

FORMAL LANGUAGE AND AUTOMATA

THEORY

Formal languages are defined by two sets of rules.

- Syntax: precise rules that tell you the symbols you are allowed to use and how to put them together into legal expression.
- Semantics: precise rules that tell you the meaning of the symbols and legal expressions.

Automata theory:

→ is the study of abstract computing devices of "machines" as well as the computational problems that can be solved using them.

→ automata - Greek Word → self-acting.

Finite automata → Devices with a small amount of memory. These are very simple machines.

Push-down automata → Devices with unbounded memory that can be accessed in a restricted way. Used to parse grammars.

Turing machines → Devices with unbounded memory. These are actual computers.

Time-bounded Turing Machines:-

- Devices with unbounded memory but bounded running time.
- These are computers that run fast.

Computational Models:-

1. Finite Automation (FA)

- recognizes regular languages.

2. Push Down Automation (PDA)

- recognizes context free languages.

3. Turing Machines (TM)

- recognizes Computable languages

Deterministic Finite automata:- (DFA)

DFA is a five-tuple

$$M = (Q, \Sigma, \delta, q_0, F)$$

Q → finite set of states

Σ → finite input alphabet.

q_0 → initial / starting state

q_0 is in Q .

$F \rightarrow$ set of final state
which is subset of Q .

$\delta \rightarrow$ A transition function

$$\delta: (Q \times \Sigma) \rightarrow Q$$

δ is defined for any q in Q and s in Σ

$\delta(q, s) = q'$, q' is another state in Q .

Transition diagram:

A transition diagram for a DFA

$A = (Q, \Sigma, \delta, q_0, F)$ is a graph defined as follows:

→ for each state in Q there is a node.

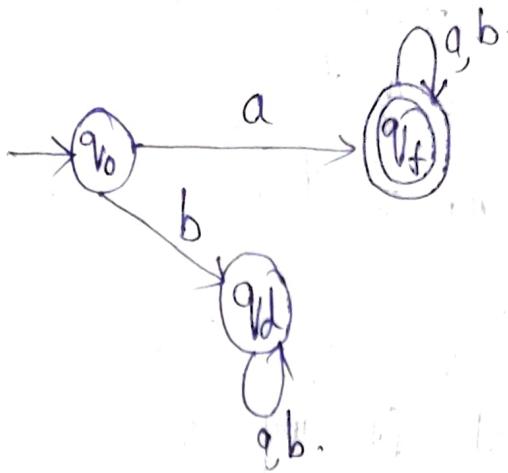
→ for each state q in Q and each input symbol a in Σ , let $\delta(q, a) = p$

Then the transition diagram has an arc from node q to node p labeled a .

→ There is an arrow into state q_0 labeled start.

→ Final state (F) are marked as double circles.

Eq:



Transition table:- (TT)

A TT is a conventional tabular representation of a function like δ that takes two arguments and returns a value.

	0	1
$\rightarrow q_0$	q_f	q_d
$*q_f$	q_f	q_f
q_d	q_d	q_f

Design of DFA:-

Step 1:- List out the possible strings in the given language.

Step 2:- Decide the no of states by identifying the length of minimum possible string.

* If all string starting with 'n' length substring $\rightarrow (n+2)$ states

* If all string ending with 'n' length minimum $(n+1)$ states.

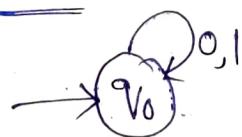
Step 8: Draw the state and while constructing
a DFA:

- Always prefer to use existing path.
- Create a new path only when there exists no path to go with.
 - For the strings starting with 'n' length substring send all the left possible combinations to the dead state.
 - For the strings that ends with 'n' length substring send all the left possible combinations to the starting state.

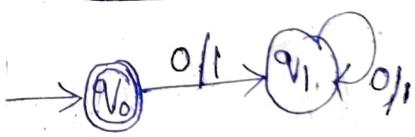
* Let $\Sigma = \{0, 1\}$ Give DFA's for

$\{\varnothing\}$, $\{\&\}$, Σ^* and Σ^+ .

For $\{\varnothing\}$:



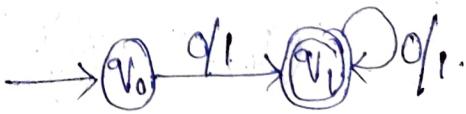
For $\{\&\}$:



For Σ^*



For Σ^+

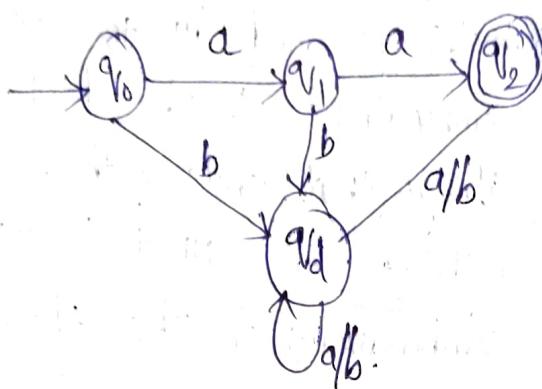


Examples for construction of DFA's

1. $\Sigma = \{a, b\} \Rightarrow$ possible strings

$L = \{aa\} \Rightarrow$ Language

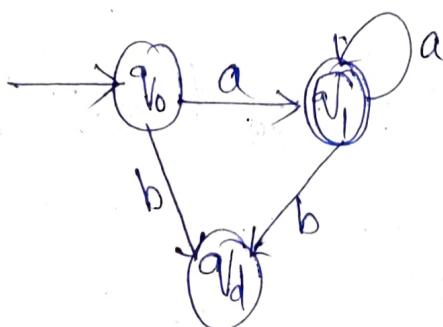
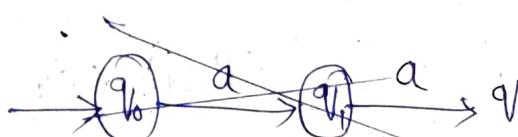
Minimum states = $2+1=3$.



