

# Numerical Optimization

## Solution to exercise sheet

review on 05.02.2024 during the exercise class

### 1. (Projected Subgradient Method)

For nonsmooth optimization we are forced to generalize the concept of classical derivatives of a function  $f$  at a point  $x_0$ . For this, we have introduced for convex functions  $f$  defined on a convex set the convex subdifferential  $\partial f$ , compare Definition 5.3.3.

a) Calculate the following sub-differentials.

i)  $\partial f(0)$ , for  $f : \mathbb{R} \rightarrow \mathbb{R}$ ,  $f(x) := \begin{cases} x^2, & x < 0, \\ x, & x \geq 0. \end{cases}$

ii)  $\partial f(0)$ , for  $f : \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $f(x) := \|x\|_2 = \sqrt{x^T x}$ .

b) The Projected Subgradient Method is a method for non-smooth optimization, where (for example) the cost function  $f$  is not differentiable in the classical sense. In contrast to the general gradient method, the Projected Subgradient Method uses on the one hand an element of the convex sub-differential instead of its classical gradient and on the other hand a projection of  $x^{(k+1)}$  onto the feasible domain  $\mathcal{F}$  (compare Algorithm 5.3.1). However, the choice of a reasonable step-size is not that trivial due to the missing smoothness of  $f$ .

Consider now the unconstrained optimization problem

$$\min_{x \in \mathbb{R}} f(x), \tag{1}$$

for  $f(x) = |x|$  with its solution  $x^* = 0$ . Use the Projected Subgradient Method with  $P_{\mathcal{F}} = id$  (because of  $\mathcal{F} = \mathbb{R}^n$ ) for solving the optimization problem (1).

Choose the step sizes

i)  $\sigma^{(k)} = \frac{1}{k+1}$ , as well as

ii)  $\sigma^{(k)} = \frac{f(x^{(k)}) - f(x^*)}{|s^{(k)}|}$ ,

and the initial vector  $x^{(0)} = 2$  for computing  $x^{(1)}, \dots, x^{(5)}$  (until  $s^{(k)} = 0$ ).

*Hint:* You can use without a proof that the convex sub-differential of  $f$  in  $x_0 = 0$  is given by  $\partial f(0) = [-1, 1]$ .

c) Consider the optimization problem (1) with  $f(x) = (|x| + 1)^2$  and its solution  $x^* = 0$ . Prove that for the Projected Subgradient Method with step size  $\sigma^{(k)} = (f(x^{(k)}) - f(x^*)) / |s^{(k)}|$ , it holds

$$|x^{(k+1)} - x^*| \leq \frac{1}{2} |x^{(k)} - x^*|, \quad k = 1, 2, \dots$$

(4 + 4 + 6 = 14 Points)

*Solution:*

a) i) With  $x_0 = 0, f(x_0) = 0$ , the subgradient condition becomes

$$\begin{aligned} f(y) &\geq f(x_0) + s^\top (y - x_0), & \forall y \in \mathcal{F} = \mathbb{R}, \\ \iff f(y) &\geq sy, & \forall y \in \mathbb{R}. \end{aligned}$$

We split the condition in

$$\begin{aligned} y^2 &\geq sy, & \forall y \in \{y < 0\}, \\ \iff y &\leq s, & \forall y \in \{y < 0\}, \end{aligned}$$

which gives  $s \geq 0$ . On the other hand we have

$$\begin{aligned} y &\geq sy, & \forall y \in \{y \geq 0\} \\ \iff 1 &\geq s, & \forall y \in \{y \geq 0\}, \end{aligned}$$

which gives  $s \leq 1$ . Together, we have

$$\partial f(0) = [0, 1].$$

ii) With  $x_0 = 0, f(x_0) = 0$ , the subgradient condition becomes

$$\begin{aligned} f(y) &\geq f(x_0) + s^\top (y - x_0), & \forall y \in \mathcal{F} = \mathbb{R}^n, \\ \iff \sqrt{y^\top y} &\geq s^\top y, & \forall y \in \mathbb{R}^n. \end{aligned}$$

This condition must also hold for the special case of  $y = s$ :

$$\begin{aligned} \|s\|_2 &= \sqrt{s^\top s} \geq s^\top s = \|s\|_2^2, \\ \iff 1 &\geq \|s\|_2. \end{aligned}$$

And indeed, with  $1 \geq \|s\|_2$  and with Cauchy-Schwarz, we have

$$\sqrt{y^\top y} = \|y\|_2 = \frac{\|y\|_2 \|s\|_2}{\|s\|_2} \geq \frac{s^\top y}{\|s\|_2} \geq s^\top y, \quad \forall y \in \mathbb{R}^n.$$

