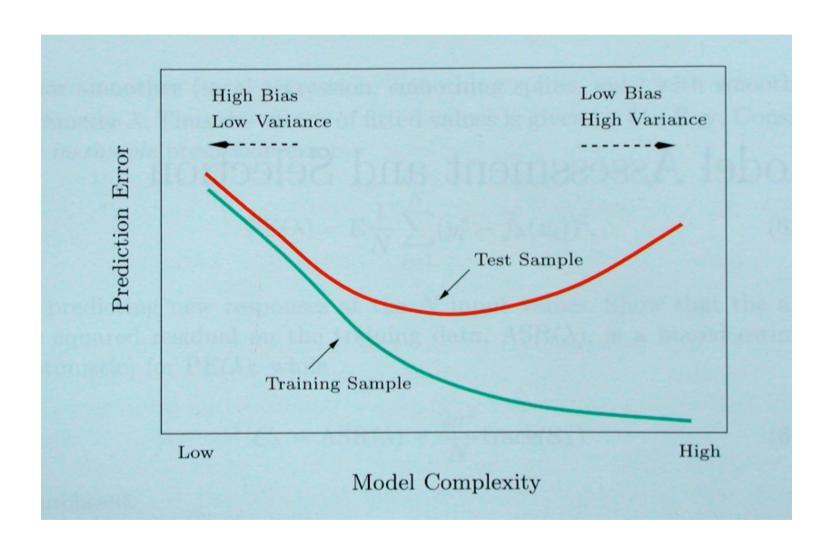
Ensemble Learning

Richa Singh

Decision Tree – Limitations and Advantages

- Trees are flexible → good expressiveness
- Trees are flexible → poor generalization
- Options:
 - Pruning
 - Early stopping
- CART: Classification and Regression Trees
- Can we combine information from multiple decision tress to improve the performance?

Bias/Variance Tradeoff



Ensemble Learning

- Simple learners:
 - Are good: Low variance, don't usually overfit
 - Are bad: High bias, can't solve hard learning problems
- Instead of learning a single (weak) classifier, learn many weak classifiers that are good at different parts of the input space
- How to combine multiple classifiers into a single one
- Works well if the classifiers are complementary
- Two types of ensemble methods:
 - Bagging
 - **Boosting**

Reduce Variance Without Increasing Bias

Averaging reduces variance:

$$Var(\bar{X}) = \frac{Var(X)}{n}$$
 (when predictions are **independent**)

Average models to reduce model variance

One problem:

only one training set

where do multiple models come from?

Bagging: Bootstrap Aggregation

- Leo Breiman (1994)
- Take repeated bootstrap samples from training set *D*.
- Bootstrap sampling: Given set D containing N training examples, create D' by drawing N examples at random with replacement from D.

• Bagging:

- Create k bootstrap samples $D_1 \dots D_k$.
- —Train the classifier on each D_i .
- Classify new instance by majority vote / average.

Bagging (Bootstrap AGgregatING)

Input: n labelled training examples (x_i, y_i) , i = 1,...,n

Algorithm:

Repeat k times:

Select m samples out of n with replacement to get training set S_i

Train classifier (decision tree, k-NN, perceptron, etc) hi on Si

Output: Classifiers h₁, ..,h_k

Classification: On test example x, output majority(h₁, .., h_k)

Example

Input: n labelled training examples (x_i, y_i) , i = 1,...,n

Algorithm:

Repeat k times:

Select m samples out of n with replacement to get training set S_i

Train classifier (decision tree, k-NN, perceptron, etc) hi on Si

How to pick m?

Popular choice: m = n

Still different from working with entire training set. Why?

