

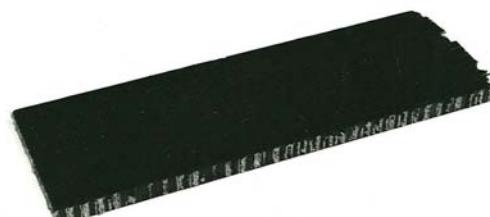
## Sandwich Panels

- two stiff strong skins separated by a light weight core
- separation of skins by core increases moment of inertia, with little increase in weight
- efficient for resisting bending + buckling
- like an I beam: faces = flanges - carry normal stress  
core = web - carries shear stress
- examples: engineering + nature

- 
- faces: composites, metals
  - cores: honeycombs, foams, balsa
    - honeycombs: lighter than foam cores for req'd stiffness, strength
    - foams: heavier, but can also provide thermal insulation
  - mechanical behavior depends on face+core properties + on geometry
  - typically, panel must have some required stiffness and/or strength
  - often, want to minimize weight - optimization problem
    - eg. refrigerated vehicles; sporting equipment (sailboats, skis)



(a)



(b)

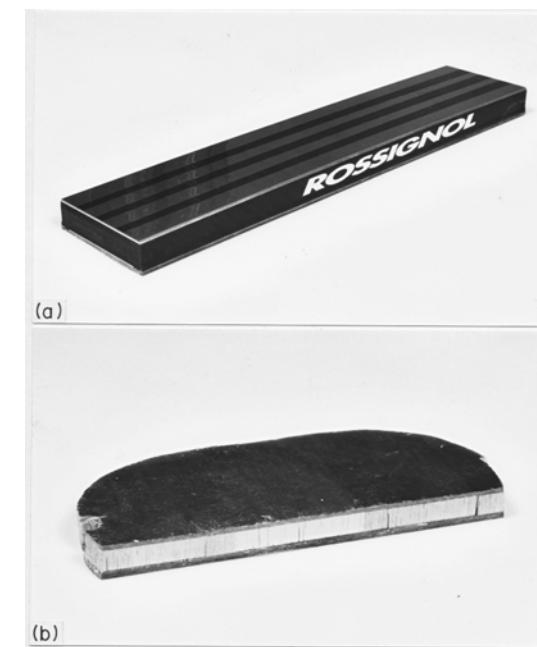
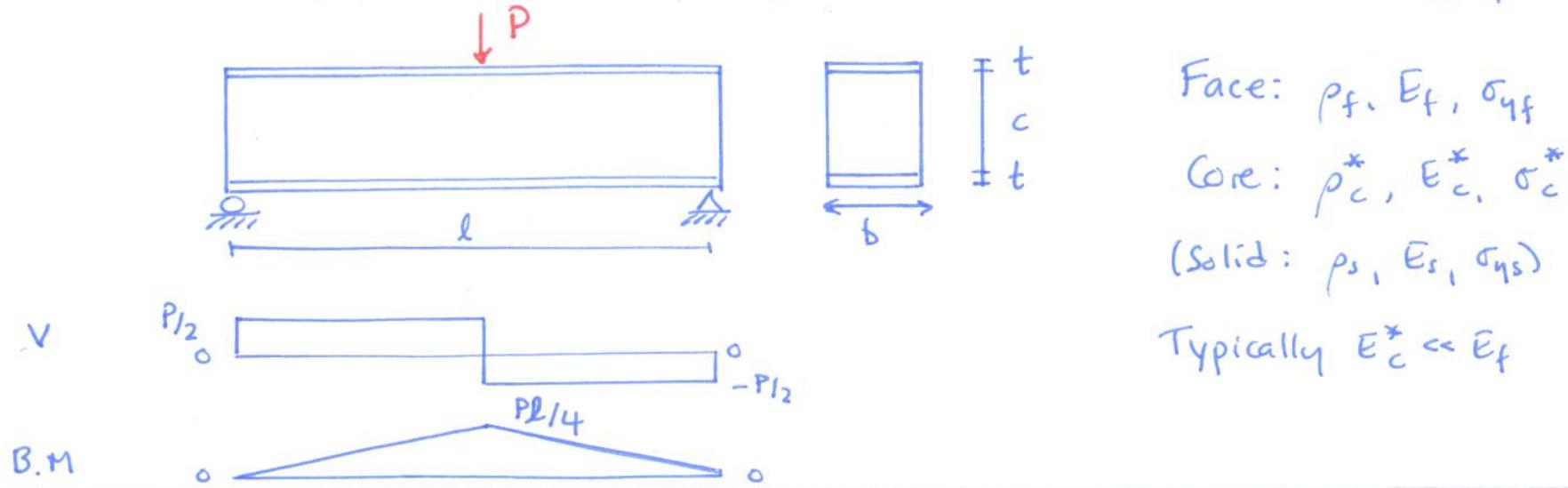


Figure removed due to copyright restrictions. See Figure 9.4:  
Gibson, L. J. and M. F. Ashby. *Cellular Solids: Structure and Properties*. Cambridge University Press, 1997.

## Sandwich beam stiffness

- analyze beams here (simpler than plates; same ideas apply)



$\delta = \delta_b + \delta_s$  : bending deflection  $\delta_b$  + shear defl " (of core)  $\delta_s$

since  $G_c^* \ll E_f$ , core shear deflections significant

$$\delta_b = \frac{Pl^3}{B_1(EI)_{eq}}$$

$B_1$  = constant, depending on loading configuration  
3 pt bend,  $B_1 = 48$

$$(EI)_{eq} = \left( \frac{E_f bt^3}{12} \times 2 \right) + E_c \frac{bc^3}{12} + E_f bt \left( \frac{c+t}{2} \right)^2 2 \quad \text{parallel axis theorem}$$

$$= \frac{E_f bt^3}{6} + \frac{E_c bc^3}{12} + \frac{E_f bt}{2} (c+t)^2$$

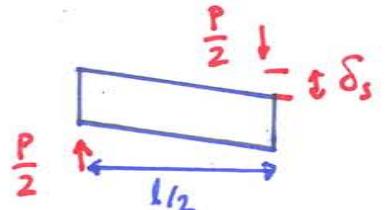
(3)

sandwich structures: typically  $E_f \gg E_c^*$  &  $c \gg t$

$$\text{approximate } (EI)_{eq} \approx E_f \frac{bt c^2}{2}$$

$$\delta_s = ?$$

core



$$T = G \gamma$$

$$\frac{P}{A} \propto G \frac{\delta_s}{l}$$

$$\delta_s = \frac{Pl}{B_2 (AG)_{eq}}$$

$$(AE)_{eq} = b \frac{(c+t)}{c} G_c \approx bc G_c$$

$$\delta = \delta_b + \delta_s$$

$$\boxed{\delta = \frac{2 Pl^3}{B_1 E_f b t c^2} + \frac{Pl}{B_2 bc G_c^*}}$$

AND note:

$$G_c^* = C_2 E_s (\rho_c^* / \rho_s)^2 \quad (\text{foam model})$$

$$C_2 \approx 3/8$$

## Minimum weight for a given stiffness

- given face + core materials
  - beam length, width, loading geometry (eg. 3pt bend,  $B_1, B_2$ )
  - find : face + core thicknesses,  $t + c$ , + core density  $\rho_c^*$  to minimize weight
- $$W = 2\rho_f g btl + \rho_c^* g bcl$$
- solve  $(P/\delta)$  eqn for  $\rho_c^*$  & substitute into weight eqn
  - solve  $\partial W/\partial c = 0$  &  $\partial W/\partial t = 0$  to get  $t_{opt}, c_{opt}$
  - substitute  $t_{opt}, c_{opt}$  into stiffness eqn  $(P/\delta)$  to get  $\rho_c^{*opt}$
- 
- note that optimization possible by foam modelling  $G_c = C_2 (\rho_s/\rho_f)^2 E_s$

$$\left(\frac{c}{l}\right)_{opt} = 4.3 \left\{ \frac{C_2 B_2}{B_1^2} \left( \frac{\rho_f}{\rho_s} \right)^2 \frac{E_s}{E_f} \left( \frac{P}{\delta b} \right) \right\}^{1/5}$$

