

## **Human Vision**

**PERCEPTION**

# SPATIAL ORIENTATION IN FLIGHT

## Limitations of the Senses

2

**Visual Sense**

**Nonvisual Senses**

# SPATIAL ORIENTATION IN FLIGHT

## Limitations of the Senses

### Visual Sense



### Nonvisual Senses

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# SPATIAL ORIENTATION IN FLIGHT

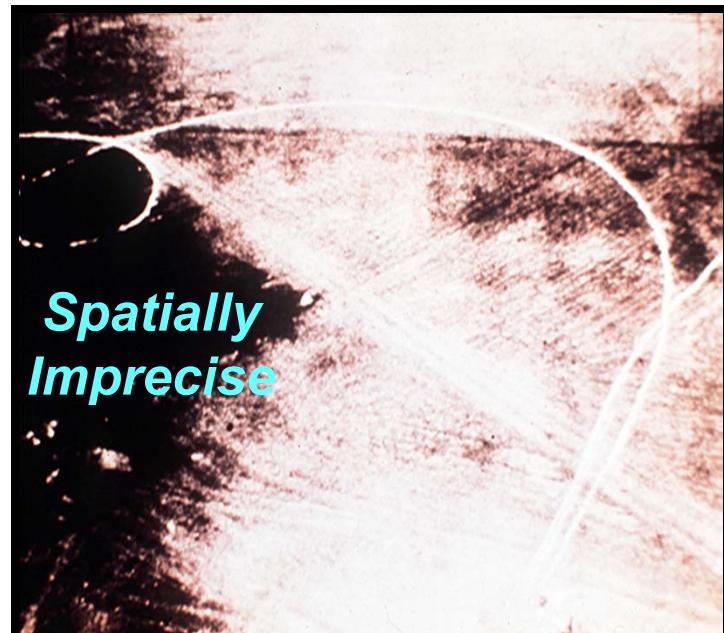
## Limitations of the Senses

### Visual Sense



*Sluggish*

### Nonvisual Senses



*Spatially  
Imprecise*

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# VISUAL ORIENTATION

## 3-D Neurobehavioral Model

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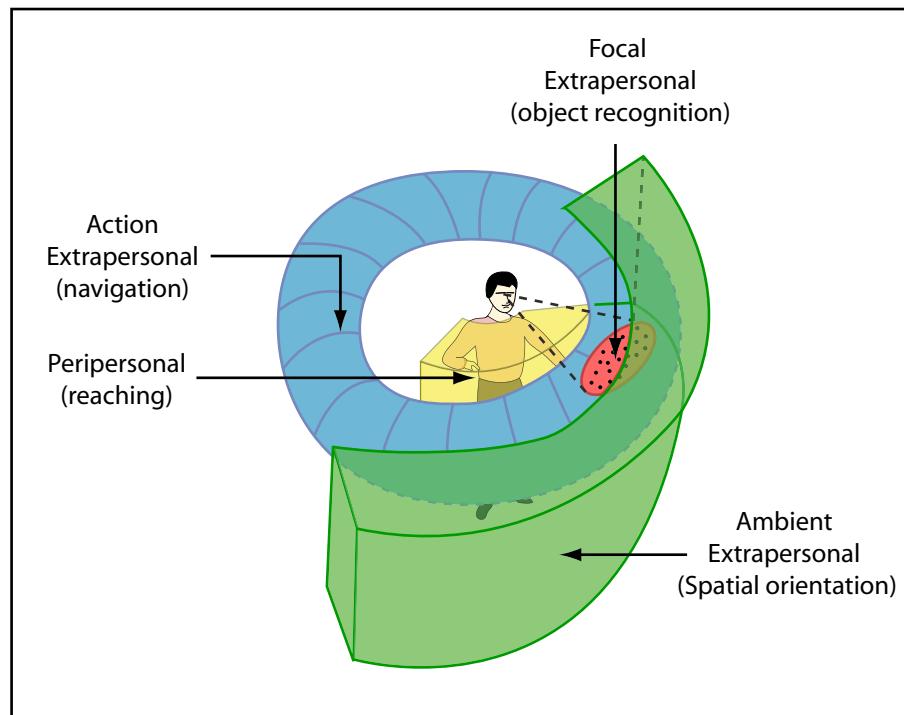


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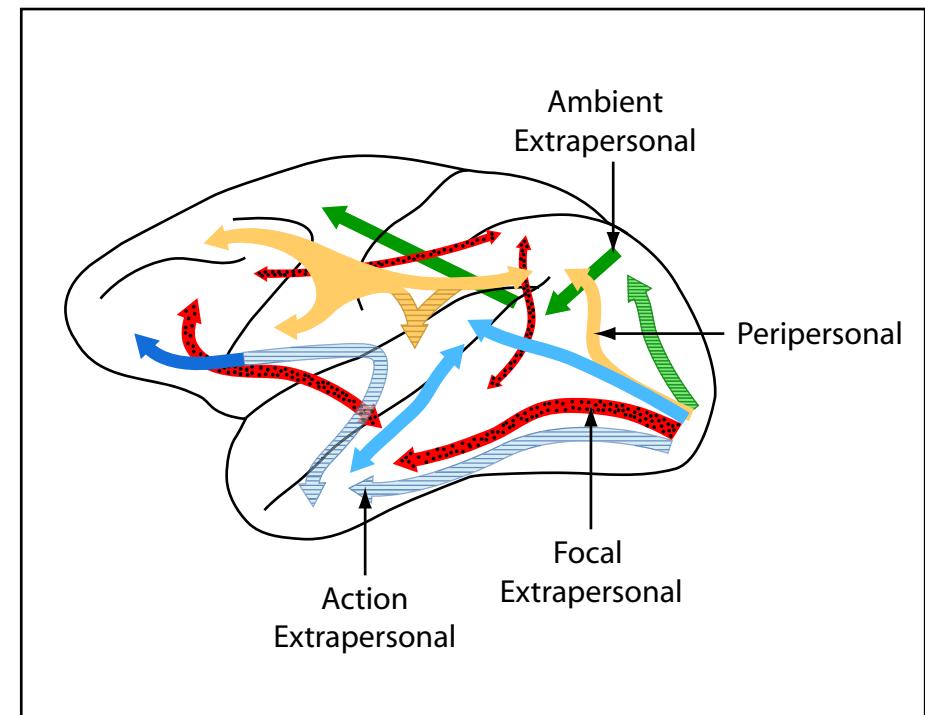


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# VISUAL ORIENTATION

## The Two Visual System Hypothesis

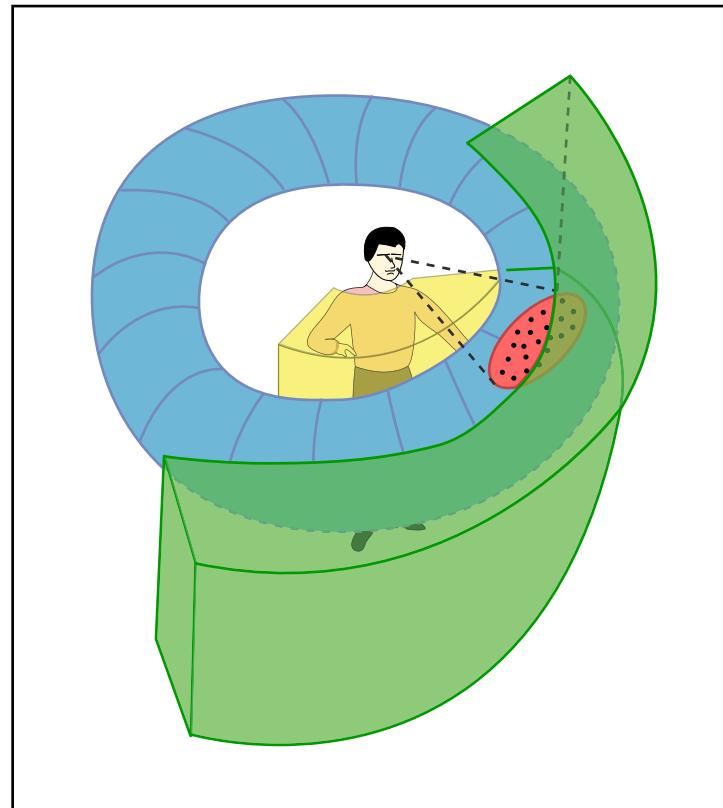


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# VISUAL ORIENTATION

## The Two Visual System Hypothesis

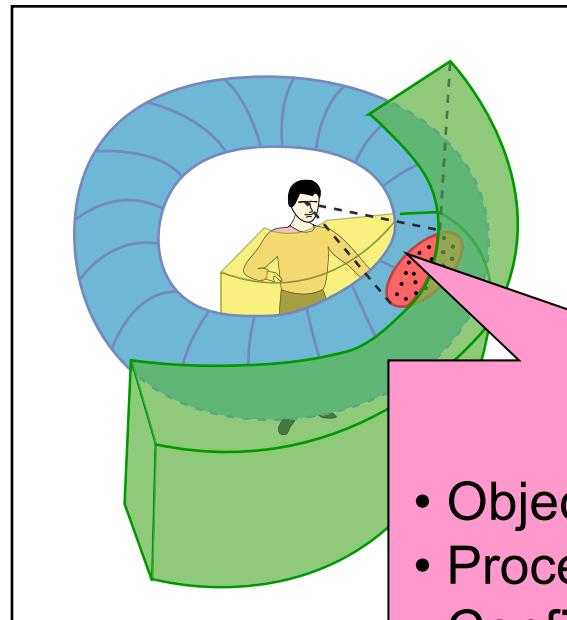


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### Focal Mode

- Object recognition (“*What?*”)
- Processes fine visual details
- Confined to central visual field
- Conscious processing  
(attention demanding)
- “Synthetic” spatial orientation

# VISUAL ORIENTATION

## The Two Visual System Hypothesis

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### Ambient Mode

- Spatial orientation ("Where?")
- Uses coarse visual inputs
- Involves entire visual field
- Preconscious processing (little attention required)
- "Natural" spatial orientation

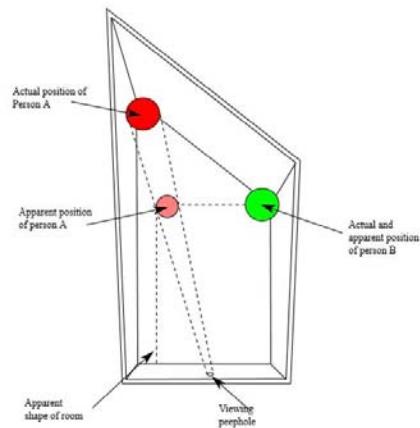
### Focal Mode

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# VISUAL ORIENTATION

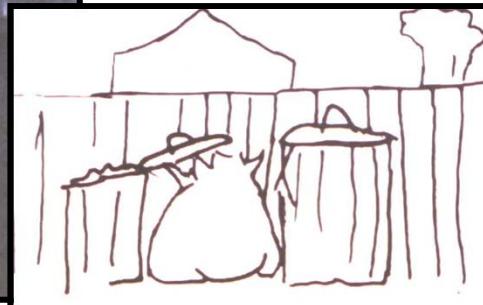
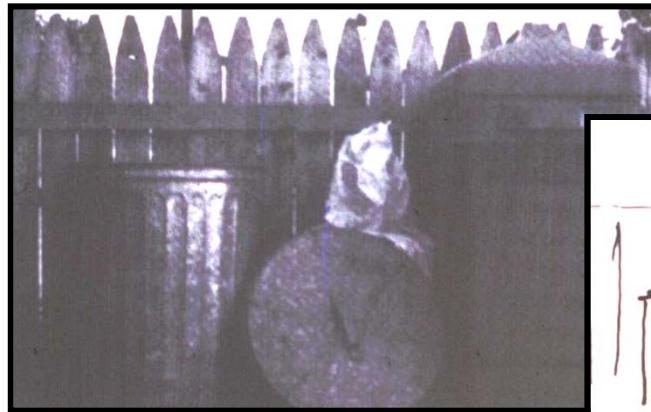
## Alterations of The Ambient Visual Frame

### **Distortion -- *The Ames Room***



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### **Distortion -- *Memory***