Bagging

Input: n labelled training examples $S = \{(x_i, y_i)\}, i = 1,...,n$

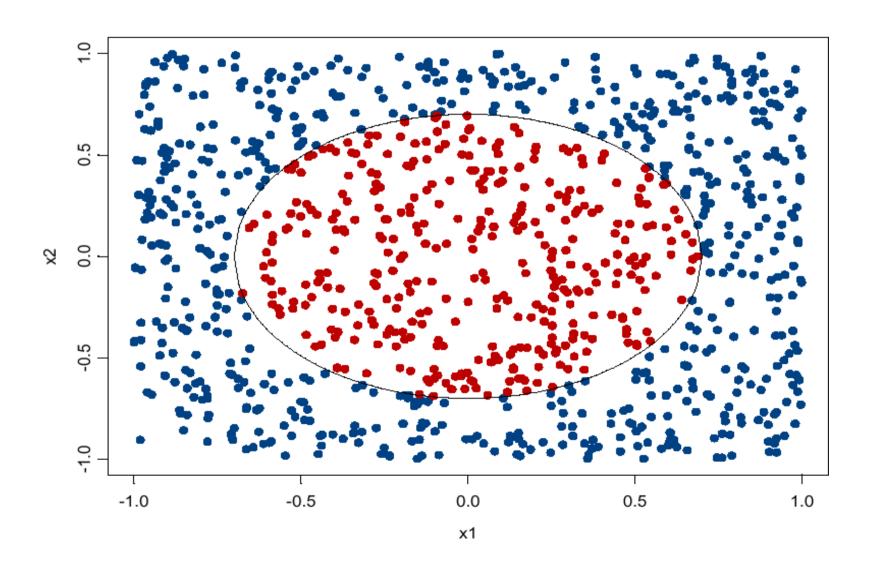
Suppose we select n samples out of n with replacement to get training set S_i

Still different from working with entire training set. Why?

$$\Pr(S_i = S) = \frac{n!}{n^n}$$
 (tiny number, exponentially small in n)
 $\Pr((x_i, y_i) \text{ not in } S_i) = \left(1 - \frac{1}{n}\right)^n \approxeq e^{-1}$

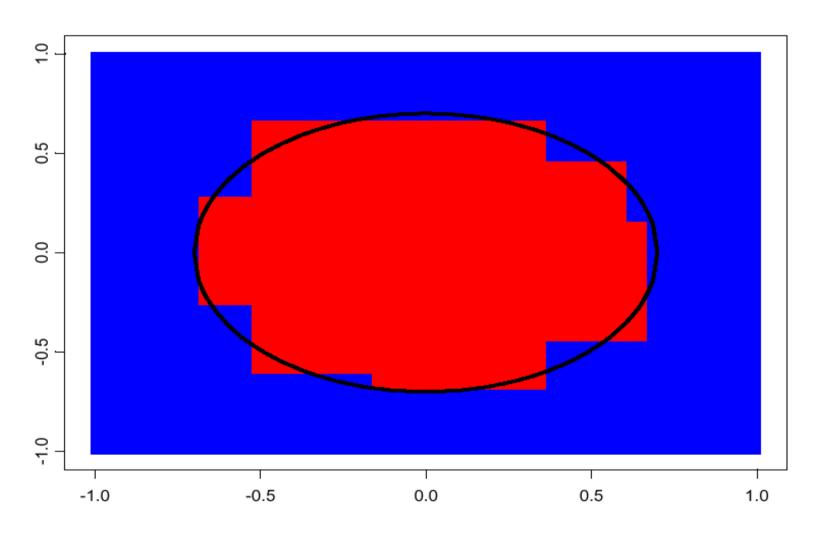
For large data sets, about 37% of the data set is left out!

