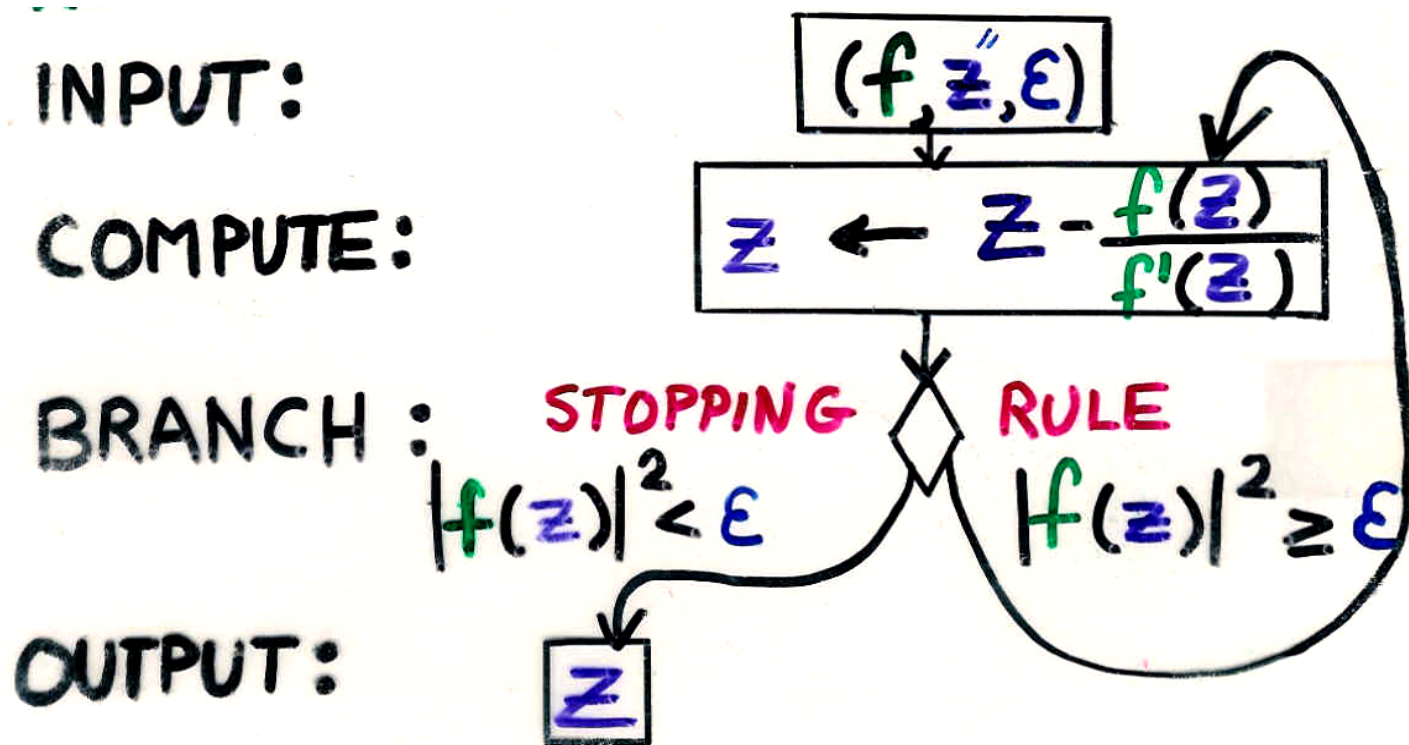
M looks like a Newton Machine inside.

M can have a finite # of built-in constants from R .

