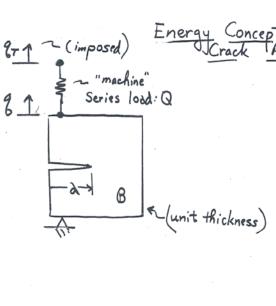
#### DEPT. OF MATERIALS SCIENCE

#### 3.35 FRACTURE AND FATIGUE

Guest lecture by Prof. David M. Parks
October 2, 2003



Energy
 Potential energy: T = π (g<sub>T</sub>, a)
 - "Machine" Strain energy: U

- "Body" Strain energy: W

$$\nabla = \int_{0}^{gm} Q(g_{m}) dg_{m}; \Rightarrow dV = Q dg_{m}$$

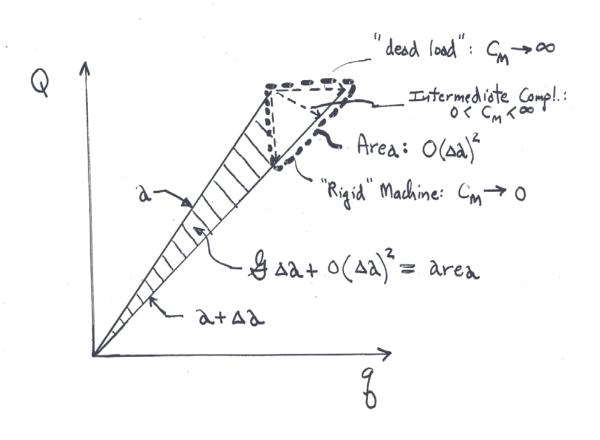
$$\nabla = \int_{0}^{gm} Q(g_{m}) dg_{m}; \Rightarrow dV = Q dg_{m}$$

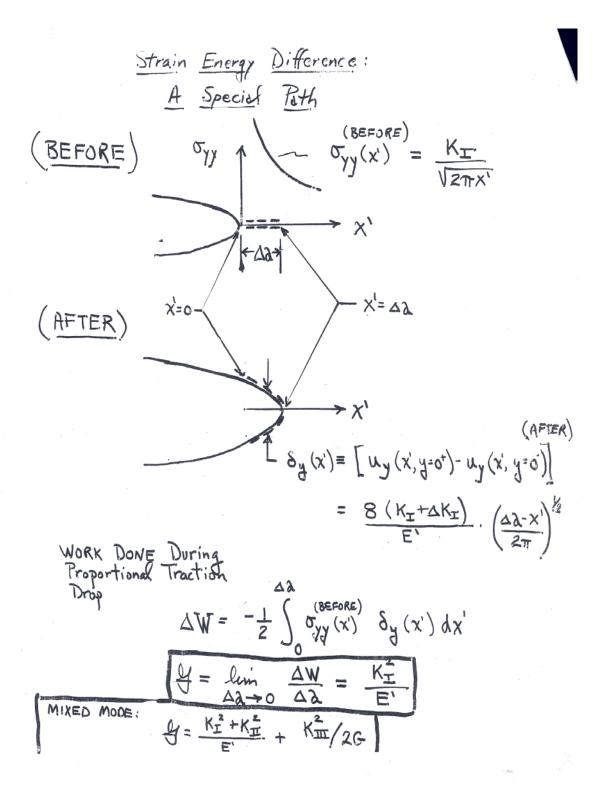
$$\nabla = \int_{0}^{gm} Q(g_{m}) dg_{m}; \Rightarrow dV = Q dg_{m}$$

$$d\pi = Q\left(\frac{dq + dq_m}{\partial x} + \left[ \int_0^q \frac{\partial Q}{\partial x} dq' \right] da$$

$$\Rightarrow \frac{\partial Q}{\partial x} = -\int_0^q \frac{\partial Q}{\partial x} dq'$$

# Machine Compliance: dgm = CMQ





The J-Integral

Assumptions (Relaxable/ Generalizable Linear elasticity/quasistatic No body forces Traction-free Crack

$$W(\underline{\varepsilon}) = \int_{0}^{\varepsilon} \underline{\sigma}(\underline{\varepsilon}) \cdot d\underline{\varepsilon} = \frac{1}{2} \underline{\sigma} \cdot \underline{\varepsilon} = \frac{1}{2} \underline{\sigma}_{ij} \underline{\varepsilon}_{ij}$$

$$Le^{+} \underline{T} = \int_{0}^{\varepsilon} \{ w n_{1} - \underline{\sigma}_{ij} n_{j} u_{i,1} \} ds$$