### **Absence -- *The “Black Hole” Approach***

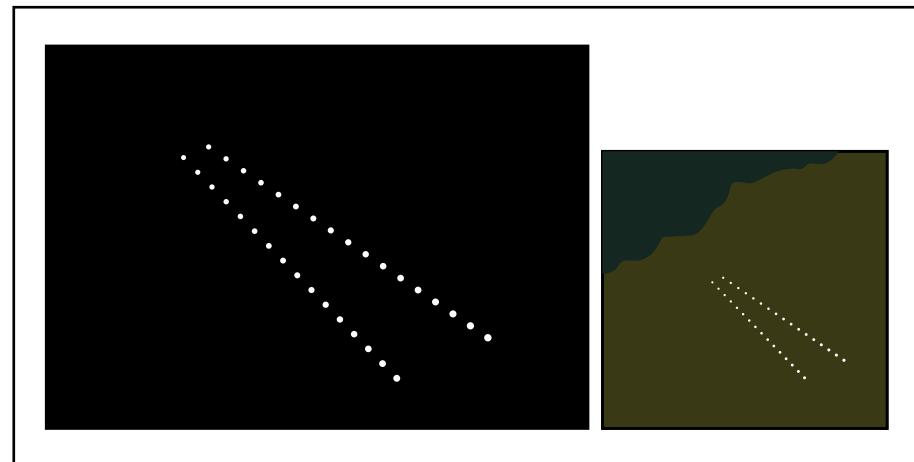


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# VISUAL ORIENTATION

## Ambient Visual Effects (Self-Motion)

### Characteristics of Vection

- Requires large retinal area (including periphery)
- More dependent on background visual field
- Relies on moving textures (sluggish response, low frequency)
- Can occur with optically degraded stimuli

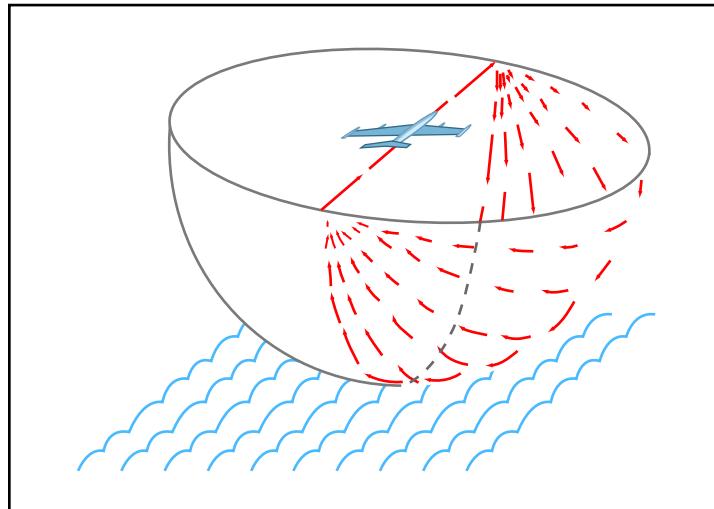


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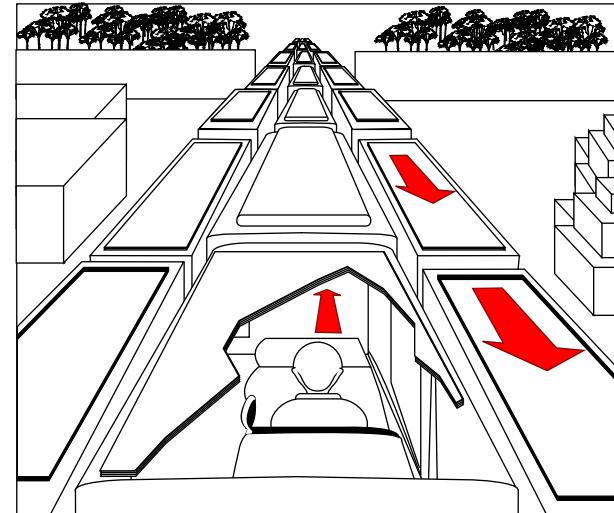


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# VISUAL ORIENTATION

## Ambient Visual Effects (Self-Position)

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### Characteristics of Field-Dependence

- Similar visual requirements asvection (e.g., reliance on background field, can tolerate optical degradation)
- Tilted scenes produce changes in perceived visual vertical, gravitational vertical and posture
- Other position effects (luminance gradients, depth)



***Rod-and-frame***

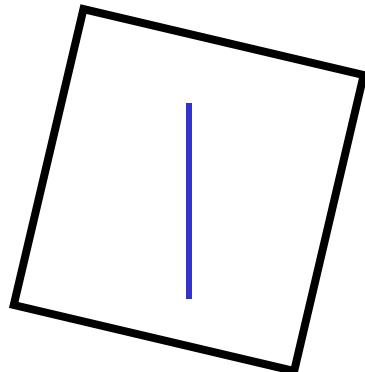
# VISUAL ORIENTATION

## Ambient Visual Effects (Self-Position)

12

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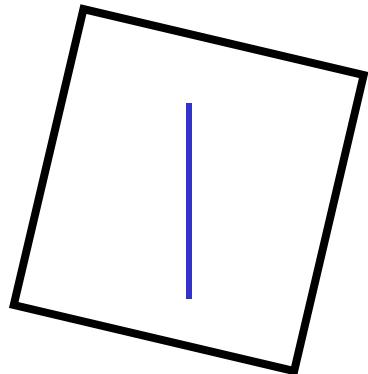
# VISUAL ORIENTATION

## Ambient Visual Effects (Self-Position)

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**Rod-and-frame**



**Postural Effects**

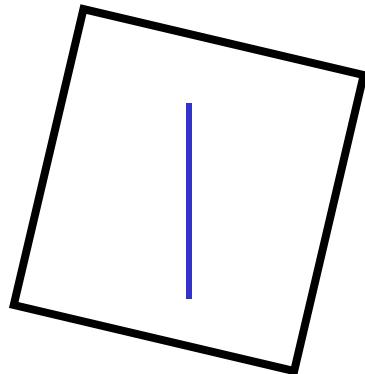
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# VISUAL ORIENTATION

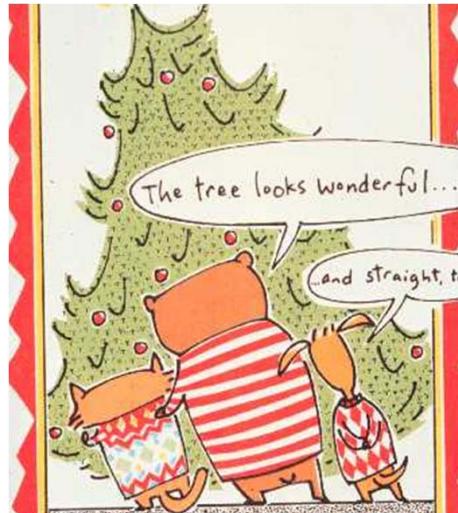
## Ambient Visual Effects (Self-Position)

### Characteristics of Field-Dependence

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**Rod-and-frame**



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**Postural Effects**



**Optokinetic-Cervical Reflex**

# VISUAL ORIENTATION

## Ambient Luminance Gradients

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### Luminance Gradients

- Light-to-Dark Gradient Important in Judging Visual Vertical
- Gradient Inversions Caused by
  - Low Sun Angles
  - Clouds
  - Terrain Shadowing
  - Lunar Reflections
- Can Result in Inversion Illusions



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# VISUAL ORIENTATION

## Ambient Luminance Gradients

16

### Luminance Gradients

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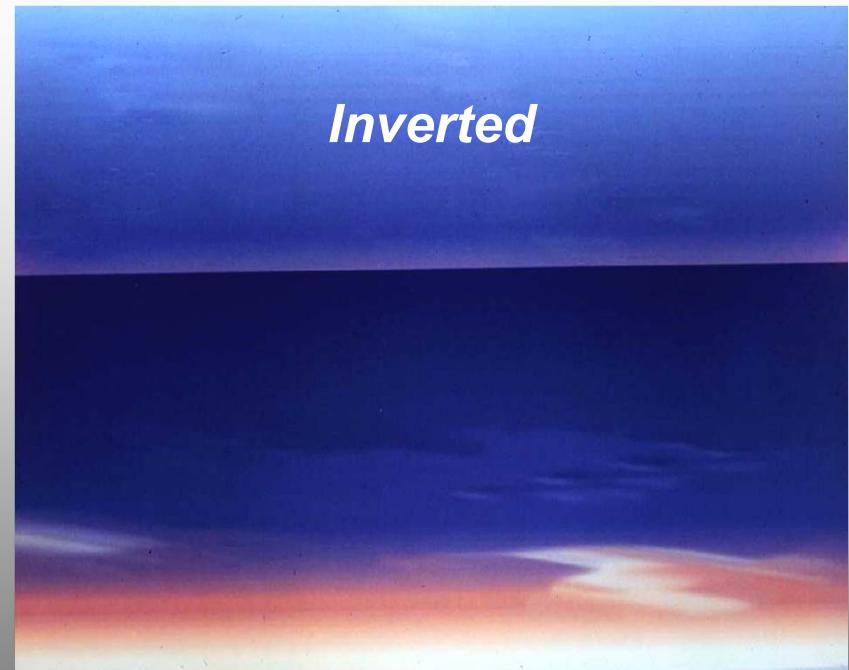
# VISUAL ORIENTATION

## Ambient Luminance Gradients

17

### Luminance Gradients

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# VISUAL ORIENTATION

## Ambient Luminance Gradients

18

### Luminance Gradients

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# VISUAL ORIENTATION

## Ambient Visual Cues to Depth

19

### Ambient Depth Cues

- Linear perspective/foreshortening
- Gradient of texture
- Motion parallax
- Illumination
- Aerial perspective



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#### ***Linear perspective***

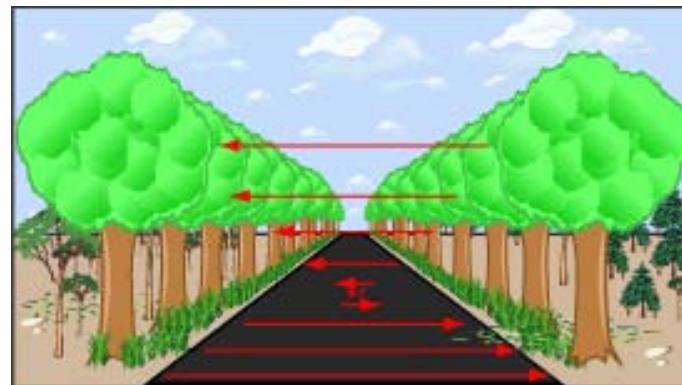


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#### ***Aerial perspective***

#### ***Motion parallax***

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# VISUAL ORIENTATION

## Ambient Visual Cues to Depth

20

### Linear Perspective & Gradient of Texture

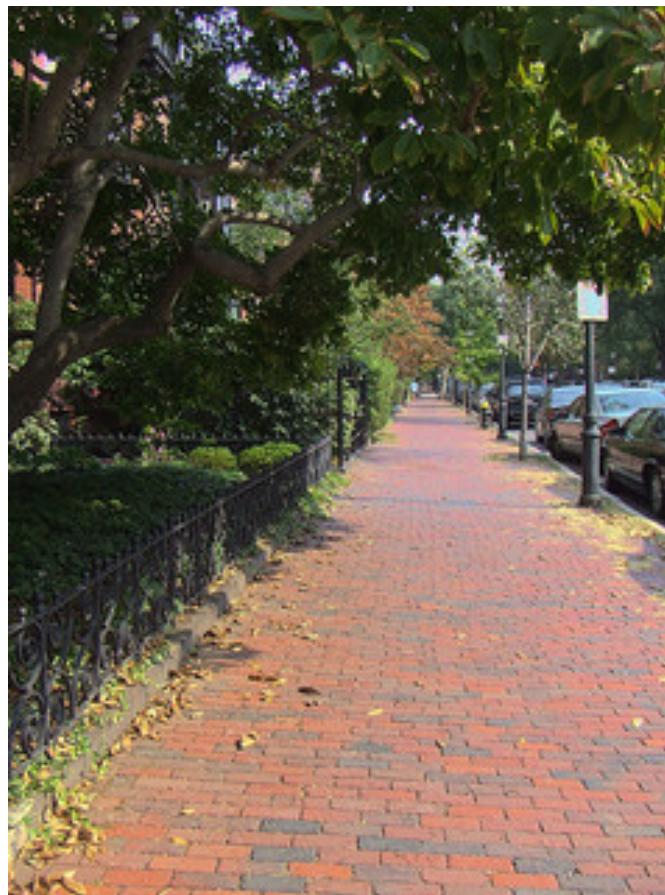


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# VISUAL ORIENTATION

## Ambient Visual Cues to Depth

21

### Ambient Depth Cues

- Linear perspective/foreshortening
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#### Linear perspective

