

# Práctica 4: ejercicio5

Código:

```
int chequeo;
```

```
int i;
```

```
int uart[9];
```

```
const int HEADER=0x59;
```

```
void setup() {
```

```
    // put your setup code here, to run once:
```

```
    Serial.begin(9600);
```

```
    Serial1.begin(115200);
```

```
}
```

```
void loop() {
```

```
    // put your main code here, to run repeatedly:
```

```
    //Serial.println("empiezo");
```

```
    Serial.println(" ");
```

```
    if (Serial1.available()) {
```

```
        if (Serial1.read()==HEADER) {
```

```
            uart[0]=HEADER;
```

```
            if (Serial1.read()==HEADER) {
```

```
                uart[1]=HEADER;
```

```
                for (i=2;i<9;i++) {
```

```
                    uart[i]=Serial1.read();
```

```
                }
```

```
                chequeo=uart[0]+uart[1]+uart[2]+uart[3]+uart[4]+uart[5]+uart[6]+uart[7];
```

Participantes:

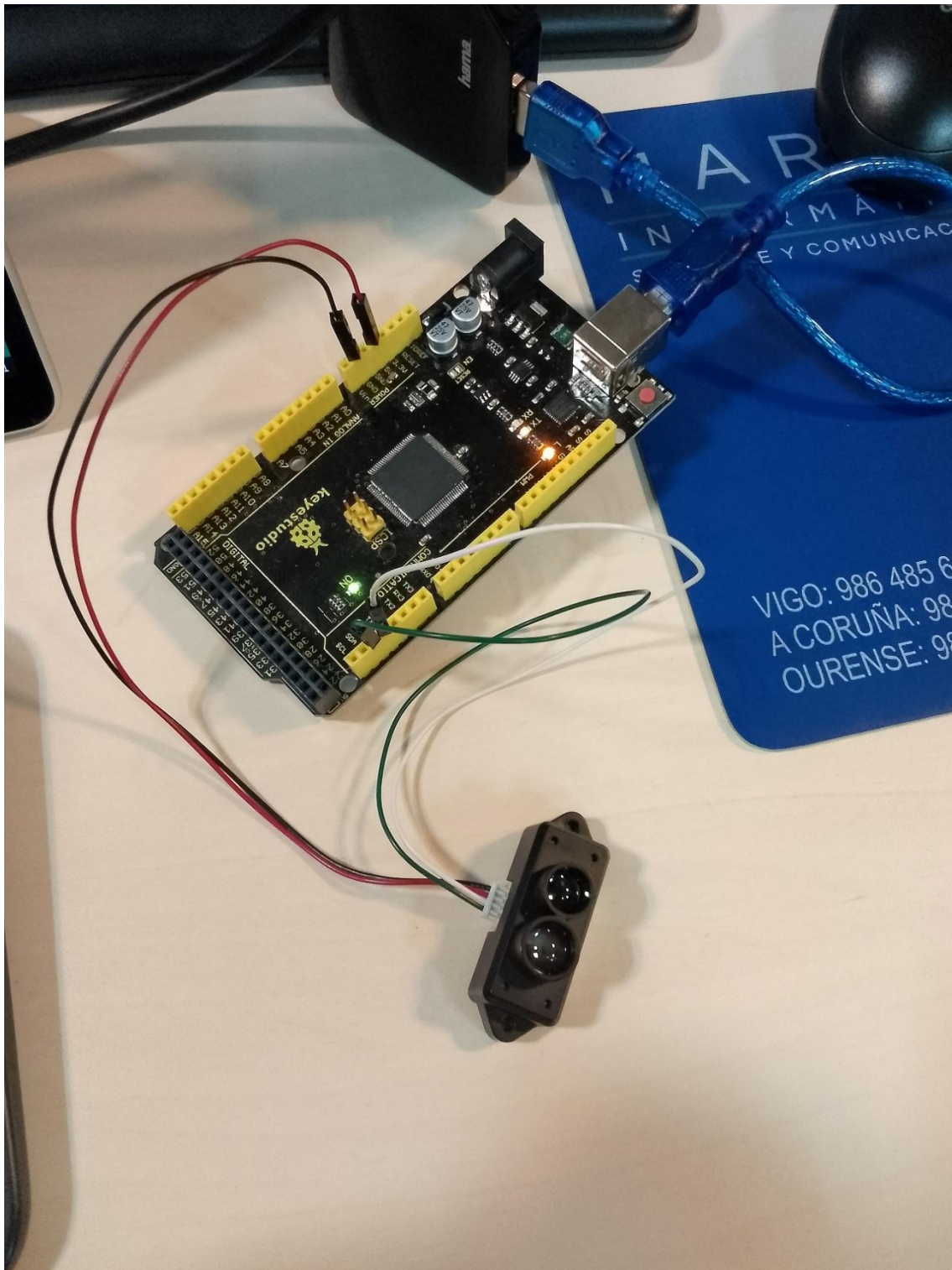
Denis Gomez Solla

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```
if(uart[8]==(chequeo&0xff)) {  
    dist=uart[2]+uart[3]*256;//calculate distance value  
    strength=uart[4]+uart[5]*256;//calculate signal strength value  
    Serial.print("dist = ");  
    Serial.print(dist);//output measure distance value of LiDAR  
    Serial.print("\t");  
    Serial.print("strength = ");  
    Serial.print(strength);//output signal strength value  
    //Serial.println("*****");  
}  
}  
}  
}  
  
}
```

Participantes:  
Denis Gomez Solla  
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-Imágenes de la práctica:



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-Enlaces a GitHub con los códigos, videos e imágenes del montaje:

[https://github.com/mans199876/proxectos1\\_practica4.git](https://github.com/mans199876/proxectos1_practica4.git)

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