

Algorithms and Data Structures

Data Types

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Content of this Lecture

- Example
- Abstract Data Types
- Realization in Java

Problem

- Suppose you are in the centre of Hamburg and are looking for the next (i.e., closest) laptop repair shop
- Fortunately, your mobile knows your position and has a list of laptop repair shops in Hamburg
- How does your mobile find the closest shop?

Classical Post-Box Problem

- Suppose a city with n boxes located at arbitrary positions
- You wake up in the middle of the city with a letter in your hand; the letter should be thrown in the closest post-box
- How do you find the closest post-box?
 - You have a list with locations of all post boxes
- Looking at a map is not the answer!
- Devise an algorithm

```
S: set_of_coordinates;
c: coordinate (x,y)
...
```



Simple Solution

How much work?

```
Input
   S: set_of_coordinates;
   c: coordinate (x,y);  # your loc
   t: coordinate;  # closest
   m: real := MAXREAL;  # smal. dist
   for each c'∈S do
    if m > distance(c,c') then
        m := distance(c,c');
        t := c';
   end if;
end for;
return t;
```

Simple Solution

```
Input
   S: set_of_coordinates;
   c: coordinate (x,y);  # your loc.
t: coordinate;  # closest box
m: real := MAXREAL;  # smal. dist
for each c'∈S do
   if m > distance(c,c') then
        m := distance(c,c');
        t := c';
   end if;
end for;
return t;
```

- How much work?
- Clearly, we can save the second call to "distance"
- Thus, we need to compute |S| distances, make |S| comparisons, and perform at most 2*|S| assignments

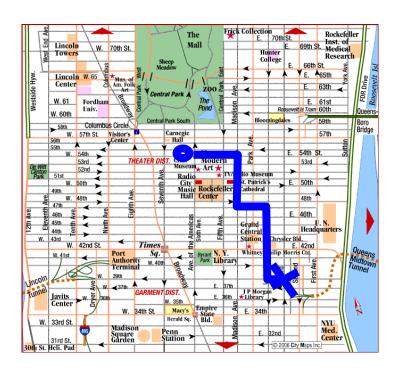
Simple Solution



- How much work?
- Clearly, we can save the second call to "distance"
- Thus, we need to compute |S| distances, make |S| comparisons, and perform at most 2*|S| assignments
- Euclidian distance
 - 6 arithmetic ops per distance

$$dist((x_1, y_1), (x_2, y_2)) = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$$

Not the only Option



- How much work?
- Clearly, we can save the second call to "distance"
- Thus, we need to compute |S| distances, make |S| comparisons, and perform at most 2*|S| assignments
- Manhattan distance
 - 5 operations, and different ones

$$dist((x_1, y_1), (x_2, y_2)) = |x_1 - x_2| + |y_1 - y_2|$$

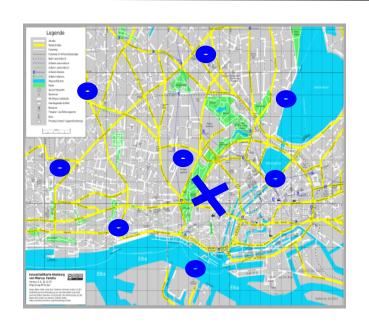
Data Structure Point of View

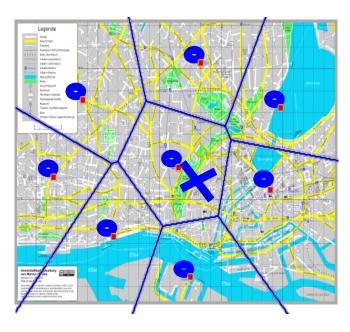
```
input
   S: set_of_coordinates;
   c: coordinate (x,y);
t: coordinate;
m: real := MAXREAL;
For each c'∈S do
   if m > dist(c,c') then
       m := dist(c,c');
       t := c';
   end if;
end for;
return t;
```

Data structures

- We need a list of coordinates
- The algorithm must iterate over the elements of this list
- A linked list would suffice
- Now assume we need to perform searches very often
 - Can we represent S in another way (S'), such that searching requires less work?
 - Note: Time for computing S' from S may be ignored
 - Performed before searching starts
 - Assuming that S does not change