Therefore it follows

$$\partial f(0) = \{s \in \mathbb{R}^n : \|s\|_2 \leq 1\}.$$

b) i) The sub-differential of  $f$  is given by

$$\partial f(x) = \begin{cases} \{-1\}, & x < 0, \\ [-1, 1], & x = 0, \\ \{1\}, & x > 0, \end{cases} \quad (2)$$

and therefore for descent directions  $d^{(k)} = \frac{-s^{(k)}}{\|s^{(k)}\|_2}$ , for  $x \neq 0$ , it is

$$d^{(k)} = \begin{cases} 1, & x < 0, \\ -1, & x > 0. \end{cases} \quad (3)$$

With these observations it follows for the Projected Subgradient Method for  $k = 0, 1, \dots, 5$  and  $x^{(0)} = 2$ :

$$\rightarrow s^{(0)} = -1, d^{(0)} = -1, \sigma^{(0)} = 1, x^{(1)} = 1;$$

$$\rightarrow s^{(1)} = 0, d^{(0)} = -1, \sigma^{(1)} = \frac{1}{2}, x^{(2)} = \frac{1}{2};$$

...

and finally we get the iteration sequence

$$x^{(0)} = 2, x^{(1)} = 1, x^{(2)} = \frac{1}{2}, x^{(3)} = \frac{1}{6}, x^{(4)} = -\frac{1}{12}, x^{(5)} = \frac{7}{60}.$$

ii) Again, we have the sub-differential (2) and the descent directions (3), for the Projected Subgradient Method it follows for  $k = 0, 1 \dots 5$  and  $x^{(0)} = 2$ :

$$\rightarrow s^{(0)} = -1, d^{(0)} = -1, \sigma^{(0)} = 2, x^{(1)} = 0;$$

$$\rightarrow s^{(1)} = 0;$$

Therefore the problem described above converges after just one iteration with the suitable stepsize  $\sigma^{(k)} = \frac{f(x^{(k)}) - f(x^*)}{|s^{(k)}|}$ .

c) We define

$$g(x) := 2(|x| + 1) \operatorname{sign}(x) \in \partial f(x),$$

a function that assigns each point a possible subgradient of  $f$ . Now, we can compute  $d^{(k)}$ :

$$d^{(k)} = \frac{-g(x^{(k)})}{|g(x^{(k)})|} = \frac{-s^{(k)}}{|s^{(k)}|} = \frac{-2(|x^{(k)}| + 1) \operatorname{sign}(x^{(k)})}{2(|x^{(k)}| + 1)} = -\operatorname{sign}(x^{(k)}).$$

Next, we compute  $\sigma^{(k)}$ :

$$\begin{aligned} \sigma^{(k)} &= \frac{f(x^{(k)}) - f(x^*)}{|s^{(k)}|} = \frac{(|x^{(k)}| + 1)^2 - 1}{2(|x^{(k)}| + 1)} = \frac{|x^{(k)}|^2 + 2|x^{(k)}|}{2|x^{(k)}| + 2} \\ &= \frac{\frac{1}{2}|x^{(k)}|(2|x^{(k)}| + 2) + |x^{(k)}|}{2|x^{(k)}| + 2} = \frac{|x^{(k)}|}{2} + \frac{|x^{(k)}|}{2|x^{(k)}| + 2}. \end{aligned} \quad (4)$$

An iteration step is defined by

$$\begin{aligned} x^{(k+1)} &= x^{(k)} + \sigma^{(k)} d^{(k)} = x^{(k)} - \operatorname{sign}(x^{(k)}) \left( \frac{|x^{(k)}|}{2} + \frac{|x^{(k)}|}{2|x^{(k)}| + 2} \right) \\ &= x^{(k)} \underbrace{\left( 1 - \frac{1}{2} - \frac{1}{2|x^{(k)}| + 2} \right)}_{\leq \frac{1}{2}} \leq \frac{1}{2} x^{(k)}. \end{aligned} \quad (5)$$

Thereby it holds that  $|x^{(k+1)} - x^*| = |x^{(k+1)}| \leq \frac{1}{2} |x^{(k)}| = \frac{1}{2} |x^{(k)} - x^*|$ .

