Lecture 3

Contaminant Transport Mechanisms and Principles

BASIC DEFINITIONS



Ground surface

Vadose zone, unsaturated zone

Below ground surface (BGS)



Capillary fringe

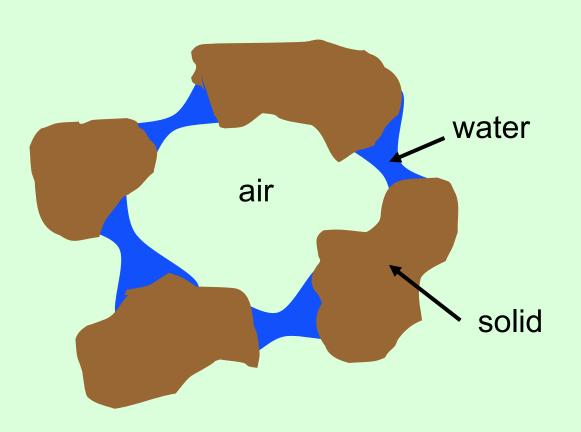
Water table / Saturated zone

Confining bed

Water-table, phreatic, or unconfined aquifer

Confined aquifer or artesian aquifer

MICRO VIEW OF UNSATURATED ZONE



Contaminant concentrations:

C_w, mg/L concentration in water

C_g, mg/L or ppmv concentration in gas

C_s, gm/kg concentration in solids

PARTITIONING RELATIONSHIPS

$$\frac{C_s}{C_w} = K_d = \frac{mg/kg \text{ solid}}{mg/L \text{ water}}$$

K_d = partition coefficient

$$\frac{C_g}{C_w} = H = \frac{\text{mol/m}^3 \text{ air}}{\text{mg/m}^3 \text{ water}}$$

H = Henry's Law constant

HENRY'S LAW CONSTANT

H has dimensions: atm m³ / mol

H' is dimensionless

H' = H/RT

R = gas constant = 8.20575×10^{-5} atm m³/mol °K

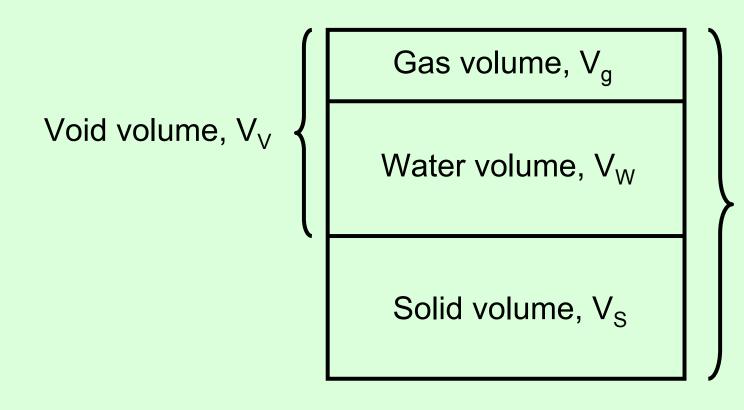
T = temperature in °K

NOTE ON SOIL GAS CONCENTRATION

Soil gas is usually reported as: ppmv = parts per million by volume

$$C_g \text{ (ppmv)} = \frac{C_g \text{ (mg/L)} \times 24,000 \text{ mL/mole}}{\text{molecular weight g/mole}}$$

VOLUME REPRESENTATION



Total volume, V_T

VOLUME-RELATED PROPERTIES

Bulk density = ρ_b = $\frac{\text{mass of solids}}{\text{total volume}}$

Porosity = n =
$$\theta$$
 = V_V/V_T

Volumetric water content or water-filled porosity = $\theta_W = V_W/V_T$

Saturation =
$$S = V_W/V_V$$

Gas-filled porosity = θ_g (or θ_a) = V_g/V_T

$$\theta_W + \theta_g = n$$

CONTAMINANT CONCENTRATION IN SOIL

Total mass in unit volume of soil:

$$C_T = \rho_b C_s + \theta_w C_W + \theta_g C_g$$

If soil is saturated, $\theta_g = 0$ and $\theta_W = n$ $C_T = \rho_b C_s + n C_W$

NOMENCLATURE FOR DARCY'S LAW

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Q = K i A

K = hydraulic conductivity

i = hydraulic gradient = dh/dL

A = cross-sectional area
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Velocity of ground-water movement

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    u = Q/n A = q/n = Ki/n = average linear velocity
    n A = area through which ground water flows
    q = Q/A = Darcy seepage velocity = Specific discharge
    For transport, n is n<sub>e</sub>, effective porosity
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ADVECTIVE FLUX

Flowing ground water carries any dissolved material with it → Advective Flux

$$J_A = n u C$$
 mass / area / time

= mass flux through unit cross section due to ground-water advection

n is needed since no flow except in pores

DIFFUSIVE FLUX

Movement of mass by molecular diffusion (Brownian motion) – proportional to concentration gradient

$$\mathbf{J_D} = -\mathbf{D_O} \frac{\partial \mathbf{C}}{\partial \mathbf{x}}$$
 in surface water !!!