Voronoi Diagrams





- Compute for every point s∈S its Voronoi area, i.e., the area in which all points have s as nearest point from S
- This is not easy, but can be achieved in O(|S|*log(|S|) time
- Nearest-neighbor search using Voronoi diagrams is O(log(|S|))
- Finding a proper data structure does pay off

More Abstract

- We want a piece of software T that
 - can store a list of coordinates
 - can compute the nearest point to a given point c
- Thus, T must support (at least) two operations
 - T.init (S: list_of_coordinate)
 - T.nearestNeighbor (c: coordinate)
 - T apparently uses another data type: "coordinate"
- Such combinations of object sets and operations on these sets are called a data type
- If we abstract from the implementation and only look at the sets and operations, we call this an abstract data type

Content of this Lecture

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Abstract Data Types (ADT)

- It ADT defines a set of operations over a set of objects of a certain (more basic) type
 - Or over multiple sets of objects of different or same types
- The set of operations (and types) is an ADT's signature
- An ADT is independent of a implementation
 - Different data structures to represent the objects
 - Different algorithms to implement the operations
 - An ADT is independent of any programming language
- Encapsulation: Objects are accessed only through the ops
- An implementation of a ADT is called a concrete (or physical) data type

Example

```
type points
import
  coordinate;
operators
  add:    points x coordinate → points;
  neighbor: points x coordinate → coordinate;
```

- ADT that we could use for our app for searching shops
- We only need two operations
 - A way to insert shops (with their coordinates)
 - A way to get the nearest shop with respect to a given coordinate
- Not the only way ...

Modeling More Details

```
type shop
import
  coordinate;
  string;
operators
  getName: shop → string;
  getCoor: shop → coordinate;
```

- An ADT defines what is necessary
 - We assume primitive data types to be given (string)
- Design of ADT is a modeling decision
 - Shop owner? Laptop models being repaired? Opening hours?
 - Depends on necessity, design choices, understandability, extensibility, personal preferences, existing ADTs, ...

Reusing Existing ADTs

- For implementing points (or shops), it would be helpful to import something that can hold a set of coordinates
- We need a list an ADT in itself
 - A parameterized ADT— a list of elements of an arbitrary ADT T
 - For our ADT points, T will be coordinate

```
type list( T)
import
  integer, bool;
operators
  isEmpty: list \rightarrow bool;
  add: list x T \rightarrow list;
  delete: list x T \rightarrow list;
  contains: list x T \rightarrow bool;
  length: list \rightarrow integer;
```

Axioms: What we Know about an ADT

- We expect operations on lists to have a certain semantic
 - Adding an element increases length by one
 - If we assume bag semantics
 - Deleting an element that doesn't exist creates an error
 - If a list is empty, its length is 0

– ...

```
type list( T)
import
  integer, bool;
operators
  isEmpty: list \rightarrow bool;
  add: list x T \rightarrow list;
  contains: list x T \rightarrow bool;
  delete: list x T \rightarrow list;
  length: list \rightarrow integer;
  axioms: \forall 1: list, \forall t: T
  length( add(1, t)) = length( 1) + 1;
  length( 1)=0 \Rightarrow isEmpty(1);
  ...
```

List versus Points

```
type points
import
  coordinate, bool, list( coordinates);
Operators
  contains: points x coordinate → bool;
    # Implement as list.contains
  add:    points x coordinate → points;
    # Implement as list.add
  neighbor: points x coordinate → coordinate;
    # Not implemented in list!
axioms
  neighbor(p,c) = {x | contains(p,x) ∧ ∀x':contains(p, x') => distance(x,c) ≤ distance(x',c);
```

- What's wrong?
 - What happens if multiple x have the same distance to c?

List versus Points

Lists, Stacks, Queues

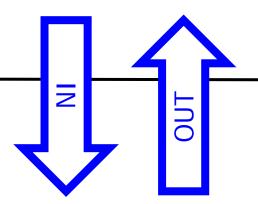
- We looked at a data type (points, shops) which essentially is a list with one special operation: nearestNeighboor
 - Canonical list operations: insert, search, delete, update, length
- There are many ways to implement the general ADT list
 - Array, linked lists, double-linked lists, trees, ...
- Two types of lists are of exceptional importance in computer science: Stacks and Queues
 - Both support mostly two operations
 - These suffice for surprisingly many problems and applications
 - Can be implemented very efficiently

Queues



- Operations: enqueue, dequeue
- Special semantic: First in, first out (FIFO)
- Breadth-first traversal, shortest paths, BucketSort, ...