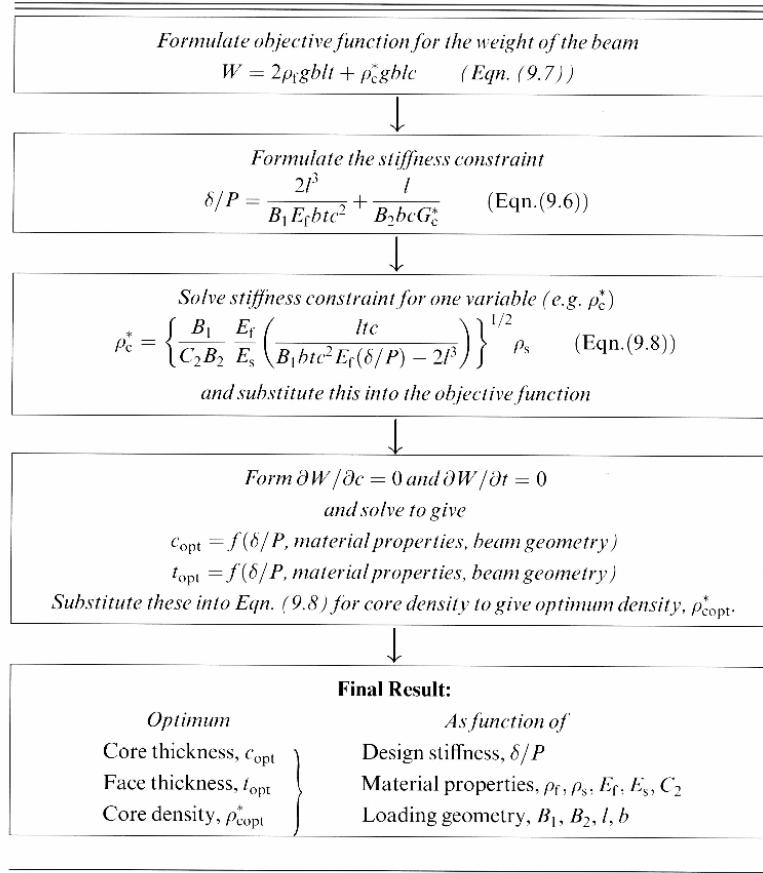
$$\left(\frac{t}{l}\right)_{opt} = 0.32 \left\{ \frac{1}{B_1 B_2 C_2} \left( \frac{\rho_s}{\rho_f} \right)^4 \frac{1}{E_f E_s} \left( \frac{P}{\delta b} \right)^3 \right\}^{1/5}$$

$$\left(\frac{\rho_c^*}{\rho_s}\right)_{opt} = 0.59 \left\{ \frac{B_1}{B_2^3 C_2^3} \left( \frac{\rho_s}{\rho_f} \right) \frac{E_f}{E_s} \left( \frac{P}{\delta b} \right)^2 \right\}^{1/5}$$

Note:  $\frac{W_{face}}{W_{core}} = \frac{1}{4}$        $\frac{\delta_b}{\delta} = \frac{1}{3}$        $\frac{\delta_s}{\delta} = \frac{2}{3}$

The design of sandwich panels with foam cores

**Table 9.3** Optimum design of a sandwich panel subject to a stiffness constraint



**Table 9.4** Optimization analysis for sandwich panels subject to a stiffness constraint

Geometry	$W_f/W_c$	$\delta_b/\delta$	$\delta_s/\delta$
Rectangular beam	1/4	1/3	2/3
Circular plate (distributed load over entire plate)	1/4	1/3	2/3
Circular plate (distributed load over radius $r$ )	1/4	1/3	2/3

## Comparison with experiments

- Al faces with rigid PU foam core
- $G_c = 0.7 E_s (\rho_c^* / \rho_s)^2$
- beams designed to have same stiffness, P/f, span l, width, b
- one set had  $\rho_c^* = \rho_c^* \text{opt}$ , varied  $t, c$
- " " "  $t = t_{\text{opt}}$ , varied  $\rho_c^*, c$
- " " "  $c = c_{\text{opt}}$ , varied  $t, \rho_c^*$
- confirms min. weight design; similar results with circular sandwich plates