 D_O is molecular diffusion coefficient [L²/T]

DIFFUSIVE FLUX

In porous medium, geometry imposes constraints:

$$\mathbf{J}_{\mathbf{D}} = -\tau \ \mathbf{D}_{\mathbf{O}} \ \mathbf{n} \frac{\partial \mathbf{C}}{\partial \mathbf{x}} = -\mathbf{D} * \mathbf{n} \frac{\partial \mathbf{C}}{\partial \mathbf{x}}$$

 τ = tortuosity factor

D* = effective diffusion coefficient

Factor n must be included since diffusion is only in pores

TORTUOSITY

Solute must travel a tortuous path, winding through pores and around solid grains

Common empirical expression: $\tau = \left(\frac{L}{L_e}\right)^2$

L = straight-line distance

 L_e = actual (effective) path

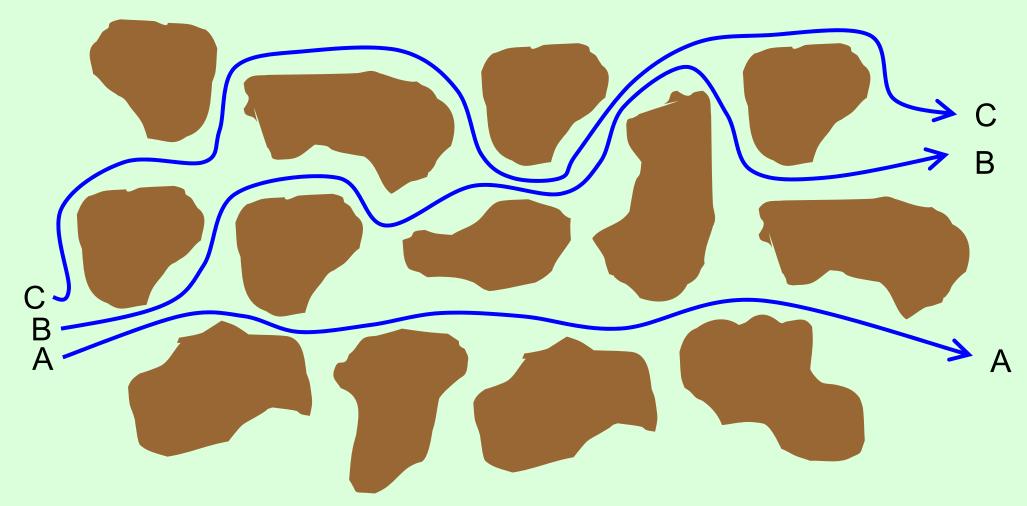
 $\tau \approx 0.7$ for sand

NOTES ON DIFFUSION

Diffusion is not a big factor in saturated groundwater flow – dispersion dominates diffusion

Diffusion can be important (even dominant) in vapor transport in unsaturated zone

MECHANICAL DISPERSION



A arrives first, then B, then $C \rightarrow mechanical dispersion$

MECHANICAL DISPERSION

Viewed at micro-scale (i.e., pore scale) arrival times A, B, and C can be predicted

Averaging travel paths A, B, and C leads to apparent spreading of contaminant about the mean

Spatial averaging → dispersion

MECHANICAL DISPERSION

Dispersion can be effectively <u>approximated</u> by the same relationship as diffusion—i.e., that flux is proportional to concentration gradient:

$$\mathbf{J_{M}} = -\mathbf{D_{M}} \, \mathbf{n} \, \frac{\partial \mathbf{C}}{\partial \mathbf{x}}$$

Dispersion coefficient, $D_M = \alpha_L u$

 α_L = longitudinal dispersivity (units of length)

TRADITIONAL VIEW OF HYDRODYNAMIC DISPERSION

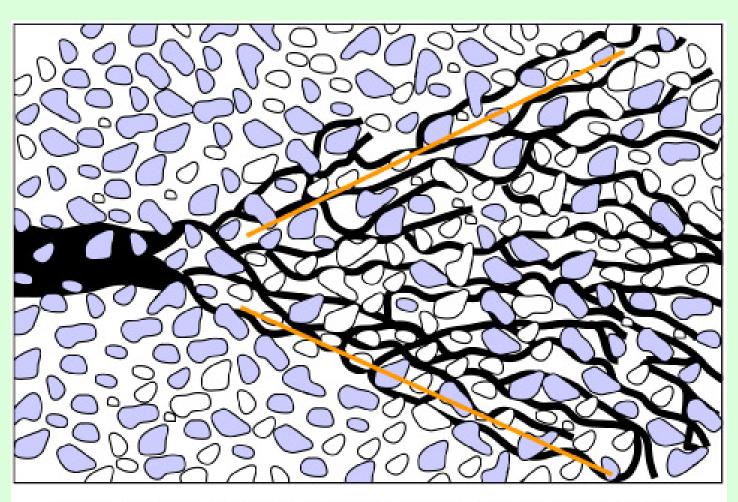


Image adapted from: Freeze, R.A., and J.A. Cherry, 1979. Groundwater. Prentice Hall, Englewood Cliffs, New Jersey. Pg. 384.