2. $\Sigma = \{a, b\}$

$L = \{a, aa, aaa, aaaa, \dots\}$

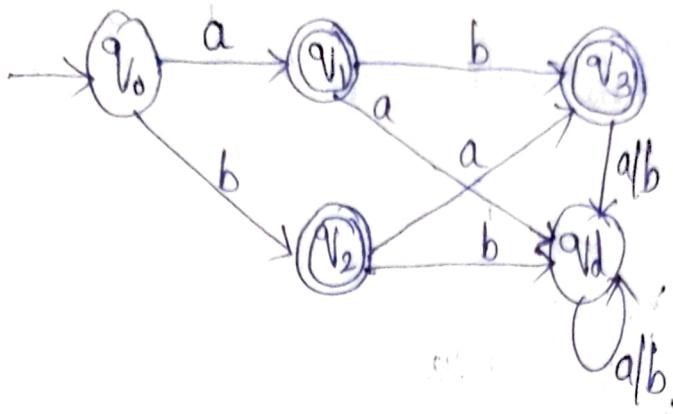
Minimum states = $1+1=2$



$$3. \Sigma = \{a, b\}$$

$$L = \{ab, ba, a, b\}$$

Minimum states = 2



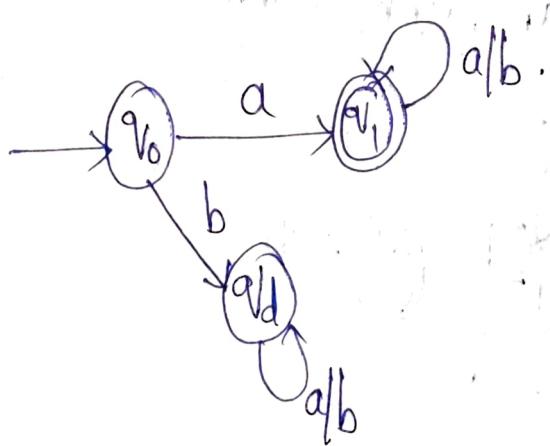
$$4. \Sigma = \{a, b\}$$

$$L = \{aw \mid w \in (a+b)^*\}$$

$$L = \{a, aa, ab, aab, aaa, \dots\}$$

Minimum states = n+1

$$= 1 + 1 = 2$$



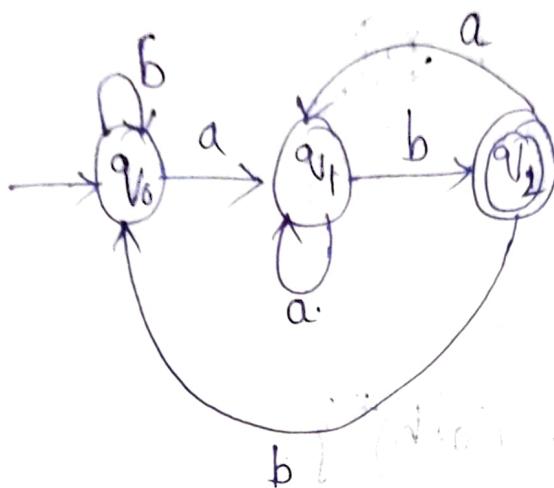
$$⑤ L = \{ w ab \mid w \in (a+b)^* \}$$

$$\Sigma = \{a, b\}$$

Minimum states = $n+1$

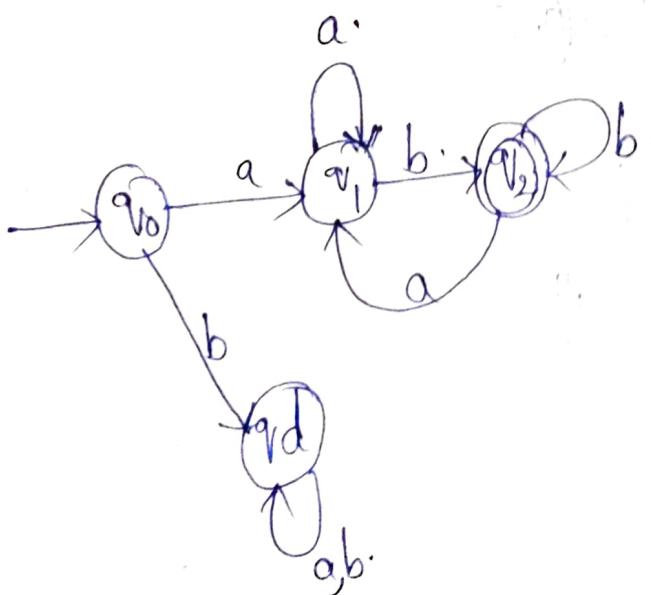
$$= 2+1=3.$$

$$L = \{ab, aab, abb, \dots\}$$



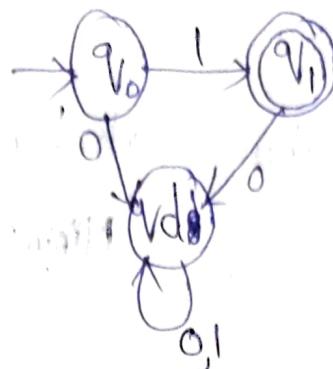
$$⑥ L = \{ awb \mid w \in (a+b)^* \}.$$

$$L = \{ab, aab, abb, aabb, abab, \dots\}.$$

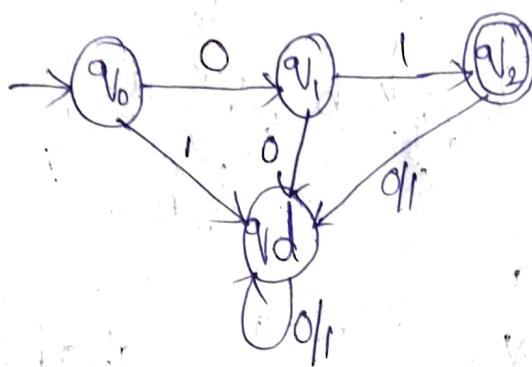


$$(7) \Sigma = \{0, 1\}$$

$$(1) L = \{1\}$$

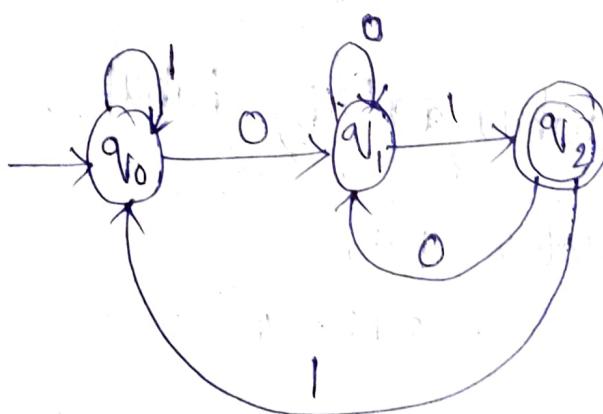


$$(2) L = \{0, 1\}^*$$



(3) If w/w is a string of 0s & 1s ending with the string 01.

