

$$20. \begin{bmatrix} -2 & 0 & 1 \\ 0 & -1 & -1 \\ 1 & 1 & -4 \end{bmatrix} X = \begin{bmatrix} 4 & 3 & 2 & 1 \\ 6 & 7 & 8 & 9 \\ 1 & 3 & 7 & 9 \end{bmatrix}$$

Working with Proofs

21. Let $A\mathbf{x} = \mathbf{0}$ be a homogeneous system of n linear equations in n unknowns that has only the trivial solution. Prove that if k is any positive integer, then the system $A^k\mathbf{x} = \mathbf{0}$ also has only the trivial solution.
22. Let $A\mathbf{x} = \mathbf{0}$ be a homogeneous system of n linear equations in n unknowns, and let Q be an invertible $n \times n$ matrix. Prove that $A\mathbf{x} = \mathbf{0}$ has only the trivial solution if and only if $(QA)\mathbf{x} = \mathbf{0}$ has only the trivial solution.
23. Let $A\mathbf{x} = \mathbf{b}$ be any consistent system of linear equations, and let \mathbf{x}_1 be a fixed solution. Prove that every solution to the system can be written in the form $\mathbf{x} = \mathbf{x}_1 + \mathbf{x}_0$, where \mathbf{x}_0 is a solution to $A\mathbf{x} = \mathbf{0}$. Prove also that every matrix of this form is a solution.
24. Use part (a) of Theorem 1.6.3 to prove part (b).

True-False Exercises

TF. In parts (a)–(g) determine whether the statement is true or false, and justify your answer.

- (a) It is impossible for a system of linear equations to have exactly two solutions.
- (b) If A is a square matrix, and if the linear system $A\mathbf{x} = \mathbf{b}$ has a unique solution, then the linear system $A\mathbf{x} = \mathbf{c}$ also must have a unique solution.
- (c) If A and B are $n \times n$ matrices such that $AB = I_n$, then $BA = I_n$.
- (d) If A and B are row equivalent matrices, then the linear systems $A\mathbf{x} = \mathbf{0}$ and $B\mathbf{x} = \mathbf{0}$ have the same solution set.

- (e) Let A be an $n \times n$ matrix and S is an $n \times n$ invertible matrix. If \mathbf{x} is a solution to the linear system $(S^{-1}AS)\mathbf{x} = \mathbf{b}$, then $S\mathbf{x}$ is a solution to the linear system $A\mathbf{y} = S\mathbf{b}$.
- (f) Let A be an $n \times n$ matrix. The linear system $A\mathbf{x} = 4\mathbf{x}$ has a unique solution if and only if $A - 4I$ is an invertible matrix.
- (g) Let A and B be $n \times n$ matrices. If A or B (or both) are not invertible, then neither is AB .

Working with Technology

T1. Colors in print media, on computer monitors, and on television screens are implemented using what are called “color models”. For example, in the RGB model, colors are created by mixing percentages of red (R), green (G), and blue (B), and in the YIQ model (used in TV broadcasting), colors are created by mixing percentages of luminescence (Y) with percentages of a chrominance factor (I) and a chrominance factor (Q). The conversion from the RGB model to the YIQ model is accomplished by the matrix equation

$$\begin{bmatrix} Y \\ I \\ Q \end{bmatrix} = \begin{bmatrix} .299 & .587 & .114 \\ .596 & -.275 & -.321 \\ .212 & -.523 & .311 \end{bmatrix} \begin{bmatrix} R \\ G \\ B \end{bmatrix}$$

What matrix would you use to convert the YIQ model to the RGB model?

T2. Let

$$A = \begin{bmatrix} 1 & -2 & 2 \\ 4 & 5 & 1 \\ 0 & 3 & -1 \end{bmatrix}, \quad B_1 = \begin{bmatrix} 0 \\ 1 \\ 7 \end{bmatrix}, \quad B_2 = \begin{bmatrix} 11 \\ 5 \\ 3 \end{bmatrix}, \quad B_3 = \begin{bmatrix} 1 \\ -4 \\ 2 \end{bmatrix}$$

Solve the linear systems $A\mathbf{x} = B_1$, $A\mathbf{x} = B_2$, $A\mathbf{x} = B_3$ using the method of Example 2.

