## TMR4

Easy Setup Registers	
Hardware Settings	
Enable Timer	
Control Mode	Roll over pulse 🔻
Ext Reset Source	T4CKIPPS pin ▼
Start/Reset Option	Software control +
Timer Clock	
Clock Source	FOSC/4 Enable Clock Sync
Clock Frequency	32.768 kHz
Polarity	Rising Edge -
Prescaler	1:64 Tenable Prescaler O/P Sync
Postscaler	1:1
Timer Period	
Timer Period 32	us ≤ 5 ms ≤ 8.192 ms
Actual Period 4.992 ms (Period calculated via Timer Period)	
Software Settings	
Enable Timer Interrupt	
Callback Function Rate	0x0 x Time Period = 0.0 ns

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20nce History ■ | R 🚳 - 🐿 - | 🦽 소 수 수 🚅 → | 1, 4, 40 년 | 점 점 | 🕋 중 😥
  13 - */
  14
            void main(void)
  15 □ {
  16
                      // Initialize the device
  17
                      SYSTEM Initialize();
  18
  19
                      clearPuTTY();
  20
  21
                      unsigned int n = 0, m = 0, counter = 0, has_switch1_changed = 0;
  22
                      float T, f;
                      int i=0, k=0;
  23
  24
  25
  26 🖨
  27
                      // Calculations for finding right PR values for the frequencies
  28
                      for(i=200;i>0;i--)
  29
                      {
  30
                      PR2 = i;
                                                                        // prescaler setting
  31
                      n = T2CONbits.CKPS;
                      T = ((float)PR2 + 1.0)*pow(2.0,n)*4.0/_XTAL_FREQ;
  32
                      f = 1/T:
  33
  34
  35
                      if(f>600)
  36
  37
                               printf("TMR2 settings: u = 0x, N = 0.0, T = 0.0,
  38
                               printf("\n\rPR2 = %u", PR2);
  39
                               break;
  40
🖭 timeEvent.c 🗴 🖭 main.c 🗴 🖭 main.c 🗴 🖭 main.c 🗴 🗎 main.c 🗴 Available Resources 🗴 Pin Module 🗴 System Module 🗴 DMA Manager 🗴 Interrupt Module 🗴
                                                                                                                                                                                                           (4 b)
Source History 💼 🔯 👼 - 👼 - 🔯 - 💆 🚭 📮 🖟 🚱 🔡 🖆 🖆 🗐 🕮 🛍 👛 🥵
  43
  44
                      //Duty cycle value stored in SFRs CCPR1H:CCPRxL
  45
                      printf("\n\rEasy Setup value of CCPR1 is %4.0f \n\r", CCPR1H*256.0+CCPR1L);
  46
                      printf("%DC = %.1f \n\r", (CCPR1H*256.0+CCPR1L)*100.0/(PR2+1)/4.0);
  47
  48
                      for (k=200; k>0; k--)
  49
  50
                      PR4 = k;
  51
                      n = T4CONbits.CKPS;
                                                                       // prescaler setting
                      T = ((float)PR4 + 1.0)*pow(2.0,n)*4.0/_XTAL_FREQ;
  52
  53
                      f = 1/T;
  54
                     if(f>600)
  55
  56
  57
                      printf("TMR4 settings: %u = 0x%x, N = %.0f, T = %f s, f = %f Hz \n\", PR4, PR4, pow(2,n)
  58
                      printf("PR4 = %u", PR4);
  59
                      break;
  60
  61
                      }
  62
  63
  64
  65
                      //Duty cycle value stored in SFRs PWMxDCH:PWMxDCL (or PWM5 INITIALIZE DUTY VALUE)
  66
                     printf("\n\rEasy Setup value of PWM5DC is %u \n\r", PWM5_INITIALIZE_DUTY_VALUE);
                      printf("%DC = %.1f \n\r", (float) PWM5_INITIALIZE_DUTY_VALUE*100.0/(PR4+1)/4.0);
  67
  68
  69
  70
```

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           while(1)
72
73
74
               // Add your application code
75
76
               has switch1 changed = poll switch1 for edges(button RD1 GetValue());
77
               DELAY milliseconds (10);
78
               if ( has_switch1_changed == 1 )
79
80
                   DELAY milliseconds(10);
81
                   counter++;
82
                    if (counter > 5) counter = 0;
83
                    printf("counter = %u \n\r", counter);
84
85
86
               switch (counter)
87
88
               case 0: PWM5 LoadDutyValue(0);
89
                        break;
90
               case 1: PR2=77;
91
                        PR4=155;
                        PWM5 LoadDutyValue (311);
92
93
                  break;
94
               case 2: PR2=51;
95
                        PR4=103:
                        PWM5_LoadDutyValue(208);
96
97
                        break:
98
               case 3: PR2=38;
99
                        PR4=77;
     ent.c. x | Main.c. x | Main.c. x | Main.c. x | Available Resources x | Fin Module x | System Module x | Lima Manager x | Interrupt Module x
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  96
                         PWM5 LoadDutyValue(208);
  97
                         break;
  98
                case 3: PR2=38;
  99
                         PR4=77;
 100
                         PWM5 LoadDutyValue(156);
 101
                         break;
 102
                 case 4: PR2=30;
 103
 104
                         PWM5 LoadDutyValue(124);
 105
                         break;
 106
                 case 5: PR2=25;
 107
 108
                         PWM5 LoadDutyValue(104);
 109
                         break;
 110
                default:
 111
                         break;
 112
 113
 114
                n = T2CONbits.CKPS;
                                        // prescaler setting
 115
                T = ((float) PR2 + 1.0) *pow(2.0,n) *4.0 / XTAL FREQ;
 116
 117
                //printf("TMR2 settings: %u = 0x%x, N = %.0f, T = %f s, f = %f Hz \n\r", PR2, PR2, po
 118
 119
                n = T4CONbits.CKPS;
                                        // prescaler setting
 120
                T = ((float)PR4 + 1.0)*pow(2.0,n)*4.0/XTAL FREQ;
 121
 122
                //printf("TMR4 settings: %u = 0x%x, N = %.0f, T = %f s, f = %f Hz \n\r", PR4, PR4, po
 123
```