$$L = \{01, 001, 101, \dots\}$$



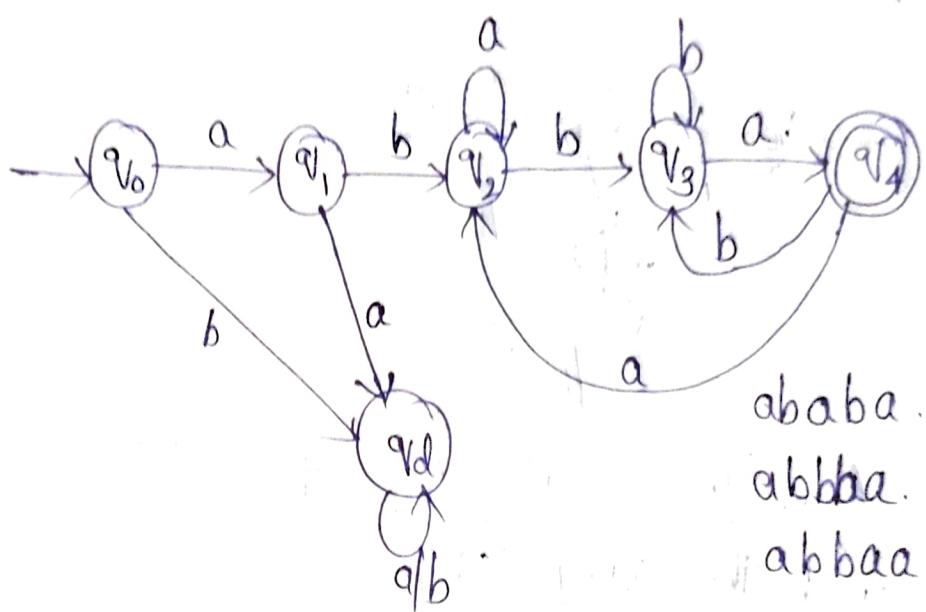
$$(8) L = \{ab^wba / (a+b)^*\}.$$

$$\Sigma = \{a, b\}$$

$$L = \{abba, ababa, abbbba, \dots\}$$

Minimum states = $n+1$

$$= 4+1 = 5$$



wabaw

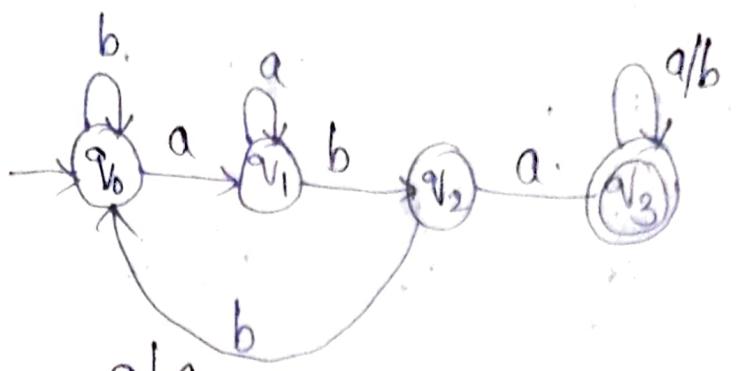
$$(9) L = \{ \text{wabaw} \in (a+b)^*\}.$$

$$\Sigma = \{a, b\}$$

$$L = \{aba, aabaa, aabab, babab, \dots\}$$

Minimum states = $n+1$

$$= 3+1 = 4.$$



aba

baba

aaba.

abba

abaa

ababa.

even

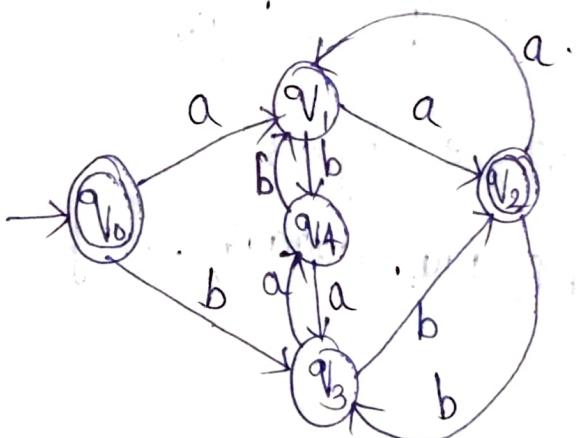
(10) Even number of a's and ~~odd~~^{even} number of b's

{ \emptyset , aabb, aaabb, ...}

minimum states = $n+1$

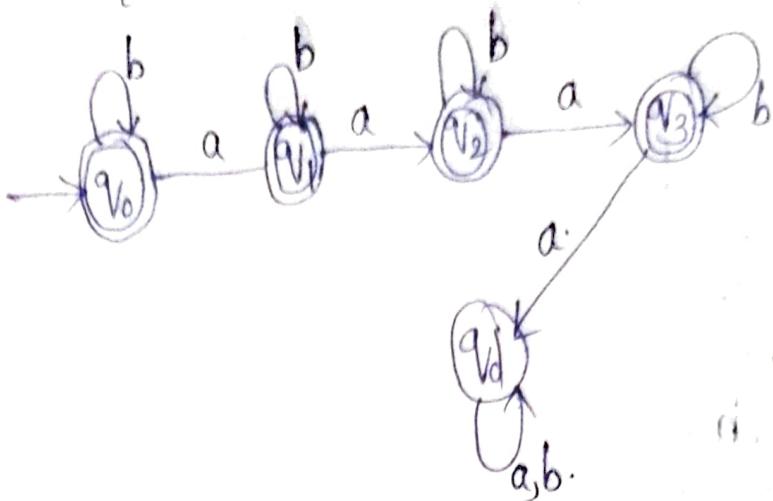
= 0+1

= 1



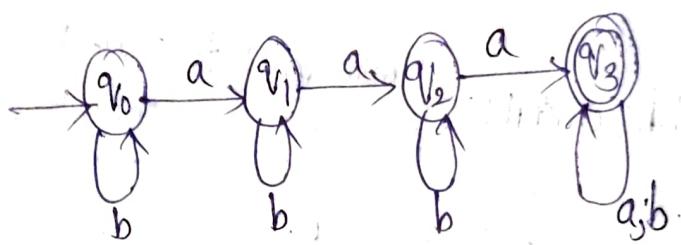
11. Atmost 3 ab.

~~{ε, baa, aab, b, ...}~~ { $\emptyset, a, aa, aab, \dots$ }



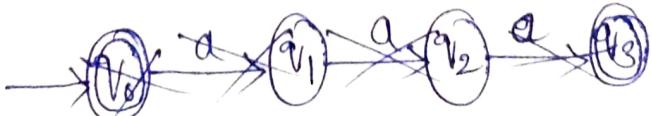
12. At least 3 a's

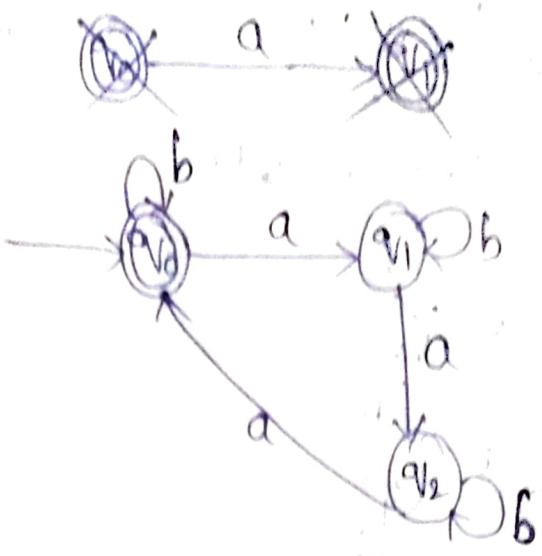
{aaa, aaab, ...}



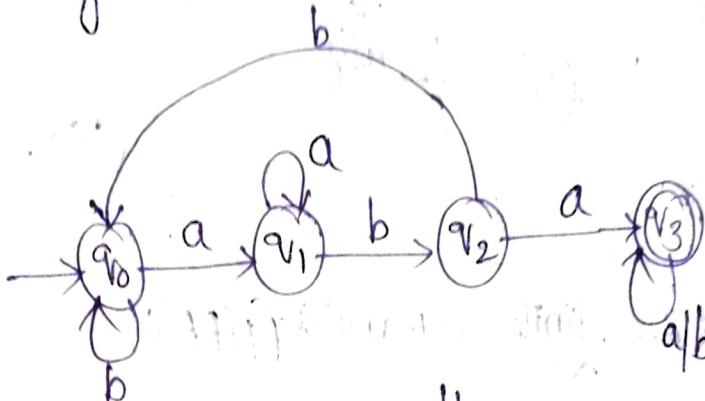
13. No of a's divisible by 3

{ $\emptyset, aaa, aaaaaa, \dots$ }





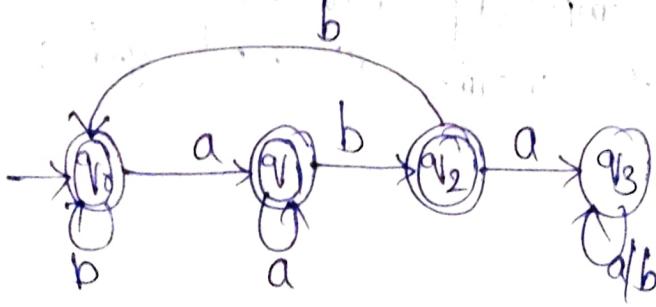
(14) String does not contain aba as substring.



