## Homework 2

**Problem 1** We have seen in class that for strongly convex and Lipschitz smooth functions, the convergence of the gradient descent algorithm is exponentially fast; whereas for convex and Lipschitz continuous functions, the convergence rate is  $\widetilde{O}(1/\sqrt{K})$ . You must have wondered which factor is more important in contributing to the faster convergence in the first case, the strong convexity or the smoothness. Now let's explore this problem by considering an objective function that is convex (but not strongly convex) and  $\beta$ -Lipschitz smooth.

1. First prove what we left off in class that if a function  $\mathcal{L}$  is convex and  $\beta$ -Lipschitz smooth (i.e.,  $\mathcal{L}(x) - \mathcal{L}(y) \leq \langle \nabla \mathcal{L}(y), x - y \rangle + \frac{\beta}{2} ||x - y||^2$ ), then

$$\mathcal{L}(x) - \mathcal{L}(y) \ge \langle \nabla \mathcal{L}(y), x - y \rangle + \frac{1}{2\beta} \|\nabla \mathcal{L}(x) - \mathcal{L}(y)\|^2.$$

2. What's the convergence rate of gradient descent over such a function  $\mathcal{L}$  that is convex (but not strongly convex) and  $\beta$ -Lipschitz smooth? Choose a set of step sizes  $h_k$  and prove the result using the technique we learned.

**Problem 2** Consider the following stochastic gradient descent algorithm.

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Algorithm 1: Stochastic gradient descent algorithm

Input: \theta_0

for k = 0, ..., K-1 do

Sample an i.i.d. set S_k uniformly at random from \{1, ..., N\}

Compute stochastic gradient \widetilde{\mathcal{L}}(\theta_k|S_k) = \frac{1}{|S_k|} \sum_{i \in S_k} \nabla \text{loss}(\theta_k|z_i)

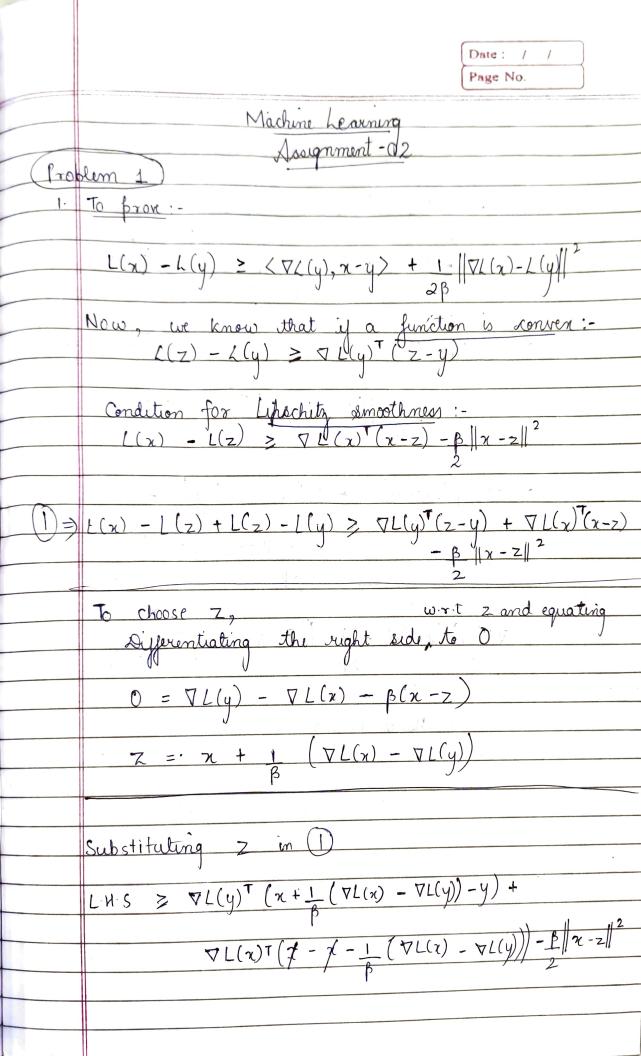
Update \theta_{k+1} = \theta_k - h_k \nabla \widetilde{\mathcal{L}}(\theta_k|S_k)

end

Return: \theta_K
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Assume that the loss functions  $\log(\theta|z)$  are convex and L-Lipschitz continuous  $(\|\nabla \log(\theta|z)\| \leq L)$  for all data points z (No need to make assumptions about the stochastic gradient variance in this case). What's the convergence rate of the stochastic gradient descent algorithm over risk  $\mathcal{L} = \frac{1}{N} \sum_{i=1}^{N} \nabla \log(\theta|z_i)$ ? Choose a set of step sizes  $h_k$  and prove the result using the technique we learned.