Stacks





- Operations: push, pop
- Special semantic: Last in, first out (LIFO)
- Call stacks, backtracking, "Kellerautomaten", ...

As Abstract Data Types

```
type stack( T)
import
  bool;
operators
  isEmpty: stack → bool;
  push: stack x T → stack;
  pop: stack → stack;
  top: stack → T;
```

```
type queue( T)
import
  bool;
operators
  isEmpty: queue → bool;
  enqueue: queue x T → queue;
  dequeue: queue → queue;
  head: queue → T;
```

Where's the difference?

Signature does not Suffice

```
type a( T)
import
  bool;
operators
  isEmpty: a → bool;
  add: a x T → a;
  remove: a → a;
  give: a → T;
```

```
type a( T)
import
  bool;
operators
  isEmpty: a → bool;
  add: a x T → a;
  remove: a → a;
  give: a → T;
```

- Where's the difference?
- From the signature alone, there is no difference
- Yet we expect a different behavior

Defining the Difference

```
type stack( T)
import
  bool;
operators
  isEmpty: stack \rightarrow bool;
  push: stack x T \rightarrow stack;
  pop: stack \rightarrow stack;
  top: stack \rightarrow T;
axioms \forall q:stack, \forall t:T
  top( push( s, t)) = t;
  pop( push( s, t)) = s;
```

```
Long version:
```

```
push(s,t) o top(s)=t' => t=t'
push(s,t) o pop(s)=s' => s=s'
```

```
type queue( T)
import
  bool;
operators
  is Empty: queue \rightarrow bool;
  enqueue: queue x T \rightarrow queue;
  dequeue: queue \rightarrow queue;
  head:
            queue \rightarrow T;
axioms ∀ q:queue, ∀ t:T
  head( enqueue(q, t)) =
    if isEmpty(q): t
    else head(q);
  dequeue( enqueue( q, t)) =
    if isEmpty(q): q
    else enqueue( dequeue(q), t);
```

Detour

```
type queue( T)
...
  dequeue( enqueue( q, t)) =
    if isEmpty( q): q
    else enqueue( dequeue(q), t);
```

```
d( e( <3,2>, 5)) = e( d( <3,2>), 5) =
        e( d( e( <3>, 2)), 5) =
        e( e( d( <3>), 2), 5) =
        e( e( d( e(<>), 3), 2), 5) =
        e( e( <<>, 2), 5) =
        e( e( <>, 5)
```

We Stop Here

- There are various ways to formally specify the behavior of operations of an ADT
- In this lecture, we only look at signature
 - No semantics (except parameters of operations)
 - Supported by most programming languages (e.g. Java)
- Algebraic specification
 - Define an algebra over the object sets of the ADT
 - Includes axioms defining the semantics of operations
 - Axioms are essential to proof aspects of a system's behavior
 - Supported by few programming languages
 - Ideally, one only specifies and never programs
- See lecture on "Modellierung und Spezifikation"

Content of this Lecture

- Data Structures Again
- Abstract Data Types
- Realization in Java

ADTs in Java

Recall

- An ADT summarizes the essential operations on a set of objects
- An ADT is independent of a realization/implementation
- Any implementation of a ADT is called a concrete data type
- Realization in Java?
- Interfaces
 - Only exhibit the essential operations on a class of objects
 - Can have different implementations
 - Can be implemented by a concrete class

Remarks

- Java does not support axioms on interfaces
 - Some other languages do, e.g. contracts in Eiffel
- Java adds functionality we mostly ignore, such as
 - Inheritance (syntactic sugar), different levels of visibility (public, protected, private, ...), overloading, ...
- Historically, ADTs are a predecessor of classes in programming languages
- ADTs can be realized at least in all OO languages
 - Critical: encapsulation you must not see anything of an object / do anything with an object that is not represented in its (public) interface

Summary

- ADT's specify the possible operations on a data structure
- ADT's are free of implementation details
- We often discuss pros/contras of different ways to implement a given ADT
- (Formal) ADTs can be used for much more
 - Proving properties of a data type
 - Proving that a concrete data type implements a ADT
 - Proving that an implementation does not hurt axioms
 - Program verification