

Ambient Sound Provides Supervision for Visual Learning



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Motivation





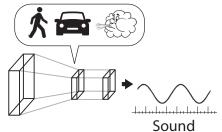


Can we learn image representations using ambient sound — instead of manual annotations — as a supervisory signal?

Task: Predict sound from a video frame. To perform this task well, the model should learn to recognize objects and scenes.

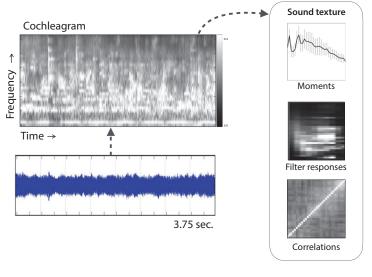


Video frame



Audio representation

We represent audio using *sound textures* — collections of time-averaged summary statistics [1].



We create a discrete label space by clustering the audio features with k-means, or with an LSH-like binary code.

- [1] J. H. McDermott and E. P. Simoncelli. Sound texture perception via statistics of the auditory periphery: evidence from sound synthesis. Neuron, 2011.
- [2] B. Zhou, A. Khosla, A. Lapedriza, A. Oliva, A. Torralba. Object detectors emerge in deep scene CNNs. ICLR 2015.
- [3] A. Owens, P. Isola, J. McDermott, A. Torralba, E.H. Adelson, W.T. Freeman. Visually indicated sounds. CVPR, 2016.
- [4] W. Gaver. What in the world do we hear?: An ecological approach to auditory event perception. *Ecological psychology*, 1993.
- [5] J. Ngiam, A. Khosla, M. Kim, J., Nam, H. Lee, A.Y. Ng. Multimodal deep learning. ICML 2011.

Sound prediction model



Images grouped by audio cluster

Classification with linear SVM

Clustered audio stats.

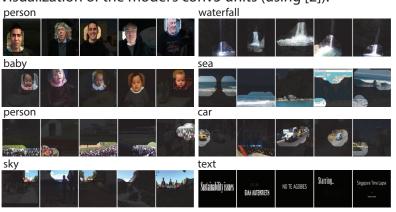
Eina tuning East D CNN

Results

The image features that our model learns perform comparably to state-of-the-art unsupervised methods on recognition tasks.

Classification with lifear 5000								Tille-turning rast N-CNN		
Method	VOC Cls. (%mAP)				SUN397 (%acc.)				Method	(%mAP)
	max5	pool5	fc6	fc7	max5	pool5	fc6	fc7	Random init. (Krähenbühl et al.)	41.3
Sound (cluster)	36.7	45.8	44.8	44.3	17.3	22.9	20.7	14.9	Sound (cluster)	44.1
Sound (binary)	39.4	46.7	47.1	47.4	17.1	22.5	21.3	21.4	Sound (binary)	43.3
Sound (spectrum only)	35.8	44.0	44.4	44.4	14.6	19.5	18.6	17.7	Tracking (Wang and Gupta)	44.0
Texton-CNN	28.9	37.5	35.3	32.5	10.7	15.2	11.4	7.6	Egomotion (Agrawal et al.)	41.8
K-means (Krähenbühl et al.)	27.5	34.8	33.9	32.1	11.6	14.9	12.8	12.4	Patch pos. (Doersch et al.)	46.6
Tracking (Wang and Gupta)	33.5	42.2	42.4	40.2	14.1	18.7	16.2	15.1	Calib. + Patch (Krähenbühl et al.	
Patch pos. (Doersch et al.)	26.8	46.1	-	-	9.8	22.2	-	-		
Egomotion (Agrawal et al.)	22.7	31.1	-	-	9.1	11.3	-	-	ImageNet (Krizhevsky et al.)	57.1
ImageNet (Krizhevsky et al.)									Places (Zhou et al.)	52.8
Dlagon (7hou et al.)	50.0	69 9	65 9	66 9	20.4	49 1	46 1	400		

Visualization of the model's conv5 units (using [2]):



The units tend to be selective for objects that are associated with a characteristic sound (e.g. people and waterfalls).