Example

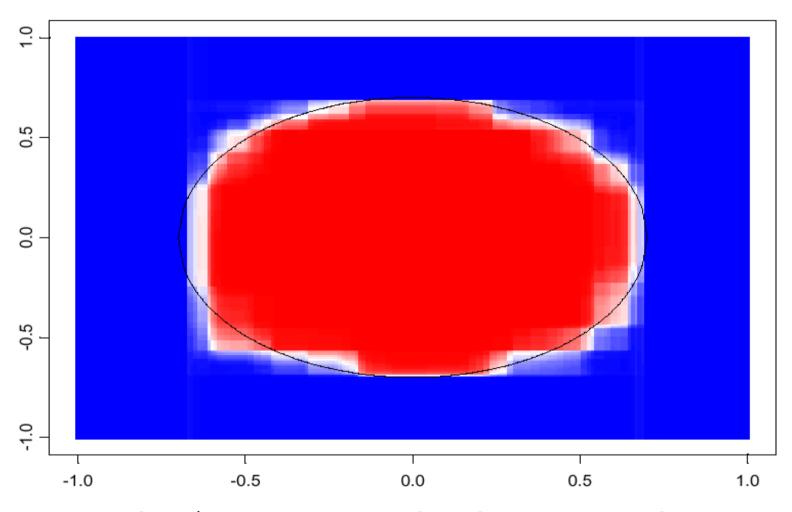


decision tree learning algorithm; very similar to ID3

CART decision boundary

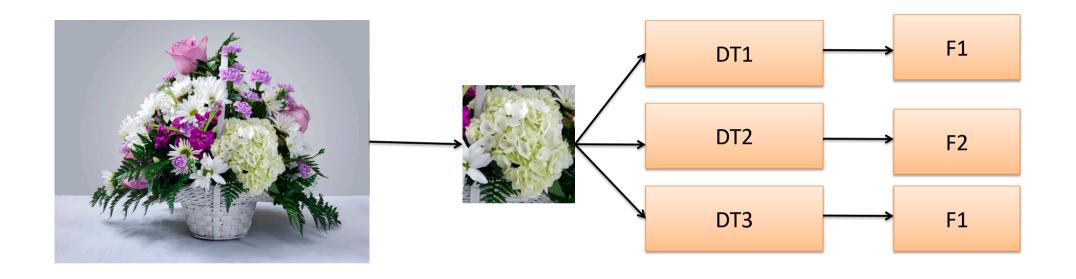


100 bagged trees



shades of blue/red indicate strength of vote for particular classification

Random Decision Forest



Majority voting: FI

Questions?

Ensemble Learning

How to combine multiple classifiers into a single one

Works well if the classifiers are complementary

This class: two types of ensemble methods:

Bagging

Boosting

Goal: Determine if an email is spam or not based on text in it

From: Yuncong Chen

Text: 151 homeworks are all graded...

Not Spam

From: Work from home solutions

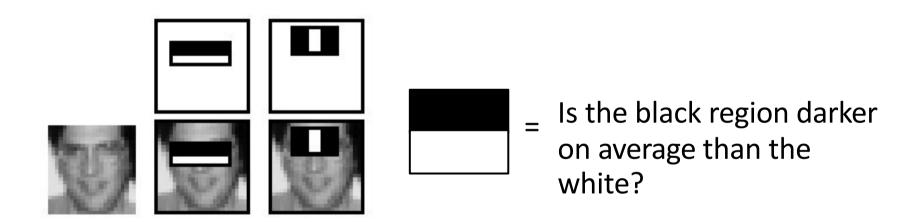
Text: Earn money without working!

Spam

Sometimes it is:

- Easy to come up with simple rules-of-thumb classifiers,
- Hard to come up with a single high accuracy rule

Goal: Detect if an image contains a face in it



Sometimes it is:

- Easy to come up with simple rules-of-thumb classifiers,
- Hard to come up with a single high accuracy rule

Weak Learner: A simple rule-of-the-thumb classifier that doesn't necessarily work very well

Strong Learner: A good classifier

Boosting: How to combine many weak learners into a strong learner?

Procedure:

- 1. Design a method for finding a good rule-of-thumb
- 2. Apply method to training data to get a good rule-of-thumb
- 3. Modify the training data to get a 2nd data set
- 4. Apply method to 2nd data set to get a good rule-of-thumb
- 5. Repeat Ttimes...

- How to get a good rule-of-thumb?
 Depends on application e.g, single node decision trees
- 2. How to choose examples on each round?

Focus on the **hardest examples** so far - namely, examples misclassified most often by previous rules of thumb

3. How to combine the rules-of-thumb to a prediction rule? Take a weighted majority of the rules

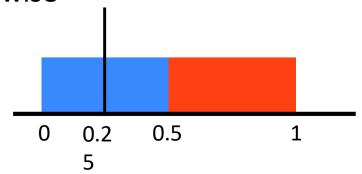
Some Notations

Let D be a distribution over examples, and h be a classifier Error of h with respect to D is:

$$err_D(h) = Pr_{(X,Y)\sim D}(h(X) \neq Y)$$

Example:

Below X is uniform over [0, 1], and Y = 1 if X > 0.5, 0 otherwise



 $err_{D}(h) = 0.25$

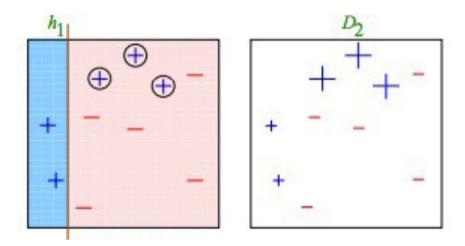
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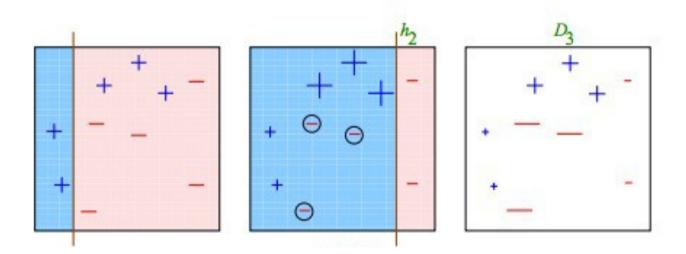
$$err_D(h) = Pr_{(X,Y)\sim D}(h(X) \neq Y)$$

h is called a **weak learner** if $err_D(h) < 0.5$

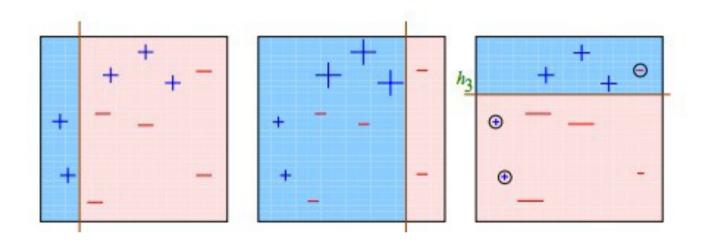
If you guess completely randomly, then the error is 0.5



Schapire, 2011

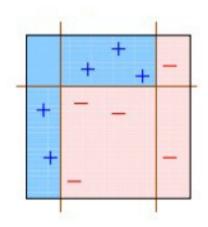


Schapire, 2011



Schapire, 2011

The Final Classifier



Schapire, 2011

Some Notation

Given training examples $\{(x_i, y_i)\}$, i = 1,...,n, we can assign weights w_i to the examples. If the w_i s sum to 1, then we can think of them as a distribution W over the examples.

The error of a classifier h wrt Wis:

$$err_W(h) = \sum_{i=1}^{n} w_i 1(h(x_i) \neq y_i)$$

Note: 1 here is the indicator function

Given training set $S = \{(x_1,y_1),...,(x_n,y_n)\},y$ in $\{-1,1\}$

For t = I,...,T

Construct distribution Dt on the examples

Find weak learner ht which has small error errot(ht) wrt Dt

Output final classifier

Initially, $D_1(i) = 1/n$, for all i (uniform)

Given Dt and ht:

$$D_{t+1}(i) = \frac{D_t(i)}{Z_t} exp(-\alpha_t y_i h_t(x_i))$$
 Weight update rule

where:

$$\alpha_t = \frac{1}{2} \ln \left(\frac{1 - err_{D_t}(h_t)}{err_{D_t}(h_t)} \right)$$

 Z_t = normalization constant

Given training set $S = \{(x_1, y_1), ..., (x_n, y_n)\}, y \text{ in } \{-1, 1\}$

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 $D_{t+1}(i)$ goes down if x_i is classified correctly by h_t , up otherwise High $D_{t+1}(i)$ means hard example

Given training set $S = \{(x_1, y_1), ..., (x_n, y_n)\}, y \text{ in } \{-1, 1\}$

For t = 1, ..., T

Construct distribution Dt on the examples

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Higher if ht has low error wrt Dt, lower otherwise. >0 if errpt(ht) < 0.5

 $Z_t = normalization constant$

Given training set $S = \{(x_1, y_1), ..., (x_n, y_n)\}, y \text{ in } \{-1, 1\}$

For t = 1, ..., T

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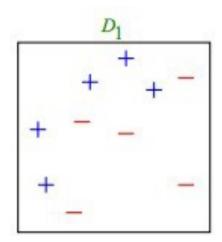
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where:

