Flow Chart

Ajjas Telematics Aim **CAN Protocol** 2 Description Manual Connection Block Diagram App Features DBC file Camera Aim Description Installation Guide **Website** Manual Aim Description **Features** Designs Calculations

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- Aim
- Description
- Bill of materials
- BOM with ANT BMS

HMI Cluster and

Telematics

- BOM with JBD BMS
- Features
 - HMI
 - Cluster features
 - ii. Features list
 - Telematics
 - i. Telematics list
- Procedure
 - Document
 - i. cluster and telematics document
- Observations
 - HMI observations
 - i. Operations
 - 1. vehicle assembly
- Designs
 - o HMI
 - i. <u>Components</u>
 - Components List
 - **Components Details** a. Arduino Mega
 - b. Buck converter

 - c. Dwin Display
 - d. MCP2515 CAN Module e. 4 channel Relay
 - f. RFID reader
 - ii. <u>Hardware Design</u>
 - Pcb fabrication file
 - Pcb Schematics file
 - Pcb Gerber files
 - iii. Software Design 1. Dwin display files
 - 2. Arduino firmware
 - Telematics
 - Components
 - Components List Component Details
 - a. ESP32

 - b. MCP2515 CAN Module
 - c. MPU6050 gyroscope d. Neo-6m GPS
 - ii. Hardware Design • Pcb fabrication file
 - Pcb Schematics file
 - Pcb Gerber files
 - iii. Software Design
 - 1. Esp32 firmware

 - Testing
 - Component testing
- Performance testing
- Reliability testing
 - Unit testing
 - Testing flowChart

- Battery CAN File
- **ANT BMS Protocol**
- JBD BMS Protocol
- Controller CAN File CAN
- - a. Efficiency calculation
 - b. Gradient Calculation
 - c. Weight Calculation
- Web app design UI
 - a. UI images
 - b. Operational Video
- Software files
 - a. Client Files

b. Server Files

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