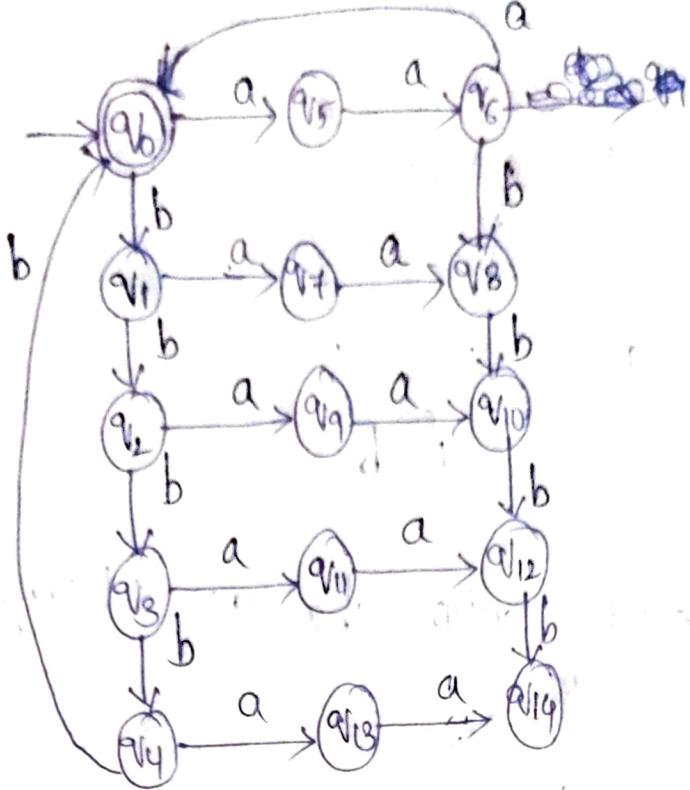
baabbaba.
abaa

String contains "aba" as
substring. So, not valid.

for string not containing "aba" substring.



15) As divisible by 3, so B's, divisible by 3.



(X).

Non-deterministic finite automata (NFA):

- In NFA, one input symbol causes to move more than one state, or a state may contain more than one transition from same input symbol.
- It is not compulsory that all the states have to consume all input symbols in Σ .

- A Non deterministic finite automata is represented by a 5-tuple $\mathcal{N} = (Q, \Sigma, \delta, q_0, F)$
- Q is finite set of states
 - Σ is finite input alphabet
 - δ is transition mapping function
 - q_0 initial state
 - F set of final states

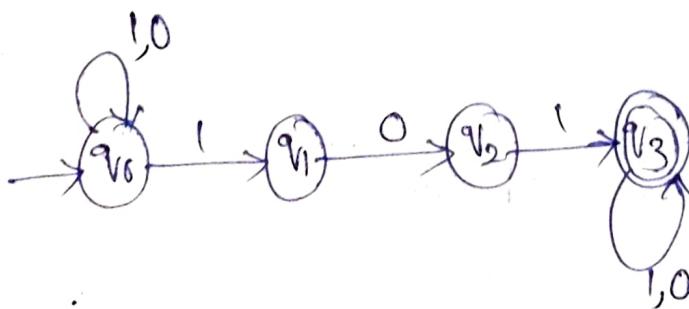
* An NFA accepts a string "w" if it is possible to make any sequence of choices of next state, while reading the characters of w and go from start state to any accepting states.

① Construct NFA for

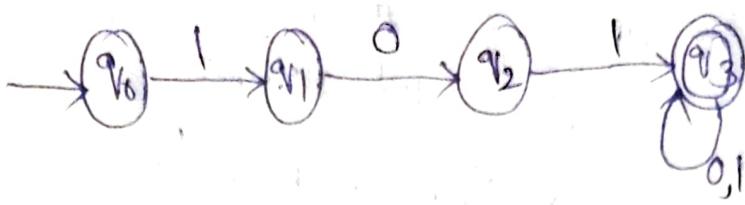
$$L = \{(1+0)^* 101 (1+0)^*\}$$

Minimum possible string = 101

$$\text{No of states} = n+1 = 3+1 = 4$$



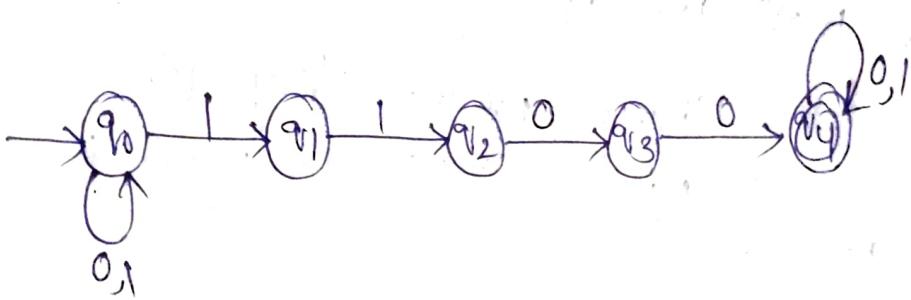
$$(1) L = \{ 101 \mid (1+0)^* \}$$



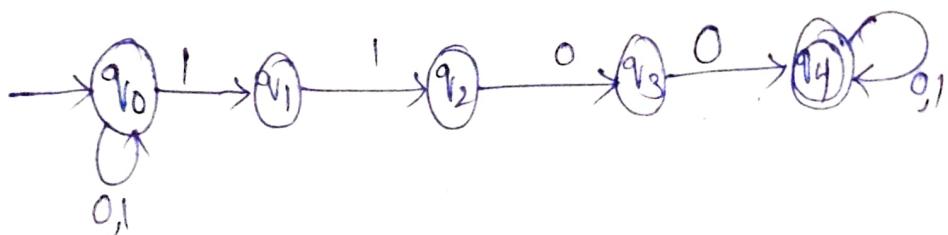
$$(2) L = \{ 1100 \}$$



$$(3) L = \{ (0+1)^* 1100 (0+1)^* \}$$



$$(4) L = 1100 \text{ as substring}$$



Equivalence between NFA & DFA

Step 1:

Convert the given transition system into transition table where each state corresponds to a row & each input symbol corresponds to a column.

Step 2:

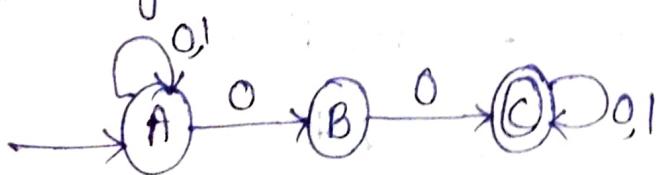
Construct the succession table which lists subsets of states reachable from the set of initial states.

Step 3:

The transition graph given by the successor table is the required deterministic system.