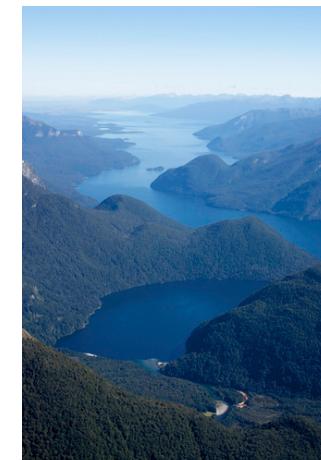


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#### Aerial perspective

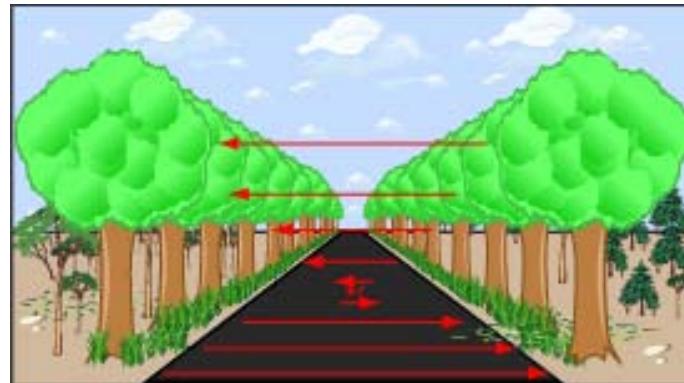


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#### *Motion parallax*

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# VISUAL ORIENTATION

## Ambient Visual Cues to Depth

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### Motion Parallax

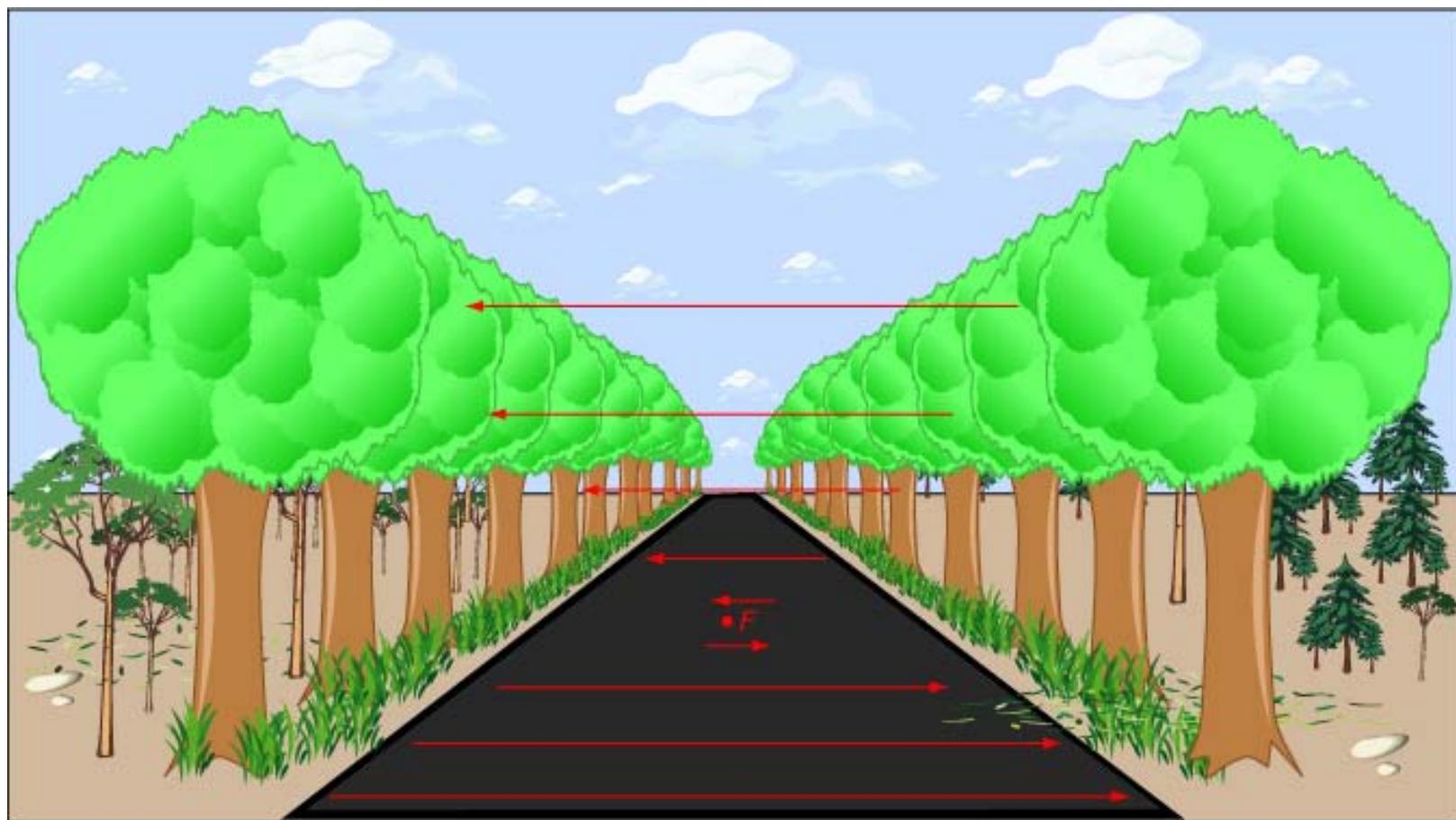


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# VISUAL ORIENTATION

## Ambient Visual Cues to Depth

23

### Ambient Depth Cues

- Linear perspective/foreshortening
- Gradient of texture
- Motion parallax
- Illumination
- Aerial perspective



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#### Linear perspective



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#### Aerial perspective

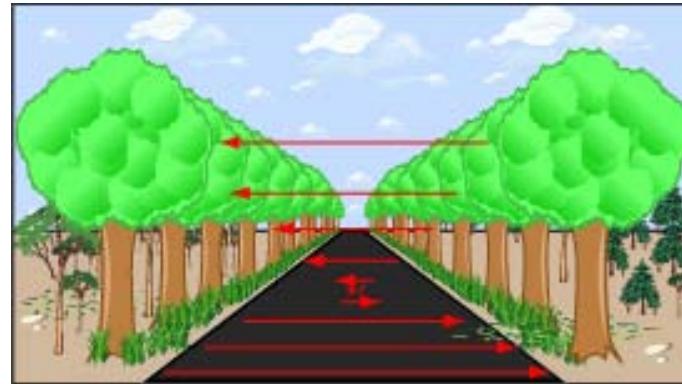


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#### *Motion parallax*

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# VISUAL ORIENTATION

## Ambient Visual Cues to Depth

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### Aerial Perspective

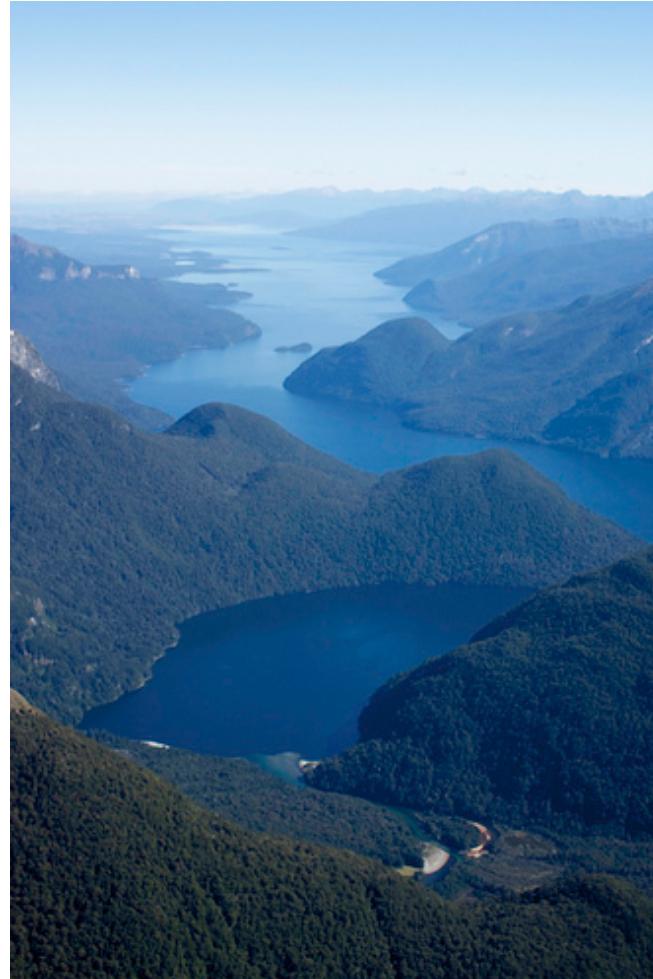


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# VISUAL ORIENTATION

## Focal Visual Effects

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### Size and Shape Constancies

Rigidity is considered to be a fundamental property of objects; therefore, deviations in the size and shape of ground objects are perceived as changes in our orientation relative to the ground



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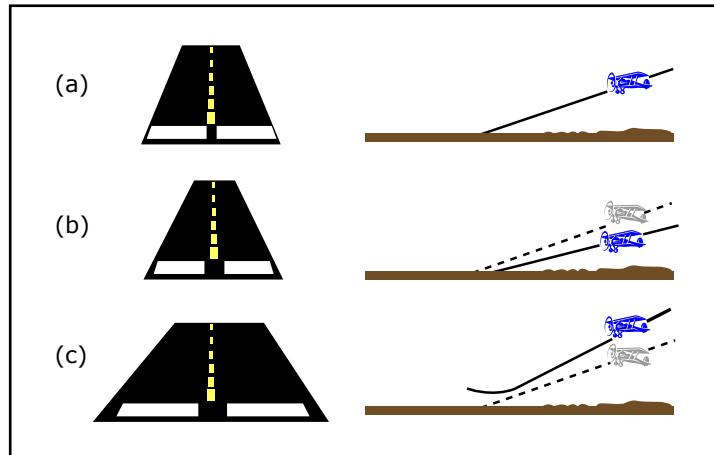


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### Size Constancy

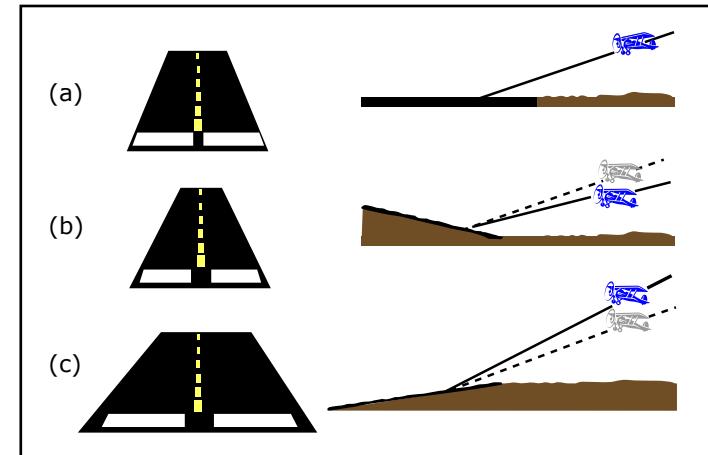


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### Shape Constancy

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# VISUAL ORIENTATION

## Focal Visual Effects

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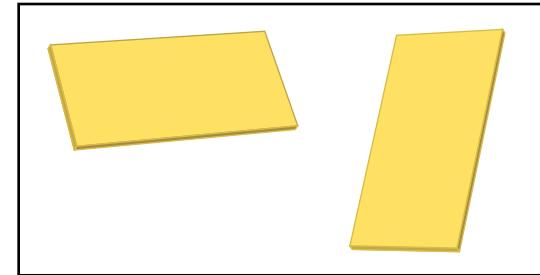


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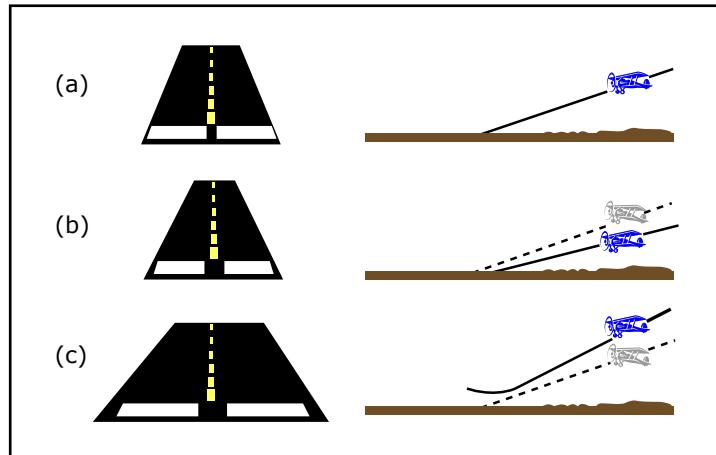