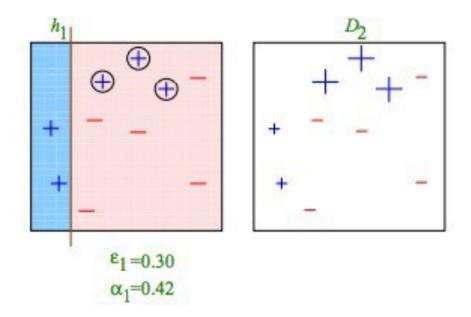
$$\alpha_t = \frac{1}{2} \ln \left(\frac{1 - err_{D_t}(h_t)}{err_{D_t}(h_t)} \right)$$

Zt = normalization constant

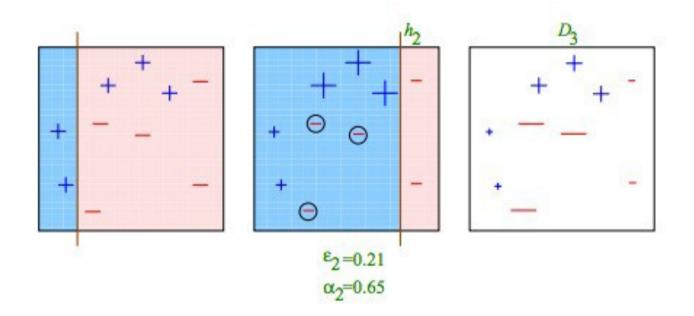
Final
$$sign(\sum_{t=1}^{T} \alpha_t h_t(x))$$



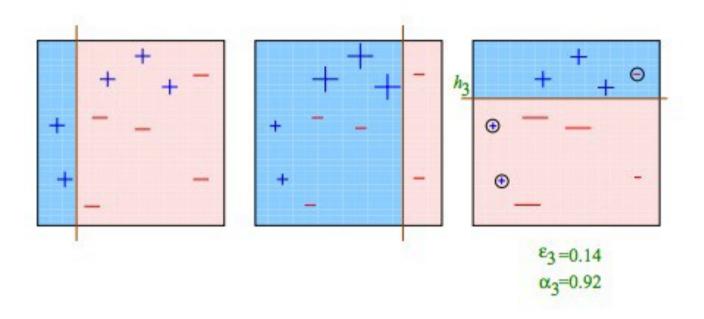
Schapire, 2011



Schapire, 2011

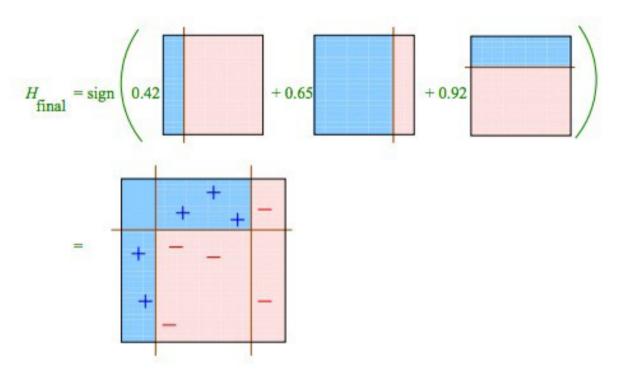


Schapire, 2011



Schapire, 2011

The Final Classifier



Schapire, 2011

How to Find Stopping Time

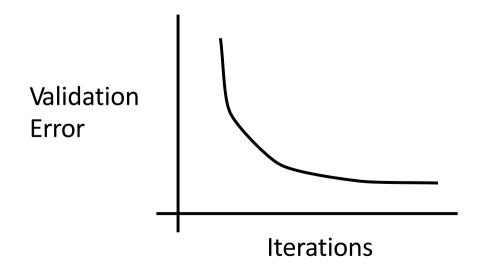
Given training set $S = \{(x_1, y_1), ..., (x_n, y_n)\}, y \text{ in } \{-1, 1\}$

For t = 1, ..., T

Construct distribution Dt on the examples

Find weak learner ht which has small error errot(ht) wrt Dt

Output final classifier



To find stopping time, use a validation dataset.

Stop when the error on the validation dataset stops getting better, or when you can't find a good rule of thumb.

Questions?