Ex:

1. Construct DFA equivalent to the following NFA.



Transition table :- (NFA)

State	0	1
$\rightarrow A$	A,B	A
B	C	\emptyset
* C	C	C

Transition table :- (DFA)

	0	1
$\rightarrow A$	{A,B}	A
{A,B}	{A,B,C}	A
* {A,B,C}	{A,B,C}	{A,C}
* {A,C}	{A,B,C}	{A,C}

$$\delta(\{A,B\}, 0) = \delta(A, 0) \cup \delta(B, 0)$$

$$= A \cup B \cup C$$

$$= ABC$$

$$\begin{aligned} \delta(\{A,B\}, 1) &= \delta(A, 1) \cup \delta(B, 1) \\ &= A \cup \emptyset \\ &= A \end{aligned}$$

$$\begin{aligned}\delta(\{A, B, C\}, 0) &= \delta(A, 0) \cup \delta(B, 0) \cup \delta(C, 0) \\ &= \{A, B\} \cup \{B\} \cup \{C\} \\ &= \{A, B, C\}\end{aligned}$$

$$\begin{aligned}\delta(\{A, B, C\}, 1) &= \delta(A, 1) \cup \delta(B, 1) \cup \delta(C, 1) \\ &= A \cup \emptyset \cup C \\ &= \{A, C\}\end{aligned}$$

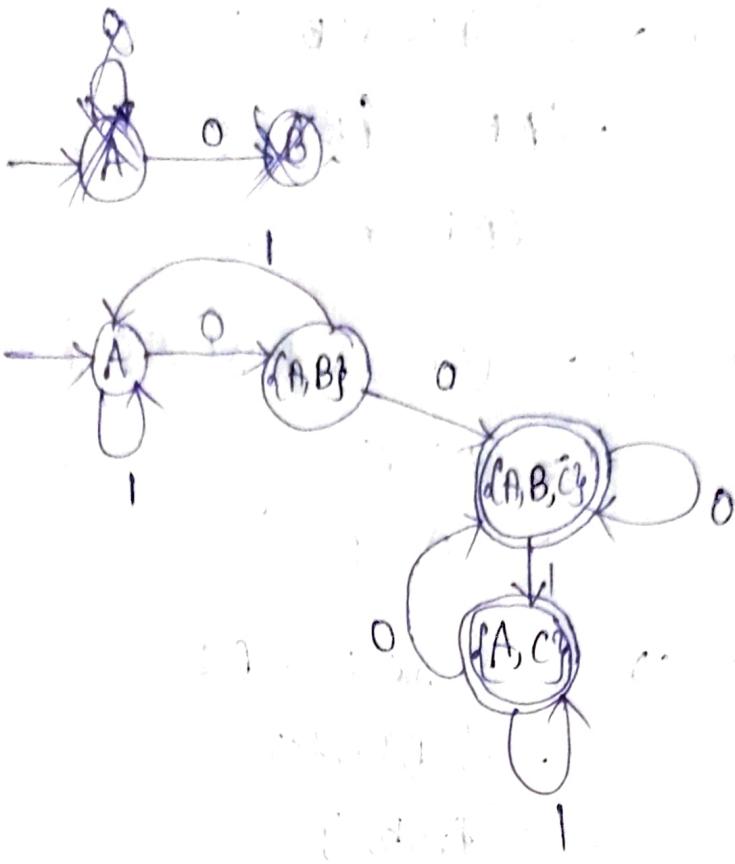
$$\begin{aligned}\delta(\{A, C\}, 0) &= \delta(A, 0) \cup \delta(C, 0) \\ &= \{A, B\} \cup \{C\} \\ &= \{A, B, C\}\end{aligned}$$

$$\begin{aligned}\delta(\{A, C\}, 1) &= \delta(A, 1) \cup \delta(C, 1) \\ &= A \cup C \\ &= \{A, C\}\end{aligned}$$

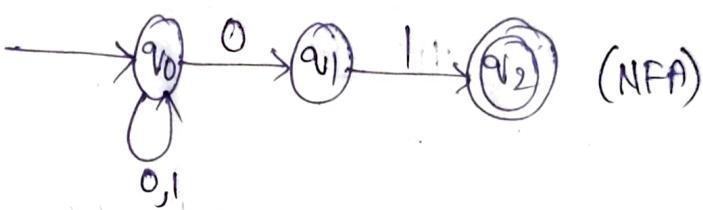
- The process is to be repeated until we didn't get any new states.
- And the final state in NFA, is the final state in DFA.

(or).

If they contain single letter also they are considered as final states.



Q.



Transition table :- (NFA)

	0	1
$\rightarrow q_0$	$\{q_0, q_1\}$	q_0
q_1	\emptyset	q_2
$* q_2$	\emptyset	\emptyset

Transition Table :- (DFA)

	0	1
- q_0	$\{q_0, q_1\}$	q_0
$\{q_0, q_1\}$	$\{q_0, q_1\}$	$\{q_0, q_2\}$
* $\{q_0, q_2\}$	$\{q_0, q_1\}$	q_0

$$\rightarrow \delta(\{q_0, q_1\}, 0) = \delta(q_0, 0) \cup \delta(q_1, 0)$$

$$= \{q_0, q_1\} \cup \emptyset$$

$$= \{q_0, q_1\}$$

$$\rightarrow \delta(\{q_0, q_1\}, 1) = \delta(q_0, 1) \cup \delta(q_1, 1)$$

$$= q_0 \cup q_2$$

$$= \{q_0, q_2\}$$

$$\rightarrow \delta(\{q_0, q_2\}, 0) = \delta(q_0, 0) \cup \delta(q_2, 0)$$

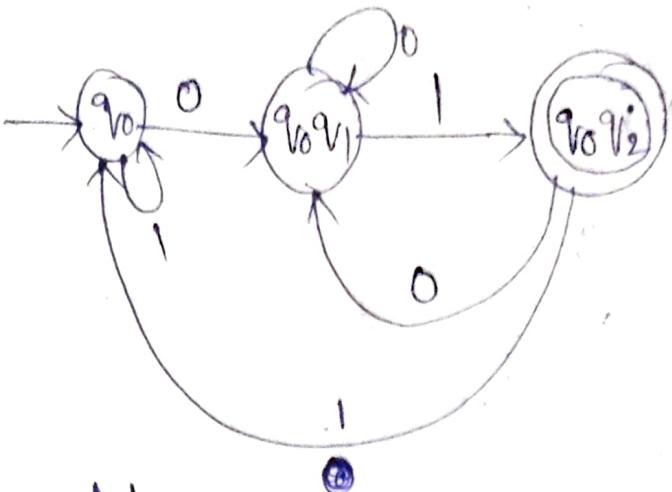
$$= \{q_0, q_1\} \cup \emptyset$$

$$= \{q_0, q_1\}$$

$$\rightarrow \delta(\{q_0, q_2\}, 1) = \delta(q_0, 1) \cup \delta(q_2, 1)$$

$$= q_0 \cup \emptyset$$

$$= q_0$$



03/09/20

NFA with epsilon :-

* having transactions without reading inputs

elimination of 'ε'

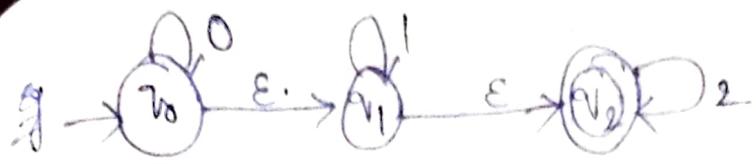
1. Suppose we want to replace 'ε' move from vertex v_1 to vertex v_2 then