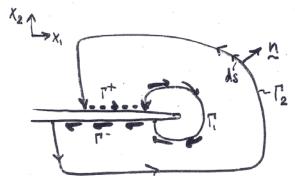
$$= \int_{0}^{\varepsilon} \{ w \delta_{1j} - \underline{\sigma}_{ij} u_{i,1} \} dA$$

$$= \int_{0}^{\varepsilon} \underbrace{\{ w \delta_{1j} - \underline{\sigma}_{ij} u_{i,1} \}} dA$$

$$= \int_{0}^{\varepsilon} \underbrace{\{ w \delta_{1j} - \underline{\sigma}_{ij} u_{i,1} \}} dA$$

$$\frac{\partial_{x_{i}} \frac{\partial w}{\partial x_{i}}}{\partial x_{i}} = \frac{\partial w}{\partial \varepsilon_{mn}} \frac{\partial \varepsilon_{mn}}{\partial x_{i}} = \frac{\partial_{x_{i}} \sigma_{mn}}{\partial x_{i}} = \frac{\partial_{x_{i}$$

## Path-Independence of J



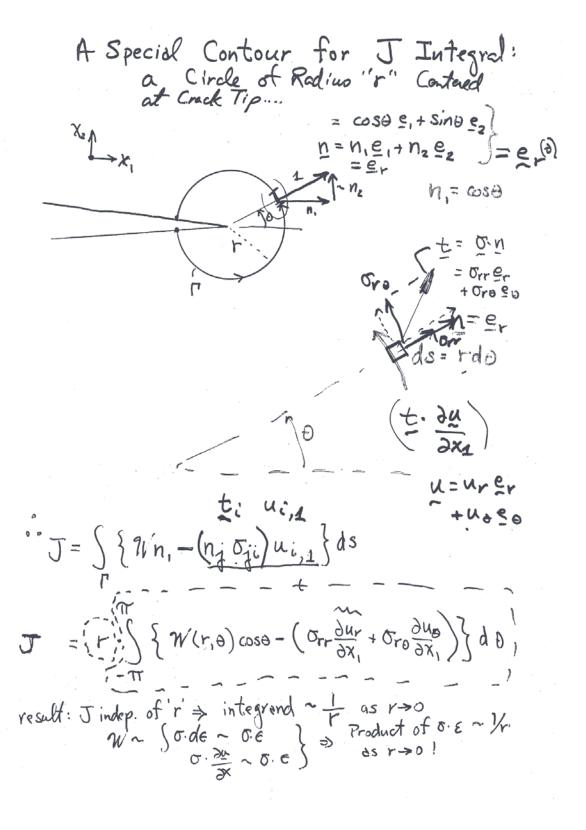
Let  $J(r) = \int \left\{ \frac{w_{n_1} - \sigma_{ij} n_j u_{i,1}}{\sigma_{ij} n_j u_{i,1}} \right\} ds$ 

tor any a path 1° starting on lower face and terminating on top face...

Path-Independence:  $J(r_1) = J(r_2) = J$ 

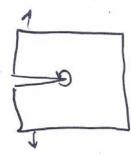
But:  $\int_{\Gamma^+} \{-\frac{1}{2} ds = \int_{\Gamma^-} \{-\frac{1}{2} ds = 0 \}$  because  $n_2 = 0$  & t := 0;  $n_3 = 0$ 

 $\frac{AND}{(-r_i)} \int_{r_i}^{\xi-1} ds = -\int_{r_i}^{\xi-1} ds \Rightarrow \left( \int_{r_i}^{\xi-1} ds = \int_{r_i}^{\xi-$ 



# Linear Elasticity: $J = \mathcal{L} = K_I^2 / E'$

· Method 1:



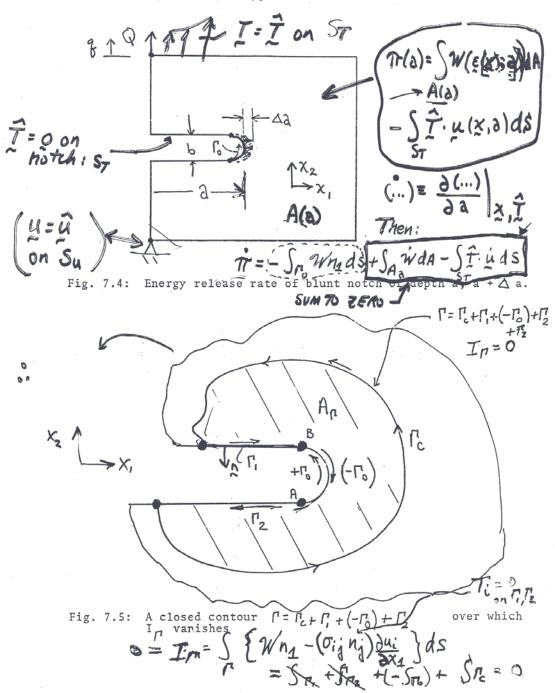
insert asymptotic  $K_I$ -fields of  $\sigma_{ij}$ ,  $\epsilon_{ij}$ ,  $u_i$ , and  $W=\frac{1}{2}\sigma_{ij}\epsilon_{ij}$  into