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### Size Constancy

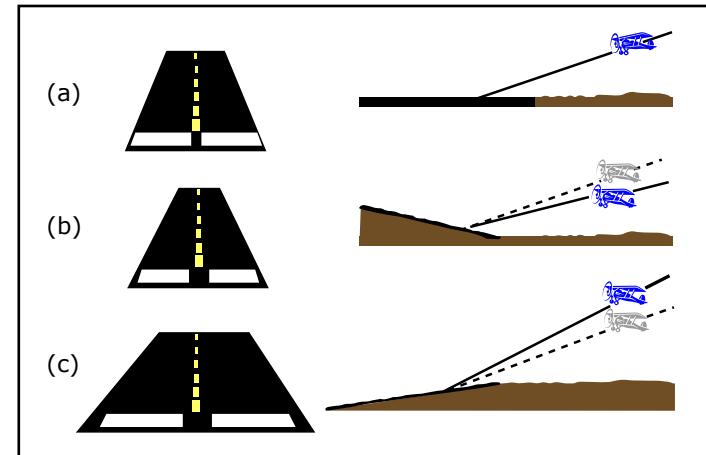


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### Shape Constancy

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# VISUAL ORIENTATION

## Focal Visual Effects

27

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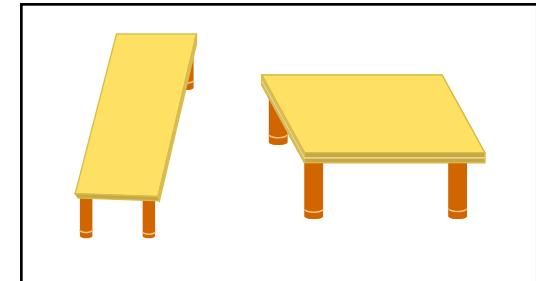


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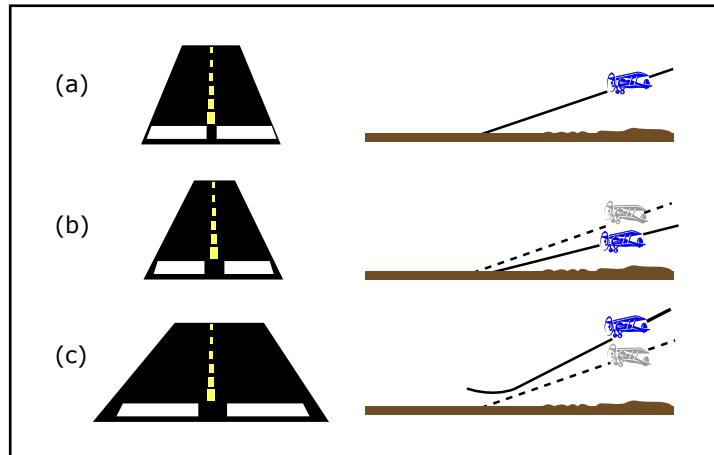


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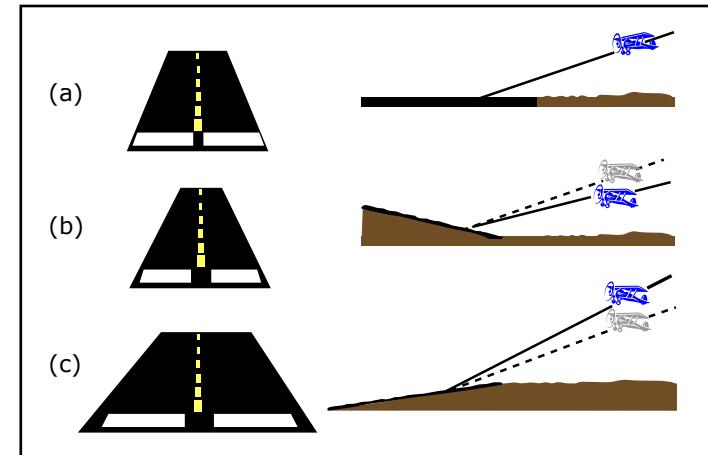


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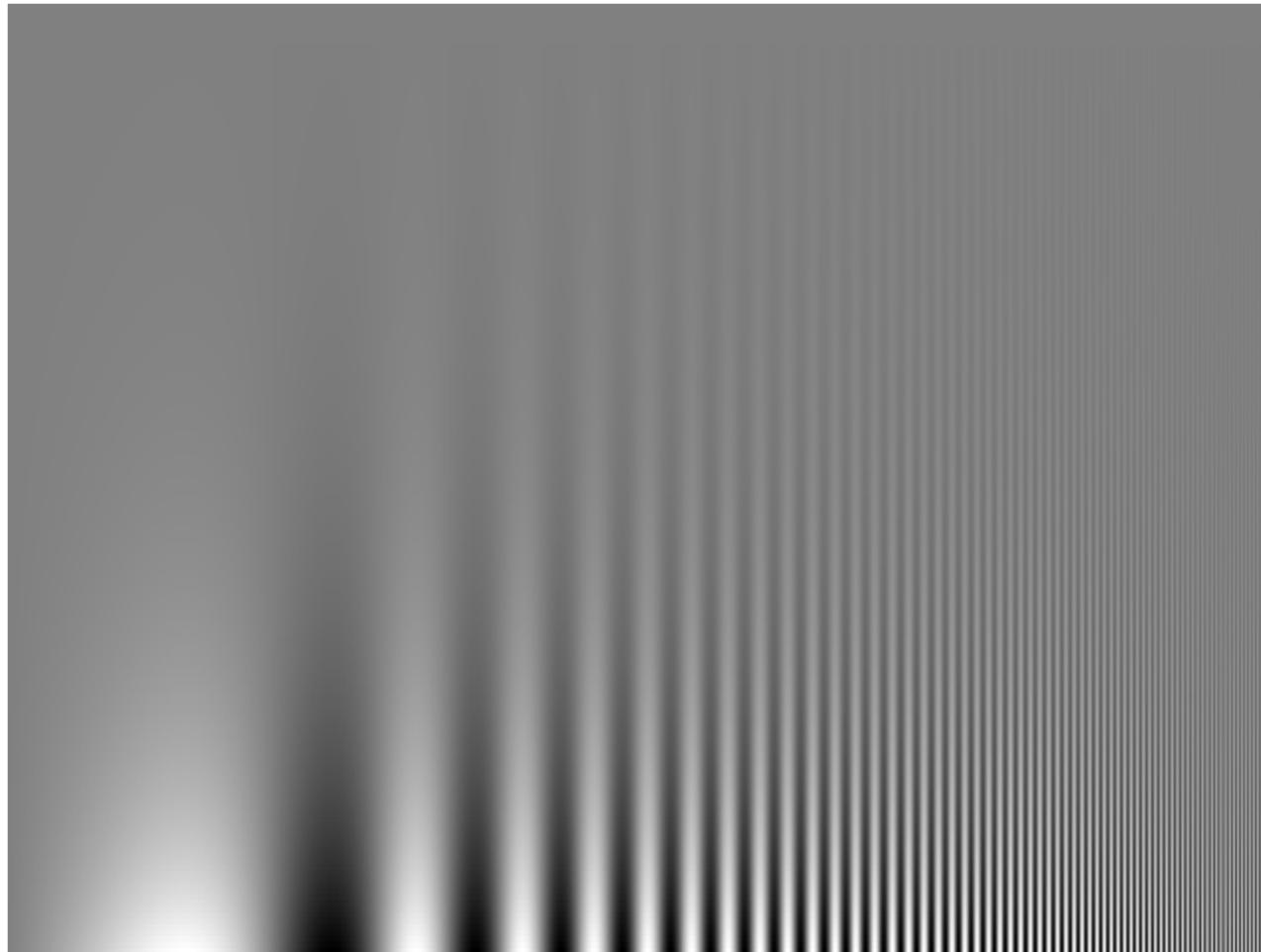
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# Contents

- Introduction
- Contrast & Frequency
- Visual Pathway, Visual Image
- Receptive Fields, Gestalt
- Color, Color deficits, after images
- Size of objects

# Spatial Frequency and Contrast

Contrast amplitude



Spatial frequency of grid

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# Optic nerve - from eye to brain

- Left visual field  
-> right brain side
- Right visual field  
-> left brain side
- Retina  $11\text{cm}^2$
- Optic nerve diameter 2mm
- convergence  
receptors ->ganglion
- divergence  
optic nerv -> visual cortex

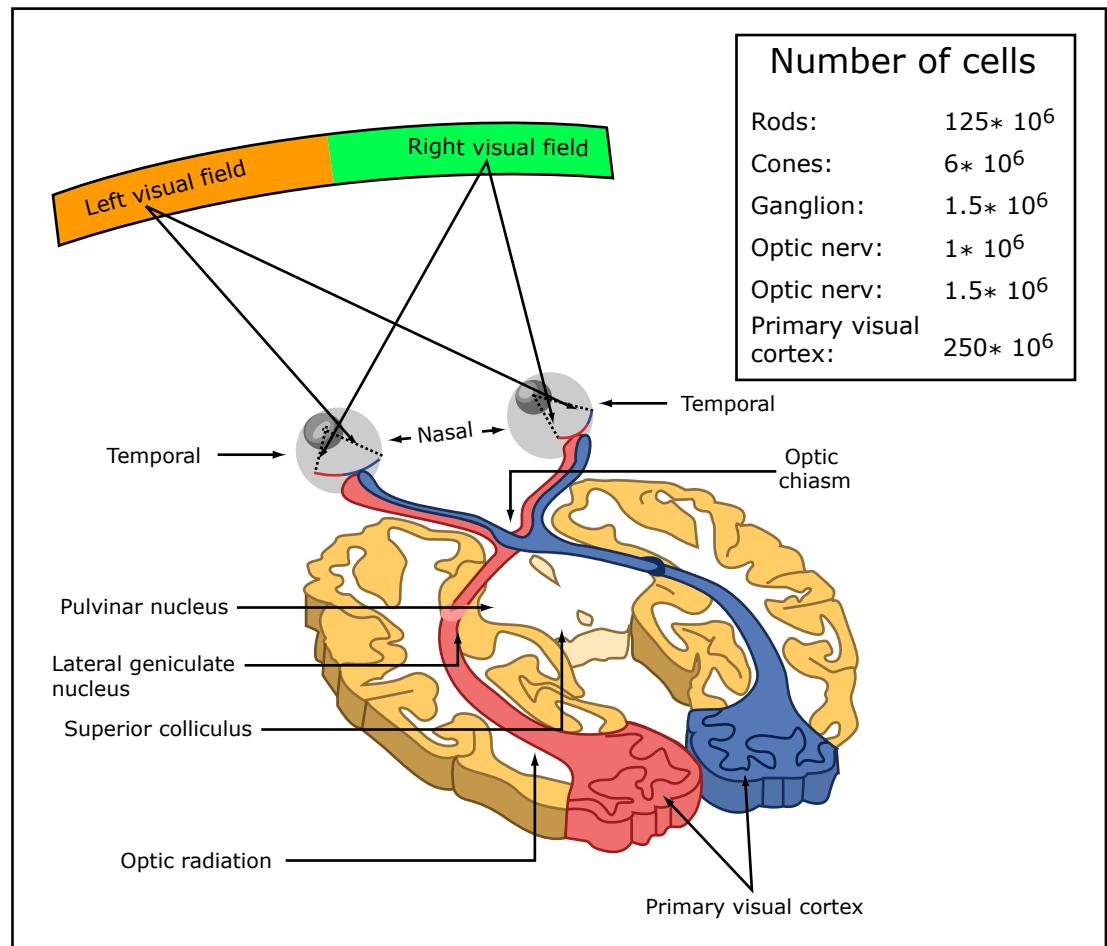


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# Rod and cone density

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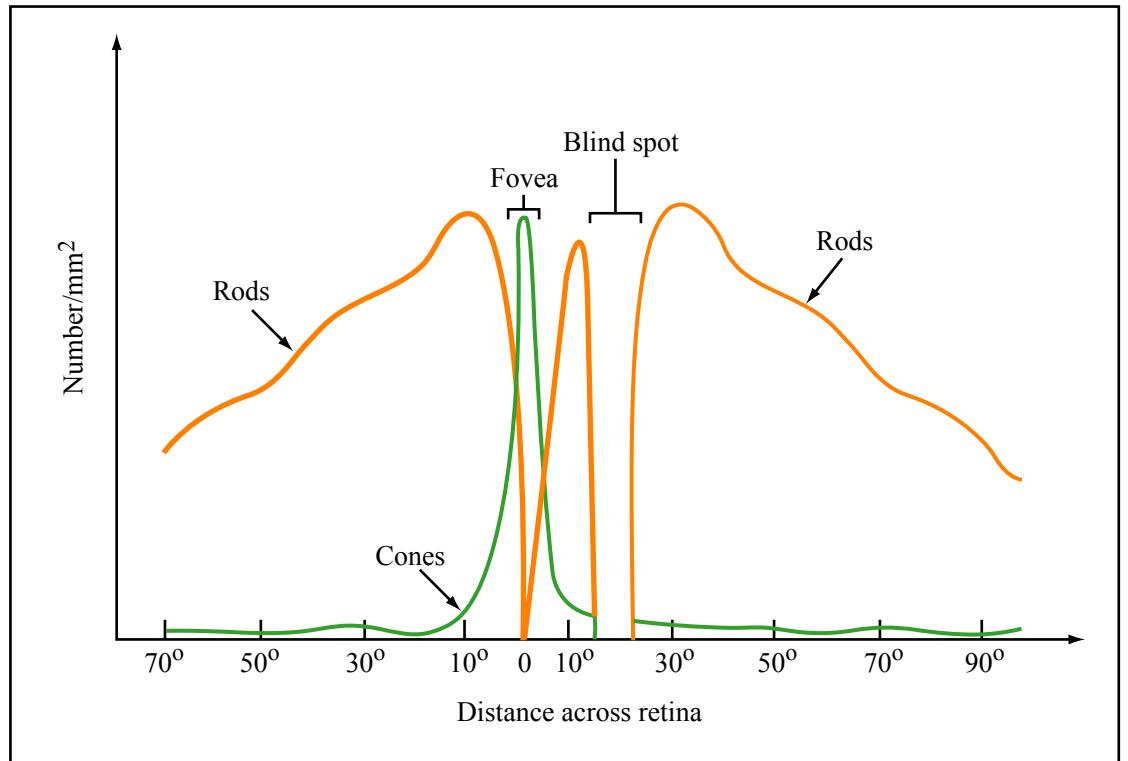