Step 1: Find all the edges starting from v_1

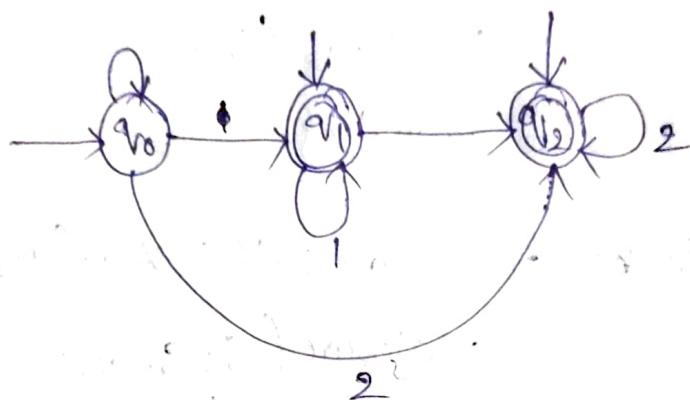
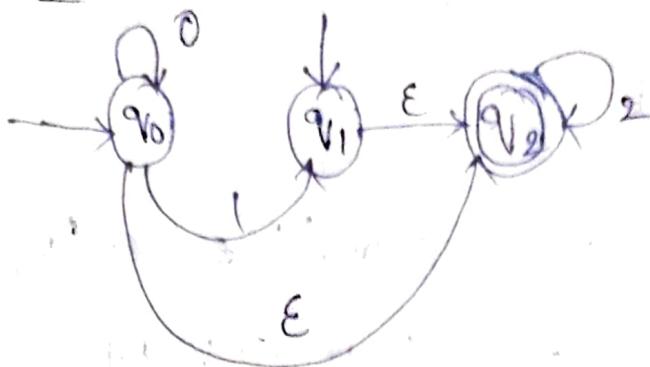
Step 2: Duplicate all these edges starting from v_1 without changing the edge labels.

Step 3: If v_1 is initial state make v_2 also as final state.

Step 4: If v_2 is final state make v_1 also as final state.



Step-1:-



Elimination of Epsilon:-

- (Pb) Construct the following NFA with 'ε' to
NFA without 'ε'



Sol: Finding ϵ -closure

$$\epsilon\text{-closure}(q_0) = \{q_0\}$$

$$\epsilon\text{-closure}(q_1) = \{q_1, q_2\}$$

$$\epsilon\text{-closure}(q_2) = \{q_2\}$$

Now find δ'

$$\begin{aligned} 1. \quad \delta'(q_0, a) &= \epsilon\text{-closure}\left(\delta(\epsilon\text{-closure}(q_0), a)\right) \\ &= \epsilon\text{-closure}\left(\delta(q_0, a)\right) \\ &= \epsilon\text{-closure}(q_1) \\ &= \{q_1, q_2\} \end{aligned}$$

$$\begin{aligned} 2. \quad \delta'(q_0, b) &= \epsilon\text{-closure}\left(\delta(\epsilon\text{-closure}(q_0), b)\right) \\ &= \epsilon\text{-closure}\left(\delta(q_0, b)\right) \\ &= \epsilon\text{-closure}(\emptyset) \\ &= \emptyset \end{aligned}$$

$$\begin{aligned} 3. \quad \delta'(q_1, a) &= \epsilon\text{-closure}\left(\delta(\epsilon\text{-closure}(q_1), a)\right) \\ &= \epsilon\text{-closure}\left(\delta(q_1, q_2), a\right) \\ &= \epsilon\text{-closure}\left(\delta(q_1, a) \cup \delta(q_2, a)\right) \\ &= \epsilon\text{-closure}(\emptyset \cup \emptyset) \\ &= \emptyset \end{aligned}$$

$$\begin{aligned}
 4. \quad \delta'(\varphi_1, b) &= \text{closure}(\delta(\text{closure}(\varphi_1), b)) \\
 &= \text{closure}(\delta(\varphi_1, \varphi_2), b) \\
 &= \text{closure}(\delta(\varphi_1, b) \cup \delta(\varphi_2, b)) \\
 &= \text{closure}(\emptyset \cup \varphi_2) \\
 &= \varphi_2
 \end{aligned}$$

$$\begin{aligned}
 5. \quad \delta(\varphi_2, a) &= \text{closure}(\delta(\text{closure}(\varphi_2), a)) \\
 &= \text{closure}(\delta(\varphi_2, a)) \\
 &= \emptyset
 \end{aligned}$$

$$\begin{aligned}
 6. \quad \delta'(\varphi_2, b) &= \text{closure}(\delta(\text{closure}(\varphi_2), b)) \\
 &= \text{closure}(\delta(\varphi_2, b)) \\
 &= \text{closure}(\varphi_2) \\
 &= \{\varphi_2\}
 \end{aligned}$$

$$\delta'(\varphi_0, a) = \{\varphi_1, \varphi_2\}$$

$$\delta'(\varphi_0, b) = \{\emptyset\}$$

$$\delta'(\varphi_1, a) = \{\emptyset\}$$

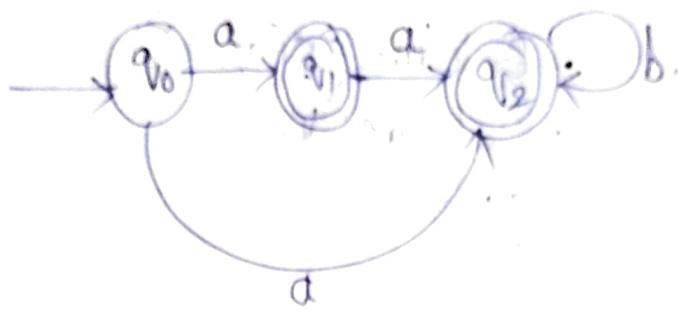
$$\delta'(\varphi_1, b) = \{\varphi_2\}$$

$$\delta'(\varphi_2, a) = \{\emptyset\}$$

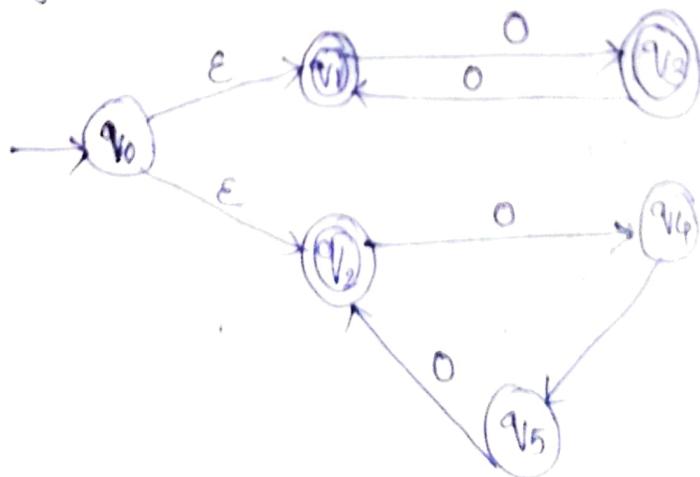
$$\delta'(\varphi_2, b) = \{\varphi_2\}$$

States	a	b
q_0	{ q_1, q_2 }	\emptyset
* q_1	\emptyset	{ q_2 }
* q_2	\emptyset	{ q_2 }

q_1, q_2 are final states as ϵ -closure of q_1 & q_2 contain the final state q_2



- ② Construct the NFA without ' ϵ ' for the given NFA with ' ϵ :



