Classifier Systems

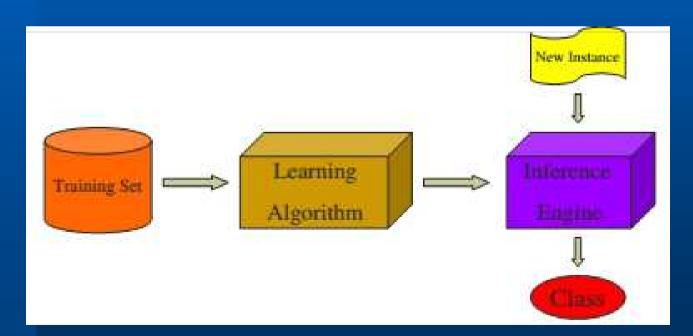
Introduction

- Learning
 - ◆ "A computer program is said to learn from experience E with respect to some class of tasks T and performan ce measure P, if its performance at tasks in T, as mea sured by P, improves with experience E"

- A checkers learning problem
 - ♦ Task T: playing checkers
 - Performance measure P: percent of games won against opponents
 - ◆ Training experience E: playing practice games against itself
- A handwriting recognition learning problem
 - Task T: recognizing and classifying handwritten words using images
 - ◆ Performance measure P: percent of words correctly identified
 - ◆ Training experience E: a database of handwritten words with given classifications

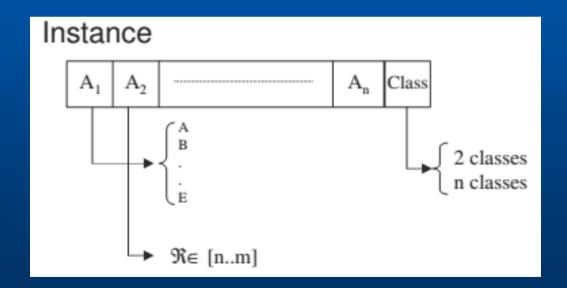
- A robot driving learning problem
 - ◆ Task T: driving on public four-lane highways using vision sensors
 - ◆ Performance measure P: average distance traveled before an error (as judged by human overseer)
 - ◆ Training experience E: a sequence of images and steering commands recorded while observing a human driver

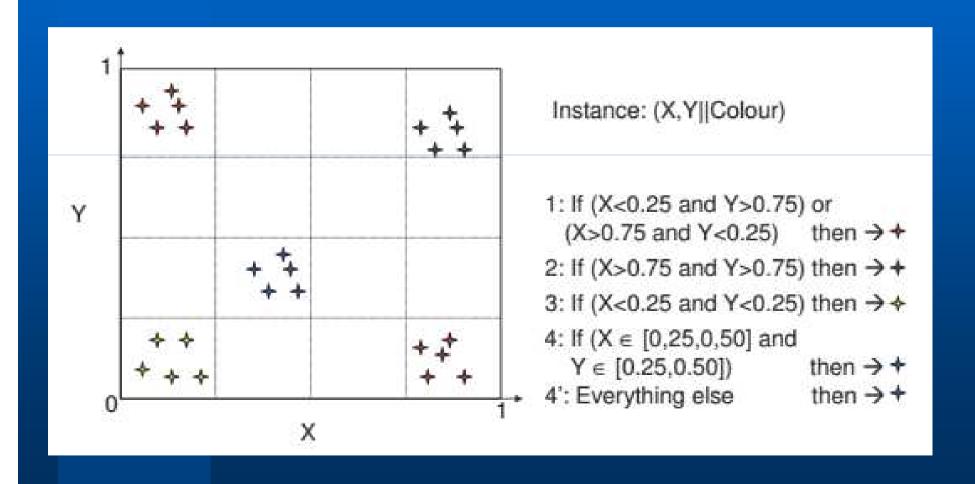
 Classification task: Learning how to label corr ectly new instances from a domain based on a set of previously labeled instances



- Goal of classification is to learn how to predict the class of an instance from its attributes
- Instance: individual, independent example of the domain that has to be learned
- Instances have regular structure:
 - ◆ Fixed number of attributes: features that characterize an instance
 - ♦ A class: a label belonging to a finite and discrete domain