## Strength of sandwich beams

- stresses in sandwich beams

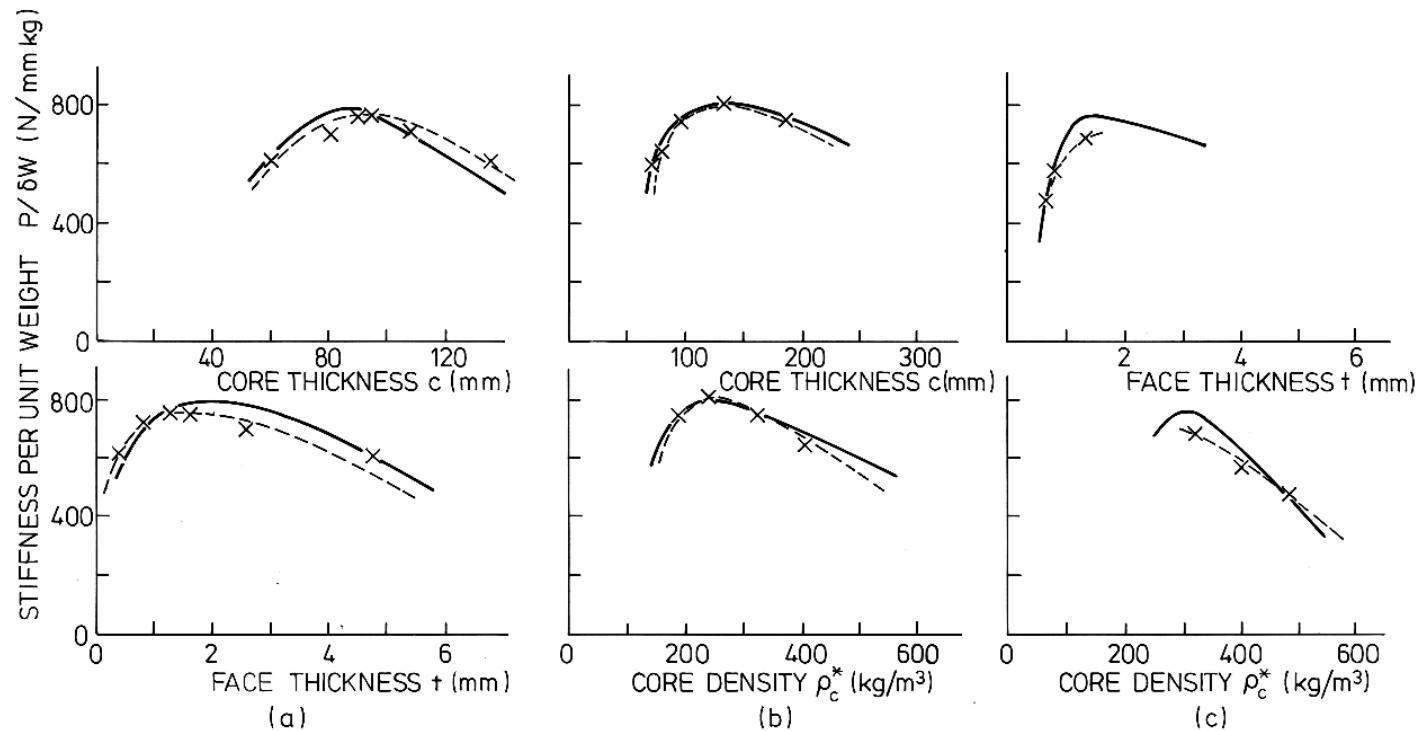
normal stresses

$$\sigma_f = \frac{My}{(EI)_{eq}} E_f = M \frac{c}{2} \frac{2}{E_f b t c^2} E_f = \frac{M}{b t c}$$

$$\sigma_c = \frac{My}{(EI)_{eq}} E_c^* = M \frac{c}{2} \frac{2}{E_f b t c^2} E_c^* = \frac{M}{b t c} \frac{E_c^*}{E_f}$$

since  $E_c^* \ll E_f$      $\sigma_c \ll \sigma_f$   $\Rightarrow$  faces carry almost all normal stress

# Minimum Weight Design



Al faces; Rigid PU foam core

Figures 7, 8, 9: Gibson, L. J. "Optimization of Stiffness in Sandwich Beams with Rigid Foam Cores." *Material Science and Engineering* 67 (1984): 125-35. Courtesy of Elsevier. Used with permission.

- for beam loaded by a concentrated load,  $P$  (eq. 3 pt bend)

$$M_{\max} = \frac{Pl}{B_3} \quad \text{eg. 3 pt bend } B_3 = 4 ; \text{ cantilever } B_3 = 1$$

$$\sigma_f = \frac{Pl}{B_3 b t c}$$

- Shear stresses vary parabolically through the cross-section, but if

$$E_f \gg E_c^* \quad \& \quad c \gg t$$

$$T_c = \frac{V}{bc}$$

$V$  = shear force at section of interest

$$T_c = \frac{P}{B_4 b c}$$

$$V_{\max} = \frac{P}{B_4} \quad (\text{eg. 3 pt bend } B_4 = 2)$$

### Failure modes

face : can yield

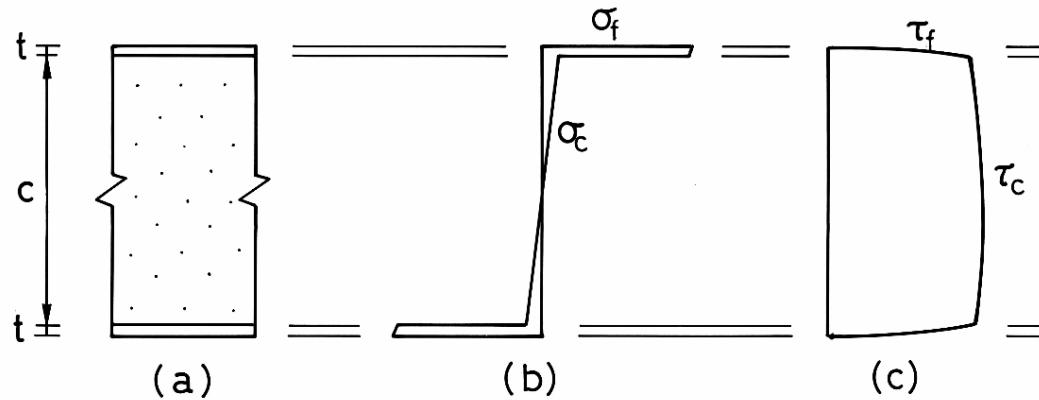
• compressive face can buckle locally - "wrinkling"