Features of Machine over \mathbf{R}

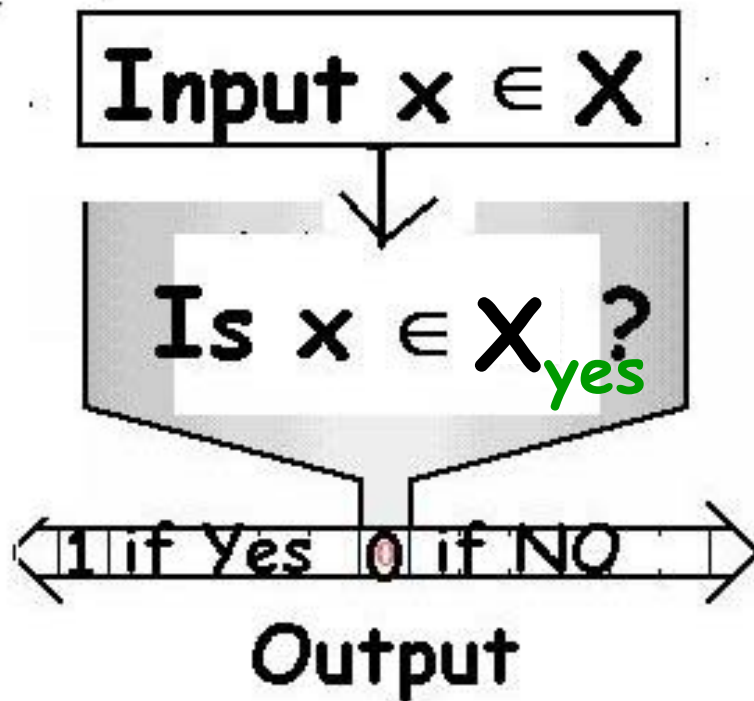
- Computation nodes: built in $g_\eta : \mathbf{R}^n \rightarrow \mathbf{R}^m$, polynomial or rational map (given by a finite # of polynomials in a finite # of variables).
- Branch: on = if \mathbf{R} , unordered ring or field,
on < if \mathbf{R} is ordered.
- Shift nodes: shift one cell right or left
- Machine is **uniform** over \mathbf{R}^n , for all n .
- **Computable fns** over \mathbf{R} : the input-output maps.
- Can construct **universal** (programmable) **machines**.
[We do not use Godel coding. The program itself is (essentially) its own code.]
- If \mathbf{R} is \mathbf{Z}_2 , we recover the **classical theory** of **computation** (and **complexity**, as we shall see).

"Newton Machine"



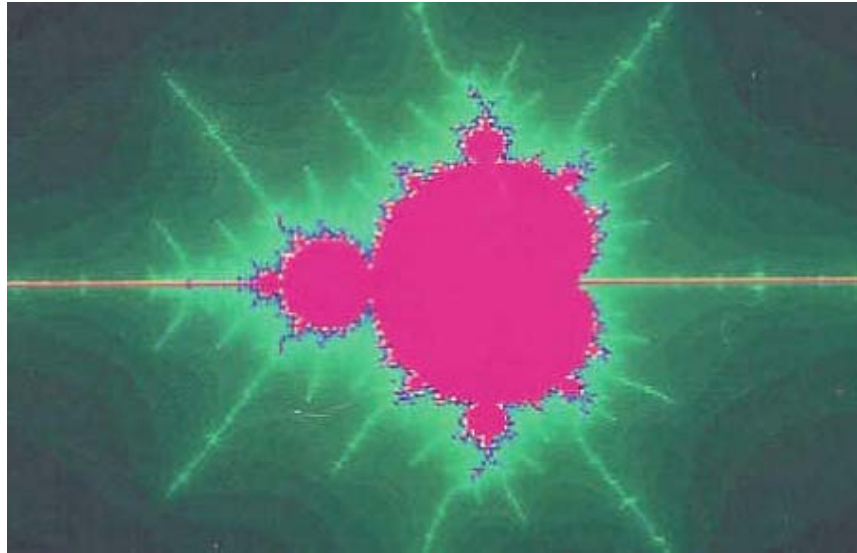
is **Perfectly good Machine** over the **Reals**

A **Problem**_R (X, X_{yes}) is **Decidable** if there is a **Machine** over **R** such that...



So, now can formally pose Penrose's question
(over the **Reals**): Is (X, X_{yes}) **decidable** over **R**?

Here **R=Reals**, $X=\mathbb{R}^2$ and $X_{\text{yes}} = \text{Mandelbrot Set}$.