ACTUAL OBSERVATIONS OF PLUMES

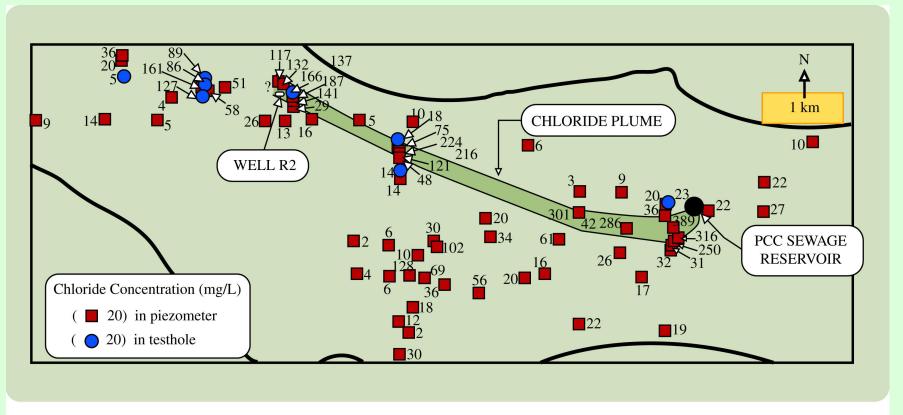
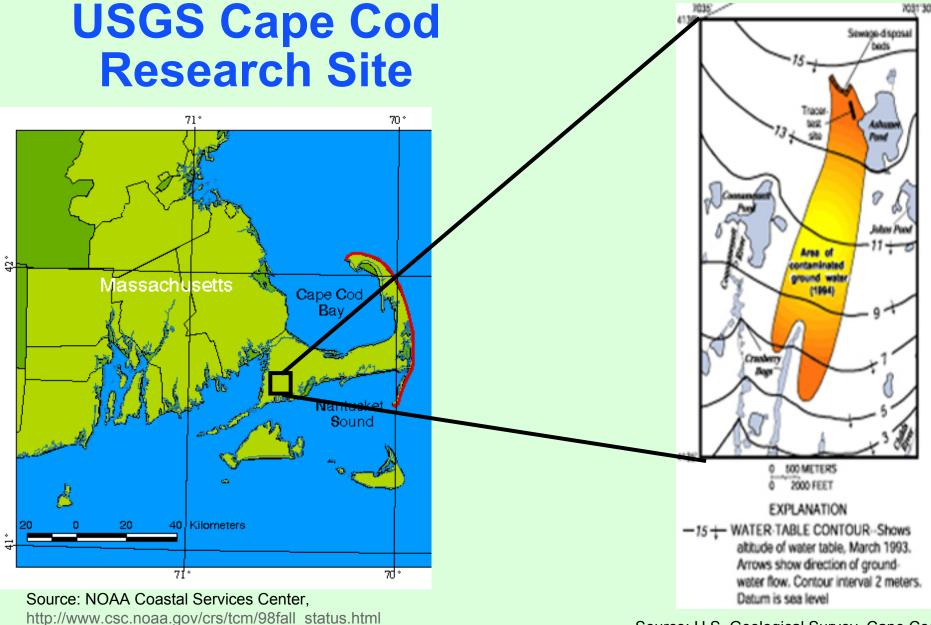


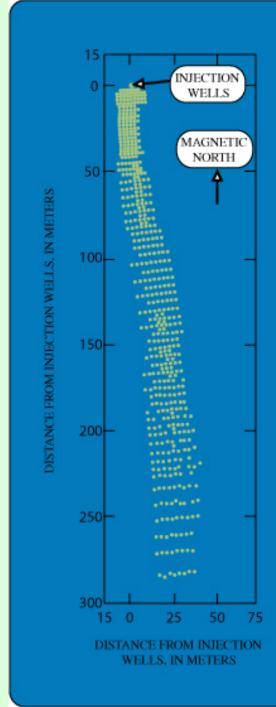
Image adapted from: Kamp, G.v.d., L..D. Luba, J.A. Cherry, and H. Maathuis, 1994. Field Study of a Long and Very Narrow Contaminant Plume. *Ground Water*. Vol. 32, No. 6, Pg. 1008. November/December 1994.



Accessed May 14, 2004.

Source: U.S. Geological Survey, Cape Cod Toxic Substances Hydrology Research Site, http://ma.water.usgs.gov/CapeCodToxics/location.html. Accessed May 14, 2004.