core : can fail in shear

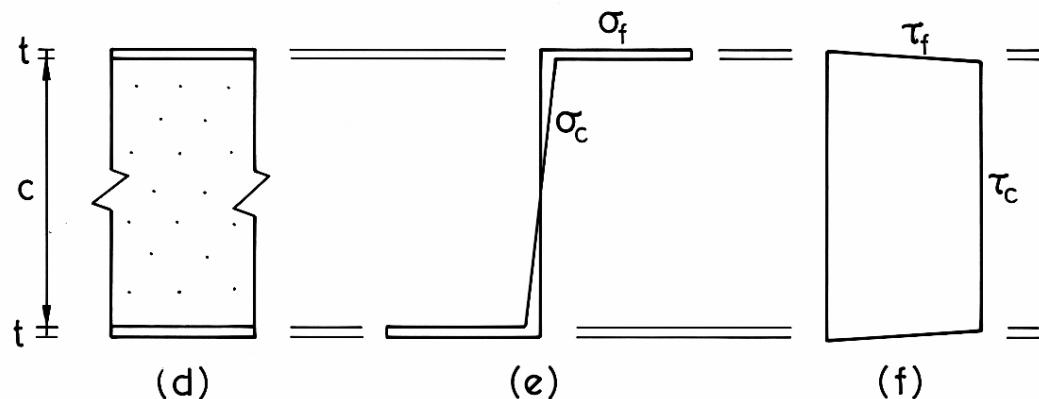
also : can have debonding + indentation

we will assume perfect bond + load distributed sufficiently to avoid indentation

# Stresses

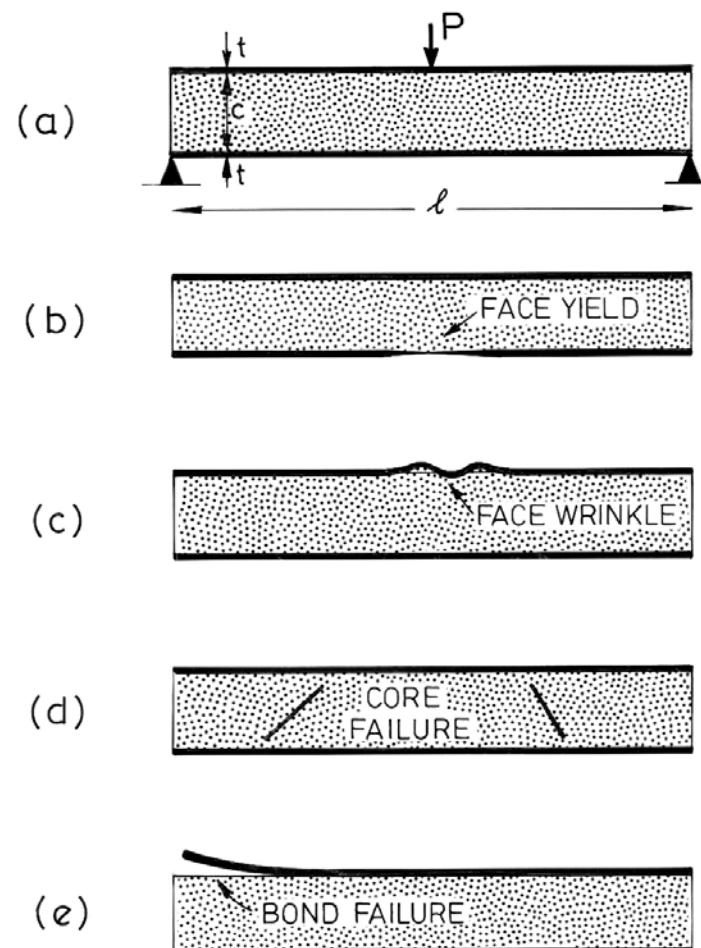


Face: Normal stress  
Core: Shear stress



Approximate stress  
distributions, for:  
 $E_c \ll E_f$  and  $t \ll c$

# Failure Modes



Gibson, L. J., and M. F. Ashby. *Cellular Solids: Structure and Properties*. 2nd ed. Cambridge University Press, © 1997. Figure courtesy of Lorna Gibson and Cambridge University Press.

(a) Face yielding

$$\sigma_f = \frac{Pl}{B_3 b t_c} = \sigma_{yf}$$

(b) Face wrinkling : when normal stress in face = local buckling stress

$$\sigma_{\text{buckling}} = 0.57 E_f^{1/3} E_c^{*2/3} \quad \text{buckling on an elastic foundation}$$

$$E_c^* = (\rho_c^*/\rho_s)^2 E_s$$

$$\sigma_{\text{buckling}} = 0.57 E_f^{1/3} E_s^{2/3} (\rho_c^*/\rho_s)^{4/3}$$

$$\text{wrinkling occurs when } \sigma_f = \frac{Pl}{B_3 b t_c} = 0.57 E_f^{1/3} E_s^{2/3} (\rho_c^*/\rho_s)^{4/3}$$

(c) Core shear failure

$$T_c = T_c^*$$

$$\frac{P}{B_4 b c} = C_{II} (\rho_c^*/\rho_s)^{3/2} \sigma_{us} \quad C_{II} \approx 0.15$$

- dominant failure load is the one that occurs at the lowest load
- how does the failure mode depend on the beam design?
- look at transition from one failure mode to another
- at the transition - two failure modes occur at same load

face yielding:  $P_{fy} = B_3 b_c(t_{f_e}) \sigma_{y_f}$

face wrinkling:  $P_{fw} = 0.57 B_3 b_c(t_{f_e}) E_f^{1/3} E_s^{2/3} (\rho_c^* / \rho_s)^{4/3}$

core shear :  $P_{cs} = C_u B_4 b_c \sigma_{y_s} (\rho_c^* / \rho_s)^{3/2}$

- face yielding + face wrinkling occur at same load if
- $$B_3 b_c(t_{f_e}) \sigma_{y_f} = 0.57 B_3 b_c(t_{f_e}) E_f^{1/3} E_s^{2/3} (\rho_c^* / \rho_s)^{4/3}$$

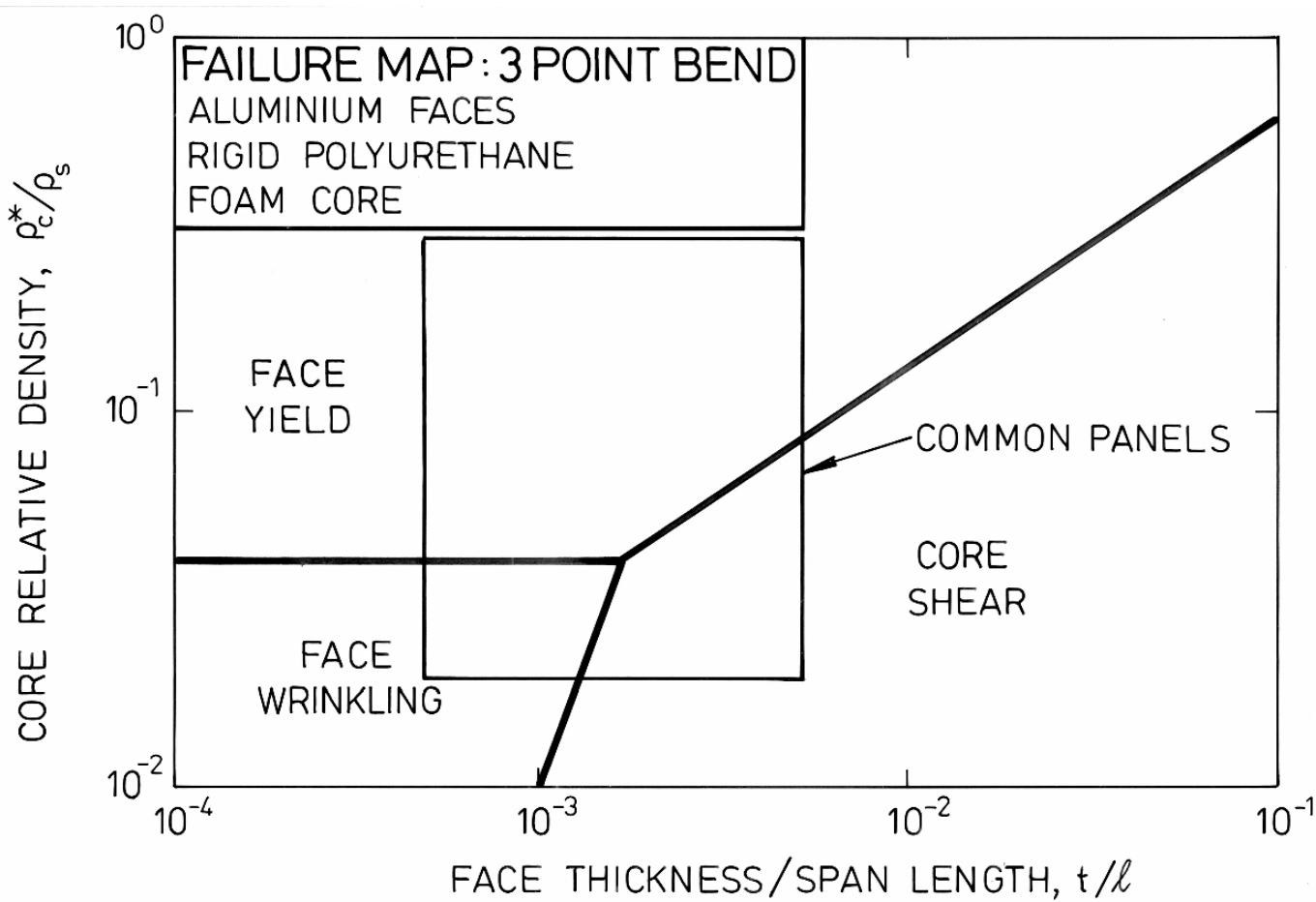
$$\text{or } (\rho_c^* / \rho_s) = \left( \frac{\sigma_{y_f}}{0.57 E_f^{1/3} E_s^{2/3}} \right)^{3/4}$$

i.e. for given face + core materials, at constant  $\rho_c^* / \rho_s$

- face yield - core shear  $\frac{t}{l} = \frac{C_{11} B_4}{B_3} \left( \frac{\rho_c^*}{\rho_s} \right)^{3/2} \left( \frac{\sigma_{ys}}{\sigma_{yf}} \right)$
- face wrinkling - core shear  $\frac{t}{l} = \frac{C_{11} B_4}{0.57 B_3} \frac{\sigma_{ys}}{E_f^{1/3} E_s^{2/3}} \left( \frac{\rho_c^*}{\rho_s} \right)^{1/6}$
- note: transition eqn only involve constants ( $C_{11}, B_3, B_4$ ), material properties ( $E_f, E_s, \sigma_{ys}$ ) &  $t/l, \rho_c^*/\rho_s$ ; do not involve core thickness, c
- can plot transition eqn on plot with axes  $\rho_c^*/\rho_s$  &  $t/l$

