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Support Vector Machines

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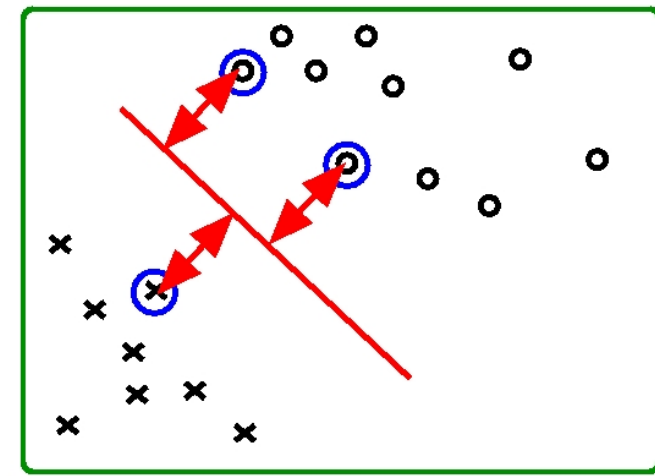
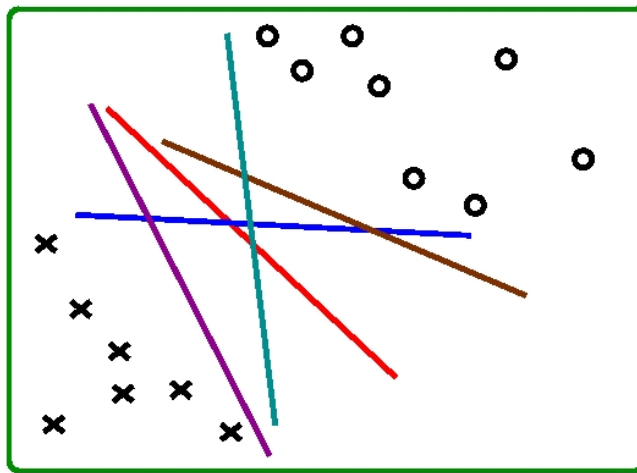
Introduction

- SVMs: sparse solutions: support vectors
- Convex optimisation: local optimal is also global
- Philosophy: different classifier formulations seek to optimise different criteria, make different assumptions, each fine in its own right
- Fisher: maximise 1-D projected margins
- SVM: maximise margins
- 2-class: generalisable to K classes: 1-1 or 1-rest
- 2 classes: ± 1 for notational convenience, not 0/1

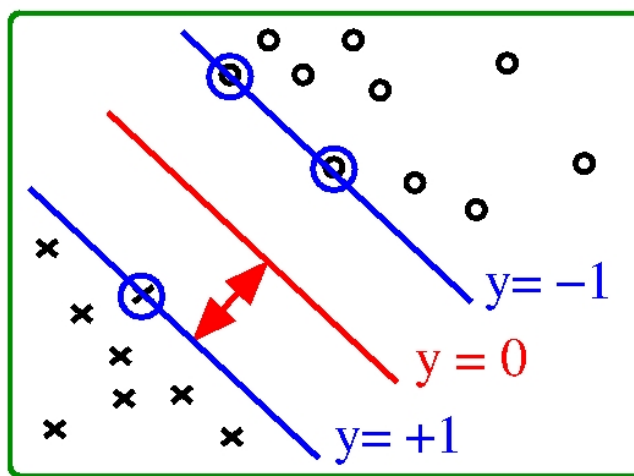
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Maximum Margin Classifiers

- 2-class restricted possible non-linearity:■
- $y(\mathbf{x}) = \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}) + b$. $y(\mathbf{x})$ is the model for target t .■
 b : bias, $\boldsymbol{\phi}(\cdot)$: feature space transformation■
- training $\{\mathbf{x}_1, \dots, \mathbf{x}_N\}$ targets $\{t_1, \dots, t_N\}$, $t_i \in \{-1, +1\}$ ■
- New data points \mathbf{x} classified acc to $y(\mathbf{x})$'s sign■
- Assume that the training data is linearly separable in the feature space i.e., \exists at least one \mathbf{w} & b :■
- $y(\mathbf{x}_i) < 0$ for $t_i = -1$ and $y(\mathbf{x}_i) > 0$ for $t_i = +1$ ■
- Combined: $t_i y(\mathbf{x}_i) > 0 \forall$ training data $\{\mathbf{x}_i, t_i\}$ ■
- Intuition: if multiple solutions, find the one which will give the smallest generalisation error■

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- Infinite possibilities
- Choose acc to some optimisation criterion
- min dist of a point from the decision boundary
- \triangle margin, to maximise
- Implicit form of the eqn of a line $w_2x_2 + w_1x_1 + b = 0$
- The two intercept form $\frac{x_2}{(-b/w_2)} + \frac{x_1}{(-b/w_1)} = 1$
- The slope-intercept form $x_2 = (\frac{-w_1}{w_2})x_1 + (\frac{-b}{w_2})$
- Take-home point#1: w determines the slope
- Take-home point#2: b : scaled distance from the origin. Why? $\frac{b}{||w||}$ is the distance from the origin.

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- **Margin:** min dist b/w decision boundary & **any** sample
- symmetric, by defn above
- **Don't worry about $y = \pm 1$, yet**
- **Aim: Maximise this margin**
- **The location of the boundary: determined by a small subset of the data points: Support Vectors**
- Decision surface: $y(\mathbf{x}) = \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}) + b = 0$
- Perp dist of \mathbf{x} from $y(\mathbf{x}) = 0$: is given by $\frac{|y(\mathbf{x})|}{\|\mathbf{w}\|}$
- **We want correct classification i.e., $t_i y(\mathbf{x}_i) > 0 \forall i$**
- $|y(\mathbf{x}_i)| = +y(\mathbf{x}_i)$ when $y(\mathbf{x}_i) > 0$ ($t_i = +1$)
- $|y(\mathbf{x}_i)| = -y(\mathbf{x}_i)$ when $y(\mathbf{x}_i) < 0$ ($t_i = -1$)
- $\implies |y(\mathbf{x})| = t_i y(\mathbf{x}_i)$, **perp dist** = $\frac{t_i y(\mathbf{x}_i)}{\|\mathbf{w}\|}$
- **Max margin:** $\arg \max_{\mathbf{w}, b} \left\{ \frac{1}{\|\mathbf{w}\|} \min_i \{ t_i [\mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_i) + b] \} \right\}$