MONITORING WELL ARRAY



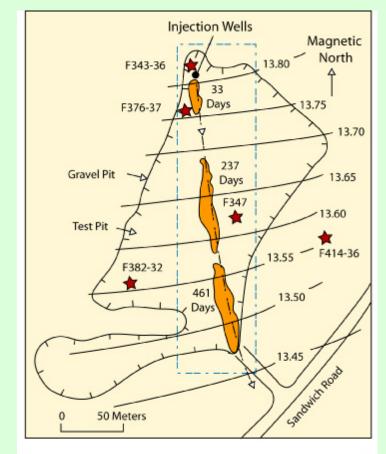
USGS MONITORING NETWORK

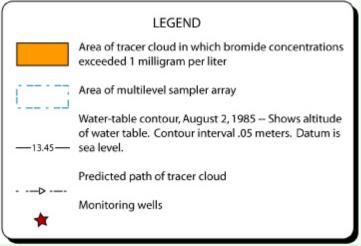


Source: http://ma.water.usgs.gov/CapeCodToxics/photo-gallery.html Photo by D.R. LeBlanc.

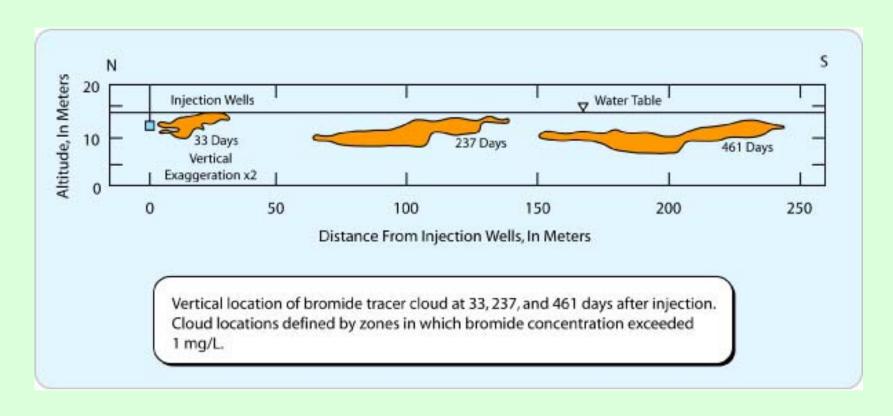
OBSERVED BROMIDE PLUME – HORIZONTAL VIEW

Significant longitudinal dispersion, but limited lateral dispersion



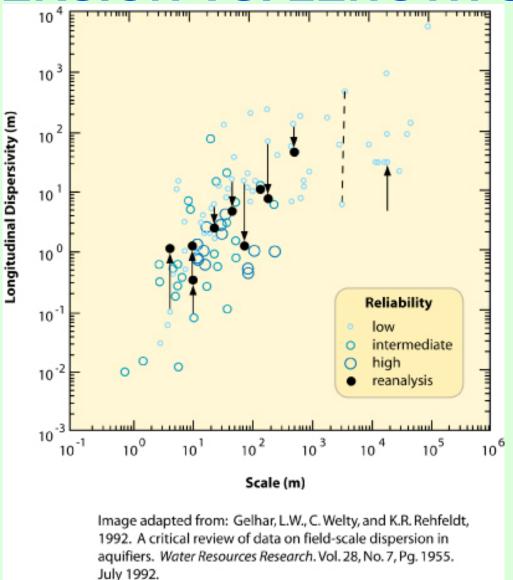


OBSERVED BROMIDE PLUME – VERTICAL VIEW



Limited vertical dispersion

LONGITUDINAL DISPERSION VS. LENGTH SCALE



Lateral and vertical dispersivity

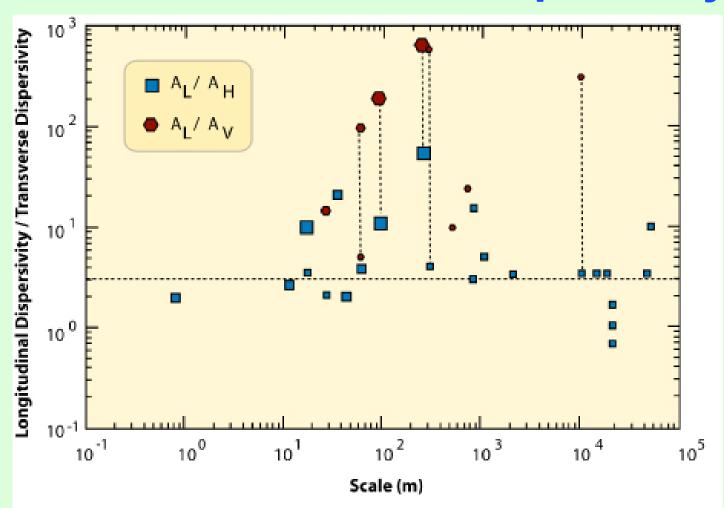


Image adapted from: Gelhar, L.W., C. Welty, and K.R. Rehfeldt, 1992. A critical review of data on field-scale dispersion in aquifiers. *Water Resources Research*. Vol. 28, No. 7, Pg. 1955. July 1992.

Combined transport from advection, diffusion, and dispersion (in one dimension):

$$J = J_A + J_D + J_M$$

$$J = nuC - D * n \frac{\partial C}{\partial x} - D_M n \frac{\partial C}{\partial x}$$

$$J = nuC - D_H \frac{\partial C}{\partial x}$$

$$D_H = D^* + D_M = \tau D_O + \alpha_L u$$

= hydrodynamic dispersion

Consider conservation of mass over control volume (REV) of aquifer.