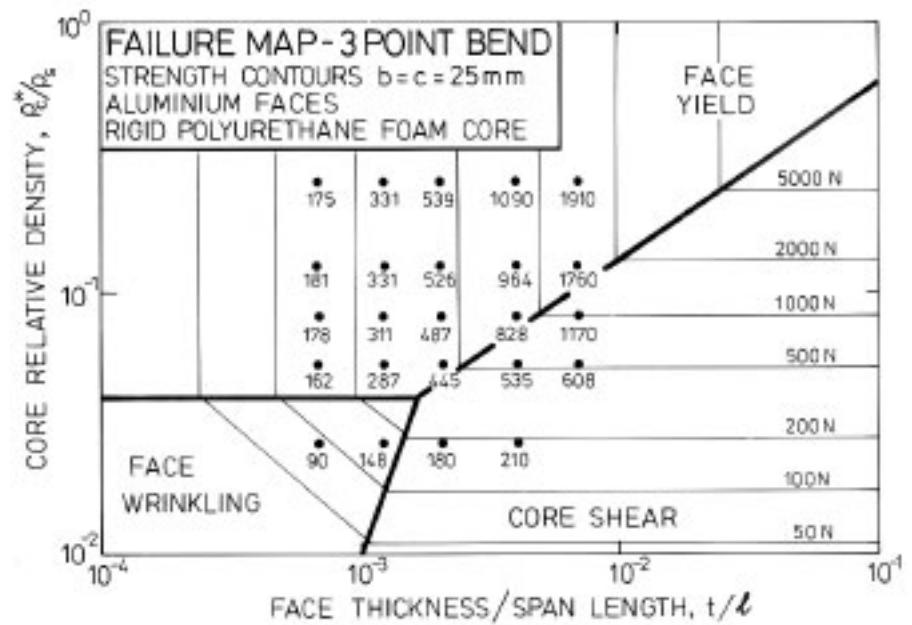
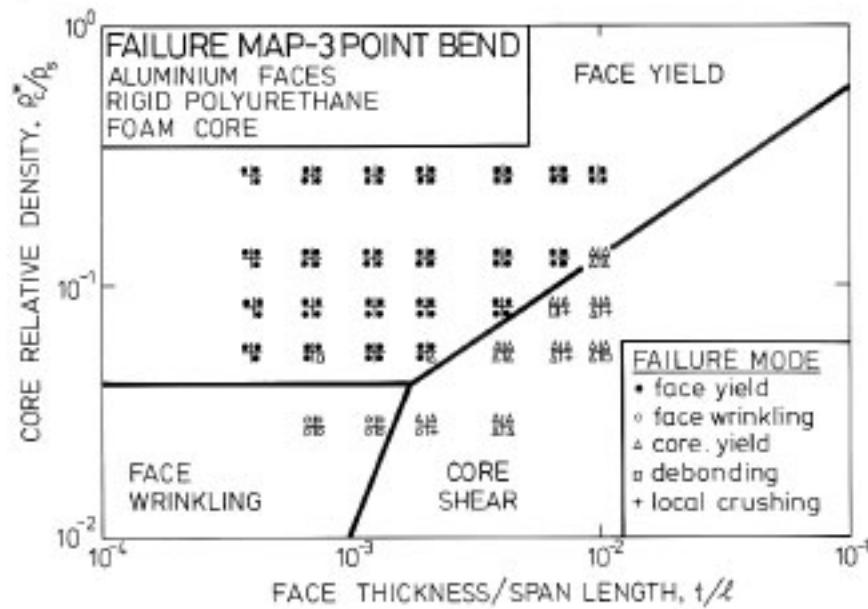
- values of axes chosen to represent realistic values of  
 $\rho_c^*/\rho_s$  - typically 0.02 to 0.3  
 $t/l$  - "  $1/2000$  to  $1/200 = 0.0005$  to 0.005
- low values of  $t/l + \rho_c^*/\rho_s \Rightarrow$  face wrinkling
  - t thin & core stiffness, which acts as elastic friction, low
- low values  $t/l$ , higher values  $\rho_c^*/\rho_s \Rightarrow$  transition to face yielding
- higher values of  $t/l \Rightarrow$  transition to core failure

# Failure Mode Map



Gibson, L. J., and M. F. Ashby. *Cellular Solids: Structure and Properties*. 2nd ed. Cambridge University Press, © 1997. Figure courtesy of Lorna Gibson and Cambridge University Press.

# Failure Map: Expts



Figures 12 and 13: Triantafillou, T. C., and L. J. Gibson. "Failure Mode Maps for Foam Core Sandwich Beams." *Materials Science and Engineering* 95 (1987): 37–53. Courtesy of Elsevier. Used with permission.

- Map shown in figure for three point bending ( $B_3 = 4, B_4 = 2$ )
- changing loading config. moves boundaries a little, but overall, picture similar
- expts on sandwich beams with Al faces + rigid PU foam cores confirm eqn
- if know  $b, c$  - can add contours of failure loads.

Minimum weight design for stiffness + strength :  $t_{opt}, c_{opt}$

given: stiffness  $P/f$

find: face + core thickness,  $t, c$ ,

strength  $P_0$

to minimize weight.

