

FROM VERIFIED FUNCTIONS TO SAFE C CODE

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MOTIVATION

- Software keeps getting more complex.
- Hardware gets cheaper and more robust.
- For some industry, development cost is high mostly because of software verification process.
- Failure can have disastrous impact on human lives or huge monetary loss.

—→ We need tools to **verify complex software**.

- Leon offers tools to reduce this cost.
- **But!** It's JVM-based hence useless for **very small devices** (e.g. pacemakers, spacecraft, ...)
- Need **native** code.
- That's why C-like languages are widely used in the industry.

- Why not but low level, verbose and error prone.
- Modern C++ or D might solve many issues from C...
- ...but no good verifiers exist.

VAL GENC = (CAST) LEON

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- ▷ Translate code into **equivalent** C99 code.
- ▷ Compile it with your favourite C compiler for your destination architecture.
- ▷ And run it **natively** on your hardware.

SUPPORTED FEATURES

TYPES

`Int` \longrightarrow `int32_t`

`Boolean` \longrightarrow `bool`

`Unit` \longrightarrow **`void`**

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`Boolean` \longrightarrow `bool`

`Unit` \longrightarrow **`void`**

`TupleN[T1, T2, ..., TN]` is generated using some kind of templates. E.g. (`Boolean`, `Int`) is:

```
typedef struct __leon_tuple_bool_int32_t_t {  
    bool    _1; // padding  
    int32_t _2;  
} __leon_tuple_bool_int32_t_t;
```

TYPES

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`Unit` \longrightarrow **`void`**

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    bool    _1; // padding  
    int32_t _2;  
} __leon_tuple_bool_int32_t_t;
```

Similarly, `Array[T]` is templatised. E.g. `Array[(Boolean, Int)]` is:

```
typedef struct __leon_array__leon_tuple_bool_int32_t_t_t {  
    __leon_tuple_bool_int32_t_t* data; // not owning the memory  
    int32_t                      length;  
} __leon_array__leon_tuple_bool_int32_t_t_t;
```

MORE ON ARRAYS

Those arrays live on the **stack** → cannot return them.

VLA (variable-length array) are used when needed.

```
def foo(size: Int, value: Int) { val a = Array.fill(size)(value) }
```

MORE ON ARRAYS

Those arrays live on the **stack** → cannot return them.

VLA (variable-length array) are used when needed.

```
def foo(size: Int, value: Int) { val a = Array.fill(size)(value) }
```

is translated into

```
void foo0(int32_t const size0, int32_t const value0) {  
    int32_t __leon_vla_buffer0[size0]; // actual memory alloc  
    for (int32_t __leon_i1 = 0; __leon_i1 < size0; ++__leon_i1) {  
        __leon_vla_buffer0[__leon_i1] = value0;  
    }  
    __leon_array_int32_t_t const a3 =  
        { .length = size0, .data = __leon_vla_buffer0 };  
}
```


Nested functions are extracted with their context.

```
def foo(x: Int) = {  
  def bar(y: Int) = x * y  
  bar(2)  
}
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```

is translated into

```
int32_t bar0(int32_t const* x0, int32_t const y6)  
{ return (*x0) * y6; }
```

```
int32_t foo0(int32_t const x0)  
{ return bar0(&x0, 2); }
```

```
def foo(x: Int) = {  
  def bar(y: Int) = {  
    def fun(z: Int) = x * y + z  
    fun(3)  
  }  
  bar(2)  
}
```

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  def bar(y: Int) = {  
    def fun(z: Int) = x * y + z  
    fun(3)  
  }  
  bar(2)  
}
```

is translated into

```
int32_t fun0(int32_t const* x0, int32_t const* y6, int32_t const z9)  
{ return (*x0) * (*y6) + z9; }
```

```
int32_t bar0(int32_t const* x0, int32_t const y6)  
{ return fun0(x0, (&y6), 3); }
```

```
int32_t foo0(int32_t const x0)  
{ return bar0(&x0, 2); }
```

IF CONSTRUCT

Unlike in Scala, **if** statements don't **return** a value. Hence

```
def foo(x: Int) {  
  val b =  
    if (x >= 0) true else false  
}
```

is translated into

```
void foo0(int32_t const x0) {  
  bool b0; // no const here  
  if (x0 >= 0) { b0 = true; }  
  else { b0 = false; }  
}
```

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is translated into

```
void foo0(int32_t const x0) {  
  bool b0; // no const here  
  if (x0 >= 0) { b0 = true; }  
  else { b0 = false; }  
}
```

```
def foo(x: Int) =  
  if (x >= 0) true else false
```

is translated into

```
bool foo1(int32_t const x0) {  
  if (x0 >= 0) { return true; }  
  else { return false; }  
}
```

WHILE CONSTRUCT

```
def dummyAbs(a: Array[Int]) {  
  var i = 0;  
  while (i < a.length) {  
    a(i) = if (a(i) < 0) -a(i) else a(i)  
    i = i + 1  
  }  
}
```

WHILE CONSTRUCT

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  var i = 0;  
  while (i < a.length) {  
    a(i) = if (a(i) < 0) -a(i) else a(i)  
    i = i + 1  
  }  
}
```

is translated into

```
void dummyAbs0(__leon_array_int32_t_t const a0) {  
  int32_t i9 = 0;  
  while (i9 < a0.length) {  
    if (a0.data[i9] < 0) { a0.data[i9] = -a0.data[i9]; }  
    else { a0.data[i9] = a0.data[i9]; }  
    i9 = i9 + 1;  
  }  
}
```


- ▷ C standard is much more lax when it comes to execution order.
- ▷ Hence the translation has to do some kind of **normalisation** to ensure the same behaviour.
- ▷ This applies to function calls, operators, and blocks.

```
def test4(b: Boolean) = {  
  var i = 10;  
  var c = 0;  
  val f = b && !b // false  
  val t = b || !b // true  
  
  while ({ c = c + 1; t } &&  
        i > 0 ||  
        { c = c * 2; f }) {  
    i = i - 1  
  }  
  
  i == 0 && c == 22  
}
```

SUBEXPRESSIONS EXECUTION ORDER – BIS

```
def test4(b: Boolean) = {  
  var i = 10;  
  var c = 0;  
  val f = b && !b // false  
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  while ({ c = c + 1; t } &&  
    i > 0 ||  
    { c = c * 2; f }) {  
    i = i - 1  
  }  
  
  i == 0 && c == 22  
}
```

```
bool test40(bool const b0) {  
  int32_t i10 = 10;  
  int32_t c2 = 0;  
  bool const f26 = b0 && (!b0);  
  bool const t8 = b0 || (!b0);  
  
  while (true) {  
    c2 = c2 + 1;  
    if (t8 && i10 > 0) { i10 = i10 - 1; }  
    else {  
      c2 = c2 * 2;  
      if (f26) { i10 = i10 - 1; }  
      else { break; }  
    }  
  }  
  
  return i10 == 0 && c2 == 22;  
}
```

RECAP'

- ▷ **BASIC TYPES**
- ▷ **TUPLES & STACK ALLOCATED ARRAYS**
- ▷ **NESTED FUNCTIONS**
- ▷ **IF & WHILE CONSTRUCTS**
- ▷ **SUBEXPRESSIONS ORDERS**

WHAT'S NEXT

- Support for non-recursive data type (**case class**).
- A case study about image processing.

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-
- ▷ Support for floating point types (**float**, **double**).
 - ▷ Support for **BigInt**, **Real**, e.g. using GMP.
 - ▷ Support for heap allocated arrays, e.g. using **malloc**.

QUESTIONS?