

LECTURE 3: APPLYING THE DISCRETIZATIONS

OUR BASIC SET UP

- EACH EDGE e_j DISCRETIZED THE EXTENDED GRID OF (N_j+2) POINTS
- THE DISCRETE 2ND DERIVATIVE OPERATOR IS A RECTANGULAR $N_j \times (N_j+2)$ MATRIX L_j^{int} WHICH MAPS TO THE INTERIOR GRID, WHERE ALL EQUATIONS ARE SATISFIED EXCEPT VERTEX CONDITIONS
- AN INTERPOLATION MATRIX $P_{int}^{(j)}$ MAPS VALUES DEFINED ON EXTENDED GRID TO INTERIOR POINT
- THE VERTEX CONDITIONS AT VERTEX v_k GIVEN BY A WIDE MATRIX OF d_k ROWS $M_{vc}^{(k)}$
 $(N_{ext} = \sum_{e_j \in EG} (N_j+2) \text{ COLUMNS WIDE})$

SOME NOTATION:

$$L_{int} = \begin{bmatrix} L_{int}^{(1)} & & & \\ & L_{int}^{(2)} & & \\ & & \ddots & \\ & & & L_{int}^{(|EG|)} \end{bmatrix} = \text{WIDE LAPLACIAN}$$

EACH BLOCK HAS TWO MORE COLUMNS THAN ROWS

$$P_{int} = \begin{bmatrix} P_{int}^{(1)} & & & \\ & P_{int}^{(2)} & & \\ & & \ddots & \\ & & & P_{int}^{(|EG|)} \end{bmatrix} = \text{MATRIX INTERPOLATING FROM } \underline{\text{EXTENDED GRID}} \text{ TO } \underline{\text{INTERIOR GRID}}$$

$$M_{vc} = \begin{bmatrix} M_{vc}^{(1)} \\ \vdots \\ M_{vc}^{(|VG|)} \end{bmatrix} \underbrace{\}_{N_{ext}}} = \text{DISCRETIZED VERTEX CONDITION}$$

$$\textcircled{1} = 2|E_G| \times N_{\text{EXT}} \quad \text{MATRIX OF ZEROS}$$

TO SOLVE PROBLEMS UNIQUELY, NEED SQUARE MATRIX

DEFINE $L_o = \begin{bmatrix} L_{\text{INT}} \\ \textcircled{1} \end{bmatrix}, \quad L_{\text{VC}} = \begin{bmatrix} L_{\text{INT}} \\ M_{\text{VC}} \end{bmatrix}$

$P_o = \begin{bmatrix} P_{\text{INT}} \\ \textcircled{1} \end{bmatrix}, \quad P_{\text{VC}} = \begin{bmatrix} P_{\text{INT}} \\ M_{\text{VC}} \end{bmatrix}$

WILL USE THESE FOUR MATRICES TO DISCRETIZE
A VARIETY OF PROBLEMS

TO SOLVE $\Delta u = f$ ON G
SUBJECT TO HOMOGENEOUS VERTEX
CONDITIONS

LET $\vec{f} = \text{VECTOR OF } f \text{ VALUES ON } X_{\text{EXT}}$
 $\vec{u} = (\text{UNKNOWN}) \text{ VECTOR OF } u \text{ VALUES ON } X_{\text{EXT}}$

SOLVE BOTH

$$L_{\text{INT}} \vec{u} = P_{\text{INT}} \vec{f} \quad \text{N INT EQNS IN N EXT VARIABLES}$$

$$\& M_{\text{VC}} \vec{u} = \vec{0} \quad \underline{2|E_G| \text{ EQNS IN N EXT VARIABLES}}$$

N EXT EQNS IN N EXT VARS

CONCATENATE

$$L_{\text{VC}} \vec{u} = P_o \vec{f}$$

EXAMPLE IN SLIDES

EIGENVALUE PROBLEMS ARE VERY SIMILAR

$$L_{\text{INT}} \vec{u} = \lambda P_{\text{INT}} \vec{u} \quad \text{ON } X_{\text{EXT}}$$

$$M_{\text{VC}} \vec{u} = \vec{0}$$

CONCATENATE

$$L_{\text{VC}} \vec{u} = \lambda P_0 \vec{u}$$

THIS IS A GENERALIZED EIGENVALUE PROBLEM

$$A \vec{v} = \lambda B \vec{v}$$

P_0 IS SINGULAR, SO WE CAN'T JUST LEFT MULTIPLY BY P_0^{-1} TO GET A STANDARD EIGENVALUE PROBLEM.