REV = Representative Elementary Volume REV must contain enough pores to get a meaningful representation (statistical average or model)

Change in contaminant mass with time

Flux in less flux out of REV

Sources and sinks due to reactions

$$\frac{\partial \mathbf{C}_{\mathsf{T}}}{\partial \mathbf{t}} = -\nabla \cdot \mathbf{J} \pm \mathbf{S/S}$$

$$\frac{\partial \mathbf{C}_{\mathsf{T}}}{\partial \mathbf{t}} = -\frac{\partial \mathbf{J}}{\partial \mathbf{x}} \pm \mathbf{S/S}$$
(2)

C_T = <u>total</u> mass (dissolved mass plus mass adsorbed to solid) per unit volume

$$= \rho_b C_S + n C_W = \rho_b C_S + n C$$
 (3)

Note: W subscript dropped for convenience and for Consistency with conventional notation

Substitute Equation 3 into Equation 2:

$$\frac{\partial (\rho_b C_s)}{\partial t} + \frac{\partial (nC)}{\partial t} = -\frac{\partial}{\partial x} \left(nuC - D_H n \frac{\partial C}{\partial x} \right) \pm S/S$$
 (4)

↑ no solid phase in flux term

 $C_S = K_d C$ by definition of K_d

<u>Assume</u> spatially uniform n, ρ_b , K_d , u, and D_H and no S/S

$$(\rho_{b}K_{d} + n)\frac{\partial C}{\partial t} = -nu\frac{\partial C}{\partial x} + nD_{H}\frac{\partial^{2}C}{\partial x^{2}}$$

$$\frac{\partial C}{\partial t} = -\frac{u}{\left(\frac{\rho_{b}K_{d} + n}{n}\right)}\frac{\partial C}{\partial x} + \frac{D_{H}}{\left(\frac{\rho_{b}K_{d} + n}{n}\right)}\frac{\partial^{2}C}{\partial x^{2}}$$

$$(6)$$

"Retardation factor", R_d

$$\frac{\rho_b \mathbf{K_d} + \mathbf{n}}{\mathbf{n}} = 1 + \frac{\rho_b \mathbf{K_d}}{\mathbf{n}} = \mathbf{R_d}$$
 (7)

Substituting Equation 7 into Equation 6:

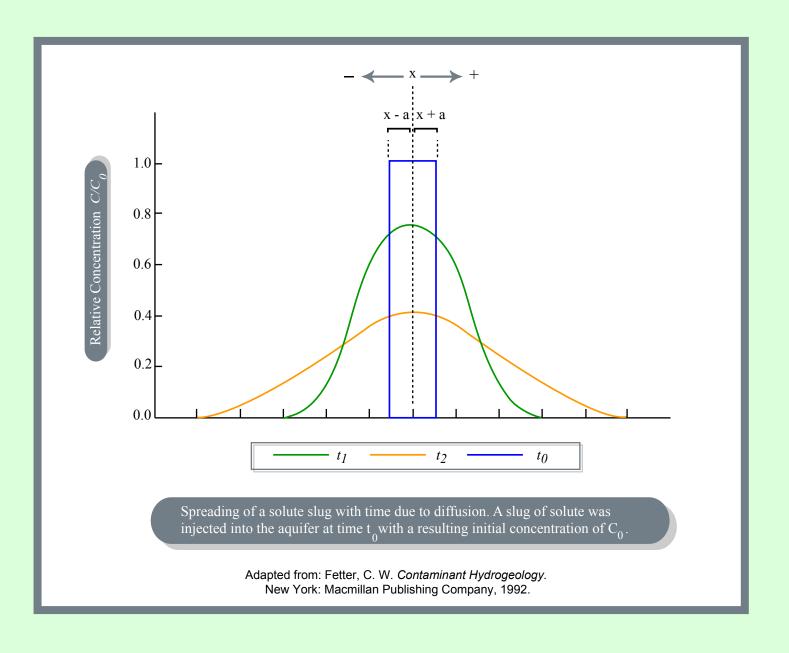
$$\frac{\partial \mathbf{C}}{\partial \mathbf{t}} = -\frac{\mathbf{u}}{\mathbf{R}_{d}} \frac{\partial \mathbf{C}}{\partial \mathbf{x}} + \frac{\mathbf{D}_{H}}{\mathbf{R}_{d}} \frac{\partial^{2} \mathbf{C}}{\partial \mathbf{x}^{2}}$$
(8)

Effect of adsorption to solids is an apparent slowing of transport of dissolved contaminants Both u and D_H are slowed