I integrand; evaluate on circle of radius "r"

 $W \sim \sigma \cdot \varepsilon \sim \left(\frac{K}{V_F}\right) \left(\frac{K}{EV_F}\right) \sim \frac{K^2}{EV_F}$   $\Rightarrow J = K_I^2 \left(\frac{E'}{E'}\right)$ 

· Method 2

Line integral J directly
evaluates & (energy flux) (Rice);  $J = \mathcal{Y} = \left( \text{previous} \cdot K_{I}^{2} / E' \right)$ 



Swan = 
$$ST$$
 uds

A(a)

PRINCIPAL OF Virtual Work

(Power)

=  $S_{1}$   $S_{2}$   $S_{3}$   $S_{4}$   $S_{5}$   $S_{7}$   $S_{10}$   $S_{10}$ 

- Traction free on 
$$\Gamma_0 = 0$$

- Traction free on  $\Gamma_0 = 0$ 

- Add zero

- Traction free on  $\Gamma_0 = 0$ 

 $T_{n} = 0 = -\int_{0}^{\infty} w_{n} - O_{ij} \eta_{j} \frac{\partial u_{i}}{\partial x_{1}} ds + \int_{0}^{\infty} w_{n} ds$   $= -\pi = \int_{0}^{\infty} w_{n} - \int_{0}^{\infty} w_{n} ds = \int_{0}^{\infty} \int_{0}^{\infty} w_{n} - h_{i} O_{ij} u_{j} ds$   $= \int_{0}^{\infty} w_{n} - h_{i} \int_{0}^{\infty} u_{j} ds = \int_{0}^{\infty} \int_{0}^{\infty} w_{n} - h_{i} O_{ij} u_{j} ds$   $= \int_{0}^{\infty} w_{n} - h_{i} \int_{0}^{\infty} u_{j} ds = \int_{0}^{\infty} \int_{0}^{\infty} w_{n} - h_{i} O_{ij} u_{j} ds$   $= \int_{0}^{\infty} w_{n} - h_{i} \int_{0}^{\infty} u_{j} ds = \int_{0}^{\infty} \int_{0}^{\infty} w_{n} - h_{i} O_{ij} u_{j} ds$   $= \int_{0}^{\infty} w_{n} - h_{i} \int_{0}^{\infty} u_{j} ds = \int_{0}^{\infty} \int_{0}^{\infty} w_{n} - h_{i} O_{ij} u_{j} ds$   $= \int_{0}^{\infty} w_{n} - h_{i} \int_{0}^{\infty} u_{j} ds = \int_{0}^{\infty} \int_{0}^{\infty} w_{n} - h_{i} O_{ij} u_{j} ds$   $= \int_{0}^{\infty} w_{n} - h_{i} \int_{0}^{\infty} u_{j} ds = \int_{0}^{\infty} \int_{0}^{\infty} w_{n} - h_{i} O_{ij} u_{j} ds$   $= \int_{0}^{\infty} w_{n} - h_{i} \int_{0}^{\infty} u_{j} ds = \int_{0}^{\infty} \int_{0}^{\infty} w_{n} - h_{i} O_{ij} u_{j} ds$   $= \int_{0}^{\infty} w_{n} - h_{i} \int_{0}^{\infty} u_{j} ds = \int_{0}^{\infty} \int_{0}^{\infty} w_{n} - h_{i} O_{ij} u_{j} ds$   $= \int_{0}^{\infty} w_{n} - h_{i} \int_{0}^{\infty} u_{j} ds$   $= \int_{0}^{\infty} w_{n} - h_{i} \int_{0$ 

 $\int_{-\pi}^{s} \int_{-\pi}^{s} \int_{-\pi}^{s} \left\{ w_{n_1} - n_i \sigma_{ij} u_{j2} \right\} ds$ 

Obvious extensions: surface tractions, body forces

area terms or crack face

traction contributions to

integral...

The utility of (the numerical value of) a conservation integral such as I inthe interpretation of fracture must rest on an aunique relation between the value and aspects of the crack tip field relevant to crack extension....

### Power Law Materials / HRR Fields