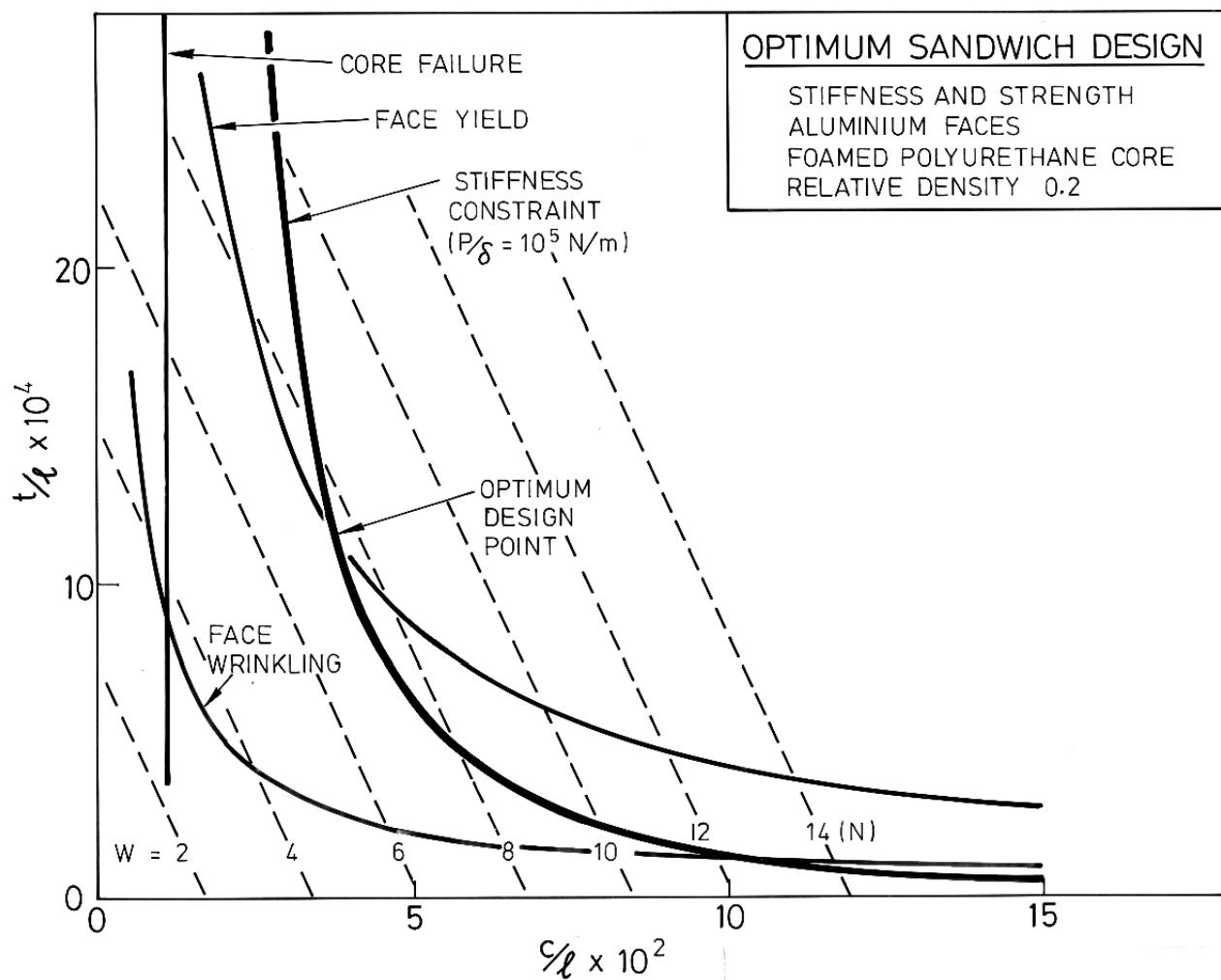
span  $l$  width  $b$

loading configuration ( $B_1, B_2, B_3, B_4$ )

face material ( $\rho_f, \sigma_{yf}, E_f$ )

core material + density ( $\rho_s, E_s, \sigma_{ys}, \rho_c^*$ )

- can obtain solution graphically, axes  $t/\epsilon + c/\epsilon$
  - eqn for stiffness constraint + each failure mode plotted
  - dashed lines - contours of weight
  - design limiting constraints are stiffness + face yielding
  - optimum point - where they intersect
  - could add  $p_c^*/p_s$  as variable on third axis + create surfaces for stiffness + failure eqn; find optimum in same way
- 
- analytical sol<sup>n</sup> possible but cumbersome
  - also, values of  $c/\epsilon$  obtained this way may be unreasonably large - then have to introduce an additional constraint on  $c/\epsilon$  (e.g.  $c/\epsilon < 0.1$ )



Gibson, L. J., and M. F. Ashby. *Cellular Solids: Structure and Properties*. 2nd ed. Cambridge University Press, © 1997. Figure courtesy of Lorna Gibson and Cambridge University Press.

## Minimum weight design : materials

- What are best materials for face + core? (stiffness constraint)
- go back to min. wt. design for stiffness
- can substitute  $(\rho_c^*)_{opt}$ ,  $t_{opt}$ ,  $C_{opt}$  into weight eqn to get min.wt.:

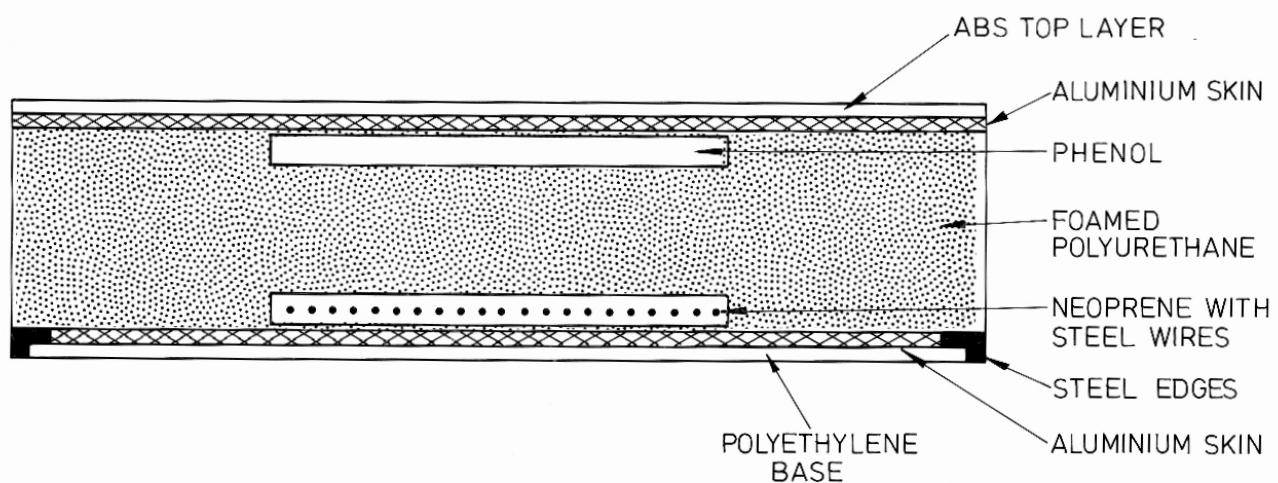
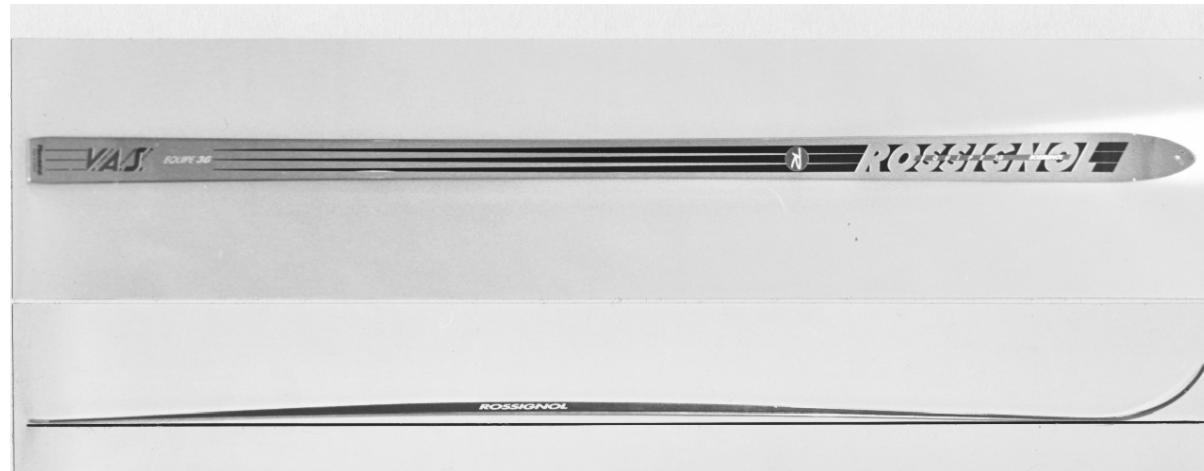
$$W = 3.18 \frac{bl^2}{B_1 B_2 C_2} \left[ \frac{1}{E_f E_s^2} \left( \frac{\rho_f \rho_s}{E_f E_s^2} \right)^4 \left( \frac{P}{\delta b} \right)^3 \right]^{1/5}$$

