

Manufactured Solution for the Compressible Navier–Stokes Equations with Large Eddy Simulation models using automatic differentiation

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Abstract

In this document, we describe the equations used for the generation of the source terms for the Navier-Stokes with Large Eddy Simulation models. We will use automatic differentiation for the source term derivation. These equations and source terms are implemented as `ad_cns_3d_les` in MASA.

1 Mathematical Model

The conservation of mass, momentum, and total energy for the Favre-filtered compressible viscous fluid may be written as:

$$\frac{\partial \bar{\rho}}{\partial t} + \frac{\partial}{\partial x_j} (\bar{\rho} \tilde{u}_j) = 0, \quad (1)$$

$$\frac{\partial \bar{\rho} \tilde{u}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{\rho} \tilde{u}_i \tilde{u}_j + \bar{p} \delta_{ij} - \tilde{\sigma}_{ji} - \tau_{ji}) = 0, \quad (2)$$

$$\frac{\partial \bar{\rho} \tilde{E}}{\partial t} + \frac{\partial}{\partial x_j} \left((\bar{\rho} \tilde{E} + \bar{p}) \tilde{u}_j + \tilde{q}_j + \gamma c_v \mathcal{Q}_j - \tilde{\sigma}_{ij} \tilde{u}_i - \mathcal{J} \right) = 0. \quad (3)$$

The resolved variables are denoted by an overbar

$$\bar{f} = \int_D f(\mathbf{x}') G(\mathbf{x}, \mathbf{x}'; \bar{\Delta}) d\mathbf{x}' \quad (4)$$

where D is the domain, G is the filter, $\bar{\Delta}$ is the filter width. For compressible flows, we use Favre-filtering, where the variable is $\tilde{f} = \frac{\bar{\rho} f}{\bar{\rho}}$. Equations (1)–(3) are known as Favre-filtered Navier–Stokes equations and, ρ is the density, $\mathbf{u} = (u, v, w)$ is the velocity in x , y or z -direction, respectively, and p is the pressure. For a calorically perfect gas, these equations are closed with two auxiliary relations for energy:

$$E = e + \frac{u_i u_i}{2}, \quad \text{and} \quad e = \frac{1}{\gamma - 1} RT, \quad (5)$$

and with the ideal gas equation of state:

$$p = \rho RT. \quad (6)$$

The diffusive fluxes

$$\tilde{\sigma}_{ij} = 2\tilde{\mu} \tilde{S}_{ij} - \frac{2}{3} \tilde{\mu} \delta_{ij} \tilde{S}_{kk}, \quad (7)$$

$$\tilde{q}_j = -\tilde{k} \frac{\partial \tilde{T}}{\partial x_j}, \quad (8)$$

where $\tilde{S}_{ij} = \frac{1}{2} \left(\frac{\partial \tilde{u}_i}{\partial x_j} + \frac{\partial \tilde{u}_j}{\partial x_i} \right)$ is the strain rate tensor, $\tilde{\mu}$ and \tilde{k} are the viscosity and thermal conductivity for the filtered temperature \tilde{T} .

The sub-filter terms for the SFS stresses, SFS heat flux, and SFS turbulent diffusion, are

$$\tau_{ij} = \bar{\rho} (\widetilde{u_i u_j} - \widetilde{u_i} \widetilde{u_j}), \quad (9)$$

$$\mathcal{Q}_j = \bar{\rho} (\widetilde{u_j T} - \widetilde{u_j} \widetilde{T}), \quad (10)$$

$$\mathcal{J}_j = \bar{\rho} (u_j \widetilde{u_k u_k} - \widetilde{u_j} \widetilde{u_k u_k}), \quad (11)$$

and need to be modeled. In this work, we choose to model the SFS terms using the standard Smagorinsky model.

The SFS stresses are modeled as

$$\tau_{ij} - \frac{\delta_{ij}}{3} \tau_{kk} = 2\mu_t \left(\widetilde{S}_{ij} - \frac{\delta_{ij}}{3} \widetilde{S}_{kk} \right) \quad (12)$$

where $\mu_t = C_s^2 \bar{\Delta}^2 \bar{\rho} |\widetilde{S}|$, $\tau_{kk} = 2C_I \bar{\Delta}^2 \bar{\rho} |\widetilde{S}|^2$, and $|\widetilde{S}| = \sqrt{2\widetilde{S}_{ij}\widetilde{S}_{ij}}$.

The SFS heat flux is modeled as

$$\mathcal{Q}_j = -\frac{\mu_t}{Pr_t} \frac{\partial \widetilde{T}}{\partial x_j} \quad (13)$$

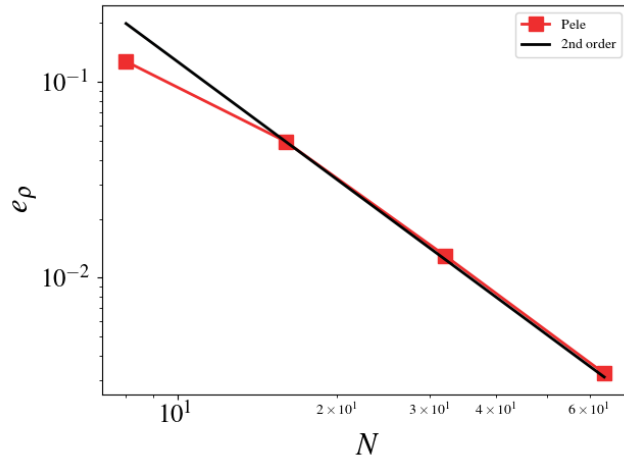
The SFS turbulent diffusion is modeled as

