

```
timeEvent.c x | main.c x | Available Resources x | Pin Module x | DMA Manager x | Interrupt Module x | System Module x
source History
12 int readKeypad();
13 int musical_note(i);
14 float T, f;
15 unsigned int n = 0, m = 0;
16 /*
17 | | | | | | | Main application
18 */
19
20
21 void main(void)
22 {
23     // Initialize the device
24     SYSTEM_Initialize();
25     clearPuTTY();
26     //unsigned int n = 0, m = 0;
27     //float T, f;
28     //unsigned int has_switch1_changed=0,has_switch2_changed=0,has_switch3_changed=0,has_switch4_changed=0;
29     int k;
30     //col_RC2_SetHigh();
31     printf("Press buttons\n");
32     char password[5];
33
34
35     printf("\nEasy Setup value of PWM5DC is %u \n", PWM5_INITIALIZE_DUTY_VALUE);
36     printf("%DC = %.1f \n\n", (float)PWM5_INITIALIZE_DUTY_VALUE*100.0/(PR2+1)/4.0);
37
38
39     while (1)
40     {
41         // Add your application code
42         //readKeypad();
43         k=readKeypad();
44         //printf("\n k = %u",k);
45         musical_note(k);
46     }
```

```
Source History 
54
55 int readKeypad()
56 {
57     int i=0;
58
59     col_RC1_SetHigh();
60     col_RC2_SetLow();
61     col_RC3_SetLow();
62     //printf("\n\rcol 1 powered\n\r");
63     if(row_RC4_GetValue()==1)
64     {
65         printf("\n\rbutton 1");
66         i=1;
67         //printf("i = %u",i);
68     }
69
70
71
72     if(row_RC5_GetValue()==1)
73     {
74         printf("\n\rbutton 4");
75         i=2;
76     }
77
78
79     if(row_RC6_GetValue()==1)
80     {
81         //printf("\n\rbutton 7");
82         i=3;
83     }
84
85     if(row_RC7_GetValue()==1)
86     {
87         //printf("\n\rbutton *");
88         i=4;
89     }
90 }
```

```
90
91
92     DELAY_milliseconds(1);
93
94     col_RC2_SetHigh();
95     col_RC1_SetLow();
96     col_RC3_SetLow();
97     //printf("\n\rcol 2 powered\n\r");
98
99     if(row_RC4_GetValue()==1)
100     {
101         //printf("\n\rbutton 2");
102         i=5;
103     }
104
105
106     if(row_RC5_GetValue()==1)
107     {
108         //printf("\n\rbutton 5");
109         i=6;
110     }
111
112
113     if(row_RC6_GetValue()==1)
114     {
115         //printf("\n\rbutton 8");
116         i=7;
117     }
118
119     if(row_RC7_GetValue()==1)
120     {
121         //printf("\n\rbutton 0");
122         i=8;
123     }
124
125
```

```
126         DELAY_milliseconds(1);
127
128         col_RC2_SetLow();
129         col_RC1_SetLow();
130         col_RC3_SetHigh();
131         //printf("\n\rcol 3 powered");
132
133         if(row_RC4_GetValue()==1)
134         {
135             //printf("\n\rbutton 3");
136             i=9;
137         }
138
139
140         if(row_RC5_GetValue()==1)
141         {
142             //printf("\n\rbutton 6");
143             i=10;
144         }
145
146
147         if(row_RC6_GetValue()==1)
148         {
149             //printf("\n\rbutton 9");
150             i=11;
151         }
152
153         if(row_RC7_GetValue()==1)
154         {
155             //printf("\n\rbutton #");
156             i=12;
157         }
158
159         return i;
160     }
161
```

```

int musical_note(i)
{
    switch(i)
    {
        case 0: PWM5_LoadDutyValue(0);
                break;
        case 1: PR2=117;
                PWM5_LoadDutyValue(236);
                break;
        case 2: PR2=112;

                PWM5_LoadDutyValue(2226);
                break;
        case 3: PR2=105;

                PWM5_LoadDutyValue(212);
                break;
        case 4: PR2=98;

                PWM5_LoadDutyValue(198);
                break;
        case 5: PR2=93;

                PWM5_LoadDutyValue(188);
                break;
        case 6: PR2=88;

                PWM5_LoadDutyValue(178);
                break;
        case 7: PR2=83;

                PWM5_LoadDutyValue(168);
                break;
        case 8: PR2=78;
    }
}

```

```
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Source History
189 PWM5_LoadDutyValue(178);
190 break;
191 case 7: PR2=83;
192
193 PWM5_LoadDutyValue(168);
194 break;
195 case 8: PR2=78;
196
197 PWM5_LoadDutyValue(158);
198 break;
199 case 9: PR2=73;
200
201 PWM5_LoadDutyValue(148);
202 break;
203 case 10: PR2=69;
204
205 PWM5_LoadDutyValue(140);
206 break;
207 case 11: PR2=66;
208
209 PWM5_LoadDutyValue(134);
210 break;
211 case 12: PR2=62;
212
213 PWM5_LoadDutyValue(126);
214 break;
215 default:
216 break;
217 }
218
219 n = T2CONbits.CKPS; // prescaler setting
220 T = ((float)PR2 + 1.0)*pow(2.0,n)*4.0/_XTAL_FREQ;
221 f = 1/T;
222 //printf("TMR2 settings: %u = 0x%x, N = %.0f, T = %f s, f = %f Hz \n\n",PR2, PR2,pow(2,n), T, f);
223
224
```