Homework 4

Problem 1 For the multi-armed bandits problem, denote X_t as the (stochastic) reward we obtain at time t. For action $a \in \mathbb{A}$, where \mathbb{A} is the set of all actions, denote μ_a as the mean reward associated with action a. Also denote $T_a(n)$ as the number of times action a has been chosen, for a total game duration of n. Assume that μ_* is the optimal mean reward. We know that the regret can be computed as:

$$R_n = \sum_{t=1}^n \left(\mu_* - \mathbb{E}[X_t] \right).$$

Prove that it can also be computed as:

$$R_n = \sum_{a \in \mathbb{A}} (\mu_* - \mu_a) \cdot \mathbb{E}[T_a(n)].$$

Problem 2 For the Markov decision process problem over a time horizon of n, we have discussed in the class the value iteration method to find the optimal policy $\pi^* = \{\pi_t^*(a_t|s_t)\}_{t=1}^n$ given knowledge about the Markov transition probabilities at each time point $\{P_t(s_{t+1}|s_t,a_t)\}_{t+1}^n$. It iterates based on the Bellman optimality equation as follows:

Initialize
$$V_{n+1}(s) = 0, \forall s \in \mathbb{S}$$

For $t = n, n - 1, \dots, 1$

$$Q_t(s, a) = r_t(s, a) + \sum_{s \in \mathbb{S}} P_t(s_{t+1} = s' | s_t = s, a_t = a) \cdot V_{t+1}(s')$$

$$V_t(s) = \max_{s \in \mathbb{A}} Q_t(s, a)$$

We can also use the following policy iteration method by maintaining and updating the policy $\pi = \{\pi_t\}_{t=1}^n$.

Initialize
$$\pi^{(0)} = \left\{ \pi_t^{(0)} \right\}_{t=1}^n$$
 randomly

For k = 1, 2, ...

Evaluate
$$Q_t^{\pi^{(k-1)}}(s,a), \forall s \in \mathbb{S}, a \in \mathbb{A}, t = 1, \dots, n$$
, using the Bellman equation (1), (2) $\pi_t^{(k)}(s) = \arg\max_{a \in \mathbb{A}} Q_t^{\pi^{(k-1)}}(s,a), \forall s \in \mathbb{S}, t = 1, \dots, n$

Question: after how many iterations K (if any), would $\pi^{(K)}$ in the policy iteration algorithm become the optimal policy? Prove your result.

The Bellman equation:

$$Q_t(s,a) = r_t(s,a) + \sum_{s \in \mathbb{S}} P_t(s_{t+1} = s' | s_t = s, a_t = a) \cdot V_{t+1}(s')$$
 (1)

$$V_t(s) = \sum_{a \in \mathbb{A}} \pi_t(a|s) \cdot Q_t(s, a)$$
 (2)

Hint: prove inductively that $\forall t \geq n - k, \, Q_t^{\pi^{(k)}} = Q_t^{\pi^*}$.

Machine Learning Homework-4

Problem! Some terms! : Xt: Reward at time t Action a $\in A$, Ma: mean reward of action a $T_a(n)$: number of times a has been chosen Me : Optimal Reward

Regret Rn = 5 (ux - E[xt]) - (1)

To Prove: Rn = \(\int_{\alpha\int} \left(\int_{\alpha} \cdot - \mu_a \right) \cdot \(\mathbb{E} \left[\T_a(n) \right] \) - (2)

from () $R_{n} = \sum_{t=1}^{n} \left(\mu_{x} - E[x_{t}] \right); x_{t} \text{ is i.i.d. (doesn't defend on } t \right)$ $= n_{\mathcal{U}_{x}} - E\left[\sum_{t=1}^{n} x_{t}\right]$

Now, $\sum_{t=1}^{n} x_t = \sum_{t=1}^{n} \sum_{t=1}^{A} x_t \cdot 1(A_t = a_t^2) = Seum the reward obtained when action, happend$

 $\rightarrow R_n = n\mu_* - \mathbb{E}\left[\sum_{t=1}^n X_t\right] = \sum_{a=1}^n \mathbb{E}\left[(\mu_* - X_t) \cdot \mathbf{1}(A_t * a_t^2)\right]$

Enfected reward in round I conditioned on At is

up = ua = action at that t

-> Rn = S(ux-ua). E(Ta(n)]

- Hence Proved

Problem ? Proof

Initialize $T(0) = \{T_t(0)\}_{t=1}^n$ randomly

for $k = 1, 2, \cdots$ Now, for t=n,n-1,...,1 => $V_{t}(s) = \sum_{\alpha \in A} T_{t}^{(k-1)}(\alpha | s) \cdot Q_{t}^{\pi(k-1)}(s, \alpha)$ $\overline{\Pi}_{t}^{(k)}(s) = \underset{\alpha \in A}{\text{arg man }} Q_{t}^{\pi(k-1)}(s, \alpha), \forall s \in S, t = 1, \dots, \eta$ We want to prove $f t \ge n - k$, $Q_t^{\pi(k)} = Q_t^{\pi^*}$ by induction $g_n^{\Pi(k)}(s,a) = \pi_a(s,a) = g_n^{\Pi^*}(s,a)$ holds for all $k \ge 0$ 2 of gt+1 = gt+1, + k = n - (t+1) holds for t+1, then for t: + K = n-t,

$$Q_{t}^{\pi(k)}(s,a) = x_{t}(s,a) + \sum_{s \in S} P_{t}(S_{t+1} = S' | \frac{s_{t} = s}{a_{t} = a}) \cdot V_{t \in T}(s')$$

$$= x_{t}(s,a) + \sum_{s \in S} P_{t}(S_{t+1} = S' | \frac{s_{t} = s}{a_{t} = a}) \left(\sum_{a \in A} \frac{(k)}{t+1}(a|s'), \frac{\pi(k)}{a_{t} = a}\right)$$

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So
$$Q_{t}^{\pi(n-1)} = Q_{t}^{\pi^{*}} \quad \text{for } t=1,2,\dots,n$$

$$=) \quad \Pi_{t}^{(n)}(s) = \underset{\alpha \in A}{\operatorname{argman}} \quad Q_{t}^{\pi(n-1)}(s,a)$$

$$= \underset{\alpha \in A}{\operatorname{argman}} \quad Q_{t}^{\pi^{*}}(s,a)$$

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$$= \Pi_{t}^{*}(s)$$

$$=) \quad \Pi^{(n)} = \Pi^{*} \quad \left[k = \log \left(\underset{\alpha \in A}{\operatorname{argman}} Q_{t}^{\pi^{*}}(s,a) \right) \right]$$

$$\vdots \quad k = n$$