- Attributes can be of diverse type
 - ♦ Nominal: discrete and finite variable
 - Integer, Continuous





Learning Paradigms and General Aspects of Learning

- Different Forms of Learning:
 - ◆ Learning agent receives feedback with respect to its actions (e.g. from a teacher)
 - ◆ Supervised Learning: feedback is received with respect to all possible actions of the agent
 - ♦ Unsupervised Learning: Learning when there is no hint at all about the correct action

Learning Paradigms and General Aspects of Learning

Inductive Learning

- ♦ It is a form of supervised learning that centers on learning a function based on sets of training examples.
- ♦ Popular inductive learning techniques include decision trees, neural networks, nearest neighbor approaches, discriminant analysis and regression.
- The performance of an inductive learning system is usually evaluated using n-fold cross-validation.

Classifier Systems

- According to Goldberg, a <u>classifier system</u> is "a machine learning system that learns syntactically simple string rules to guide its performance in an arbitrary environment".
- First implemented of a system called CS1 by Holland/Reitman(1978).
- Learning Classifier Systems (LCS) are one of the major families of techniques that apply evolutionary computation to machine learning tasks
- Machine learning: How to construct programs that automatically learn from experience
- LCS are almost as ancient as GAs, Holland made one of the first proposals

Classifier Systems

• Example of classifier rules:

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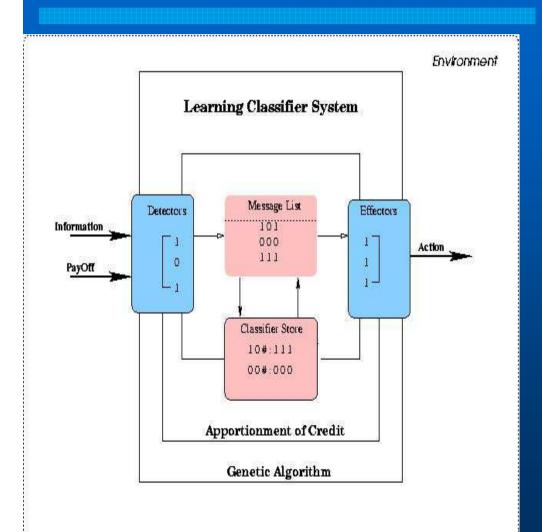
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• Fitness of a classifier is defined by its surrounding environments that pays payoff to classifiers and extract fees from classifiers.

Classifier System



- Learn simple string rules in an arbitrary environment
- A *classifier* is a simple string rule
- Components
 - Rule and Message System
 - Apportionment of credit system
 - ◆ Genetic Algorithm

Knowledge representations

- All the initial approaches were rule-based
- In recent years several knowledge representations have been used in the LCS
- For example:
 - ♦ Decision Trees
 - Neural Network

Generating better rules

- Use a Genetic Algorithm (GA) to generate new rules
- A classifier's strength (S) is used as its fitness
- Similar to the simple genetic algorithm
 - ◆ Entire population is <u>not</u> replaced at the next generation
- Crowding to maintain diversity
- Mutation over a ternary alphabet {1, 0, #}
- Selection is performed using roulette-wheel selection

Paradigms of LCS

- The Michigan approach
 - ♦ Holland & Reitman, 78
- The Pittsburgh approach
 - ♦ Smith, 80
- The Iterative Rule Learning approach
 - ♦ Venturini, 93

The Pittsburgh approach

- This approach is the closest one to the standard concept of GA
- Each individual is a complete solution to the classification problem
- Traditionally this means that each individual is a variable-length set of rules
- GABIL [De Jong & Spears, 93] is a well known representative of this approach

The Pittsburgh approach

- More than one rule could be used to classify a given instance
- Match process: deciding which rule is used in these cases
- An usual approach is that individuals are interpret ed as a decision list [Rivest, 87]: an ordered rule set