EXAMPLE IN SLIDES

STATIONARY NLS

$$\Delta \psi + \lambda \psi + 2\psi^3 = 0 \quad \text{NOTE } \psi: G \rightarrow \mathbb{R}$$

ASSUME $\lambda \in \mathbb{R}$ IS GIVEN

RECALL NEWTON'S METHOD $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$

GIVEN A GUESS x_n s.t $f(x_n) \neq 0$

$$\text{Let } x_{n+1} = x_n + \delta$$

$$f(x_{n+1}) = f(x_n + \delta)$$

$$\approx f(x_n) + Df|_{x_n} \cdot \delta$$

$$\text{let } \delta \text{ SOLVE } Df|_{x_n} \delta = -f(x_n)$$

$$\text{SOL } x_{n+1} = x_n + \delta$$

FOR OUR PROBLEM

$$f(\psi; \lambda) = \Delta\psi + \lambda\psi + 2\psi^3$$

$$DF(\psi, \lambda) = \Delta + \lambda + 6\psi^2$$

OF COURSE δ IS SUBJECT TO VERTEX CONDITIONS

$$(\Delta + \lambda + 6\psi_n^2)\delta = -(\Delta\psi_n + \lambda\psi_n + 2\psi_n^3)$$

DISCRETIZE TO THE INTERIOR POINTS

$$(L_{INT} + P_{INT} \cdot (6 \text{Diag} \psi_n^2 + \lambda I))\delta = -L_{INT}\psi_n - P_{INT}(\lambda I + 2 \text{Diag} \psi_n^3)$$

+ VERTEX CONDITIONS

$$M_{VC}\delta = 0$$

EXTEND L_{INT} ON LEFT WITH M_{VC} , ALL OTHER MATRICES WITH ZEROES

$$\underbrace{(L_{VC} + P_0(6 \text{Diag} \psi_n^2 + \lambda I))}_{\text{myMatrix}(\psi_n, \lambda)}\delta = \underbrace{-L_0\psi_n - P_0(\lambda\psi_n + 2 \text{Diag} \psi_n^3)}_{\text{myFunction}(\psi_n, \lambda)}$$

TIME-STEPPING FOR EVOLUTIONARY PDE ON QUANTUM GRAPHS

RECALL SOME BASIC TIME-STEPPING ALGORITHMS FOR

$$\begin{cases} \frac{du}{dt} = f(u) \\ u(0) = u_0 \end{cases}$$

Fix $h \ll 1$. Let $t_n = nh$, $n=0,1,2,\dots$
 $u_n \approx u(t_n)$

FORWARD EULER

$$\frac{d}{dt} \Big|_{t=t_n} = \frac{u(t_{n+1}) - u(t_n)}{h} + O(h)$$

Let x_n
 SOLVE $\frac{u_{n+1} - u_n}{h} = f(x_n)$
 $u_{n+1} = u_n + h f(u_n)$ } AN EXPLICIT METHOD

LOCAL TRUNCATION ERROR $O(h^2) \rightarrow$ GLOBAL $O(h)$

LET'S TAKE $f(u) = \mu \Delta u$ ON A QUANTUM GRAPH G

CONTINUOUS IN SPACE $u_{n+1} = u_n + h \mu \Delta u_n$

NOW DISCRETIZE. THIS MUST HOLD ON THE
INTERIOR GRID.

$$P_{\text{INT}} \vec{u}_{n+1} = (P_{\text{INT}} + \mu L_{\text{INT}}) \vec{u}_n$$

BUT \vec{u}_{n+1} MUST ALSO SATISFY DISCRETIZED
VERTEX CONDITIONS

$$M_{VC} \vec{u}_{n+1} = \vec{0}$$

STACK THE TWO EQUATIONS

$$\begin{bmatrix} P_{INT} \\ M_{CV} \end{bmatrix} \vec{u}_{n+1} = \left[\frac{P_{INT} + h\mu L_{INT}}{\Theta} \right] \vec{u}_n$$

$$P_{VC} \vec{u}_{n+1} = (P_0 + h\mu L_0) \vec{u}_n$$

THIS IS IMPLICIT. \vec{u}_{n+1} GIVEN AS THE SOLUTION TO A SYSTEM OF ALGEBRAIC EQNS.