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- On average 120 rods converge on 1 ganglion cell
- On average 6 cones converge on 1 ganglion cell

# Image properties

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- Image quality created by retina is not homogenous
- Color vision mainly in fovea
- Resolution decreases in periphery
  - Best resolution for color in the fovea
  - Best resolution for b/w  $20^\circ$  parafovea

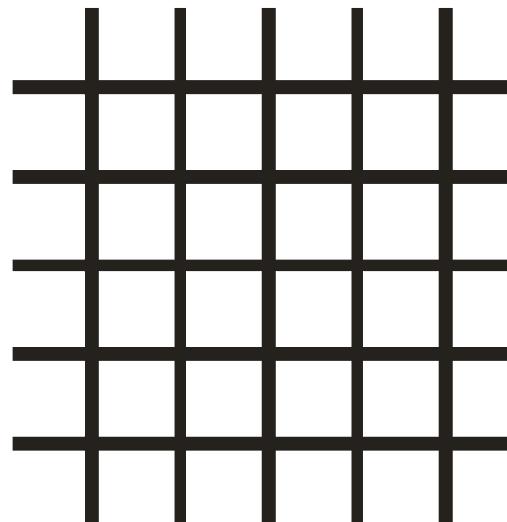
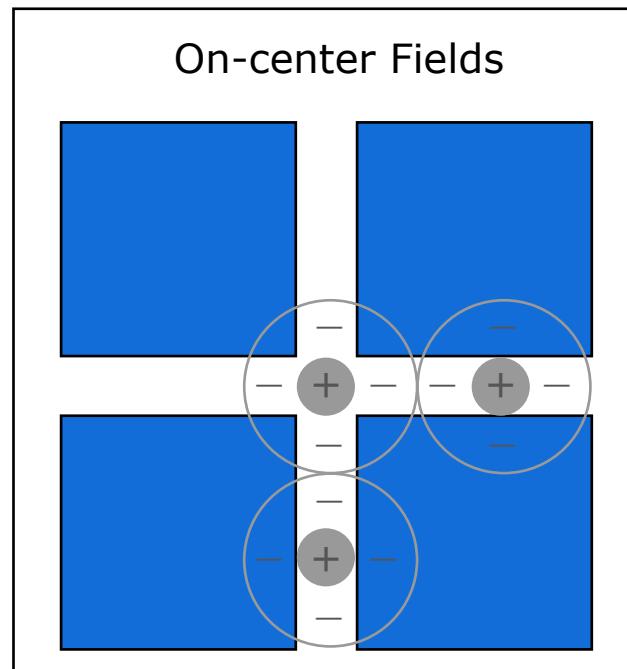
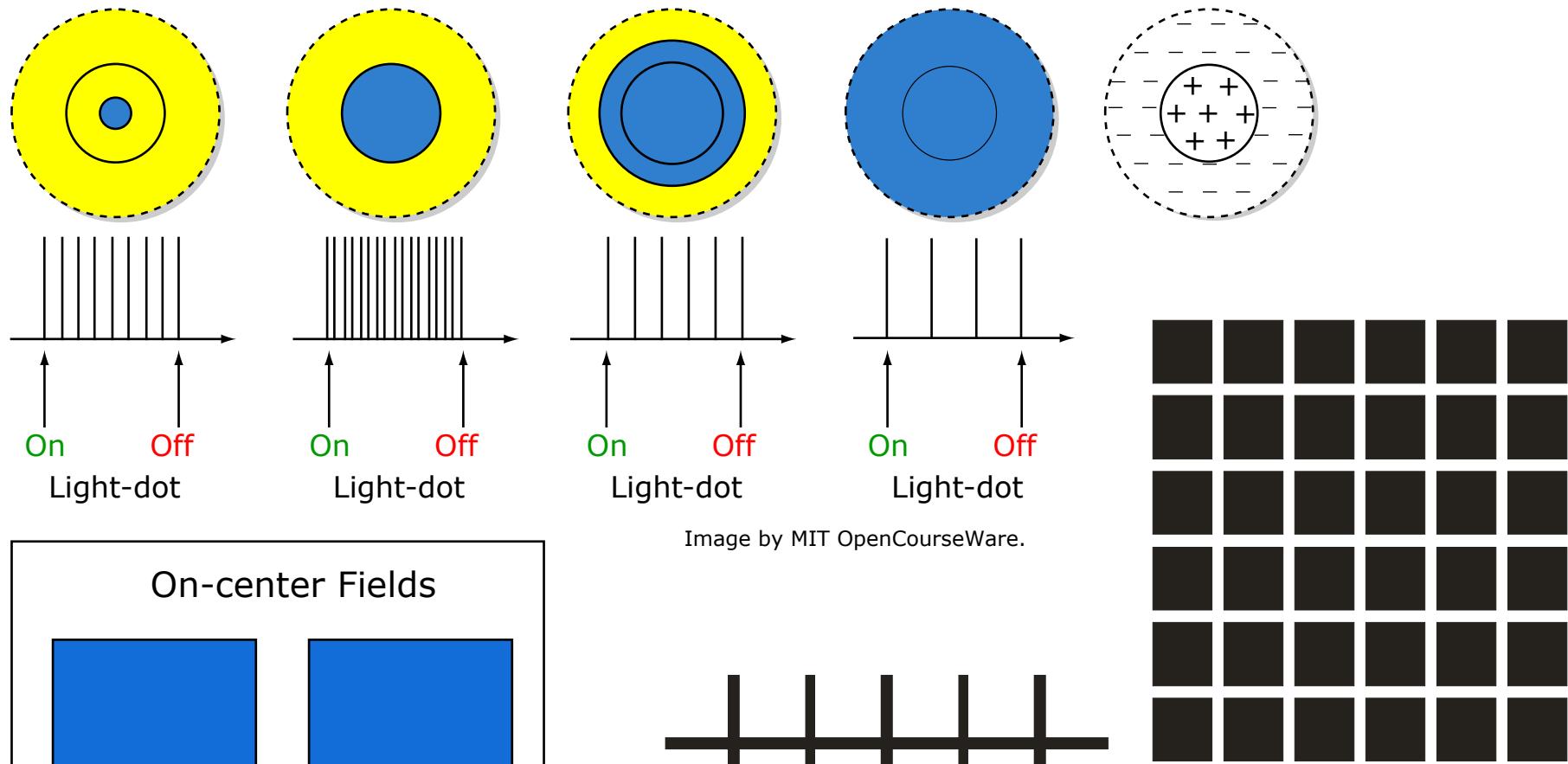
L C C M A O  
C X A T  
A I I Y E S T • A I G R  
F N O N N T  
C I I T

# Questions

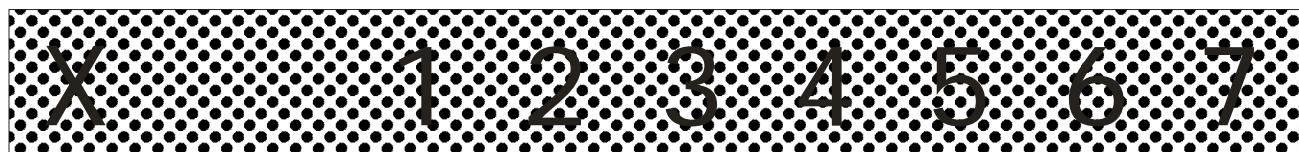
- How come that we perceive such a nice and homogenous image of our surrounding?
- What happened to the blind-spot hole?
- Why do we perceive color in the periphery?

# Receptive Fields

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# Filling the blind spot



- Close your left eye and fixated with the right eye the X. Which number is missing? What is the color pattern at the position of the missing number?
- The blind spot is filled with the surrounding pattern.

# Figure and background

- The total visual input is organized into figures and background.
- The Gestalt-laws describe principles how figure and ground are separated.
- **Figures** are in front, have a border, connected, “things”.
- The **background** is behind the figure, without border, uninterrupted, homogenous.

# Gestalt-laws

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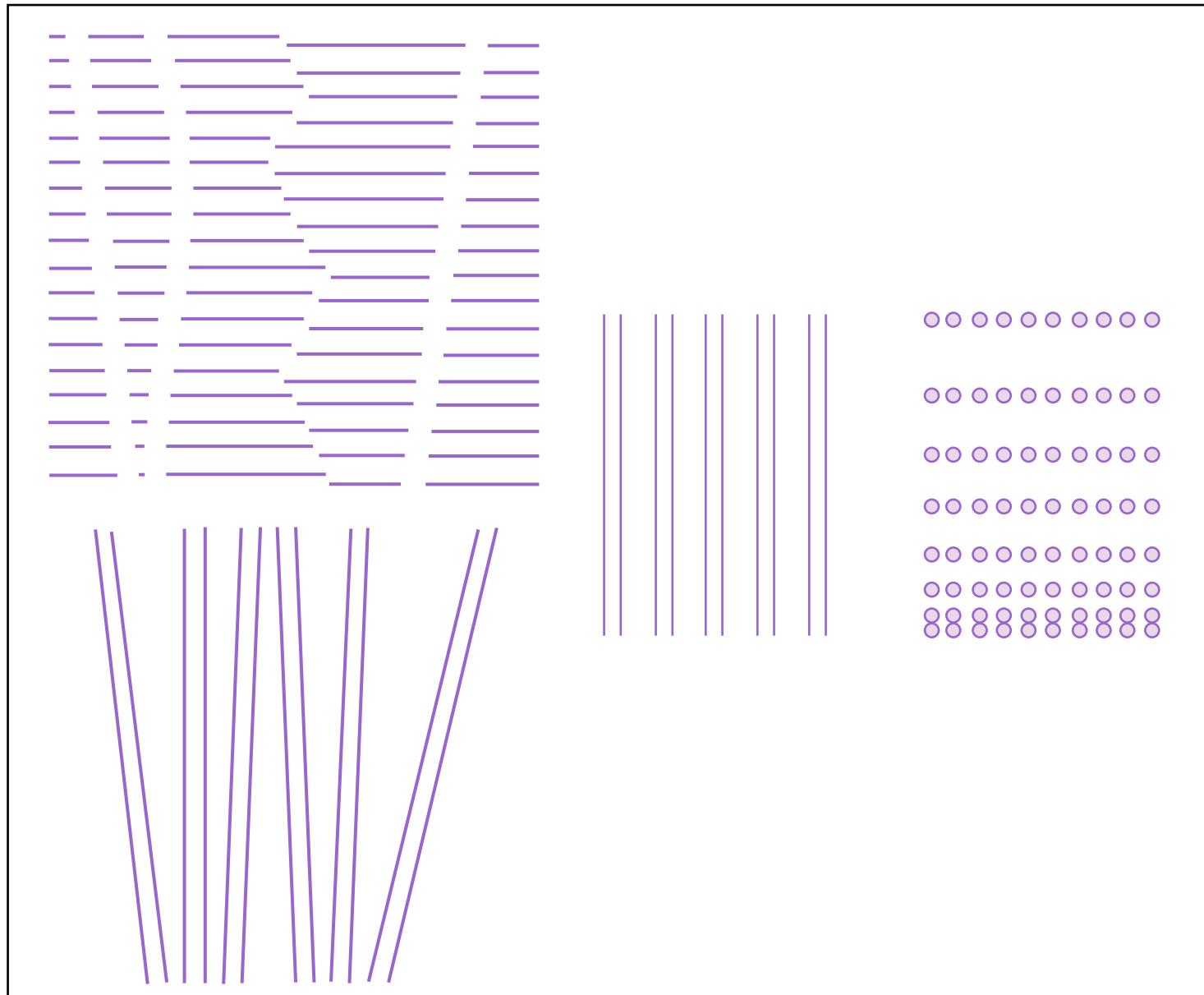