*Theorem (Blum, Smale).

The **Mandelbrot Set** is **Undecidable/Reals**

Complexity Theory over a Ring

For $x \in R^\infty = \cup R^n$

Size $x=n$ if $x \in R^n$ (vector length)

Time_M(x) = # of nodes from *input* to *output*

$(X, X_{\text{yes}}) \in P_R$ if \exists **Decision Machine** M & **poly**
such that for each $x \in X$, $T_M(x) < \text{poly}(\text{size } x)$

$(X, X_{\text{yes}}) \in NP_R$ if $\exists (Y, Y_{\text{yes}}) \in P_R$ & **poly**
such that for each $x \in X$, \exists **witness** $w \in R^{\text{poly}(\text{size } x)}$
 $[x \in X_{\text{yes}} \iff (x, w) \in Y_{\text{yes}}]$

If $R = Z_2 = \{0, 1\}$ then $T_M(x) \sim$ bit cost and so,
recover classical complexity theory,

i.e. $P_{Z_2} = P_{\text{(classical)}}$ and $NP_{Z_2} = NP_{\text{(classical)}}$

• Let HN_R be the problem of deciding whether or not a given polynomial system over R has a solution (zero) over R .

So, $HN_R = (X, X_{yes})$ where

$$X = \{f^* = (f_1, \dots, f_m) \mid f_i \in R[x_1, \dots, x_n], m, n > 0\}$$

$$X_{yes} = \{f \in X \mid \exists \zeta \in R^n, f_i(\zeta_1, \dots, \zeta_n) = 0, i=1, \dots, m\}$$

• $HN_R \in NP_R$:

If $f = (f_1, \dots, f_m) \in X_{yes}$ then $\exists w \in R^n$ such that $f_i(w_1, \dots, w_n) = 0, i=1, \dots, m$

(w =witness and checking that $f(w)=0$ is poly-time)

• **Theorem** (Cook/Levin '71) $P = NP \Leftrightarrow SAT \in P$

• **Theorem** (Karp '72) $P = NP \Leftrightarrow TSP^* \in P$

*or Hamiltonian circuit or any of 19 other problems.

• **Theorem** (BSS '89) $P_R = NP_R \Leftrightarrow HN_R \in P_R$
where $R = \mathbb{Z}_2$ or the reals \mathbb{R} or the complex
#s \mathbb{C} or...any field.

Proof* Given $(X, X_{yes}) \in NP_R$ and instance $x \in X$,

Code (in poly-time): $x \rightarrow f_x$ (poly system/ R)

such that $x \in X_{yes} \Leftrightarrow f_x$ has a zero over R .

(*Poly-time Reduction)

• **Theorem** (Cook/Levin '71) $P = NP \Leftrightarrow SAT \in P$

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where $R = \mathbb{Z}_2$ or the reals R or the complex
#s \mathbb{C} or....any field.

So, HN_R is Universal NP-complete Problem.



New Problem: Does $P_R = NP_R$?

*Complexity and **Real** Computation*

(BCSS, 98, Springer-Verlag)

Preface by **Dick Karp** (last paragraph):

“It is interesting to speculate as to whether the questions of *whether* $\mathbf{P}_R = \mathbf{NP}_R$ and *whether* $\mathbf{P}_C = \mathbf{NP}_C$ are related to each other and to the *classical* **P versus NP question**.

... I am inclined to think that the three questions are very different and need to be attacked independently. ...”

But... Transfer Principles (BCSS)

Transfer (of complexity results) from one domain to another.

Theorem_(BCSS) $P_C = NP_C \Leftrightarrow P_{\tilde{Q}} = NP_{\tilde{Q}} \Leftrightarrow P_K = NP_K$

(K is algebraically closed and of characteristic 0)

Theorem $P_C = NP_C \Rightarrow BPP \supseteq NP$

Pascal Koiran

(hidden in '93 paper) ...



• **Transfer Results** provide important **connections** between the **two** approaches to computing.