Qd:- Finding ϵ -closure:-

$$\epsilon\text{-closure}(q_0) = \{q_0, q_1, q_2\}$$

$$\epsilon\text{-closure}(q_1) = \{q_1\}$$

$$\epsilon\text{-closure}(q_2) = \{q_2\}$$

$$\epsilon\text{-closure}(q_3) = \{q_3\}$$

$$\epsilon\text{-closure}(q_4) = \{q_4\}$$

$$\epsilon\text{-closure}(q_5) = \{q_5\}.$$

Ques

$$\begin{aligned}\delta'(q_0, 0) &\approx \epsilon\text{-closure}(\delta(\epsilon\text{-closure}(q_0), 0)) \\&= \epsilon\text{-closure}(\delta(q_0, q_1, q_2), 0) \\&\approx \epsilon\text{-closure}(\delta(q_0, 0) \cup \delta(q_1, 0) \cup \delta(q_2, 0)) \\&= \epsilon\text{-closure}(q_3 \cup q_4) \\&= \epsilon\text{-closure}(q_3) \cup \epsilon\text{-closure}(q_4) \\&= \{q_3, q_4\}.\end{aligned}$$

$$\begin{aligned}\delta'(q_1, 0) &= \epsilon\text{-closure}(\delta(\epsilon\text{-closure}(q_1), 0)) \\&= \epsilon\text{-closure}(\delta(q_1), 0) \\&= \epsilon\text{-closure}(q_3) \\&= q_3.\end{aligned}$$

$$\begin{aligned}
 \delta^1(q_2, 0) &= \text{\varepsilon-closure}(\delta(\text{\varepsilon-closure}(q_2), 0)) \\
 &= \text{\varepsilon-closure}(q_{V_4}) \\
 &= \{q_{V_4}\}
 \end{aligned}$$

$$\begin{aligned}
 \delta^1(q_3, 0) &= \text{\varepsilon-closure}(\delta(\text{\varepsilon-closure}(q_3), 0)) \\
 &= \text{\varepsilon-closure}(q_1) \\
 &= \{q_1\}
 \end{aligned}$$

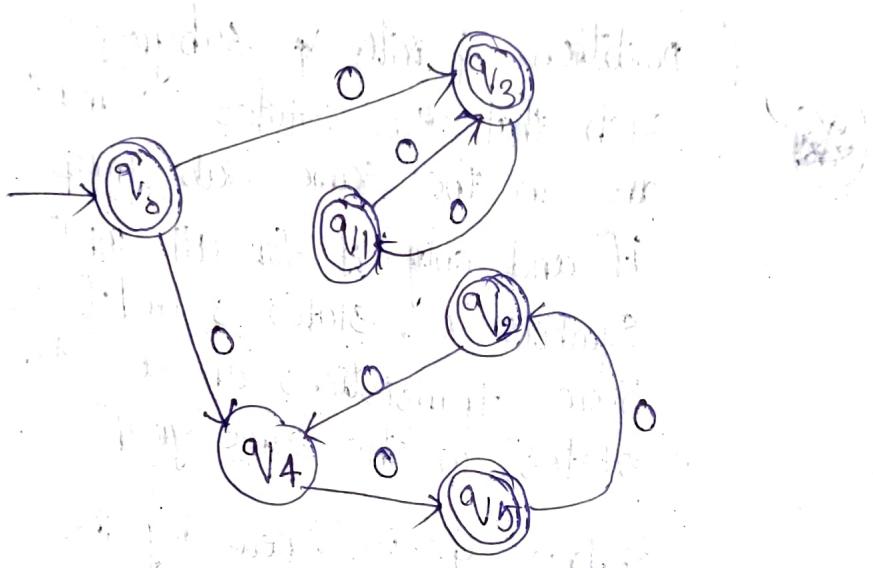
$$\begin{aligned}
 \delta^1(q_4, 0) &= \text{\varepsilon-closure}(\delta(\text{\varepsilon-closure}(q_4), 0)) \\
 &= \text{\varepsilon-closure}(q_{V_5}) \\
 &= \{q_{V_5}\}
 \end{aligned}$$

$$\begin{aligned}
 \delta^1(q_5, 0) &= \text{\varepsilon-closure}(\delta(\text{\varepsilon-closure}(q_5), 0)) \\
 &= \text{\varepsilon-closure}(q_2) \\
 &= \{q_2\}.
 \end{aligned}$$

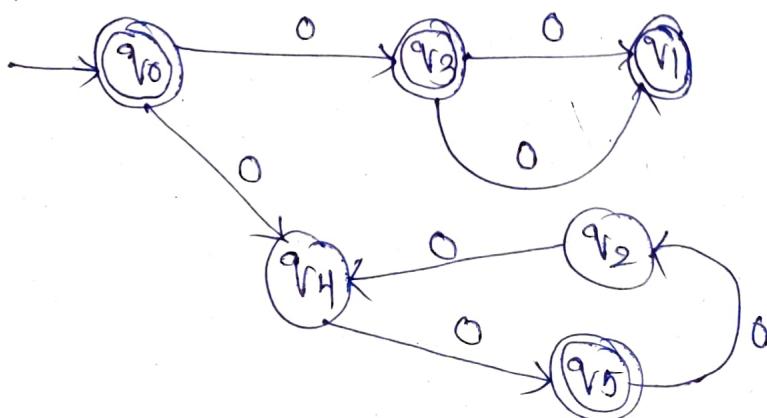
Here the input '1' is not there. So,

$\delta^1(q_0, \emptyset) = \emptyset$	$\delta^1(q_{V_4}, 1) = \emptyset$
$\delta^1(q_1, \emptyset) = \emptyset$	$\delta^1(q_{V_5}, 1) = \emptyset$
$\delta^1(q_2, 1) = \emptyset$	
$\delta^1(q_3, 1) = \emptyset$	

States	0	1
* q_0	{ q_3, q_4 }	\emptyset
* q_1	{ q_3 }	\emptyset
* q_2	{ q_4 }	\emptyset
* q_3	{ q_1 }	\emptyset
q_4	{ q_5 }	\emptyset
* q_5	{ q_2 }	\emptyset



NFA with out ~~but~~ epsilon.



Minimization of DFA :-

04/09/20

Given DFA:

→ start with at least two groups:

S and S-F.

→ Repeat the following algorithm until no more progress can be made.

* initially, let $\Pi_{\text{new}} = \Pi$

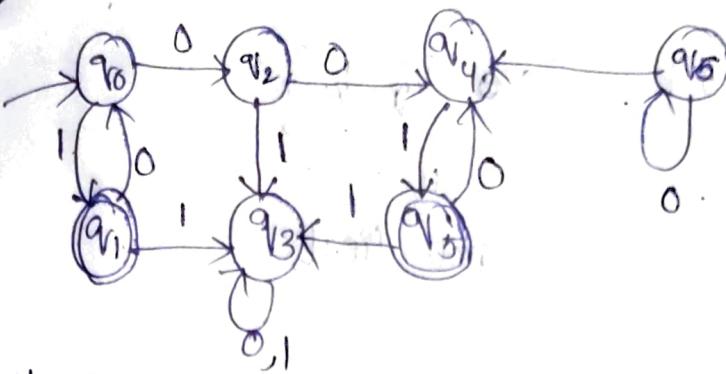
for (each group G of Π)



{ partition G into subgroups such that two states s and t are in the same subgroup if and only if for all input symbols 'a', states s and t have transitions on 'a' to states in the same group.

