

Part (a)

Listen to the recording you made, stored in the file `recording.wav`. You can load recordings using the `load_recording` function that we have written for you and imported. You can play recordings using the `play` function that we have also written and imported.

```
In [1]: import numpy as np
        from utils import load_recording, play, save_recording

        RECORDING_FILE = "recording.wav"

        r = load_recording(RECORDING_FILE)
        play(r)
```

-0:10

Part (b)

Let \vec{r} be your recording. Let us say you have access to the true lecture given by \vec{l} . You know that your received vector and the lecture have the relationship

$$\vec{r} = \alpha \vec{l} + \vec{n},$$

where α is an unknown constant. Estimate \vec{n} by projecting \vec{r} onto \vec{l} to recover α . What remains is \vec{n} . Assume that \vec{l} is orthogonal to \vec{n} .

```
In [5]: # Note that l and r are 1D arrays, not 2D arrays, so calling np.linalg
        def projection(l, r):
            return np.dot(l, r) / (np.linalg.norm(l)**2) * l
```

```
In [6]: def recover_noise(r, l):
        return r - projection(l, r)
```

```
In [7]: #We use the technique above to recover candidate interference signals.

#noisy_lectures contains the lecture recordings with interference
noisy_lectures = [load_recording("noisy_lecture_{}.wav".format(i+1)) for i in range(10)]

# lectures contains the clean lectures that you played to understand the
lectures = [load_recording("lecture_{}.wav".format(i+1)) for i in range(10)]

# interferences is a matrix whose columns contain the possible interference signals
interferences = np.column_stack([recover_noise(r_i, l_i) for r_i, l_i in zip(noisy_lectures, lectures)])

#you can change the index 0 below to play different lectures and recover the clean signal
play(lectures[0])
play(noisy_lectures[0])
play(interferences[:, 0])
```

-0:14

-0:20

-0:21

Part (c)

Now, given \vec{r} and the \vec{n}_i , and the model

$$\vec{r} = \vec{l} + \sum_{i=1}^s \beta_i \vec{n}_i,$$

use least squares to recover \vec{l} . The \vec{n}_i are computed from the \vec{r}_i using your function from the previous part.

```
In [11]: #r is the signal you have recorded
r = load_recording(RECORDING_FILE)

# Project r onto the interference signals to recover the component of
# What remains must be the lecture.

A = interferences
b = r

# Hint, use least squares
betas = np.linalg.lstsq(A, b)[0]
print(betas)

# This is the recovered lecture. Have you successfully recovered a
# noise-free signal? Or is it still noisy?
l = b - A.dot(betas)

play(l)
```

```
[-0.07080106 -0.09364032  0.11021623  0.02728798]
```

```
-0:16
```

Part (d)

Now, we will include the effect of the travel time of the noise signals, using the model

$$\vec{r} = \vec{l} + \sum_{i=1}^s \beta_i \vec{n}_i^{(k_i)}.$$

Recover \vec{l} using this new model, using OMP, by filling in the blanks in the below code block.

```

In [51]: from utils import cross_correlate

r = load_recording(RECORDING_FILE)
interferences = [recover_noise(r_i, l_i) for r_i, l_i in zip(noisy_lea

k = np.zeros(4, "int")

vecs = []

# the initial residual for OMP
residual = r

for _ in range(4):
    best_corr = float("-inf")
    best_vec = None
    # We first iterate over all the interferences n_i
    for i, n_i in enumerate(interferences):
        # for each interference, we look through its correlation with

        # Fill in the arguments to cross_correlate
        for k_i, corr in enumerate(cross_correlate(
            residual,
            n_i
        )): # This function returns a vector of cross correlation values
            # the residual/received signal with every possible delay of

            # we find the (noise, shift) pair that maximizes the corre
            if corr > best_corr:
                best_corr = corr
                best_vec = (i, k_i)
    i, k_i = best_vec
    k[i] = k_i

    # we shift the best noise by the best shift and add it to our list
    vecs.append(np.roll(interferences[i], k[i]))

A = np.column_stack(vecs) # this is the matrix that captures all t

# Use least squares to update the residual
residual = residual - np.array(vecs).T.dot(np.linalg.lstsq(np.array

l = residual
play(l)

```

-0:00

In []:

