The putty shows same answers before and after and the Libraries are included with separate functions called in main file.

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ov 1월 [2] - 등 - 등 - (전 두 문 문 다 | 상 등 등 | 열 연 | 이 표 | 설 교 많
10
      SYSTEM Initialize();
11
      float originala, originalb, originalc, originald, originale, originalf, originalg;
12
      float x=2.25,y=3.72,A=4.27,beta=35.0,D=6.85,alpha=33.0,R1=2.15,g=9.81,theta=43.0,a=0.5,k=20,k2=100,a2=0,b=2,n=200;
13
      originala= z(x,y);
15
      originalb= R(A,beta);
      originalc= X(D,alpha);
      originald= v(R1,g,theta);
      originale= e(a,k);
      originalf= f(k2);
      originalg= integral(a2,b,n);
      printf("\n\r\n' original answers in order are as follows: \n\r %f %f %f %f %f %f %f", originala, originalb, original
23
      float newa, newb, newc, newd, newe, newf, newg;
      25
26
      newa=z(x1,v1);
      newb=R(A1,beta1);
28
      newc=X(D1,alpha1);
29
      newd=v(R2,q,thetal);
      newe=e(a1,k3);
30
31
      newf=f(k4);
      newg=integral(a3,b1,n2);
      printf("\n\r The new values calculated are as follows: \n\r %f %f %f %f %f %f %f", newa, newb, newc, newd, newe, newf, newg);
main.c x Library4.h x Library4.c x
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Source
           #define pi 4.0*atanf(1.0)
   1
           float z(float x, float y);
   2
           float R(float A, float beta);
   3
           float X(float D, float alpha);
   4
           float v(float R, float q, float theta);
   5
           float e(float a, float k);
   6
           float f(float k);
           float integral(float a, float b, float n);
   8
```

```
Pamain.c x Library4.h x Library4.c x
= #include <stdio.h>
  1
      #include <stdlib.h>
  2
     #include <string.h>
  3
     #include <math.h>
  5
     #include "Library4.h"
  6
  7
  8
  9
      float z(float x, float y)
    = {
 10
           float z;
 11
           z = sqrt(pow(x, 2) + pow(y, 2));
 12
           return z;
 13
 14
      float R(float A, float beta)
 15
     {
 16
          float R;
 17
          R = A*cos(beta*pi/180);
 18
           return R;
 19
 20
 21
      float X(float D, float alpha)
 22
 23
 24
           float X;
           X=D*pow(tan(alpha*pi/180), 2);
 25
           return X;
 26
 27
 28
```

```
main.c x Library4.h x Library4.c x
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 28
        float v(float R, float g, float theta)
 29
 30
     □ {
            float v;
 31
            v= sqrt(R*q*tan(theta*pi/180));
 32
            return v;
 33
 34
 35
        float e(float a, float k)
 36
 37
     = {
            int i=0;
 38
            float sumK=0;
 39
 40
            for (i=0; i<=k; i++)</pre>
 41
 42
                 sumK += pow(0.5,i);
 43
 44
 45
            return sumK;
 46
 47
 48
        float f(float k)
     = {
 49
            int 1=0, sumL=0;
 50
 51
            for (1=0;1<=k;1++)
 52
 53
 54
                 sumL += 1;
 55
```

```
main.c x Library4.h x Library4.c x
Source History 📹 👺 👼 • 👼 • 🍳 😎 🚭 📮 📮 🔗 😓 🧐 🖆 🖆 🚳 🗎 🗳 🚉 🔡
 59
      float integral(float a, float b, float n)
 60 □ {
 61
          int i=0;
 62
 63
          float deltax= (b-a)/n; //delta x for the approximated integral solution
 64
 65
          float X=0, X1=0, Xn=0, sum1=0, sum2=0; // the Simpson's rule terms up to f of X1
 66
 67
          for (i=0; i<=n; i++)</pre>
 68
 69
              X1=0.5*i;
 70
 71
              if(i==0)
 72
                  X1 = 0.5*a;
 73
 74
 75
              }
 76
              else
 77
 78
                          if(i==n)
 79
                              {
                             Xn=0.5*b;
 80
 81
                              }
                              else
 82
 83
 84
                                     if(i%2 == 0)
 85 PuT
4.347517 3.497779 2.888852 4.434878 1.999999 5050.000000 1.333333
The new values calculated are as follows:
4.945230 16.662221 0.149387 7.548188 2.000000 1275.000000 2.674048
original answers in order are as follows:
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```