## 2. (Projected Subgradient Method)

- a) Apply the routine `projected_subgradient_method.m` to the Wolfe function

$$f^{\text{Wolfe}}(x, y) := \begin{cases} 5\sqrt{9x^2 + 16y^2}, & x \geq |y|, \\ 9x + 16|y|, & 0 < x < |y|, \\ 9x + 16|y| - x^9, & x \leq 0 \end{cases}$$

using different step sizes  $\sigma^{(k)} = n/(k+1)$ , e.g.  $n = 1, 2, 3$ . Plot the iteration path together with the solution  $x^* = (1, 0)^T$  and the contour lines of  $f^{\text{Wolfe}}$ .

- b) Write a MATLAB routine

$$\mathbf{x} = \text{Projection\_Parabel}(\mathbf{x}, \mathbf{a}, \mathbf{b}),$$

which performs a projection on the convex set

$$\mathcal{F} = \{(x, y)^T \in \mathbb{R}^2 : y \geq (x - a)^2 + b\},$$

where  $a, b \in \mathbb{R}$  are two parameters. Solve the constrained optimization problem

$$\min_{(x, y)^T \in \mathcal{F}} f^{\text{Wolfe}}(x, y)$$

for different parameter  $a$  and  $b$  by using the Projected Subgradient Method. Plot again the iteration path together with the set  $\mathcal{F}$  and the contour lines of  $f^{\text{Wolfe}}$ .

(6 + 6 = 12 Points)

*Solution:*

- a) The script could look like

```
clear, close all
clc

xmax = [-2, 6];
ymax = [-2, 4];

a = 0;
b = -0.5;

f = @(x) wolfe(x);
x0 = [5; 4];
sigma = @(k) 3/(k+1);
subgrad_f = @(x) Subgrad.Wolfe(x);
proj = @(x) x; %Exercise 2b
% proj = @(x) Projection.Parabel(x, a, b); %Exercise 2c
tol = 1e-2;
maxIt = 1000;
x_sol = [-1; 0];
outflag = 0;

[x, f_val, X, iter] = projected_subgradient_method(f, subgrad_f, proj, x0, ...
                                                    maxIt, sigma, tol, ...
                                                    outflag);
```

```

[XX, YY] = meshgrid(linspace(xmax(1),xmax(2),200), linspace(ymax(1),ymax(2),200));
ZZ = zeros(size(XX));
for i = 1:size(XX,1)
    for j = 1:size(XX,2)
        ZZ(i,j) = wolfe([XX(i,j); YY(i,j)]);
    end
end

figure();
[~,c] = contour(XX,YY,ZZ,150);
hold on;
nb = plot(XX(1,:), (XX(1,:) - a).^2 + b, 'linewidth',3, 'color',[0.8500,0.3250,0.0980]);
p = plot(X(1,:), X(2,:), '-*', 'linewidth',3,'color',[0, 0.4470, 0.7410]);
so = plot(x_sol(1), x_sol(2), 'ko','linewidth',2, MarkerSize=10);
sg = plot(X(1,end), X(2,end), 'rx','linewidth',2, MarkerSize=10);

xlim(xmax);
ylim(ymax);

tit = '\textbf{Iterations of the Projected Subgradient Method}';
xlab = '$x$';
ylab = '$y$';
leg = legend([c,nb,p,so,sg], '\, Wolfe-function', '\, convex set $\mathcal{F}$', ...
             '\, Subgradient Iterations', ...
             '\, sol $x^*$', '\, $x^{\{k\}}$');

title(tit, 'Interpreter','latex')
xlabel(xlab,'Interpreter','latex')
ylabel(ylab,'Interpreter','latex')
set(leg, 'Interpreter','latex','Location','north','FontSize',20);

set(gca,'TickLabelInterpreter', 'latex', 'FontSize',20)
set(gcf,'units','normalized','outerposition',[0 0.05 1 0.9]); % Maximize figure window

% wolfe-function
function fx = wolfe(x)
    if x(1) >= abs(x(2))
        fx = 5*sqrt(9*x(1)^2 + 16*x(2)^2);
    elseif x(1) <= 0
        fx = 9*x(1) + 16*abs(x(2)) - x(1)^9;
    else
        fx = 9*x(1) + 16*abs(x(2));
    end
end
end

```

b) The function `Projection_Parabel.m` could look like

```

function [x] = Projection_Parabel(x, a, b)

if (x(1) - a)^2 + b <= x(2)
    return
end
p = zeros(4,1);
p(1) = -2;
p(2) = 6*a;
p(3) = 2*x(2) - 1 - 2*b - 6*a^3;
p(4) = x(1) + 2*a*b - 2*x(2)*a + 2*a^3;

r = roots(p);
r = r(imag(r)==0);

```

```
yr = (r - a).^2 + b;  
  
if length(r) ~= 1  
    error('something went wrong');  
end  
  
x = [r; yr];  
  
end
```