1.7 Diagonal, Triangular, and Symmetric Matrices

In this section we will discuss matrices that have various special forms. These matrices arise in a wide variety of applications and will play an important role in our subsequent work.

Diagonal Matrices

A square matrix in which all the entries off the main diagonal are zero is called a **diagonal matrix**. Here are some examples:

$$\begin{bmatrix} 2 & 0 \\ 0 & -5 \end{bmatrix}, \quad \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad \begin{bmatrix} 6 & 0 & 0 & 0 \\ 0 & -4 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 8 \end{bmatrix}, \quad \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

A general $n \times n$ diagonal matrix D can be written as

$$D = \begin{bmatrix} d_1 & 0 & \cdots & 0 \\ 0 & d_2 & \cdots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & d_n \end{bmatrix} \quad (1)$$

Confirm Formula (2) by showing that

$$DD^{-1} = D^{-1}D = I$$

A diagonal matrix is invertible if and only if all of its diagonal entries are nonzero; in this case the inverse of (1) is

$$D^{-1} = \begin{bmatrix} 1/d_1 & 0 & \cdots & 0 \\ 0 & 1/d_2 & \cdots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & 1/d_n \end{bmatrix} \quad (2)$$

You can verify that this is so by multiplying (1) and (2).

Powers of diagonal matrices are easy to compute; we leave it for you to verify that if D is the diagonal matrix (1) and k is a positive integer, then

$$D^k = \begin{bmatrix} d_1^k & 0 & \cdots & 0 \\ 0 & d_2^k & \cdots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & d_n^k \end{bmatrix} \quad (3)$$

► EXAMPLE 1 Inverses and Powers of Diagonal Matrices

If

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

then

$$A^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{3} & 0 \\ 0 & 0 & \frac{1}{2} \end{bmatrix}, \quad A^5 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -243 & 0 \\ 0 & 0 & 32 \end{bmatrix}, \quad A^{-5} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{243} & 0 \\ 0 & 0 & \frac{1}{32} \end{bmatrix}$$

Matrix products that involve diagonal factors are especially easy to compute. For example,

$$\begin{bmatrix} d_1 & 0 & 0 \\ 0 & d_2 & 0 \\ 0 & 0 & d_3 \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \\ a_{31} & a_{32} & a_{33} & a_{34} \end{bmatrix} = \begin{bmatrix} d_1 a_{11} & d_1 a_{12} & d_1 a_{13} & d_1 a_{14} \\ d_2 a_{21} & d_2 a_{22} & d_2 a_{23} & d_2 a_{24} \\ d_3 a_{31} & d_3 a_{32} & d_3 a_{33} & d_3 a_{34} \end{bmatrix}$$

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \\ a_{41} & a_{42} & a_{43} \end{bmatrix} \begin{bmatrix} d_1 & 0 & 0 \\ 0 & d_2 & 0 \\ 0 & 0 & d_3 \end{bmatrix} = \begin{bmatrix} d_1 a_{11} & d_2 a_{12} & d_3 a_{13} \\ d_1 a_{21} & d_2 a_{22} & d_3 a_{23} \\ d_1 a_{31} & d_2 a_{32} & d_3 a_{33} \\ d_1 a_{41} & d_2 a_{42} & d_3 a_{43} \end{bmatrix}$$

In words, to multiply a matrix A on the left by a diagonal matrix D , multiply successive rows of A by the successive diagonal entries of D , and to multiply A on the right by D , multiply successive columns of A by the successive diagonal entries of D .

Triangular Matrices

A square matrix in which all the entries above the main diagonal are zero is called **lower triangular**, and a square matrix in which all the entries below the main diagonal are zero is called **upper triangular**. A matrix that is either upper triangular or lower triangular is called **triangular**.

▶ **EXAMPLE 2** Upper and Lower Triangular Matrices

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ 0 & a_{22} & a_{23} & a_{24} \\ 0 & 0 & a_{33} & a_{34} \\ 0 & 0 & 0 & a_{44} \end{bmatrix}$$

A general 4×4 upper triangular matrix

$$\begin{bmatrix} a_{11} & 0 & 0 & 0 \\ a_{21} & a_{22} & 0 & 0 \\ a_{31} & a_{32} & a_{33} & 0 \\ a_{41} & a_{42} & a_{43} & a_{44} \end{bmatrix}$$

A general 4×4 lower triangular matrix

Remark Observe that diagonal matrices are both upper triangular and lower triangular since they have zeros below and above the main diagonal. Observe also that a *square* matrix in row echelon form is upper triangular since it has zeros below the main diagonal.