SOLUTION OF TRANSPORT EQUATION

Equation 8 can be solved with a variety of boundary conditions

In general, equation predicts a spreading Gaussian cloud



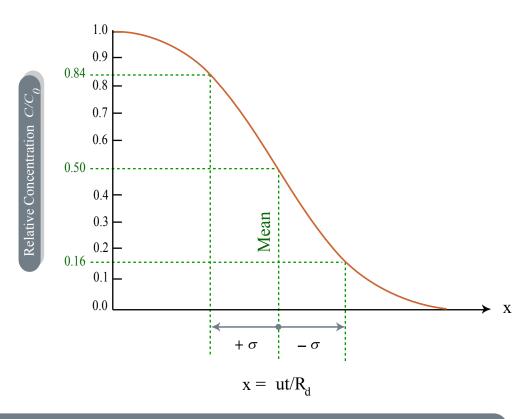
1-D SOLUTION OF TRANSPORT EQUATION

For instantaneous placement of a long-lasting source (for example, a spill that leaves a residual in the soil), solution is:

$$C(x,t) = \frac{C_o}{2} \operatorname{erfc} \left(\frac{R_d x - ut}{\sqrt{4R_d D_H t}} \right)$$

Where $C_o = C(x=0, t) = constant concentration at source location <math>x = 0$

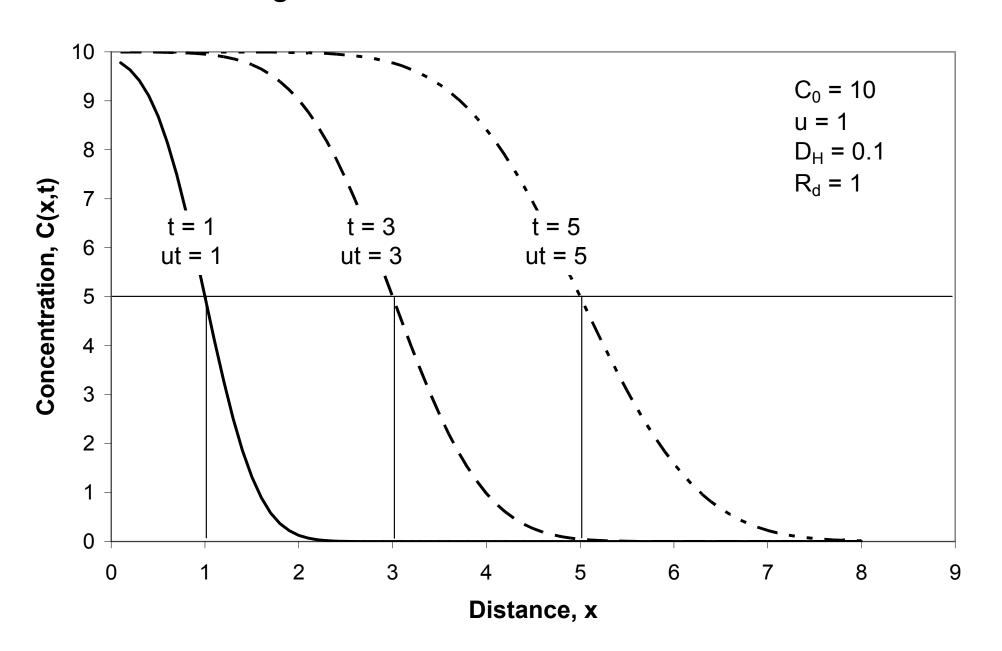
Solution is a front moving with velocity u/R_d



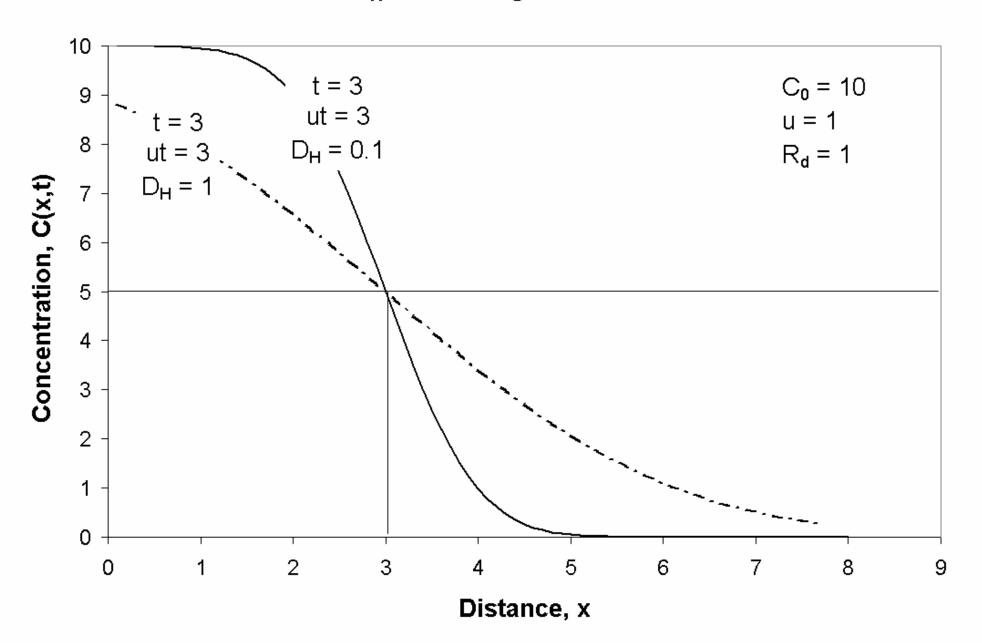
The profile of a diffusing front as predicted by the complementary error function.