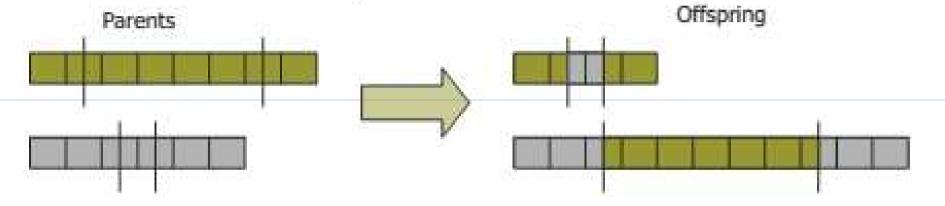
Instance 1 matches rules 2, 3 and 7 → Rule 2 will be used Instance 2 matches rules 1 and 8 → Rule 1 will be used Instance 3 matches rule 8 → Rule 8 will be used Instance 4 matches no rules → Instance 4 will not be classified

Pittburgh-style Systems

- Pittsburgh approach systems usually have to cope with variable length chromosomes.
- Popular Pittsburgh-style systems include:
 - Smith's LS-1-system (learns symbolic rule-sets)
 - Janikov's GIL system
 - ♦ Giordana&Saita's REGAL (learns symbolic concept descriptions)
 - ◆ DELVAUX (learns numerical Bayesian rule-sets)

The Pittsburgh approach

Crossover operator



 Mutation operator: classic GA mutation of bit inversion

Paradigms of LCS

- In the other two approaches each individual is a rule
- What happens usually in the evolutionary process of a GA?
 - ♦ All individuals converge towards a single solution
- Our solution is a set of rules. Therefore we need some mechanism to guarantee that we generate all of them.
- Each approach uses a different method for that

The Michigan approach

- Each individual (classifier) is a single rule
- The whole population cooperates to solve the classification problem
- A reinforcement learning system is used to identify the good rules
- A GA is used to explore the search space for more r ules
- XCS [Wilson, 95] is the most well-known Michigan LCS

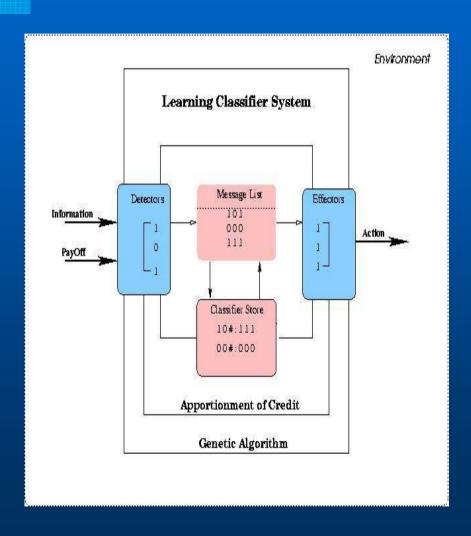
The Michigan approach

- What is Reinforcement Learning?
 - * "a way of programming agents by reward and punishment without needing to specify how the task is to be achieved".
 - ♦ Rules will be evaluated example by example, receiving a positive/negative reward
 - ◆ Rule fitness will be updated incrementally with this reward
 - ♦ After enough trials, good rules should have high fitness

The Iterative Rule Learning approach

- Each individual is a single rule
- Individuals compete as in a standard GA
 - ♦ A single GA run generates one rule
- Instances already covered by previous rules are removed from the training set of the next iteration
- The GA is run iteratively to learn all rules that solve the problem
- Also known as separate-and-conquer

- A *classifier* is a simple string rule
- Classifier System
 - rule-message system,
 - apportionment of credit mechanism
 - ♦ GA
- Advantages of CS
 - rules are simple
 - use fixed length representation
 - parallel activation



- The Learning Classifier Systems means EC techniques applied to Machine Learning
- Description of the three main paradigms
 - ◆ Pittsburgh
 - Michigan
 - ♦ Iterative rule learning

- Description of several knowledge representations
 - ◆ Rule based
 - Nominal attributes
 - Continuous attributes
 - Decision trees

- Applications to real-world domains
 - ♦ Medical
 - ◆ Industrial
 - Military
- Recent trends
 - ♦ Explore better
 - Model the problem better
 - ◆ Understand better