Properties of Triangular Matrices

▲ Figure 1.7.1

Example 2 illustrates the following four facts about triangular matrices that we will state without formal proof:

- A square matrix $A = [a_{ij}]$ is upper triangular if and only if all entries to the left of the main diagonal are zero; that is, $a_{ij} = 0$ if $i > j$ (Figure 1.7.1).
- A square matrix $A = [a_{ij}]$ is lower triangular if and only if all entries to the right of the main diagonal are zero; that is, $a_{ij} = 0$ if $i < j$ (Figure 1.7.1).
- A square matrix $A = [a_{ij}]$ is upper triangular if and only if the i th row starts with at least $i - 1$ zeros for every i .
- A square matrix $A = [a_{ij}]$ is lower triangular if and only if the j th column starts with at least $j - 1$ zeros for every j .

The following theorem lists some of the basic properties of triangular matrices.

THEOREM 1.7.1

- The transpose of a lower triangular matrix is upper triangular, and the transpose of an upper triangular matrix is lower triangular.
- The product of lower triangular matrices is lower triangular, and the product of upper triangular matrices is upper triangular.
- A triangular matrix is invertible if and only if its diagonal entries are all nonzero.
- The inverse of an invertible lower triangular matrix is lower triangular, and the inverse of an invertible upper triangular matrix is upper triangular.

Part (a) is evident from the fact that transposing a square matrix can be accomplished by reflecting the entries about the main diagonal; we omit the formal proof. We will prove (b), but we will defer the proofs of (c) and (d) to the next chapter, where we will have the tools to prove those results more efficiently.

Proof(b) We will prove the result for lower triangular matrices; the proof for upper triangular matrices is similar. Let $A = [a_{ij}]$ and $B = [b_{ij}]$ be lower triangular $n \times n$ matrices,

and let $C = [c_{ij}]$ be the product $C = AB$. We can prove that C is lower triangular by showing that $c_{ij} = 0$ for $i < j$. But from the definition of matrix multiplication,

$$c_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \cdots + a_{in}b_{nj}$$

If we assume that $i < j$, then the terms in this expression can be grouped as follows:

$$c_{ij} = \underbrace{a_{i1}b_{1j} + a_{i2}b_{2j} + \cdots + a_{i(j-1)}b_{(j-1)j}}_{\substack{\text{Terms in which the row} \\ \text{number of } b \text{ is less than} \\ \text{the column number of } b}} + \underbrace{a_{ij}b_{jj} + \cdots + a_{in}b_{nj}}_{\substack{\text{Terms in which the row} \\ \text{number of } a \text{ is less than} \\ \text{the column number of } a}}$$

In the first grouping all of the b factors are zero since B is lower triangular, and in the second grouping all of the a factors are zero since A is lower triangular. Thus, $c_{ij} = 0$, which is what we wanted to prove. ◀

► EXAMPLE 3 Computations with Triangular Matrices

Consider the upper triangular matrices

$$A = \begin{bmatrix} 1 & 3 & -1 \\ 0 & 2 & 4 \\ 0 & 0 & 5 \end{bmatrix}, \quad B = \begin{bmatrix} 3 & -2 & 2 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

It follows from part (c) of Theorem 1.7.1 that the matrix A is invertible but the matrix B is not. Moreover, the theorem also tells us that A^{-1} , AB , and BA must be upper triangular. We leave it for you to confirm these three statements by showing that

$$A^{-1} = \begin{bmatrix} 1 & -\frac{3}{2} & \frac{7}{5} \\ 0 & \frac{1}{2} & -\frac{2}{5} \\ 0 & 0 & \frac{1}{5} \end{bmatrix}, \quad AB = \begin{bmatrix} 3 & -2 & -2 \\ 0 & 0 & 2 \\ 0 & 0 & 5 \end{bmatrix}, \quad BA = \begin{bmatrix} 3 & 5 & -1 \\ 0 & 0 & -5 \\ 0 & 0 & 5 \end{bmatrix} \quad \blacktriangleleft$$

Observe that in Example 3 the diagonal entries of AB and BA are the same, and in both cases they are the products of the corresponding diagonal entries of A and B . In the exercises we will ask you to prove that this happens whenever two upper triangular matrices or two lower triangular matrices are multiplied.