Adapted from Fetter, C. W. *Contaminant Hydrogeology*. New York: Macmillan Publishing Company, 1992.

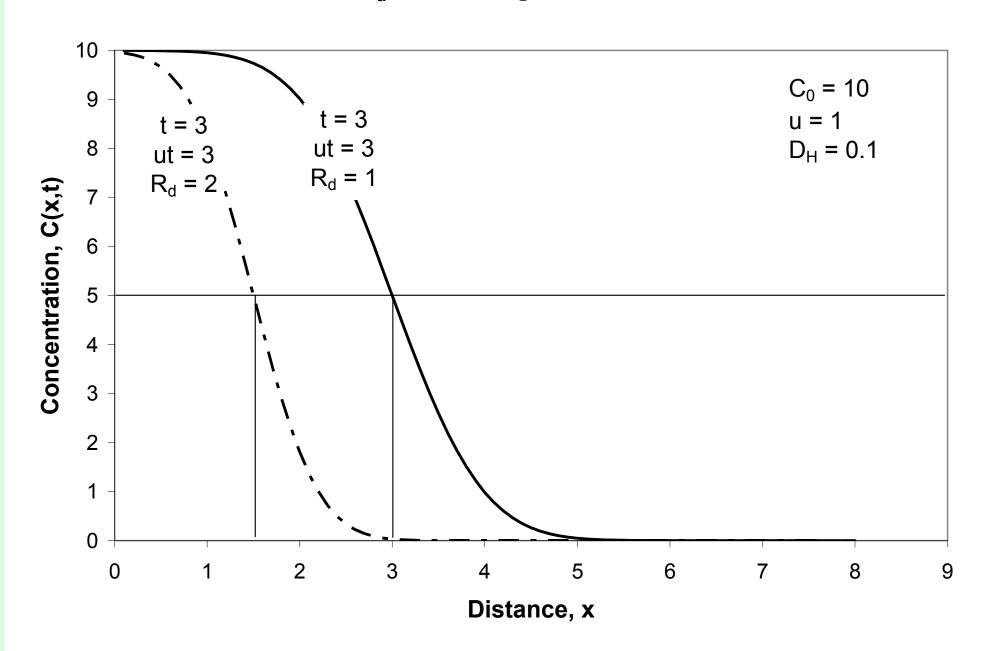
Moving front of contaminant from constant source



Effect of D_H on moving front of contaminant



Effect of R_d on moving front of contaminant



1-D SOLUTIONS

Transport of a Conservative Substance from Pulse and Continuous Sources

Dimensions

1-D

M, *M* are instantaneous or continuous plane sources

$$M\left[\frac{M}{L^2}\right]$$

$$\dot{M} \left[\frac{M}{L^2 T} \right]$$

Pulse Input of Mass M

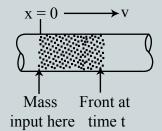
$$C = \frac{M}{2n\pi^{1/2}} \frac{M}{t^{1/2}\sqrt{D_x}} \exp \left[\frac{(x-vt)^2}{4D_x t}\right]$$

$$x = 0 \longrightarrow v$$

$$t = 0 \quad t = t_1$$

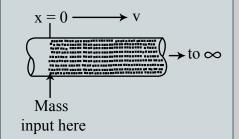
Continuous Input of Mass Per Unit Time \dot{M} Starting at Time t = 0

$$C = \frac{\dot{M}}{2nv} \operatorname{erfc}\left(\frac{x - vt}{2\sqrt{D_x t}}\right)$$



Continuous Input of Mass Per Unit Time \dot{M} in Steady State

$$C = \frac{\dot{M}}{nv}$$
 (for $x > 0$)



Adapted from: Hemond, H. F. and E. J. Fechner-Levy. *Chemical Fate and Transport in the Environment.* 2nd ed. San Diego: Academic Press, 2000.

2-D SOLUTIONS

Transport of a Conservative Substance from Pulse and Continuous Sources

Dimensions

2-D M. M are instantaneous or continuous line sources

$$M\left[\frac{M}{L}\right]$$

$$\dot{M} \left[\frac{M}{L-T} \right]$$

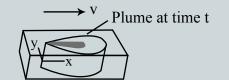
Pulse Input of Mass M

$$C = \frac{M}{4n\pi t \sqrt{D_x} D_y} - \left[\frac{(x-vt)^2}{4D_x t} + \frac{y^2}{4D_y t} \right]$$

$$\begin{array}{ccc}
 & \downarrow & \downarrow \\
 & t = 0 & t = t_1 \\
 & \downarrow & \downarrow \\
 & \downarrow & \downarrow & \downarrow \\$$

