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**Class : TY-IT-A**

**Roll No : 54**

**Batch No : B2**

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**Lab No : 02 Part B**

**Problem Statement : 8 Puzzle using A\* algorithm**

**Code:**

```
#include <iostream>
#include <vector>
#include <algorithm>
using namespace std;

struct node
{
    vector<vector<int>> arr; // matrix
    int level;
    int h;
    node *prev;
    node()
    {
        level = 0;
        prev = NULL;
        h = 0;
    }
};

void printmatrix(vector<vector<int>> mat)
{
    cout << "\nBoard Position:\n";
    for (int i = 0; i < 3; i++)
    {
        for (int j = 0; j < 3; j++)
        {
            cout << mat[i][j] << "\t";
        }
        cout << endl;
    }
}

// calculate heuristic value
int getscore(vector<vector<int>> &ans, vector<vector<int>> mat)
{
    int cnt;
    for (int i = 0; i < 3; i++)
    {
        for (int j = 0; j < 3; j++)
```

```

        {
            if (mat[i][j] != ans[i][j])
            {
                cnt++;
            }
        }
    }
    cout << "\nHeuristic value: " << cnt;
    return cnt;
}

```

```

// comparing nodes based on heuristic values
bool comp(node a, node b)
{
    return a.h < b.h;
}

```

```

bool isinset(node a, vector<node> b)
{
    for (int i = 0; i < b.size(); i++)
    {
        if (a.arr == b[i].arr)
        {
            return true;
        }
    }
    return false;
}

```

```

void printlist(vector<node> open)
{
    for (auto iter : open)
    {
        printmatrix(iter.arr);
    }
}

```

```

void getpath(node curr, vector<node> &ans)
{
    node *temp = &curr;
    try
    {
        while (temp != NULL)
        {
            ans.push_back(*temp);
            temp = temp->prev;
        }
    }
    catch (const bad_alloc &e)
    {
        cout << "\nFailed in while loop" << e.what() << '\n';
    }
}

```

```

void addmove(node current, vector<vector<int>> goal, int i, int j, int posi, int
posj, vector<node> &openset, vector<node> &closet)
{

```

```

node newstate;
newstate = current;
swap(newstate.arr[i][j], newstate.arr[posi][posj]);
if (!isinset(newstate, closet) && !isinset(newstate, openset))
{
    newstate.level = current.level + 1;
    newstate.h = newstate.level + getscore(goal, newstate.arr);
    cout << "\nValue of node(f') is: " << newstate.h;
    node *temp = new node();
    *temp = current;
    newstate.prev = temp;
    openset.push_back(newstate);
}
}

void possiblemove(node current, vector<vector<int>> goal, vector<node> &openset,
vector<node> &closet)
{
    int posi, posj, val;
    int i, j;
    for (i = 0; i < 3; i++)
    {
        for (j = 0; j < 3; j++)
        {
            val = current.arr[i][j]; // storing index of vacant space and generating
possible moves by calling add function
            if (val == 0)
            {
                posi = i;
                posj = j;
                break;
            }
        }
    }
    i = posi;
    j = posj;
    if (i - 1 >= 0)
    {
        addmove(current, goal, i - 1, j, posi, posj, openset, closet);
    }
    if (i + 1 <= 3)
    {
        addmove(current, goal, i + 1, j, posi, posj, openset, closet);
    }
    if (j - 1 >= 0)
    {
        addmove(current, goal, i, j - 1, posi, posj, openset, closet);
    }
    if (j + 1 <= 3)
    {
        addmove(current, goal, i, j + 1, posi, posj, openset, closet);
    }
}

bool astar(vector<vector<int>> goal, vector<vector<int>> start)
{
    vector<node> openset;

```

```

vector<node> closet;
node current;
current.arr = start;
current.level = 0; // g value also called
as actual cost
current.h = current.level + getscore(goal, current.arr); // f value
openset.push_back(current);
while (openset.size() > 0)
{
    // sorting the nodes based on their f values
    sort(openset.begin(), openset.end(), comp);
    node temp = openset[0];
    cout << "\nPrinting Open Set:\n";
    printlist(openset);
    if (temp.arr == goal)
    {
        vector<node> ans;
        getpath(temp, ans);
        for (int i = ans.size() - 1; i >= 0; i--)
        {
            printmatrix(ans[i].arr);
        }
        return true;
    }
    // removing node from open set
    openset.erase(openset.begin());
    cout << "\nPrinting the openset after removing best node:\n";
    printlist(openset);
    cout << "\nPrinting the close set after adding best node to it: \n";
    closet.push_back(temp);
    printlist(closet);
    // generate possible moves
    possiblemove(temp, goal, openset, closet);
}
return false;
}

```

```

int main()
{
    vector<vector<int>> ans(3, vector<int>(3));
    ans[0][0] = 1;
    ans[0][1] = 2;
    ans[0][2] = 3;
    ans[1][0] = 8;
    ans[1][1] = 0;
    ans[1][2] = 4;
    ans[2][0] = 7;
    ans[2][1] = 6;
    ans[2][2] = 5;
    vector<vector<int>> mat(3, vector<int>(3));
    int sum = 36;
    cout << "Enter the elements of matrix:\n";
    for (int i = 0; i < 3; i++)
    {
        for (int j = 0; j < 3; j++)
        {
            cin >> mat[i][j];

```

```

        sum = sum - mat[i][j];
    }
}
if (sum != 0)
{
    cout << "\nInvalid Input";
    return 0;
}
if (astar(ans, mat))
{
    cout << "\nSuccessful in solving 8 puzzle";
}
else
{
    cout << "\nFailed in solving 8 puzzle";
}
return 0;
}

```

## Output:

Enter the elements of matrix:

1 0 3

8 2 4

7 6 5

Heuristic value: 2

Printing Open Set:

Board Position:

1        0        3

8        2        4

7        6        5

Printing the openset after removing best node:

Printing the close set after after adding best node to it:

Board Position:

1        0        3

8        2        4

7        6        5

Heuristic value: 0

Value of node(f') is: 1

Heuristic value: 3

Value of node(f') is: 4

Heuristic value: 3

Value of node(f') is: 4

Printing Open Set:

Board Position:

1	2	3
8	0	4
7	6	5

Board Position:

0	1	3
8	2	4
7	6	5

Board Position:

1	3	0
8	2	4
7	6	5

Board Position:

1	0	3
8	2	4
7	6	5

Board Position:

1	2	3
8	0	4
7	6	5

Successful in solving 8 puzzle

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Enter the elements of matrix:

1	5	3
2	4	6
8	7	9

Invalid Input

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