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# Perceptual categories

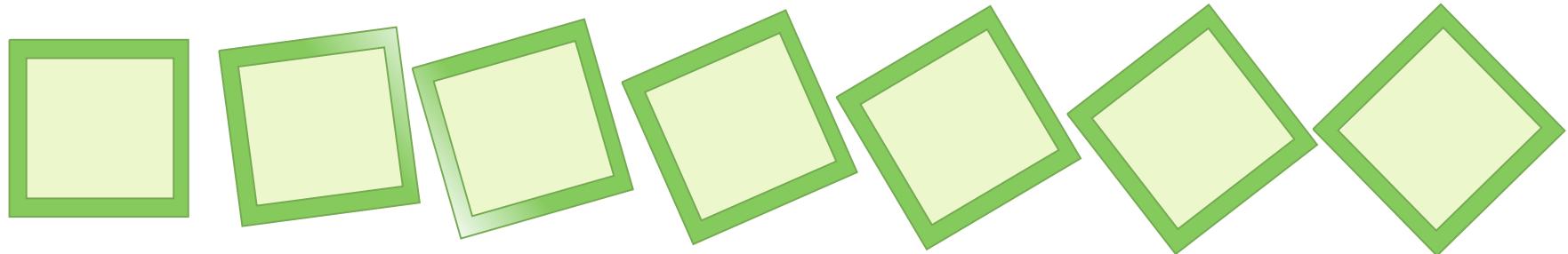


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Square.....Diamond

- The shapes in-between are neither square nor diamond.
- Our perception is organized in categories, even if the stimuli are continuous.

# Perceptual categories: Reproducing shapes

- Figure in B is the drawing when the shape of the Figure A is given as a tactile stimulus (without vision).

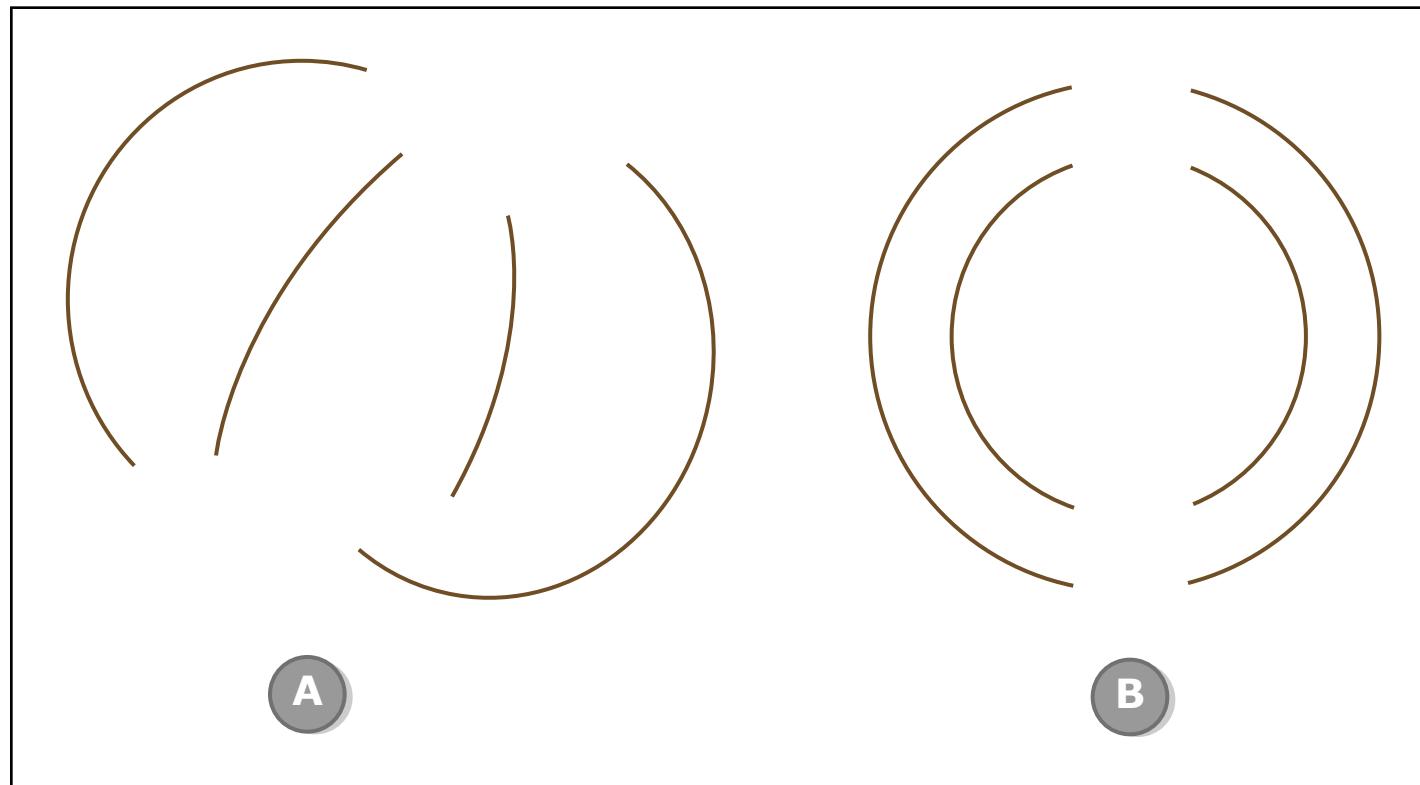
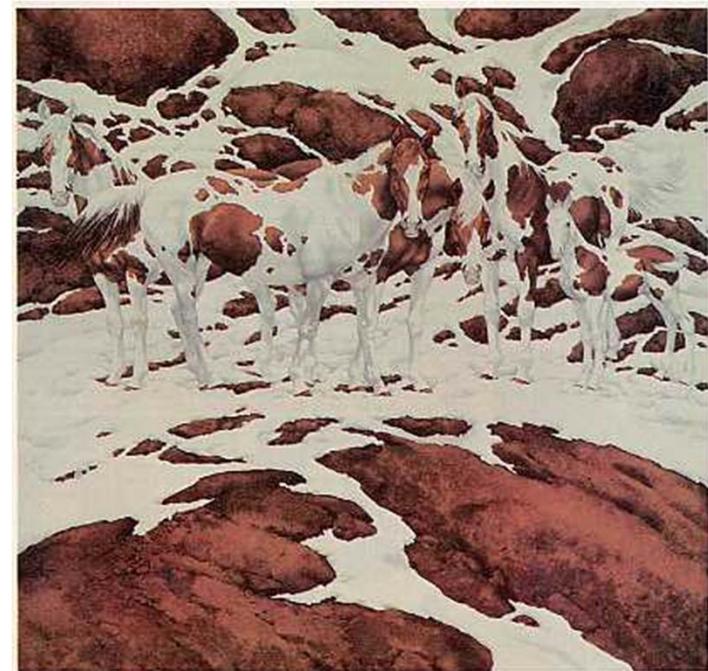


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# Emergence

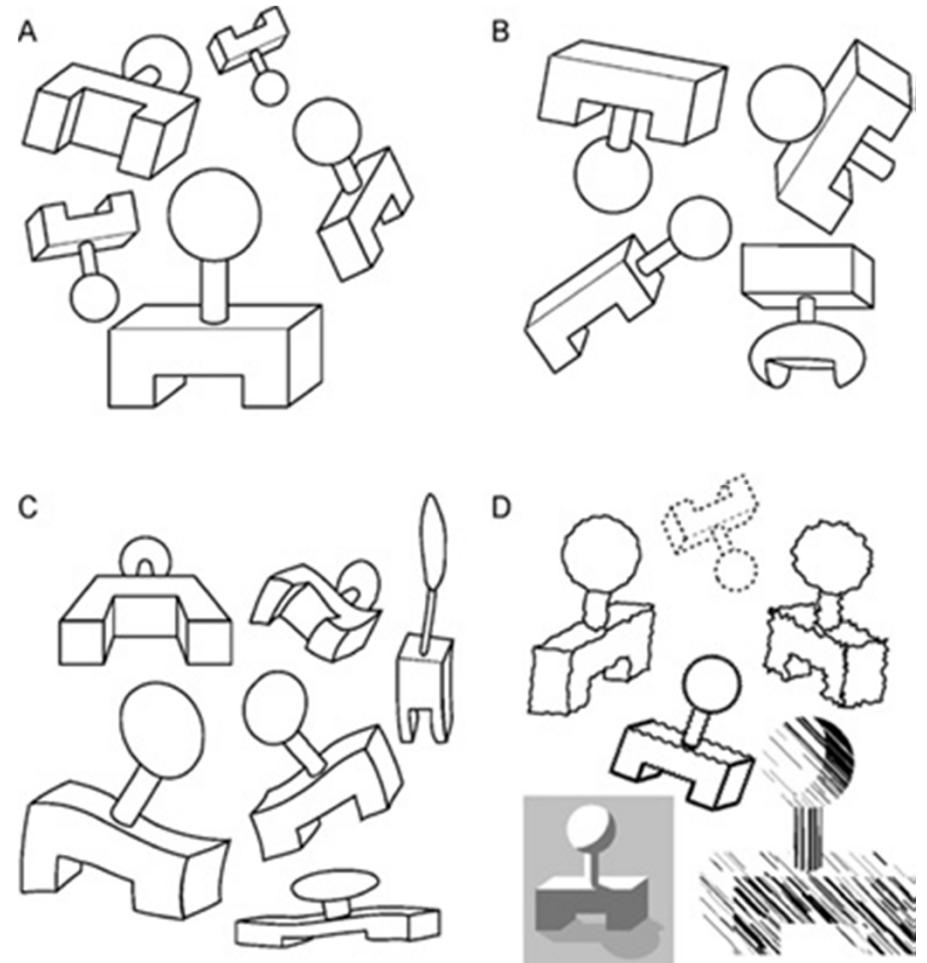


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- The dog is perceived as a whole, all at once.
- We do not construct the “dog” by first identifying its parts, e.g. combining feet, ears, nose, tail, etc.

# Invariance

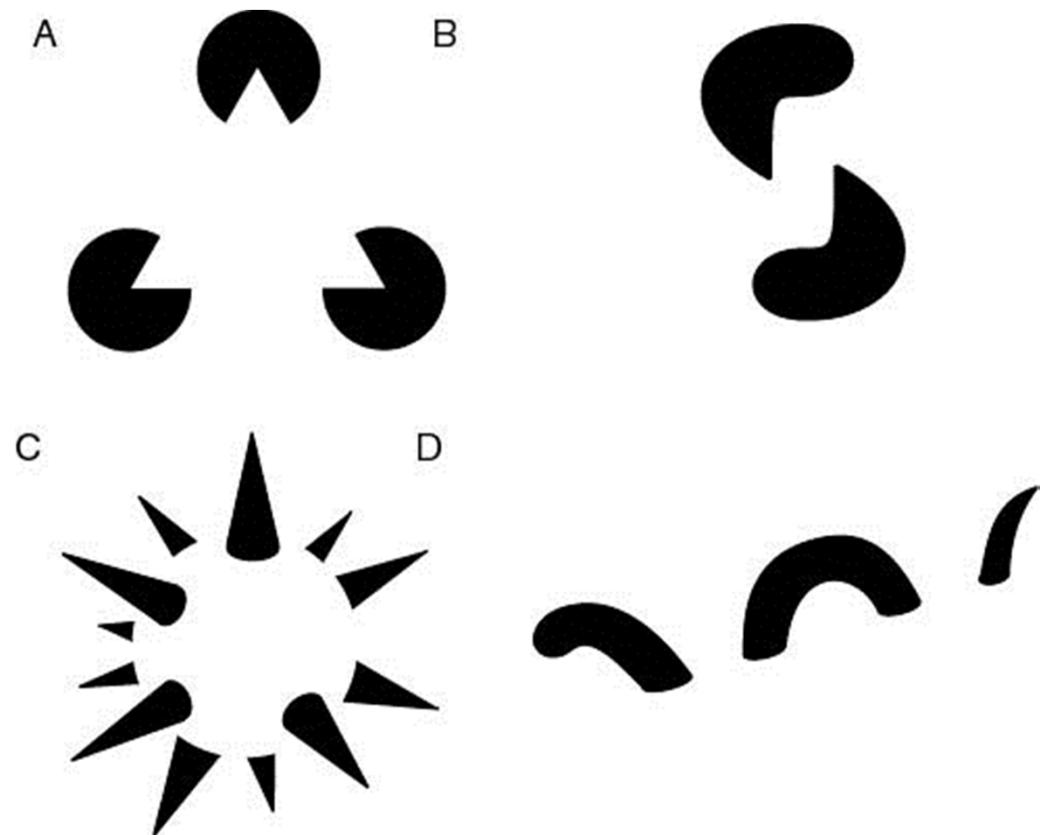
- simple geometrical objects are recognized independent of rotation, translation, and scale, (and other deformations)
- Objects in A are immediately recognized as the same shape,
- are different from those in B,
- are the same as in C despite perspective and elastic deformations,
- and can be depicted using different graphic elements as in D.



