

CS411-AS4 Problems

1. Rotate by 45° about axis given by $(0, 1, 0)$
 $(0, 1, 0) \rightarrow y\text{-axis}.$

$$R_y(\theta) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1/\sqrt{2} & -1/\sqrt{2} & 0 \\ 0 & 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad \theta = 45^\circ //$$

$$\rightarrow \begin{bmatrix} 1/\sqrt{2} & 0 & 1/\sqrt{2} & 0 \\ 0 & 1 & 0 & 0 \\ -1/\sqrt{2} & 0 & 1/\sqrt{2} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} //$$

2. Rotate vector $(1, 1, 0)$ to be aligned with $(0, 1, 0)$
 $(y\text{-axis})$ in homogeneous co-ordinates.
 $(1, 1, 0) \rightarrow (0, 1, 0)$

we can rotate about z by 45°

$$R_z(\theta) = \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} & 0 & 0 \\ 1/\sqrt{2} & 1/\sqrt{2} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

3. $R_u(\theta) = I + \sin\theta U + (1 - \cos\theta)U^2.$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 1/\sqrt{2} \\ 0 & 0 & -1/\sqrt{2} \\ -1/\sqrt{2} & 1/\sqrt{2} & 0 \end{bmatrix} + \begin{bmatrix} -(\sqrt{2}-1)/\sqrt{2} & (\sqrt{2}-1)/\sqrt{2} & 0 \\ (\sqrt{2}-1)/\sqrt{2} & -(\sqrt{2}-1)/\sqrt{2} & 0 \\ 0 & 0 & -2+\sqrt{2} \end{bmatrix}$$

$$= \begin{bmatrix} 1/\sqrt{2} & (\sqrt{2}-1)/\sqrt{2} & 0 \\ (\sqrt{2}-1)/\sqrt{2} & 1/\sqrt{2} & -1/\sqrt{2} \\ -1/\sqrt{2} & 1/\sqrt{2} & -2+\sqrt{2} \end{bmatrix} = R_y R_z R_y //$$

1.4. $P = (1, 2, 3)$ $u = (1, 0, 1)$
 $v = (-1, -2, -3)$

Compute transformation matrix:

For direction of flight,

Rotation about $\rightarrow \left[\frac{-1}{\sqrt{14}}, \frac{-2}{\sqrt{14}}, \frac{-3}{\sqrt{14}} \right]$

$$R_x = \begin{bmatrix} -1/\sqrt{14} & -2/\sqrt{14} & -3/\sqrt{14} & 0 \\ 2/\sqrt{14} & -1/\sqrt{14} & -3/\sqrt{14} & 0 \\ -3/\sqrt{14} & -2/\sqrt{14} & 1/\sqrt{14} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Rotation for the up vector will be a rotation about y-axis by 45° .

$$R_y = \begin{bmatrix} \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} & 0 \\ 0 & 1 & 0 & 0 \\ -1/\sqrt{2} & 0 & 1/\sqrt{2} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Translate by $(1, 2, 3)$

$$T = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$M = T R_y R_x = \begin{bmatrix} -0.75 & -0.83 & -0.37 & 1 \\ -0.53 & -0.26 & -0.53 & 2 \\ -0.37 & -0.94 & 0.75 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

1.5

$$r_1 = [1, 2, 3, 3] \quad r_2 = [2, 3, 4, 4] \quad r_3 = [3, 4, 4, 5] \quad r_4 = [0, 0, 0, 1]$$

$$= \begin{bmatrix} 1 & 2 & 3 & 3 \\ 2 & 3 & 4 & 4 \\ 3 & 4 & 4 & 5 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$v = (0, 0, 1)$ compute transform on v by M .

$$(M^{-1})^T = \begin{bmatrix} -4 & 4 & -1 & 0 \\ 4 & -5 & 2 & 0 \\ -1 & 2 & -1 & 0 \\ 1 & -2 & 0 & 1 \end{bmatrix} //$$

transformed v in 3DH $= (M^{-1})^T v =$

$$\begin{bmatrix} -4 & 4 & -1 & 0 \\ 4 & -5 & 2 & 0 \\ -1 & 2 & -1 & 0 \\ 1 & -2 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ -1 \\ 1 \end{bmatrix}$$

$$[-1, 2, -1, 1] \rightarrow 3D (-1, 2, -1) //$$

1.6

If we want to preserve the z -coordinate.
we can use the orthographic projection matrix
 I which leaves the point at $(1, 2, 3) //$

1.7.

$$P = (1, 2, 3) \quad v = (0, -1, 1)$$

Align v with z axis...

$$\begin{bmatrix} 1 & 0 & \cot \alpha \cos \phi & 0 \\ 0 & 1 & \cot \alpha \sin \phi & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

solving, $\cot \alpha \cos \phi = 0$
 $-1 + \cot \alpha \sin \phi = 0$ — (1)
 — (2)

$\therefore \phi = \cos^{-1} 0 \Rightarrow \phi = 90^\circ //$

substituting,

$-1 + \cot \alpha \sin 90 = 0$
 $\Rightarrow \cot \alpha = 1 \Rightarrow \alpha = \cot^{-1}(1)$
 $\alpha = 45^\circ //$

\therefore The point (3DH) $= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 5 \\ 3 \\ 1 \end{bmatrix}$

In 3D $\Rightarrow (1, 5, 3) //$

1.8 $P = (1, 2, 3)$ be 3D point. $f = 10M.$

$P' = \begin{bmatrix} 10 & 0 & 0 & 0 \\ 0 & 10 & 0 & 0 \\ 0 & 0 & 10 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 10 \\ 20 \\ 30 \\ 1 \end{bmatrix}$

3DH \rightarrow 3D $\rightarrow (3.33, 6.66, 10) //$