Symmetric Matrices

DEFINITION 1 A square matrix A is said to be **symmetric** if $A = A^T$.

It is easy to recognize a symmetric matrix by inspection: The entries on the main diagonal have no restrictions, but mirror images of entries across the main diagonal must be equal. Here is a picture using the second matrix in Example 4:

$$\begin{bmatrix} 1 & 4 & 5 \\ 4 & -3 & 0 \\ 5 & 0 & 7 \end{bmatrix}$$

► EXAMPLE 4 Symmetric Matrices

The following matrices are symmetric, since each is equal to its own transpose (verify).

$$\begin{bmatrix} 7 & -3 \\ -3 & 5 \end{bmatrix}, \quad \begin{bmatrix} 1 & 4 & 5 \\ 4 & -3 & 0 \\ 5 & 0 & 7 \end{bmatrix}, \quad \begin{bmatrix} d_1 & 0 & 0 & 0 \\ 0 & d_2 & 0 & 0 \\ 0 & 0 & d_3 & 0 \\ 0 & 0 & 0 & d_4 \end{bmatrix} \quad \blacktriangleleft$$

Remark It follows from Formula (14) of Section 1.3 that a square matrix A is symmetric if and only if

$$(A)_{ij} = (A)_{ji} \quad (4)$$

for all values of i and j .

The following theorem lists the main algebraic properties of symmetric matrices. The proofs are direct consequences of Theorem 1.4.8 and are omitted.

THEOREM 1.7.2 If A and B are symmetric matrices with the same size, and if k is any scalar, then:

- (a) A^T is symmetric.
- (b) $A + B$ and $A - B$ are symmetric.
- (c) kA is symmetric.

It is not true, in general, that the product of symmetric matrices is symmetric. To see why this is so, let A and B be symmetric matrices with the same size. Then it follows from part (e) of Theorem 1.4.8 and the symmetry of A and B that

$$(AB)^T = B^T A^T = BA$$

Thus, $(AB)^T = AB$ if and only if $AB = BA$, that is, if and only if A and B commute. In summary, we have the following result.

THEOREM 1.7.3 The product of two symmetric matrices is symmetric if and only if the matrices commute.

► EXAMPLE 5 Products of Symmetric Matrices

The first of the following equations shows a product of symmetric matrices that *is not* symmetric, and the second shows a product of symmetric matrices that *is* symmetric. We conclude that the factors in the first equation do not commute, but those in the second equation do. We leave it for you to verify that this is so.

$$\begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} -4 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} -2 & 1 \\ -5 & 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} -4 & 3 \\ 3 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 3 \end{bmatrix} \quad \blacktriangleleft$$

Invertibility of Symmetric Matrices

In general, a symmetric matrix need not be invertible. For example, a diagonal matrix with a zero on the main diagonal is symmetric but not invertible. However, the following theorem shows that if a symmetric matrix happens to be invertible, then its inverse must also be symmetric.

THEOREM 1.7.4 If A is an invertible symmetric matrix, then A^{-1} is symmetric.

Proof Assume that A is symmetric and invertible. From Theorem 1.4.9 and the fact that $A = A^T$, we have

$$(A^{-1})^T = (A^T)^{-1} = A^{-1}$$

which proves that A^{-1} is symmetric. \blacktriangleleft

Products AA^T and $A^T A$ are Symmetric

Matrix products of the form AA^T and $A^T A$ arise in a variety of applications. If A is an $m \times n$ matrix, then A^T is an $n \times m$ matrix, so the products AA^T and $A^T A$ are both square matrices—the matrix AA^T has size $m \times m$, and the matrix $A^T A$ has size $n \times n$. Such products are always symmetric since

$$(AA^T)^T = (A^T)^T A^T = AA^T \quad \text{and} \quad (A^T A)^T = A^T (A^T)^T = A^T A$$

