

Mansi Maheshwari

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EDUCATION

University of Massachusetts Amherst

Amherst, MA

Master's of Science in Computer Science **GPA 4.0**

Aug. 2024 – May 2026

- **Relevant Coursework:** Neural Networks, Reinforcement Learning, Robotics, Algorithms for Data Science, Research Methods, Research Writing
- **Master's Thesis:** Lifelong Reinforcement Learning in Embodied Settings

University of Washington

Seattle, WA

Bachelor's of Science in Electrical Engineering

Aug. 2018 – June 2022

- **Relevant Coursework:** Fundamentals of Optimization and Machine Learning, Signal Processing, Multivariate Calculus, Statistical Methods for Science, Embedded Systems

PUBLICATIONS

M. Maheshwari, B. da Silva, and J. Raisbeck *AltNet: Alternating Network Resets for Plasticity*. In **Proceedings of the Conference on Lifelong Learning Agents (CoLLAs)**, 2025.

M. Maheshwari, J. Raisbeck, and B. da Silva *AltNet: Addressing the Plasticity-Stability Dilemma in Reinforcement Learning*. In **Submission** at the International Conference on Autonomous Agents and Multiagent Systems (AAMAS), 2026.

RELEVANT EXPERIENCE

Research Assistant (Reinforcement Learning and Robotics)

July 2024 – Present

Autonomous Learning Lab, University of Massachusetts

Amherst, MA

- Developed **AltNet**, a novel deep reinforcement learning architecture that improves **continual learning**, enhances **sample efficiency by 30%**, and increases **safety in non-stationary robotic environments**.
- Evaluated agents on robotics control tasks and game environments (DeepMind Control Suite, MuJoCo).
- Adapting the proposed architecture for **deployment on real robotic platforms**.
- **Published** this research in workshop at the Conference on Lifelong Learning Agents (**CoLLAs**) 2025; Full version in submission at the Conference on Autonomous Agents and Multiagent Systems (**AAMAS**) 2026.

Artificial Intelligence Research and Development Intern

May 2025 – Aug 2025

CNH Industrial, Perception Team - Autonomous Vehicles

Scottsdale, AZ

- Led the design and development of an **efficient, scalable vision architecture** unifying **object detection and segmentation** through a **transformer based YOLO multihead model** for autonomous vehicles.
- Improved computational efficiency by **~43%**, meeting strict latency requirements.
- Developed and documented a multi-task architecture that would allow new vision tasks to be added with minimal compute overhead, establishing a **scalable foundation for future vision capabilities**.
- Investigated **multi-modal perception** strategies by fusing image and sensor data, future-proofing the architecture for richer sensing modalities.

Software Engineer

July 2022 – July 2024

Nordstrom

Seattle, WA

- **Optimized** workflow by **automating** multiple engineering tasks (Java) in **distributed systems**.
- Achieved 80% test coverage for large-scale **data integrity** through JUnit **Integration Tests** for multiple projects.
- Led **end-to-end development** (requirements gathering, design discussions, code reviews, testing, and deployment) of a feature to stop awarding points for alcohol purchase.

TEACHING EXPERIENCE

Instructor, Fundamentals of Artificial Intelligence <i>University of Washington</i>	May 2025 – Jul 2025 <i>Remote</i>
<ul style="list-style-type: none">Instructed a 10-day, 30-hour course introducing high school students to core AI concepts including machine learning, deep learning, computer vision, large language models, and ethical AI; guided students in completing final projects synthesizing learned skills.Co-developed the curriculum and designed accessible, visually engaging slide decks and coding exercises to support conceptual understanding.Fostered an inclusive and interactive classroom environment through live polls (Poll Everywhere), quizzes (Kahoot), reflection activities, and curated videos showcasing real-world AI applications to enhance engagement and conceptual understanding.	

Subject Matter Expert, Artificial Intelligence <i>iCEV Multimedia</i>	Sept 2025 – Present <i>Remote</i>
<ul style="list-style-type: none">Provided subject-matter expertise for the Introduction to Artificial Intelligence course, ensuring conceptual accuracy, effective pedagogy, and alignment with educational standards.Reviewed lesson plans, identify gaps in learning progression, and deliver feedback to enhance student comprehension and engagement.Collaborated with curriculum designers to improve instructional materials and integrate real-world AI examples for accessibility and impact.	

PROJECTS

Human Following Robot, Autonomous Cinematography	Feb 2025 – May 2025
<ul style="list-style-type: none">Designed and implemented a mobile robot pipeline integrating perception (YOLOv7 for human detection and tracking), path planning (DWA-based trajectory generation), and real-time control (PID-based actuation) to autonomously follow and film a moving subject.	
Multi-Modal Conversational Recommender System	Aug 2024 – Dec 2024
<ul style="list-style-type: none">Built a multi-modal recommendation pipeline (tabular, visual, text) using CLIP encoders and BERT-based retrieval, with LLM explainability (GPT-4) to generate transparent rationales and enhance user trust.	

AWARDS AND SCHOLARSHIPS

Finalist, Three Minute Thesis <i>10 students were selected throughout the university to present their research</i>	March 2025
Lawrence & Lucille Frey Endowed Electrical Engineering Scholarship <i>Merit-based scholarship given to a select few students at the University of Washington</i>	2020 – 2021