Transfer Principles (BCSS)

Transfer (of complexity results) from one domain to another.

Theorem_(BCSS) $P_C = NP_C \Leftrightarrow P_{\tilde{Q}} = NP_{\tilde{Q}} \Leftrightarrow P_K = NP_K$

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Theorem $P_C = NP_C \Rightarrow BPP \supseteq NP$

Proof

1. \leftarrow

2. \rightarrow

1. $NP \subseteq \text{BooleanPart}(NP_C)$ via $x(x-1)$

2. $BP(P_C) \subseteq BPP$ via coin tosses:

Can eliminate **complex constants** probabilistically with **small number** of **small numbers** (Use **Schwartz's Lemma** and **Prime Number Theorem**.)



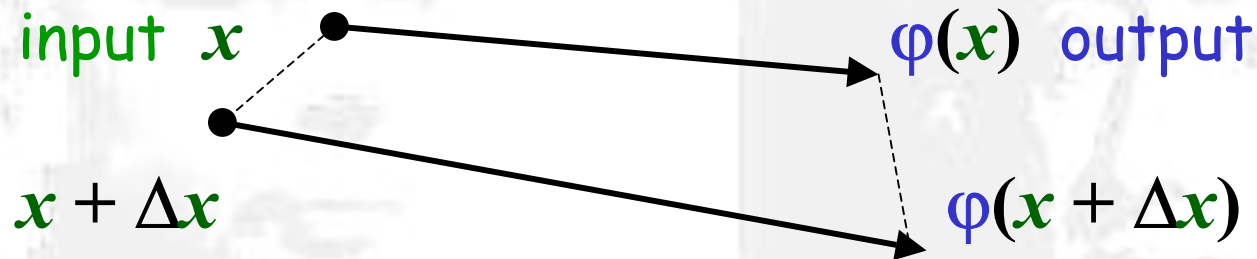
Introducing Condition and Round-off into Complexity Theory

or where

Turing meets Newton!

Introducing Condition and Round-off into Complexity Theory *or where* Turing meets Newton!

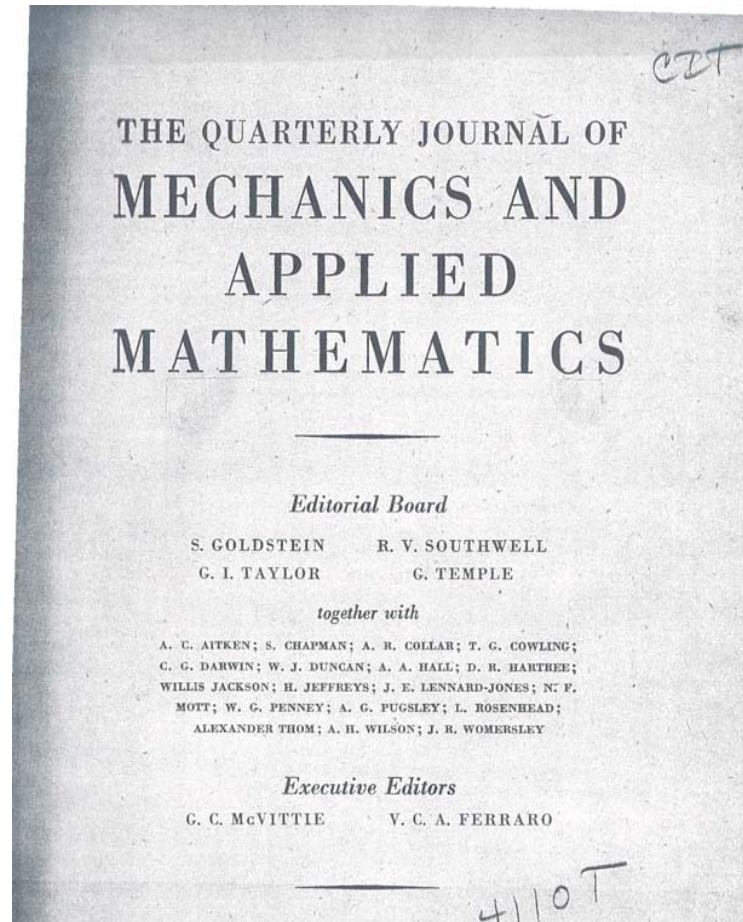
The **condition** of a problem (instance) measures how small perturbations of the **input** will alter the **output**.