- THE IMPLICITY IS LINEAR IN THE UNKNOWN \vec{u}_{n+1}
- THE MATRIX P_{VC} IS WELL-CONDITIONED.
ALL ITS SINGULAR VALUES ONLY VARY BY A FEW ORDERS OF MAGNITUDE.
- STILL, THE UNDERLYING EQUATION IS STIFF
THE RHS HAS LARGE NEGATIVE EIGENVALUES
- NEED TO TAKE $h \ll 1$ FOR STABILITY

RECALL WHY : SCALAR EXAMPLE

$$\frac{dx}{dt} = \lambda x \quad \lambda < 0$$

EXACT SOLUTION

$$x = x_0 e^{\lambda t} \xrightarrow[t \rightarrow \infty]{} 0$$

FWD EULER

$$x_{n+1} = x_n + \lambda h x_n = (1 + \lambda h) x_n$$

$$\text{SUM UP: } x_n = (1 + h\lambda)^n x_0$$

$$\text{NEED } \lim_{n \rightarrow \infty} x_n = 0 \Rightarrow |1 + h\lambda| < 1$$

$$-1 < 1 + h\lambda < 1 \\ 0 < |\lambda| h < 2 \Rightarrow \boxed{h < \frac{2}{|\lambda|}}$$

THE SOLUTION: IMPLICIT METHOD

ON ODE $x_{n+1} = x_n + h f(x_{n+1})$

MODEL PROBLEM $x_{n+1} = x_n + h \lambda x_{n+1}, \lambda < 0$

$$(1 - h\lambda)x_{n+1} = x_n$$

$$x_n = \underbrace{(1 - h\lambda)^{-n}}_{1-h\lambda > 1} x_0 \xrightarrow[h \rightarrow \infty]{\rightarrow 0} \text{if } h > 0$$

CONTINUOUS $u_{n+1} = u_n + h \mu \Delta u_{n+1}$

DISCRETIZE TO INTERIOR GRID: $P_{int} \vec{u}_{n+1} = P_{int} \vec{u}_n + h \mu L_{int} \vec{u}_{n+1}$
 $(P_{int} - h \mu L_{int}) \vec{u}_{n+1} = P_{int} \vec{u}_n$

EXTEND WITH VERTEX CONDITIONS ON u_{n+1}

$$\left[\frac{P_{int} - h \mu L_{int}}{M_{vc}} \right] \vec{u}_{n+1} = P_0 \vec{u}_n$$

THIS WON'T HAVE STEPSIZE RESTRICTIONS, BUT
IS STILL ONLY FIRST-ORDER IN h .

CRANK-NICHOLSON: 2ND ORDER IN TIME

ON THE QUANTUM GRAPH: EVALUATE AT $t = t_n + \frac{h}{2}$

$$\frac{u_{n+1} - u_n}{h} = \frac{1}{2}(\Delta u_{n+1} + \Delta u_n)$$

$$u_{n+1} - \frac{h}{2} \Delta u_{n+1} = u_n + \frac{h}{2} \Delta u_n$$

DISCRETIZE ON INTERIOR

$$(P_{int} - \frac{h}{2} L_{int}) \vec{u}_{n+1} = (P_{int} + \frac{h}{2} L_{int}) \vec{u}_n$$

+ VERTEX CONDITIONS $M_{vc} \vec{u}_{n+1} = 0$

$$\left[\frac{P_{int} - \frac{h}{2} L_{int}}{M_{vc}} \right] \vec{u}_{n+1} = (P_0 + \frac{h}{2} L_0) \vec{u}_n$$

EQUIVALENTLY

$$(P_{VC} - \frac{h}{2} L_{VC}) \vec{u}_{n+1} = (P_0 + \frac{h}{2} L_0) \vec{u}_n$$

QUESTION FOR NEXT TIME

HOW CAN WE EFFICIENTLY SIMULATE
 $i u_t + \Delta u + \sigma |u|^2 u = 0$?