Using your derivation, what's the optimal choice of the batch size  $n = |S_k|$ ? Is the stochastic gradient descent algorithm more efficient than gradient descent in this case?



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$$\geq \nabla L(y)^{\mathsf{T}}(x-y) + \frac{1}{\beta} \nabla L(y)^{\mathsf{T}} (\nabla L(x) - \nabla L(y))$$

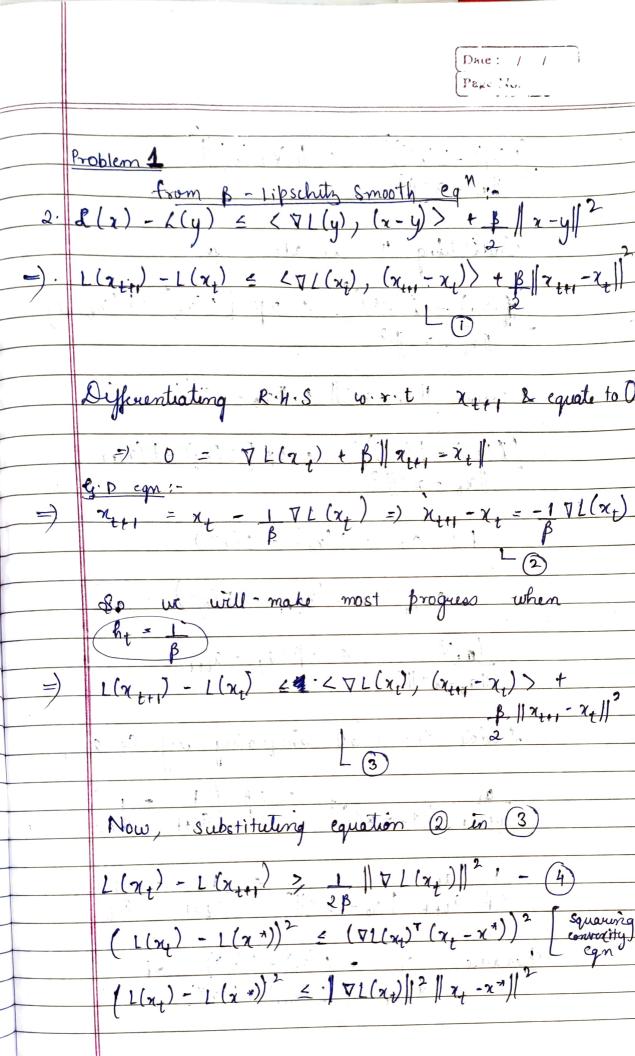
$$+ \frac{1}{\beta} \nabla L(x)^{\mathsf{T}} (\nabla L(x) - \nabla L(y))$$

$$= \frac{1}{2\beta} \left\| \nabla L(x) - \frac{1}{2\beta} \left( \nabla L(x) - \frac{1}{2\beta} \right) \left( \nabla L(y) - \frac{1}{2\beta} \right) \right\|^{2}$$

$$\frac{1}{2} \left\| \nabla L(y)^{T} (x - y) + \frac{1}{2} \left\| \nabla L(x) - L(y) \right\|^{2} - \frac{1}{2} \left\| \nabla L(x) - L(y) \right\|^{2}$$

$$\frac{2}{2\beta} \nabla L(y)^{T}(x-y) + \frac{1}{2\beta} \left\| \nabla L(y) - L(y) \right\|^{2}$$