$$\frac{\|\phi(x + \Delta x) - \phi(x)\|}{\|\Delta x\|} \quad \text{or } \textit{relative} \quad \frac{\|\phi(x + \Delta x) - \phi(x)\|}{\|\Delta x\|} / \frac{\|\phi(x)\|}{\|x\|}$$

If quotient is **large**, instance is **ill-conditioned** so requires more accuracy and hence more resources to compute with small error.

Return
again to...



*The Quarterly Journal of Mechanics and
Applied Mathematics, vol. I, 1948*

ROUNDING-OFF ERRORS IN MATRIX PROCESSES

By A. M. TURING

(National Physical Laboratory, Teddington, Middlesex)

[Received 4 November 1947]

SUMMARY

A number of methods of solving sets of linear equations and inverting matrices are discussed. The theory of the rounding-off errors involved is investigated for some of the methods. In all cases examined, including the well-known 'Gaussian elimination process', it is found that the errors are normally quite moderate: no exponential build-up need occur.

Included amongst the methods considered is a generalization of Choleski's method which appears to have advantages over other known methods both as regards accuracy and convenience. This method may also be regarded as a rearrangement of the elimination process.

This paper contains descriptions of a number of methods for solving sets of linear simultaneous equations and for inverting matrices, but its main concern is with the theoretical limits of accuracy that may be obtained in the application of these methods, due to rounding-off errors.

The best known method for the solution of linear equations is Gaussian

$$(8.1) \quad \begin{array}{rcl} 1.4x + & 0.9y & = 2.7 \\ -0.8x + & 1.7y & = -1.2 \end{array}$$

$$(8.2) \quad \begin{array}{rcl} -0.786x + 1.709y & = & -1.173 \\ -0.8 \ x + 1.7 \ y & = & -1.2 \end{array}$$

The set of equations (8.2) is *fully equivalent* to (8.1), but clearly if we attempt to solve (8.2) by numerical methods involving rounding-off errors we are almost certain to get much less accuracy than if we worked with equations (8.1).

We should describe the equations (8.2) as an *ill-conditioned* set, or, at any rate, as ill-conditioned compared with (8.1). It is characteristic of ill-conditioned sets of equations that small percentage errors in the coefficients given may lead to large percentage errors in the solution.

$$(8.1) \quad \begin{array}{rcl} 1.4x + 0.9y & = & 2.7 \\ -0.8x + 1.7y & = & -1.2 \end{array}$$

$$(8.2) \quad \begin{array}{rcl} -0.786x + 1.709y & = & -1.173 \\ -0.8x + 1.7y & = & -1.2 \end{array}$$

The set of equations (8.2) is *fully equivalent* to (8.1), but clearly if we attempt to solve (8.2) by numerical methods involving rounding-off errors we are almost certain to get much less accuracy than if we worked with equations (8.1).

$$3^{\text{rd}} \text{equation} = .01(1^{\text{st}} \text{equation}) + 2^{\text{nd}} \text{equation}$$