- 
- faces:  $W$  minimize  $\rho_f$  with materials that minimize  $\frac{\rho_f}{E_f}$  (or maximize  $E_f/\rho_f$ )
  - core:  $W$  minimize  $\rho_s$  or max.  $E_s^{1/2}/\rho_s$
  - note: faces of sandwich loaded by normal stress, axially  
if have solid material loaded axially, want to maximize  $E/\rho$
  - core loaded in shear  $\Rightarrow$  in the foam, cell edges bend  
if have solid material, loaded as beam + in bending + want to  
minimize weight for a given stiffness, Maximize  $E^{1/2}/\rho$
  - sandwich panels may have face + core same material eg. Al face Al foam core.  
Then want to maximize  $E^{3/5}/\rho$   
in integral polymer face/core  
"structural polymer foams"

## Case study: Downhill ski design

- stiffness of ski gives skier right "feel"
- too flexible - difficult to control
- too stiff - skier suspended, as on a plank, between bumps
- skis designed primarily for stiffness
- originally skis made from a single piece of wood
- next - laminated wood skis with denserwood (ash, hickory) on top of lighter wood core (pine, spruce)
- modern skis - sandwich beams
  - faces - fiber composites or Al
  - core - honeycombs, foams (eg. rigid PU), balsa ] controls stiffness.
- additional materials
  - bottom - layer of polyethylene - reduces friction
  - short strip phenol - screw binding in
  - neoprene strip ~ 300mm long - damping
  - steel edges - better control

# Ski Case Study



Gibson, L. J., and M. F. Ashby. *Cellular Solids: Structure and Properties*. 2nd ed. Cambridge University Press, © 1997. Figures courtesy of Lorna Gibson and Cambridge University Press.

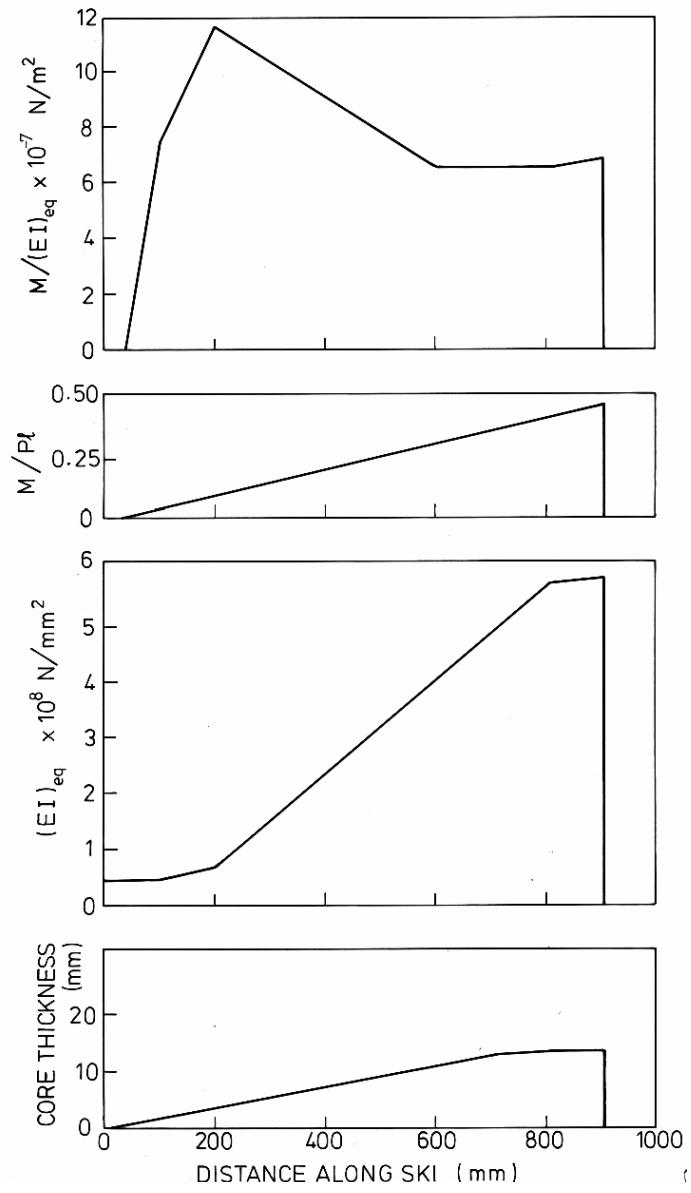
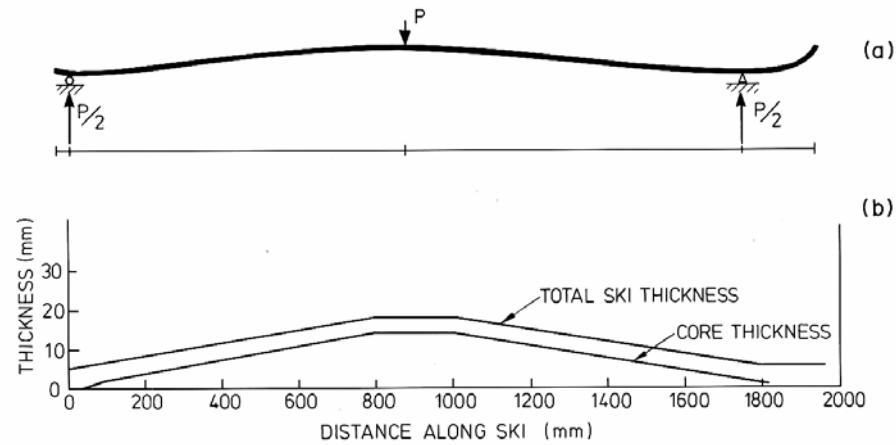
## Ski case study

- Properties of face + core materials

	Al	Solid PU	Foam PU
$\rho$ (Mg/m <sup>3</sup> )	2.7	1.2	0.53
E (GPa)	70	1.94	0.38
G (GPa)	-	-	0.14

- ski geometry
  - Al faces constant thickness t
  - PU foam core - c varies along length, thickest at centre, where moment highest
  - ski cambered
  - mass of ski = 1.3 kg (central 1.7 m, neglecting tip + tail)

# Ski Case Study



Gibson, L. J., and M. F. Ashby. *Cellular Solids: Structure and Properties*. 2nd ed. Cambridge University Press, © 1997. Figures courtesy of Lorna Gibson and Cambridge University Press.