Replace G in Π_{new} by the set of all subgroups formed;

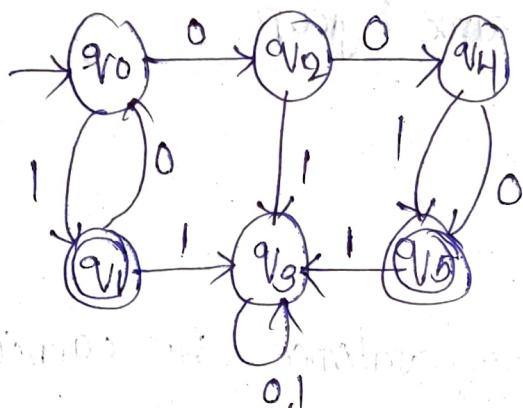
}



Step-1

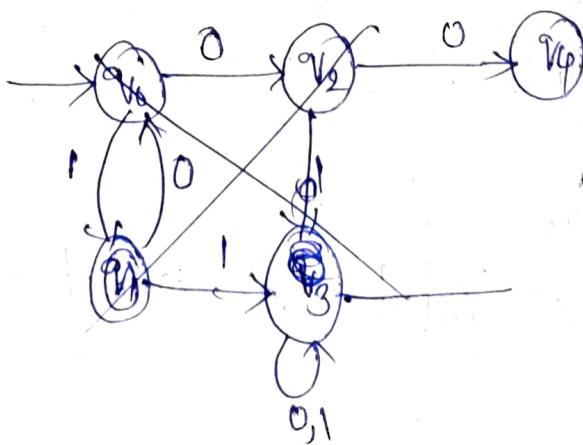
- * Here, q_6 is unreachable state
(As we cannot reach it from source code q_0).

So, we have to remove unreachable state and associated transitions.



Step-2:

- * Identify the dead state and remove it and associated transitions.



$T_0 = \{q_1, q_5\}$, $\{q_0, q_3, q_4\}$
 ↓
 final ↓
 non final

$$\Pi_1 = ?$$

Find the transition for above groups
for each input

$$S(q_1, 0) = q_0$$

$$S(q_5, 0) = q_4$$

* Based on '0' input we cannot divide as they are in same group

$$S(q_1, 1) = \emptyset$$

$$S(q_5, 1) = \emptyset$$

* Based on '1' equivalence we cannot further divide q_1 & q_5

$$\Rightarrow S(q_0, 0) = q_2$$

$$S(q_2, 0) = q_4$$

$$S(q_4, 0) = q_2$$

* Based on '0' input we cannot further divide.

$$\delta(v_0, 1) = v_1$$

$$\delta(v_2, 1) = \phi$$

$$\delta(v_4, 1) = v_5$$

$$\Pi_1 = \{v_1, v_5\}, \{v_0, v_4\}, \{v_2\}$$

$$\delta(v_1, 0) = v_0, \quad \delta(v_1, 1) = \phi$$

$$\delta(v_5, 0) = v_4, \quad \delta(v_5, 1) = \phi$$

we cannot divide $\{v_1, v_5\}$ based on 1
and 0 equivalence.

$$\delta(v_0, 0) = v_2$$

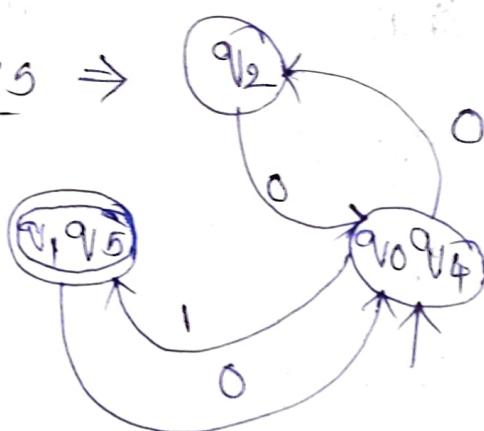
$$\delta(v_4, 0) = v_2$$

$$\delta(v_0, 1) = v_1$$

$$\delta(v_4, 1) = v_5$$

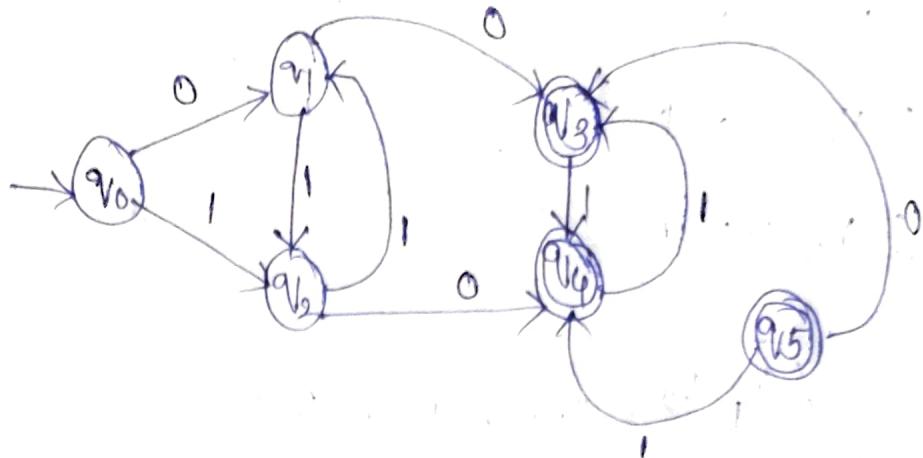
$$\Pi_2 = \{v_1, v_5\}, \{v_0, v_4\}, \{v_2\}.$$

Final states \Rightarrow

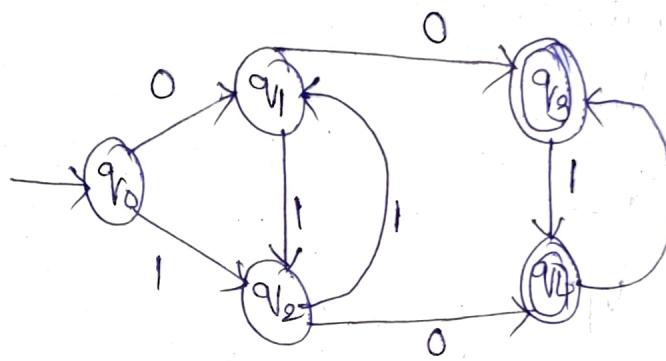


keep the final states and initial states
from the given diagram.

Pb



Sol: From the given diagram it is clear that ' q_5 ' is unreachable state. Hence remove it and states associated with it.



$$\pi_0 = \{q_0, q_1, q_2\} \quad \underbrace{\text{non-final}}_{\text{non-final}} \quad \text{and} \quad \pi_1 = \{q_3, q_4\} \quad \underbrace{\text{final}}_{\text{final}}$$

$$\delta(q_0, 0) = q_1.$$

$$\delta(q_1, 0) = q_3.$$

$$\delta(q_2, 0) = q_4.$$

Based on the '0' equivalence we can divide them as.

$$\pi_1 = \{v_0\}, \{v_1, v_2\}, \{v_3, v_4\}.$$

$$\begin{aligned} S(v_1, 0) &= v_3 \\ S(v_2, 0) &= v_4 \end{aligned} \quad \left. \begin{array}{l} \text{Belongs to same group} \\ \text{so we cannot divide them.} \end{array} \right\}$$

$$\begin{aligned} S(v_1, 1) &= v_2 \\ S(v_2, 1) &= v_1 \end{aligned} \quad \left. \begin{array}{l} \text{Belongs to same group} \\ \text{so we cannot divide them.} \end{array} \right\}$$

$$\begin{aligned} S(v_3, 0) &= \emptyset \\ S(v_4, 0) &= \emptyset \end{aligned} \quad \left. \begin{array}{l} \text{Belongs to same group} \\ \text{so we cannot divide them} \end{array} \right\}$$

$$\begin{aligned} S(v_3, 1) &= v_4 \\ S(v_4, 1) &= v_3 \end{aligned} \quad \left. \begin{array}{l} \text{Belongs to same group} \\ \text{so we cannot divide them.} \end{array} \right\}$$

$$\pi_2 = \{v_0\}, \{v_1, v_2\}; \{v_3, v_4\}$$

Final diagram :-