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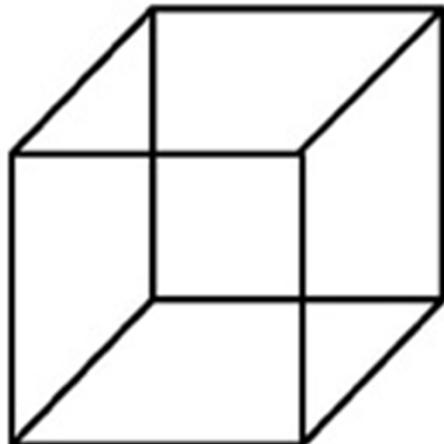
# Reification

- The perceived object can contain more information as given by the sensory input. (e.g. ball in C)
- Mostly for spatial information.



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# Multistable perception



Necker cube



Rubin's Figure / Vase

- Ambiguous perceptual experiences (2 figures share a common border) lead to multistable perception. The experiences pop back and forth between two or more alternative interpretations.

# What are the components?

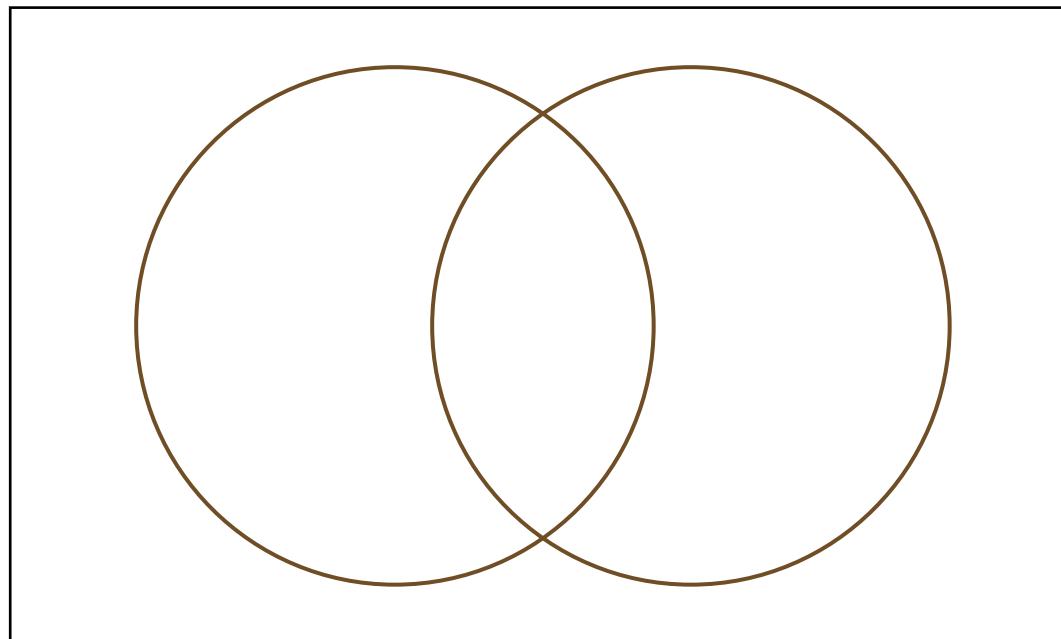


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# Some of the combinations

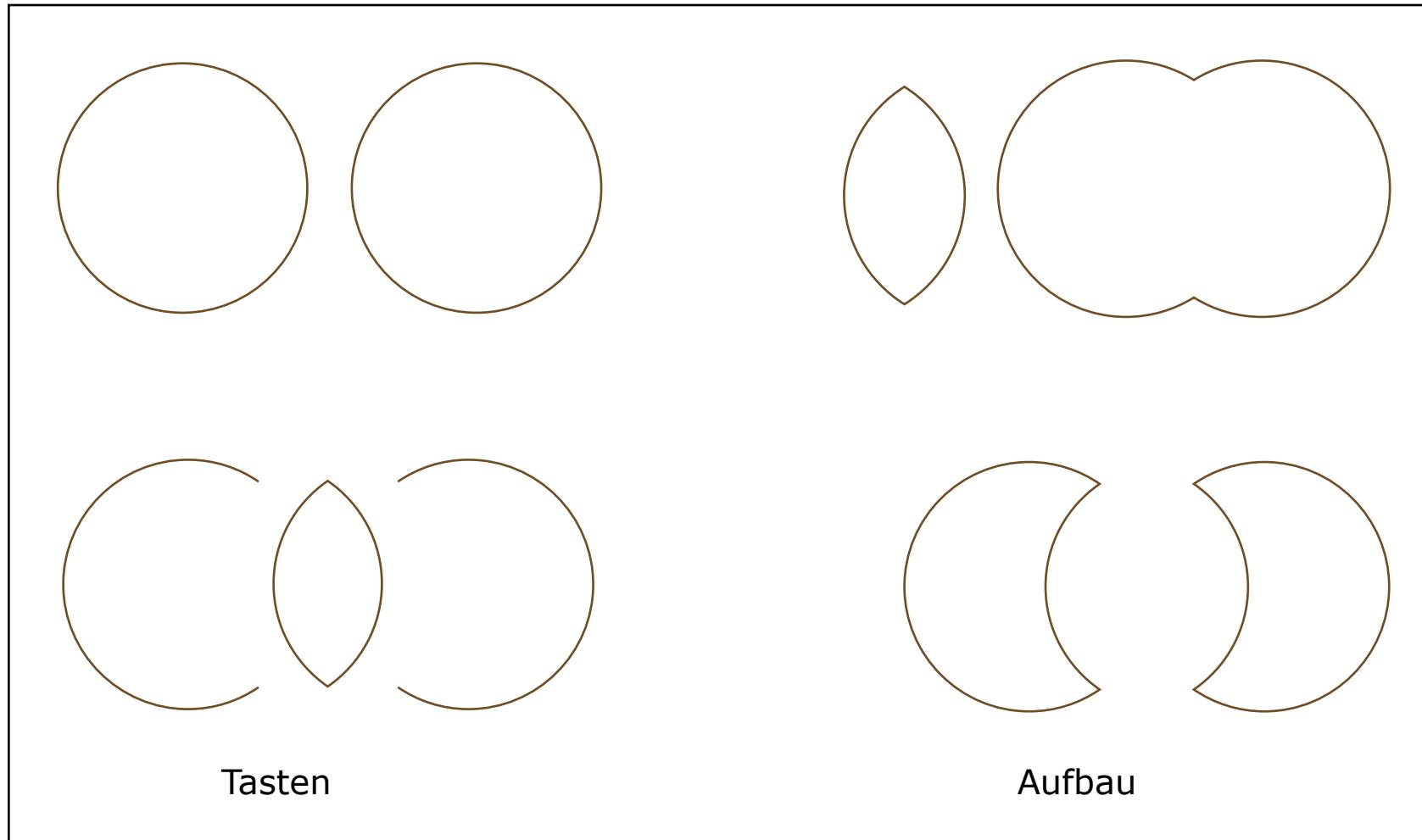


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# Color

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- Wavelength - physics
- Color - perception

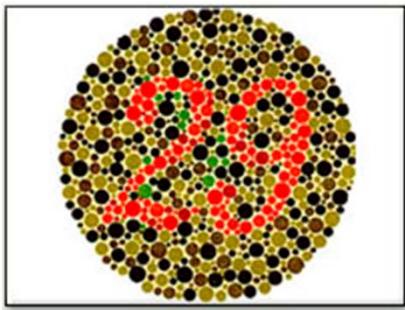
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# Color blindness

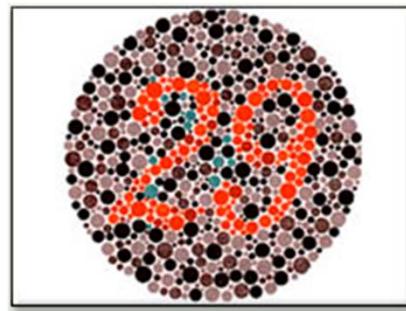
- Normal color vision is **trichromat**, 3 cone types are used.
- **Dichromacy**, most common Red-Green color blindness lacking or reduced long-wavelength or medium-wavelength cones (4-8% of the male population!)  
includes: Protanopia (rare), Deutanopia (1% m), Protanomaly (1% m), Deuteranomaly (6% m)
- **Monochromacy**, complete inability to distinguish any colors  
cone monochromacy (only 1 cone type)  
rod monochromacy (only rods)
- Human Factors  
Color codes  
(Maps, Signals, etc)

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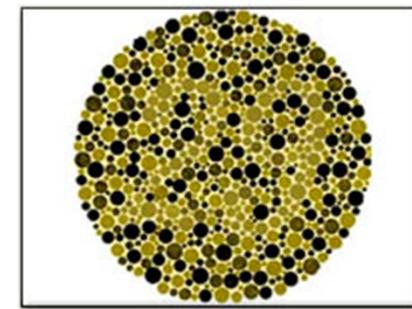
# Color blindness - samples



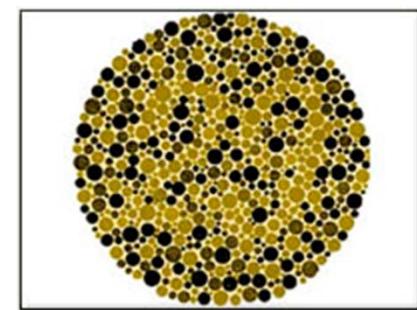
Trichormat  
(all cones)



Tritanopia  
(S-cone)



Protanopia  
(L-cone)

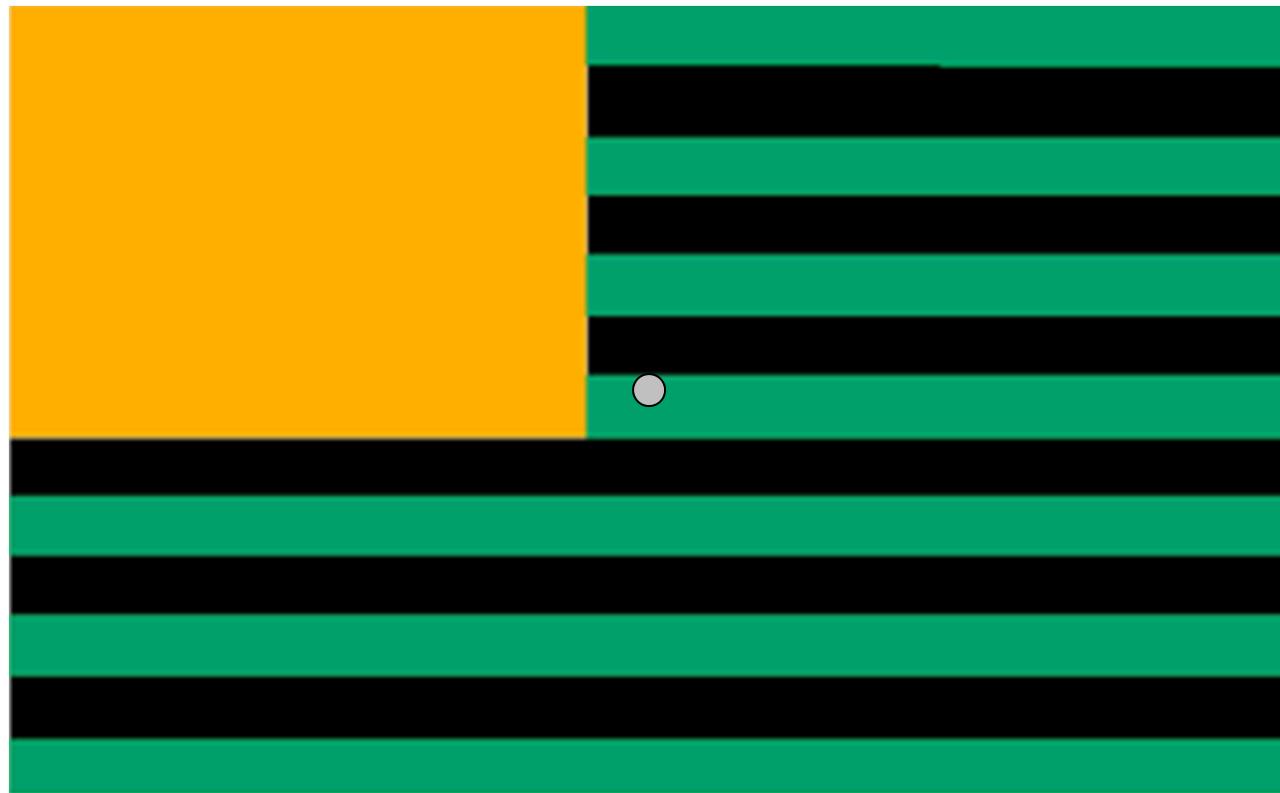


Deutanopia  
(M-cone)