$$\mathcal{J}_j = \widetilde{u_k} \tau_{jk} \quad (14)$$

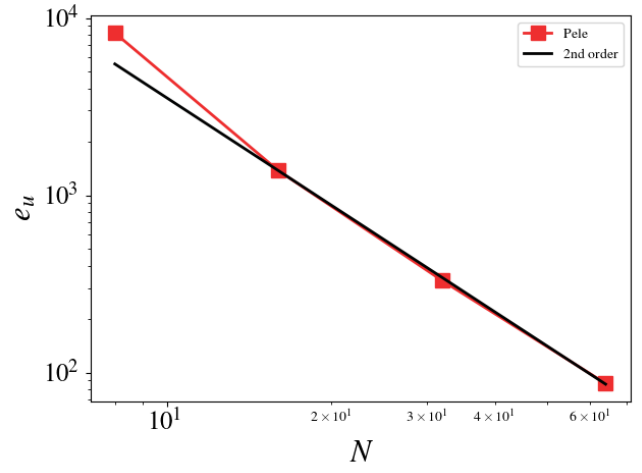
The source terms for these equations are obtained through automatic differentiation as implemented in MASA and METAPHYSICL. These equations and source terms are implemented as `ad_cns_3d_les` in MASA.

2 Results

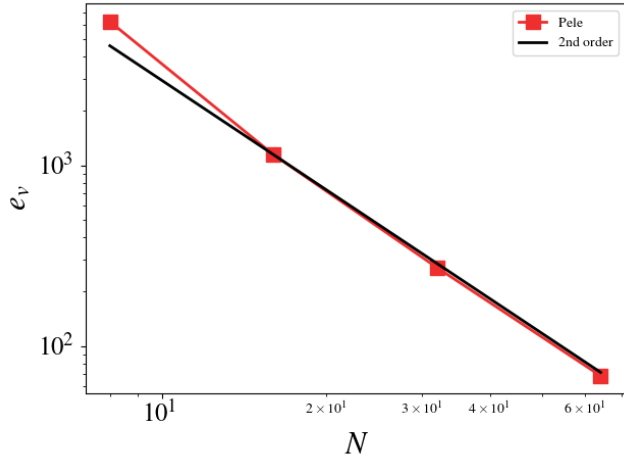
The method of manufactured solutions was used to verify the PeleC code at the National Renewable Energy Laboratory. PeleC is a second order finite volume code used in combustion applications. For these cases, the Reynolds, Mach, and Prandtl numbers were set to 1 to ensure that the different physics were equally important (viscosity, conductivity, and bulk viscosity are non-zero and determined by the appropriate non-dimensional number). The CFL condition was fixed to 0.1 to ensure that the predictor-corrector time stepping method found a solution to the system of equations. The initial solution was initialized to the exact solution. Periodic boundaries are imposed everywhere. The Large Eddy Simulation (LES) constants, C_s and C_I , were chosen such that the turbulent eddy viscosity was comparable to the viscosity, i.e. $\frac{\mu_t}{\mu} = \mathcal{O}(1)$. Since the model scales with the mesh spacing, C_s and C_I were scaled inversely with the mesh spacing for the mesh refinement studies. For example, C_s is set to 2 for the 8^3 mesh and set to 4 for the 16^3 mesh (for C_I , it is 1 and 4, respectively). A convergence study shows second order for Pele's treatment of the compressible Navier-Stokes equations with the constant Smagorinsky Large Eddy Simulation model, Figure 1.



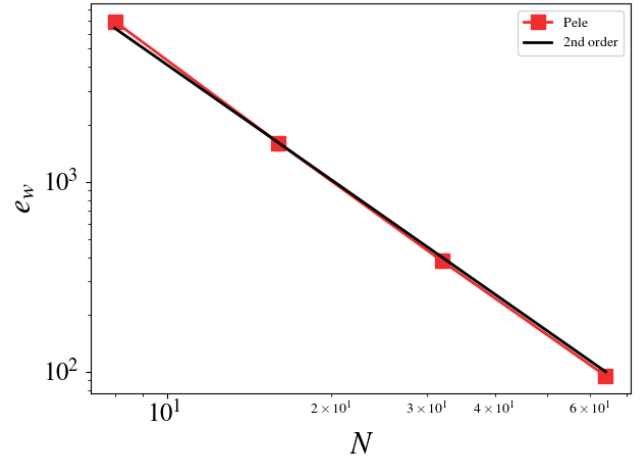
(a) Density.



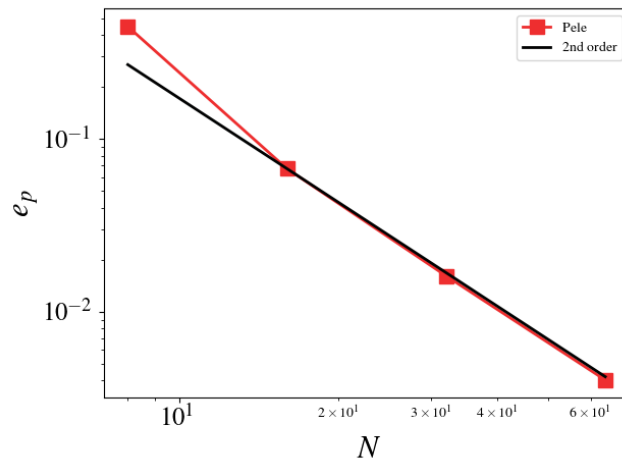
(b) u_1 .



(c) u_2 .



(d) u_3 .



(e) Pressure.

Figure 1: L_2 error as a function of N , the number of elements per side of the cube.