Hence Proved



Multiply R.H.S by 
$$\frac{\alpha_{k+1}}{\alpha_k} \leq 1$$
 - mequality remains
$$t=T-1$$

$$= \frac{1}{2} + \frac{1}$$

$$\frac{1}{2\beta 11x_0 - x^* \|^2}$$

L(x+)-L(x\*) = 2 | 1/20-x\*/2 It converges 0 (1) with step ding 1

 $\frac{1}{a_T} \geq \frac{T}{2\beta ||x_0 - x^*||^2}$ 

Pxoblem 2

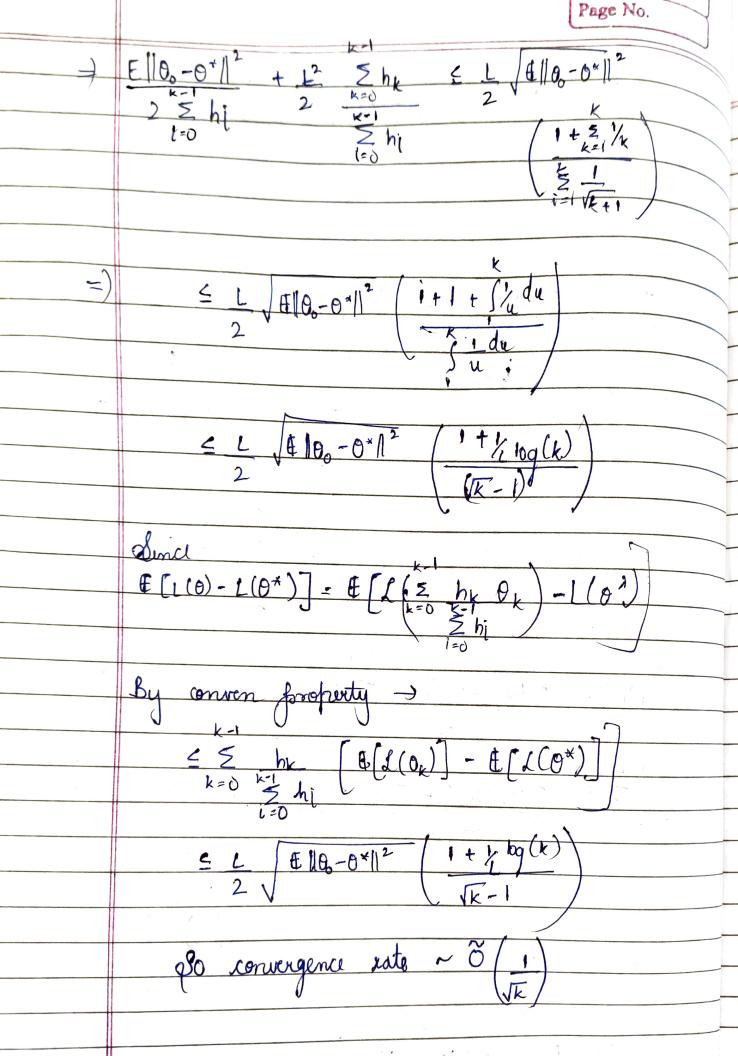
$$L(0|z) \sim \text{Convex } 1 - \text{Lipschitz} \quad \text{Continuous for all}$$

$$\int_{z \sim 0}^{z} \|\nabla L(0_{k}|c_{k}\|^{2} \leq b^{2}) \int_{z \sim 0}^{z} \text{some sondant } b^{2} \text{ variance}$$

$$\int_{z \sim 0}^{z \sim 0} \|\nabla L(0_{k}|c_{k}\|^{2} \leq b^{2}) \int_{z \sim 0}^{z} \text{some sondant } b^{2} \text{ variance}$$

$$\int_{z \sim 0}^{z \sim 0} \|\nabla L(0_{k}|c_{k}\|^{2} \leq b^{2}) \int_{z \sim 0}^{z \sim 0} |\nabla L(0_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_{k}|c_$$

$$\begin{array}{c} \sum_{k=0}^{k+1} h_{k} \left[ \left[ \left( \left( 0_{k} \right) - L \left( 0^{k} \right) \right] \leq \mathbb{E} \left\| 0_{k} \cdot 0^{k} \right\|^{2} + \frac{1}{2} \left\| \frac{1}{2} \right\| \frac{1}{2} \left\| \frac{1}{2} \left$$



Page No. (ii) Since #[L(0)-L(0\*)] ~ O(1), the optimal choice of iid n = |Sx| that optimal choice for gradient descent - convergence rate of GD ~ O(1) but for each interation, GD have quadient more than SGID => (SGID is more efficient)