► **EXAMPLE 6** The Product of a Matrix and Its Transpose Is SymmetricLet A be the 2×3 matrix

$$A = \begin{bmatrix} 1 & -2 & 4 \\ 3 & 0 & -5 \end{bmatrix}$$

Then

$$A^T A = \begin{bmatrix} 1 & 3 \\ -2 & 0 \\ 4 & -5 \end{bmatrix} \begin{bmatrix} 1 & -2 & 4 \\ 3 & 0 & -5 \end{bmatrix} = \begin{bmatrix} 10 & -2 & -11 \\ -2 & 4 & -8 \\ -11 & -8 & 41 \end{bmatrix}$$

$$A A^T = \begin{bmatrix} 1 & -2 & 4 \\ 3 & 0 & -5 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ -2 & 0 \\ 4 & -5 \end{bmatrix} = \begin{bmatrix} 21 & -17 \\ -17 & 34 \end{bmatrix}$$

Observe that $A^T A$ and $A A^T$ are symmetric as expected. ◀

Later in this text, we will obtain general conditions on A under which $A A^T$ and $A^T A$ are invertible. However, in the special case where A is *square*, we have the following result.

THEOREM 1.7.5 If A is an invertible matrix, then $A A^T$ and $A^T A$ are also invertible.

Proof Since A is invertible, so is A^T by Theorem 1.4.9. Thus $A A^T$ and $A^T A$ are invertible, since they are the products of invertible matrices. ◀

Exercise Set 1.7

► In Exercises 1–2, classify the matrix as upper triangular, lower triangular, or diagonal, and decide by inspection whether the matrix is invertible. [Note: Recall that a diagonal matrix is both upper and lower triangular, so there may be more than one answer in some parts.] ◀

1. (a) $\begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix}$

(b) $\begin{bmatrix} 0 & 0 \\ 4 & 0 \end{bmatrix}$

(c) $\begin{bmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & \frac{1}{5} \end{bmatrix}$

(d) $\begin{bmatrix} 3 & -2 & 7 \\ 0 & 0 & 3 \\ 0 & 0 & 8 \end{bmatrix}$

2. (a) $\begin{bmatrix} 4 & 0 \\ 1 & 7 \end{bmatrix}$

(b) $\begin{bmatrix} 0 & -3 \\ 0 & 0 \end{bmatrix}$

(c) $\begin{bmatrix} 4 & 0 & 0 \\ 0 & \frac{3}{5} & 0 \\ 0 & 0 & -2 \end{bmatrix}$

(d) $\begin{bmatrix} 3 & 0 & 0 \\ 3 & 1 & 0 \\ 7 & 0 & 0 \end{bmatrix}$

► In Exercises 3–6, find the product by inspection. ◀

3. $\begin{bmatrix} 3 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ -4 & 1 \\ 2 & 5 \end{bmatrix}$

4. $\begin{bmatrix} 1 & 2 & -5 \\ -3 & -1 & 0 \end{bmatrix} \begin{bmatrix} -4 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 2 \end{bmatrix}$

5. $\begin{bmatrix} 5 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & -3 \end{bmatrix} \begin{bmatrix} -3 & 2 & 0 & 4 & -4 \\ 1 & -5 & 3 & 0 & 3 \\ -6 & 2 & 2 & 2 & 2 \end{bmatrix}$

6. $\begin{bmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} 4 & -1 & 3 \\ 1 & 2 & 0 \\ -5 & 1 & -2 \end{bmatrix} \begin{bmatrix} -3 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 2 \end{bmatrix}$

► In Exercises 7–10, find A^2 , A^{-2} , and A^{-k} (where k is any integer) by inspection. ◀

7. $A = \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix}$

8. $A = \begin{bmatrix} -6 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix}$

9. $A = \begin{bmatrix} \frac{1}{2} & 0 & 0 \\ 0 & \frac{1}{3} & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix}$

10. $A = \begin{bmatrix} -2 & 0 & 0 & 0 \\ 0 & -4 & 0 & 0 \\ 0 & 0 & -3 & 0 \\ 0 & 0 & 0 & 2 \end{bmatrix}$

► In Exercises 11–12, compute the product by inspection. ◀

$$11. \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$12. \begin{bmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} 3 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 7 \end{bmatrix} \begin{bmatrix} 5 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