Will illustrate reconciliation of 2 Traditions with

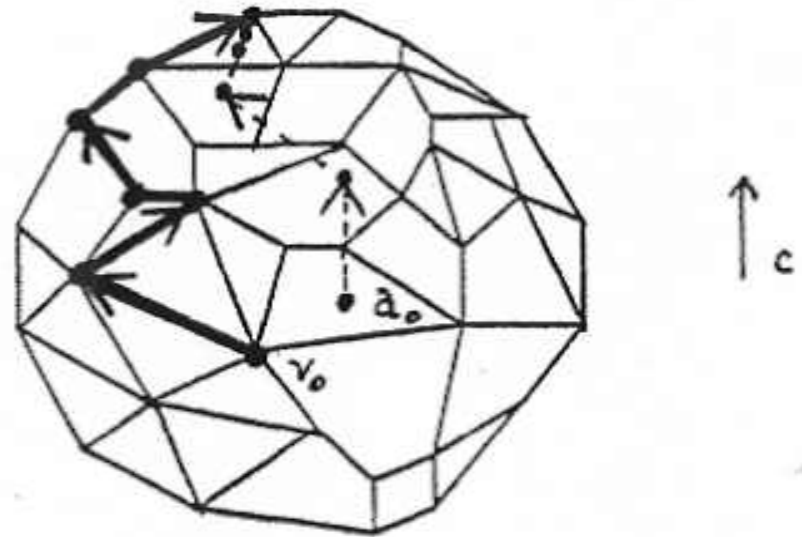
My Favorite Example

Linear Programming Problem

- $\max \quad c \cdot x$
- such that $Ax \leq b$
- $x \geq 0$

$c \in \mathbb{R}^n$, $b \in \mathbb{R}^m$

A , real $m \times n$ matrix



My Favorite Example

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• Simplex Method (Dantzig '47)
Exponential (n, m) (Klee-Minty '72)

• Ellipsoid Method (Khachiyan '79)
Poly in **Input Word size (in bits)**

• Interior-Point Method (Karmarkar 84)
***Polynomial (input word bit size)**

*Recall, **small** perturbations (of **input**) can cause **large** differences in (**input**) **WordSize**:

$1 \sim 1 + \frac{1}{2}^n$ but **WordSize**(1)=1 \sim **WordSize**($1 + \frac{1}{2}^n$)=n+1

My Favorite Example

Linear Programming Problem

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***Polynomial (input word bit size)**

Not paying attention to the distinction between these **metrics** has caused both an incompleteness in the **analysis** and a confusion in the **comparison** of different algorithms for the **LPP**.

Condition Numbers and Complexity

Linear Systems: Given $Ax=b$. Solve for x .

Turing: $\kappa(A) = ||A|| ||A^{-1}||$

• **Theorem** (Eckart-Young 1936). $\kappa(A) \sim 1/d_F(A, \Sigma)$
where Σ is space of *ill-posed* problem instances. i.e.
 Σ is the space of *non-invertible* matrices, and
distance d_F is wrt the Frobenious norm.



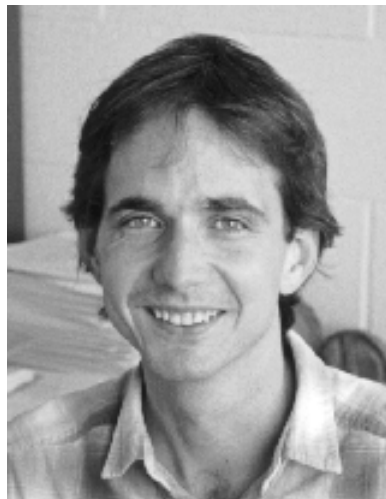
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• Linear Programming: Given $Ax=b, x \geq 0$. Solve for x .
(Blum89) (Renegar95) $C(A, b) = \|(A, b)\| / d((A, b), \Sigma_{m,n})$



$\Sigma_{m,n}$ is the boundary of the space of feasible pairs (A, b)

Condition Numbers and Complexity

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(Blum89)(Renegar95) $C(A, b) = \|(A, b)\| / d((A, b), \Sigma_{m,n})$

• **Theorem** (Renegar Interior Point Algorithm): If feasible, # of iterations to get ϵ -approximation of the optimal value is poly in $n, m, \log C(A, b, c)$ and $|\log \epsilon|$.

• **Theorem** (Cucker-Pena Algorithm with Round-Off): If feasible, produces δ -approx to a feasible point in (bit) time $O((m+n)^{3.5}(\log(m+n) + \log C(A) + |\log \delta|)^3)$. The finest precision required is a *round-off* unit of $1/c(m+n)^{12} C(A)^2$.

Computing over the Reals: Where Turing Meets Newton



~~The END~~