

Manuel Boldrer

Postdoctoral Scholar

Address: Prof. Henketstraat, 25

2628KK Delft, Netherlands

✉ manuel.boldrer@gmail.com

Born in Trento (Italy) on 29.07.1992

CV Updated in November 2022

Work Experiences

- May '22 - Present **Postdoctoral Scholar**, *Cognitive Robotics Department, Delft University of Technology, Netherlands.*
- **Supervisor:** Laura Ferranti
 - **Title:** Secure and Private Robot Control
- Oct '18-Sep '20 **Teaching support activity**, *held at University of Trento, Italy, (80 hours).*
- **Department:** Information Engineering and Computer Science (DISI)
 - **Course:** Systems Theory
- Jun-Nov 2018 **Scholarship**, *held at University of Trento, Italy.*
- **Title:** Distributed estimation and control algorithms for a team of service robots

Education

- Nov '18-May '22 **PhD Student in Mechatronics, 34th cycle**, *University of Trento, Italy.*
- **Supervisors:** Daniele Fontanelli, Luigi Palopoli
 - **Title:** Distributed control algorithms for a team of service robots
 - **PhD Committee:** Lucia Pallottino, Dimos Dimarogonas, Andrea Del Prete.
 - **Research Interests:** Multi-agent systems, Distributed control, Robotics.
- Sep '21-Feb '22 **Visiting Scholar**, *University of California, Riverside, United States.*
- **Supervisor:** Fabio Pasqualetti
 - **Research Activity:** Networked system control, Reinforcement learning
- Sep '15-Mar '18 **Master's degree in Mechatronics Engineering**, *University of Trento, Italy.*
- **Curriculum in Electronics and Robotics**
 - **Grade:** magna cum laude
 - **Master thesis:** "Control of a Synchrotron with LMI-based Techniques".
 - *Advisor:* Luca Zaccarian
- Sep '12-Jul '15 **Bachelor's degree in Industrial Engineering**, *University of Trento, Italy.*
- **Methodological Curriculum**
 - **Bachelor thesis:** "Study of Lateral Vibrations in a Beam".
 - *Advisor:* Daniele Bortoluzzi
- Sep '06-Jun '12 **Secondary Education Diploma**, *Liceo Scientifico "L. Da Vinci", Trento, Italy.*

Publications

Journal Articles

- [J6] **M. Boldrer, L. Lyons, L. Palopoli, D. Fontanelli, L. Ferranti**, *Time-inverted Kuramoto Model Meets Lissajous Curves: Multi-Robot Persistent Monitoring and Target Detection*, in IEEE Robotics and Automation Letters, In press, Nov. 2022.
- [J5] **M. Boldrer, L. Palopoli, D. Fontanelli**, *A Unified Lloyd-based Framework for Multi-Agent Collective Behaviours*, in Elsevier, Robotics and Autonomous Systems, Jul. 2022.
- [J4] **M. Boldrer, F. Pasqualetti, L. Palopoli, D. Fontanelli**, *Multi-Agent Persistent Monitoring via Time-Inverted Kuramoto Dynamics*, in IEEE, Control Systems Letters, May 2022.
- [J3] **M. Boldrer, A. Antonucci, P. Bevilacqua, L. Palopoli, D. Fontanelli**, *Multi-Agent Navigation in Human-Shared Environments: a Safe and Socially-Aware Approach*, in Elsevier, Robotics and Autonomous Systems, Dec. 2021.
- [J2] **M. Boldrer, P. Bevilacqua, L. Palopoli, D. Fontanelli**, *Graph Connectivity Control of a Mobile Robot Network with Mixed Dynamic Multi-Tasks*, in IEEE Robotics and Automation Letters, Feb. 2021.
- [J1] **M. Boldrer, M. Andreetto, S. Divan, L. Palopoli, D. Fontanelli**, *Socially-aware Reactive Obstacle Avoidance Strategy based on Limit Cycle*, in IEEE Robotics and Automation Letters, Feb. 2020.

Refereed Conference Publications

- [C5] **M. Boldrer, F. Riz, F. Pasqualetti, L. Palopoli, D. Fontanelli**, *Time-Inverted Kuramoto Dynamics for κ -Clustered Circle Coverage*, In IEEE Conf. on Decision and Control (CDC), Dec. 2021.
- [C4] **M. Boldrer, D. Fontanelli, A. Antonucci, L. Palopoli**, *A Novel Framework for Multi-Agent Navigation in Human-Shared Environments*, In Italian Institute of Robotics and Intelligent Machines Conference (I-RIM), Oct. 2021, (***Best Student Paper Finalist***).
- [C3] **M. Boldrer, L. Palopoli, D. Fontanelli**, *Lloyd-based Approach for Robots Navigation in Human-shared Environments*, In IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Oct. 2020.
- [C2] **M. Boldrer, L. Palopoli, D. Fontanelli**, *Socially-aware Multi-agent Velocity Obstacle based Navigation for Nonholonomic Vehicles*, In IEEE Computer Software and Applications Conference (COMPSAC), Jul. 2020.
- [C1] **M. Boldrer, D. Fontanelli, L. Palopoli**, *Coverage control and distributed consensus-based estimation for mobile sensing networks in complex environments*, In IEEE Conf. on Decision and Control (CDC), Dec. 2019.

Language Skills

Italian	Mother tongue
English	Fluent

Computer Skills

Languages	C++, L ^A T _E X, MatLab, Phyton
Other Software	Ansys, Maple, Maplesim, Mathematica, NI LabVIEW, Blender, Microsoft Office Package

Links

Linkedin.com	Manuel Boldrer - Professional profile.
Google Scholar	Google Scholar Profile. Website Personal website