► In Exercises 13–14, compute the indicated quantity. ◀

$$13. \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}^{39}$$

$$14. \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}^{1000}$$

► In Exercises 15–16, use what you have learned in this section about multiplying by diagonal matrices to compute the product by inspection. ◀

$$15. (a) \begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix} \begin{bmatrix} u & v \\ w & x \\ y & z \end{bmatrix} \quad (b) \begin{bmatrix} r & s & t \\ u & v & w \\ x & y & z \end{bmatrix} \begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix}$$

$$16. (a) \begin{bmatrix} u & v \\ w & x \\ y & z \end{bmatrix} \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} \quad (b) \begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix} \begin{bmatrix} r & s & t \\ u & v & w \\ x & y & z \end{bmatrix}$$

► In Exercises 17–18, create a symmetric matrix by substituting appropriate numbers for the \times 's. ◀

$$17. (a) \begin{bmatrix} 2 & -1 \\ \times & 3 \end{bmatrix} \quad (b) \begin{bmatrix} 1 & \times & \times & \times \\ 3 & 1 & \times & \times \\ 7 & -8 & 0 & \times \\ 2 & -3 & 9 & 0 \end{bmatrix}$$

$$18. (a) \begin{bmatrix} 0 & \times \\ 3 & 0 \end{bmatrix} \quad (b) \begin{bmatrix} 1 & 7 & -3 & 2 \\ \times & 4 & 5 & -7 \\ \times & \times & 1 & -6 \\ \times & \times & \times & 3 \end{bmatrix}$$

► In Exercises 19–22, determine by inspection whether the matrix is invertible. ◀

$$19. \begin{bmatrix} 0 & 6 & -1 \\ 0 & 7 & -4 \\ 0 & 0 & -2 \end{bmatrix} \quad 20. \begin{bmatrix} -1 & 2 & 4 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

$$21. \begin{bmatrix} 1 & 0 & 0 & 0 \\ 2 & -5 & 0 & 0 \\ 4 & -3 & 4 & 0 \\ 1 & -2 & 1 & 3 \end{bmatrix} \quad 22. \begin{bmatrix} 2 & 0 & 0 & 0 \\ -3 & -1 & 0 & 0 \\ -4 & -6 & 0 & 0 \\ 0 & 3 & 8 & -5 \end{bmatrix}$$

► In Exercises 23–24, find the diagonal entries of AB by inspection. ◀

$$23. A = \begin{bmatrix} 3 & 2 & 6 \\ 0 & 1 & -2 \\ 0 & 0 & -1 \end{bmatrix}, \quad B = \begin{bmatrix} -1 & 2 & 7 \\ 0 & 5 & 3 \\ 0 & 0 & 6 \end{bmatrix}$$

$$24. A = \begin{bmatrix} 4 & 0 & 0 \\ -2 & 0 & 0 \\ -3 & 0 & 7 \end{bmatrix}, \quad B = \begin{bmatrix} 6 & 0 & 0 \\ 1 & 5 & 0 \\ 3 & 2 & 6 \end{bmatrix}$$

► In Exercises 25–26, find all values of the unknown constant(s) for which A is symmetric. ◀

$$25. A = \begin{bmatrix} 4 & -3 \\ a+5 & -1 \end{bmatrix}$$

$$26. A = \begin{bmatrix} 2 & a-2b+2c & 2a+b+c \\ 3 & 5 & a+c \\ 0 & -2 & 7 \end{bmatrix}$$

► In Exercises 27–28, find all values of x for which A is invertible. ◀

$$27. A = \begin{bmatrix} x-1 & x^2 & x^4 \\ 0 & x+2 & x^3 \\ 0 & 0 & x-4 \end{bmatrix}$$

$$28. A = \begin{bmatrix} x - \frac{1}{2} & 0 & 0 \\ x & x - \frac{1}{3} & 0 \\ x^2 & x^3 & x + \frac{1}{4} \end{bmatrix}$$

29. If A is an invertible upper triangular or lower triangular matrix, what can you say about the diagonal entries of A^{-1} ?

30. Show that if A is a symmetric $n \times n$ matrix and B is any $n \times m$ matrix, then the following products are symmetric:

$$B^T B, \quad B B^T, \quad B^T A B$$

► In Exercises 31–32, find a diagonal matrix A that satisfies the given condition. ◀

$$31. A^5 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \quad 32. A^{-2} = \begin{bmatrix} 9 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

33. Verify Theorem 1.7.1(b) for the matrix product AB and Theorem 1.7.1(d) for the matrix A , where

$$A = \begin{bmatrix} -1 & 2 & 5 \\ 0 & 1 & 3 \\ 0 & 0 & -4 \end{bmatrix}, \quad B = \begin{bmatrix} 2 & -8 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 3 \end{bmatrix}$$

34. Let A be an $n \times n$ symmetric matrix.

(a) Show that A^2 is symmetric.