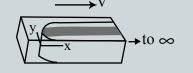
Continuous Input of Mass Per Unit Time \dot{M} Starting at Time t = 0

$$C = \frac{\mathcal{M}}{4n\pi t} \frac{\exp\left[\frac{(x-vt)^2}{4D_x t} + \frac{y^2}{4D_y t}\right]}{4D_x t} \left\| C = \frac{\dot{\mathcal{M}}}{4n\pi^{1/2} (vr)^{1/2} \sqrt{D}_y} \exp\left[\frac{(x-r)v}{2D_x}\right] \operatorname{erfc}\left(\frac{r-vt}{2\sqrt{D_x}t}\right) \right\| C = \frac{\dot{\mathcal{M}}}{2n\pi^{1/2} (vr)^{1/2} \sqrt{D}_y} \exp\left[\frac{(x-r)v}{2D_x}\right] \left\| C = \frac{\dot{\mathcal{M}}}{2n\pi^{1/2} (vr)^{1/2} \sqrt{D}_y} \exp\left[\frac{(x-r)v}{2D_x}\right] \right\| C = \frac{\dot{\mathcal{M}}}{2n\pi^{1/2} (vr)^{1/2} \sqrt{D}_y} \exp\left[\frac{(x-r)v}{2D_x}\right] \left\| C = \frac{\dot{\mathcal{M}}}{2n\pi^{1/2} (vr)^{1/2} \sqrt{D}_y} \exp\left[\frac{(x-r)v}{2D_x}\right] \right\| C = \frac{\dot{\mathcal{M}}}{2n\pi^{1/2} (vr)^{1/2} \sqrt{D}_y} \exp\left[\frac{(x-r)v}{2D_x}\right] \left\| C = \frac{\dot{\mathcal{M}}}{2n\pi^{1/2} (vr)^{1/2} \sqrt{D}_y} \exp\left[\frac{(x-r)v}{2D_x}\right] \right\| C = \frac{\dot{\mathcal{M}}}{2n\pi^{1/2} (vr)^{1/2} \sqrt{D}_y} \exp\left[\frac{(x-r)v}{2D_x}\right] \left\| C = \frac{\dot{\mathcal{M}}}{2n\pi^{1/2} (vr)^{1/2} \sqrt{D}_y} \exp\left[\frac{(x-r)v}{2D_x}\right] \exp\left[\frac{(x$$



Continuous Input of Mass Per Unit Time **M** in Steady State

$$C = \frac{\dot{M}}{2n\pi^{1/2}(vr)^{1/2}\sqrt{D_y}} \exp \left[\frac{(x-r)v}{2D_x}\right]$$



Adapted from: Hemond, H. F. and E. J. Fechner-Levy. Chemical Fate and Transport in the Environment. 2nd ed. San Diego: Academic Press, 2000.

3-D SOLUTIONS

Transport of a Conservative Substance from Pulse and Continuous Sources

Dimensions

3-D M, M are instantaneous or continuous point sources

$$M\left[\frac{M}{L}\right]$$

$$\dot{M} \left[\frac{M}{T} \right]$$

Pulse Input of Mass M

$$C = \frac{M}{8n\pi^{3/2} t^{3/2} \sqrt{D_x D_y D_z}}$$

$$\exp - \left[\frac{(x - vt)^2}{4D_x t} + \frac{y^2}{4D_y t} + \frac{z^2}{4D_z t} \right]$$

$$z = \frac{M}{8n\pi r \sqrt{D_y D_z}} \exp \left[\frac{(x - r)v}{2D_x} \right] \exp \left[\frac{r - vt}{2D_x} \right]$$

$$z = \frac{M}{8n\pi r \sqrt{D_y D_z}} \exp \left[\frac{(x - r)v}{2D_x} \right]$$

$$z = \frac{M}{8n\pi r \sqrt{D_y D_z}} \exp \left[\frac{(x - r)v}{2D_x} \right]$$

$$z = \frac{M}{4n\pi r \sqrt{D_y D_z}} \exp \left[\frac{(x - r)v}{2D_x} \right]$$

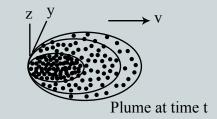
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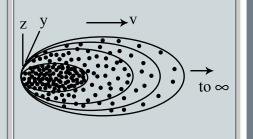
Continuous Input of Mass Per Unit Time \dot{M} Starting at Time t = 0

$$C = \frac{\dot{M}}{8n\pi r \sqrt{D_y D_z}} exp \left[\frac{(x-r)v}{2D_x} \right] erfc \left(\frac{r-vt}{2\sqrt{D_x t}} \right)$$



Continuous Input of Mass Per Unit Time M in Steady State

$$C = \frac{\dot{M}}{4n\pi r \sqrt{D_y D_z}} \exp \left[\frac{(x-r)v}{2D_x} \right]$$



Adapted from: Hemond, H. F. and E. J. Fechner-Levy. Chemical Fate and Transport in the Environment. 2nd ed. San Diego: Academic Press, 2000.