# Color vision - after images 1

- Fixate center dot on flag for 1 minute, then look at a white surface



# Color vision - after images 2



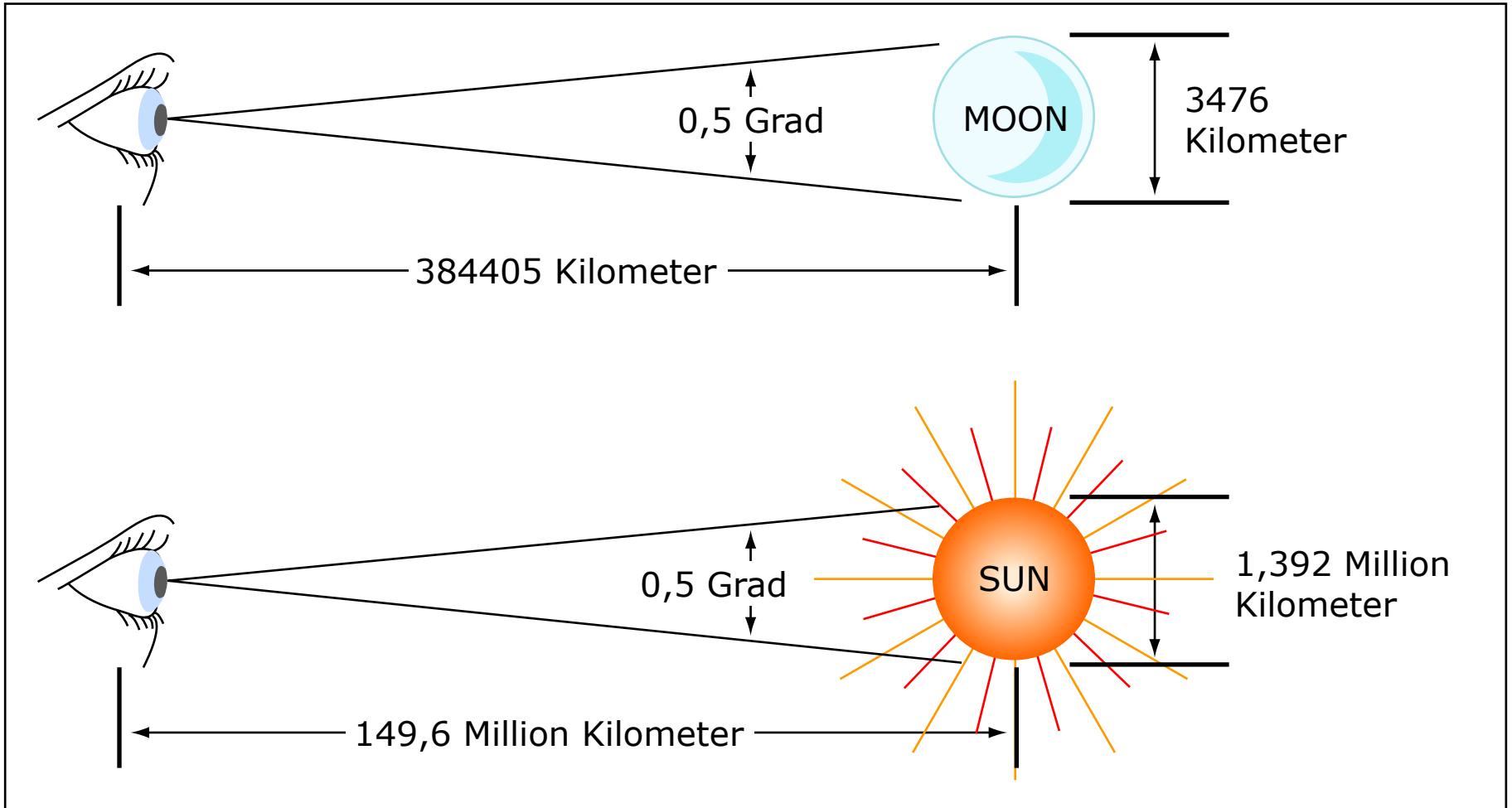


Image by MIT OpenCourseWare.

# Perceived size

52

- How to estimate the distance of person?

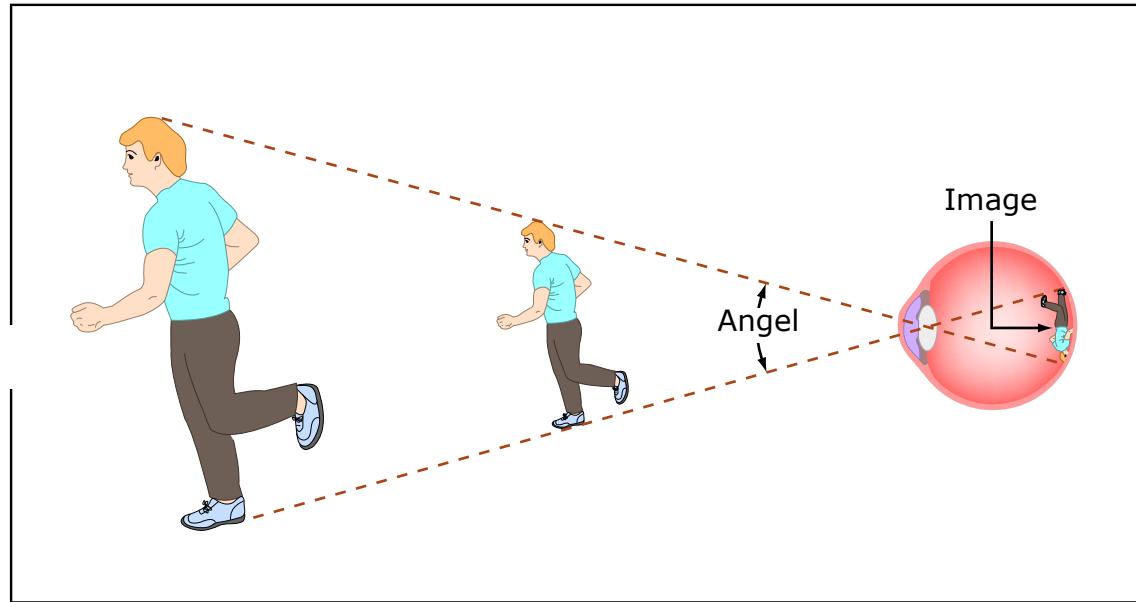
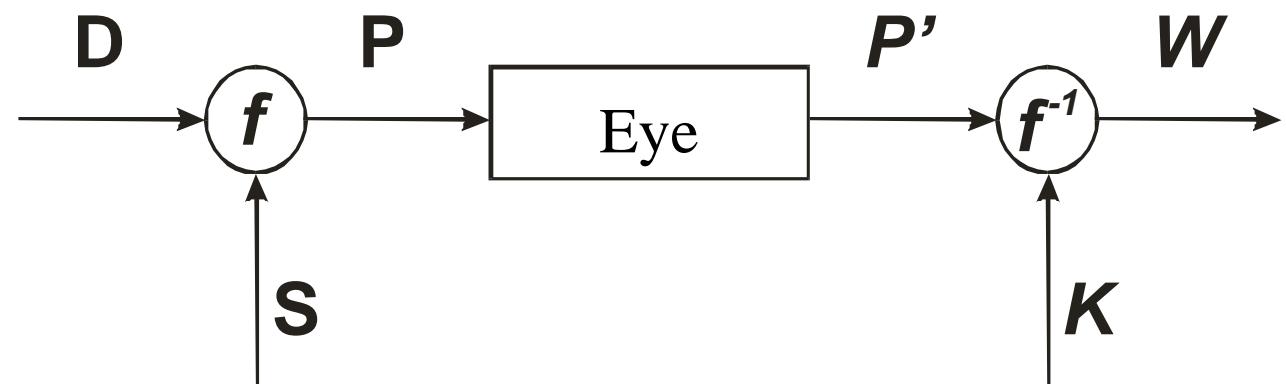


Image by MIT OpenCourseWare.

$$P = D/S$$

$$W = P' * K$$



# Additional Slides

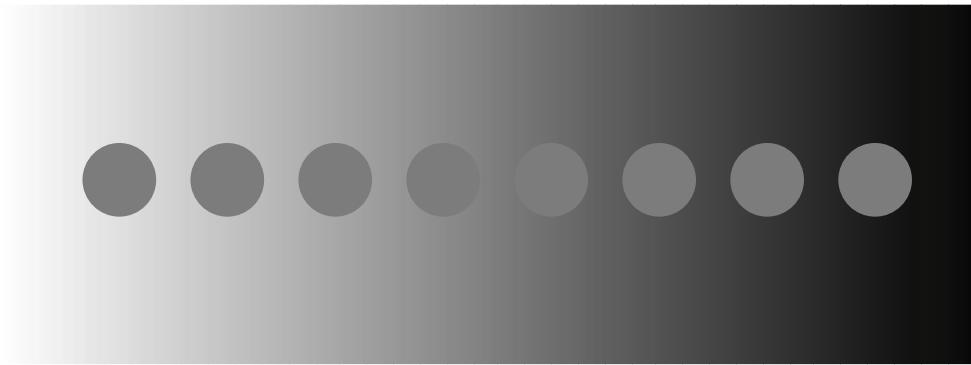
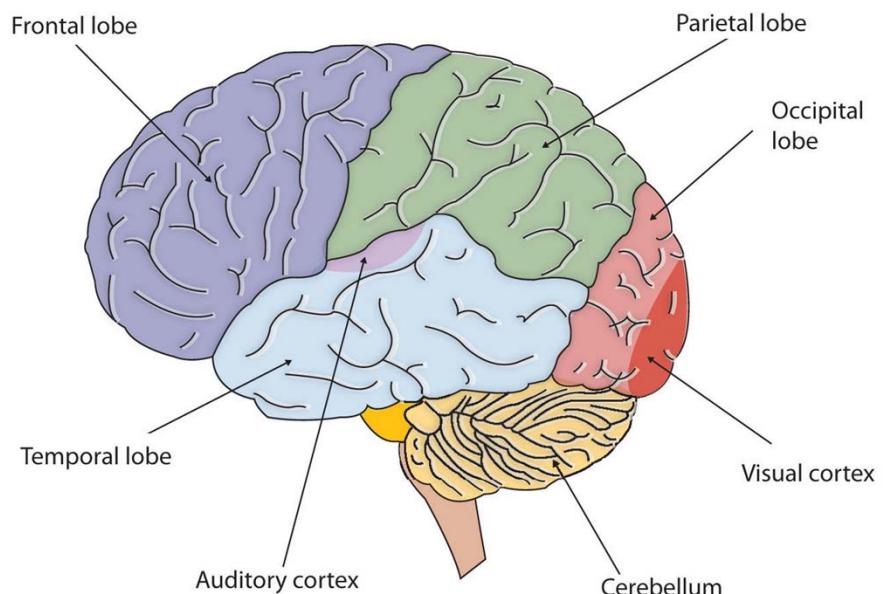


Image by MIT OpenCourseWare.

# Major parts

- **Occipital lobe:** visual perception system
- E.g., visuospatial processing, discrimination of movement and colour discrimination



Adapted from Stangor, C. *Introduction to Psychology*. Flatworld Knowledge, 2010. Courtesy of Flatworld Knowledge.

# Sensory Maps - Homunculus

Image of Homunculus removed due to copyright restrictions.

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