(b) Show that $2A^2 - 3A + I$ is symmetric.

35. Verify Theorem 1.7.4 for the given matrix A .

$$(a) A = \begin{bmatrix} 2 & -1 \\ -1 & 3 \end{bmatrix} \quad (b) A = \begin{bmatrix} 1 & -2 & 3 \\ -2 & 1 & -7 \\ 3 & -7 & 4 \end{bmatrix}$$

36. Find all 3×3 diagonal matrices A that satisfy $A^2 - 3A - 4I = 0$.

37. Let $A = [a_{ij}]$ be an $n \times n$ matrix. Determine whether A is symmetric.

$$(a) a_{ij} = i^2 + j^2 \quad (b) a_{ij} = i^2 - j^2$$

$$(c) a_{ij} = 2i + 2j \quad (d) a_{ij} = 2i^2 + 2j^3$$

38. On the basis of your experience with Exercise 37, devise a general test that can be applied to a formula for a_{ij} to determine whether $A = [a_{ij}]$ is symmetric.

39. Find an upper triangular matrix that satisfies

$$A^3 = \begin{bmatrix} 1 & 30 \\ 0 & -8 \end{bmatrix}$$

40. If the $n \times n$ matrix A can be expressed as $A = LU$, where L is a lower triangular matrix and U is an upper triangular matrix, then the linear system $A\mathbf{x} = \mathbf{b}$ can be expressed as $LU\mathbf{x} = \mathbf{b}$ and can be solved in two steps:

Step 1. Let $U\mathbf{x} = \mathbf{y}$, so that $LU\mathbf{x} = \mathbf{b}$ can be expressed as $L\mathbf{y} = \mathbf{b}$. Solve this system.

Step 2. Solve the system $U\mathbf{x} = \mathbf{y}$ for \mathbf{x} .

In each part, use this two-step method to solve the given system.

$$(a) \begin{bmatrix} 1 & 0 & 0 \\ -2 & 3 & 0 \\ 2 & 4 & 1 \end{bmatrix} \begin{bmatrix} 2 & -1 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix}$$

$$(b) \begin{bmatrix} 2 & 0 & 0 \\ 4 & 1 & 0 \\ -3 & -2 & 3 \end{bmatrix} \begin{bmatrix} 3 & -5 & 2 \\ 0 & 4 & 1 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 4 \\ -5 \\ 2 \end{bmatrix}$$

► In the text we defined a matrix A to be symmetric if $A^T = A$. Analogously, a matrix A is said to be **skew-symmetric** if $A^T = -A$. Exercises 41–45 are concerned with matrices of this type. ◀

41. Fill in the missing entries (marked with \times) so the matrix A is skew-symmetric.

$$(a) A = \begin{bmatrix} \times & \times & 4 \\ 0 & \times & \times \\ \times & -1 & \times \end{bmatrix} \quad (b) A = \begin{bmatrix} \times & 0 & \times \\ \times & \times & -4 \\ 8 & \times & \times \end{bmatrix}$$

42. Find all values of a, b, c , and d for which A is skew-symmetric.

$$A = \begin{bmatrix} 0 & 2a - 3b + c & 3a - 5b + 5c \\ -2 & 0 & 5a - 8b + 6c \\ -3 & -5 & d \end{bmatrix}$$

43. We showed in the text that the product of symmetric matrices is symmetric if and only if the matrices commute. Is the product of commuting skew-symmetric matrices skew-symmetric? Explain.

Working with Proofs

44. Prove that every square matrix A can be expressed as the sum of a symmetric matrix and a skew-symmetric matrix. [Hint: Note the identity $A = \frac{1}{2}(A + A^T) + \frac{1}{2}(A - A^T)$.]

45. Prove the following facts about skew-symmetric matrices.

(a) If A is an invertible skew-symmetric matrix, then A^{-1} is skew-symmetric.

(b) If A and B are skew-symmetric matrices, then so are A^T , $A + B$, $A - B$, and kA for any scalar k .