## bending stiffness

- plot  $c$  vs.  $x$ , distance along ski
- calculated  $(EI)_{eq}$  vs  $x$
- calculated Moment applied vs  $x$
- get  $M/(EI)_{eq}$  vs  $x$
- can then find bending deflection,  $\delta_b = 0.28 P$
- shear deflection found from avg. equiv. shear rigidity

$$\delta_s = \frac{Pl}{(AG)_{eq}} = 0.0045 P$$

- $\delta = \delta_b + \delta_s = 0.29 P$        $P/\delta = 3.5 \text{ N/mm}$       measured  $P/\delta = 3.5 \text{ N/mm}$ .
- note current design  $\delta_s \ll \delta_b$ ; at optimum  $\delta_s \sim 2\delta_b$  (constant  $c$ )
- can ski be redesigned to give same stiffness,  $P/\delta$ , at lower weight?
- If use optimization method described earlier (assuming  $c = \text{constant along layout}$ )

$$c_{opt} = 70 \text{ mm}$$

$$t_{opt} = 0.095 \text{ mm}$$

$$\rho_{c, opt}^* = 29 \text{ kg/m}^3$$

mass = 0.31 kg  $\Rightarrow$  75% reduction from current design

But this design impractical

$\Rightarrow c$  too large,  $t$  too small

Alternative approach:

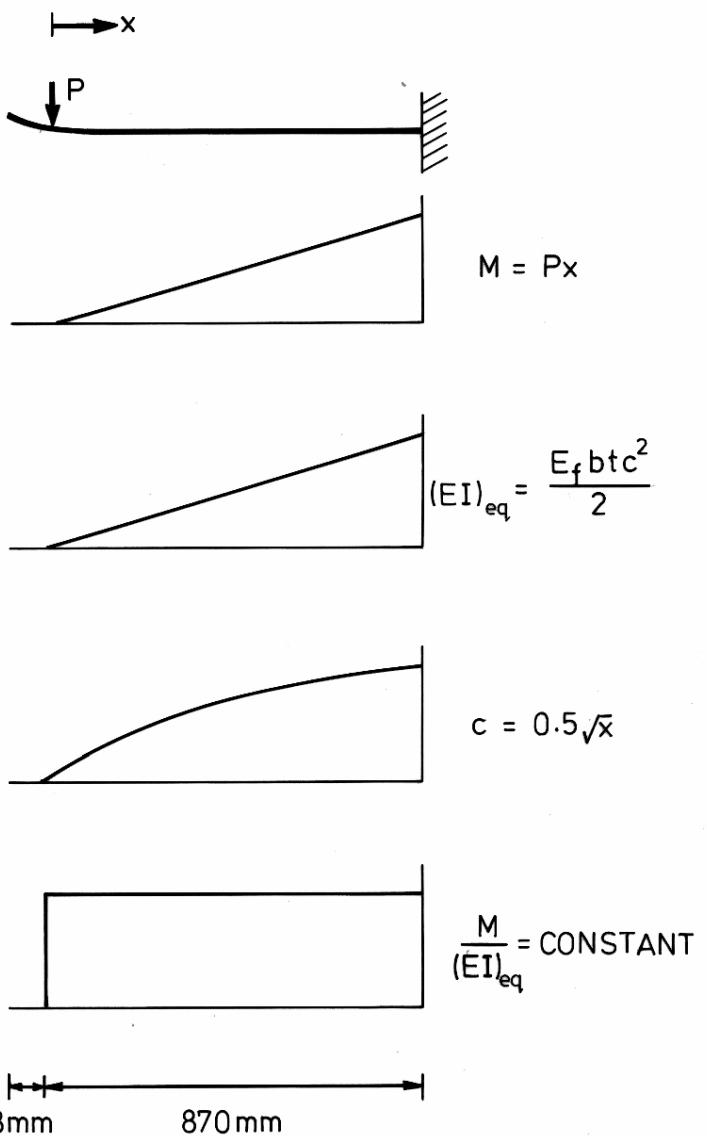
- fix  $c = \text{max. value practical under binding}$  & profile  $c$  to give constant  $M/(EI)_{\text{eq}}$  along length of ski (use  $c_{\text{max}} = 15\text{mm}$ )
- find values of  $t, \rho_c^*$  to minimize wt. for  $P/\delta = 3.5\text{ N/mm}$ .
- Moment  $M$  varies linearly along the length of the ski
- Want  $(EI)_{\text{eq}}$  to vary linearly, too;  $(EI)_{\text{eq}} = E_f b t c^2 / 2$
- Want  $c \propto \sqrt{x}$ , distance along length of ski

- half length of ski is  $870\text{mm}$  &  $c_{\text{max}} = 15\text{mm}$

$$c = 15 \left( \frac{x}{870} \right)^{1/2} = 0.51x^{1/2} \text{ (mm)}$$

- can now do minimum weight analysis with

$$\delta = \frac{\frac{Pl^3}{2}}{B_1 E_f b t (c_{\text{max}} + t)^2} + \frac{Pl}{B_2 C_2 b c_{\text{max}} (\rho_c^*/l_s)^2 E_s}$$



- $B_1$  - corresponds to beam with constant  $M/EI$
- $B_2$  - cantilever value ( $B_2=1$ ) multiplied by avg. value of  $c$  divided by maximum value of  $c$   $B_2 = \frac{2}{3}$
- solve stiffness eq'n for  $\rho_c^*$ , substitute into weight eq'n + take  $\frac{\partial w}{\partial t} = 0$
- solve for  $t_{opt}$ , then  $\rho_c^{*opt}$
- find:  $C_{max} = 15 \text{ mm}$        $\rho_c^{*opt} = 163 \text{ kg/m}^3$   
 $t_{opt} = 1.03 \text{ mm}$       mass = 0.88 kg  $\Rightarrow$  31% less than current design

### Daedalus

- MIT designed + built human powered aircraft (1980s)
  - flew 72 miles in  $\sim 4$  hrs. from Crete to Santorini, 1988
  - Kanellos Kanellopoulos - Greek bicyclist champion pedalled + flew
- |          |                           |                                                               |
|----------|---------------------------|---------------------------------------------------------------|
| mass     | $68.5 \# = 31 \text{ kg}$ | propeller: kevlar faces, PS foam core (11' long)              |
| length   | $29' = 8.8 \text{ m}$     | wing + trailing edge strips kevlar faces / rohacell foam core |
| wingspan | $112' = 34 \text{ m}$     | tail surface struts: carbon composite faces, balsa core       |

# Daedalus



Mass = 31 kg

Length = 8.8m

Wingspan = 34m

Propeller blades = 3.4m

Courtesy of NASA. Image is in the public domain. [NASA Dryden Flight Research Center Photo Collection.](#)

Flew 72 miles, from Crete to Santorin, in just under 4 hours

Sandwich panels: propeller, wing and tail trailing edge strips, tail surface struts

Image: MIT Archives

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3.054 / 3.36 Cellular Solids: Structure, Properties and Applications

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