46. Prove: If the matrices A and B are both upper triangular or both lower triangular, then the diagonal entries of both AB and BA are the products of the diagonal entries of A and B .

47. Prove: If $A^T A = A$, then A is symmetric and $A = A^2$.

True-False Exercises

TF. In parts (a)–(m) determine whether the statement is true or false, and justify your answer.

(a) The transpose of a diagonal matrix is a diagonal matrix.

(b) The transpose of an upper triangular matrix is an upper triangular matrix.

(c) The sum of an upper triangular matrix and a lower triangular matrix is a diagonal matrix.

(d) All entries of a symmetric matrix are determined by the entries occurring on and above the main diagonal.

(e) All entries of an upper triangular matrix are determined by the entries occurring on and above the main diagonal.

(f) The inverse of an invertible lower triangular matrix is an upper triangular matrix.

(g) A diagonal matrix is invertible if and only if all of its diagonal entries are positive.

(h) The sum of a diagonal matrix and a lower triangular matrix is a lower triangular matrix.

(i) A matrix that is both symmetric and upper triangular must be a diagonal matrix.

(j) If A and B are $n \times n$ matrices such that $A + B$ is symmetric, then A and B are symmetric.

(k) If A and B are $n \times n$ matrices such that $A + B$ is upper triangular, then A and B are upper triangular.

(l) If A^2 is a symmetric matrix, then A is a symmetric matrix.

(m) If kA is a symmetric matrix for some $k \neq 0$, then A is a symmetric matrix.

Working with Technology

T1. Starting with the formula stated in Exercise T1 of Section 1.5, derive a formula for the inverse of the “block diagonal” matrix

$$\begin{bmatrix} D_1 & 0 \\ 0 & D_2 \end{bmatrix}$$

in which D_1 and D_2 are invertible, and use your result to compute the inverse of the matrix

$$M = \begin{bmatrix} 1.24 & 2.37 & 0 & 0 \\ 3.08 & -1.01 & 0 & 0 \\ 0 & 0 & 2.76 & 4.92 \\ 0 & 0 & 3.23 & 5.54 \end{bmatrix}$$

1.8 Matrix Transformations

In this section we will introduce a special class of functions that arise from matrix multiplication. Such functions, called “matrix transformations,” are fundamental in the study of linear algebra and have important applications in physics, engineering, social sciences, and various branches of mathematics.

Recall that in Section 1.1 we defined an “ordered n -tuple” to be a sequence of n real numbers, and we observed that a solution of a linear system in n unknowns, say

$$x_1 = s_1, \quad x_2 = s_2, \dots, \quad x_n = s_n$$

can be expressed as the ordered n -tuple

$$(s_1, s_2, \dots, s_n) \quad (1)$$

Recall also that if $n = 2$, then the n -tuple is called an “ordered pair,” and if $n = 3$, it is called an “ordered triple.” For two ordered n -tuples to be regarded as the same, they must list the same numbers in the same order. Thus, for example, $(1, 2)$ and $(2, 1)$ are different ordered pairs.

The set of all ordered n -tuples of real numbers is denoted by the symbol R^n . The elements of R^n are called **vectors** and are denoted in boldface type, such as **a**, **b**, **v**, **w**, and **x**. When convenient, ordered n -tuples can be denoted in matrix notation as column vectors. For example, the matrix

$$\begin{bmatrix} s_1 \\ s_2 \\ \vdots \\ s_n \end{bmatrix} \quad (2)$$

can be used as an alternative to (1). We call (1) the **comma-delimited form** of a vector and (2) the **column-vector form**. For each $i = 1, 2, \dots, n$, let \mathbf{e}_i denote the vector in R^n with a 1 in the i th position and zeros elsewhere. In column form these vectors are

$$\mathbf{e}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \quad \mathbf{e}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \quad \dots, \quad \mathbf{e}_n = \begin{bmatrix} 0 \\ 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$$

We call the vectors $\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_n$ the **standard basis vectors** for R^n . For example, the vectors

$$\mathbf{e}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \quad \mathbf{e}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \quad \mathbf{e}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

are the standard basis vectors for R^3 .

The term “vector” is used in various ways in mathematics, physics, engineering, and other applications. The idea of viewing n -tuples as vectors will be discussed in more detail in Chapter 3, at which point we will also explain how this idea relates to more familiar notion of a vector.