

# Learning and identification in DiD designs

Marx et al. (2023): "Parallel Trends and Dynamic Choices"

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# Motivation (I)

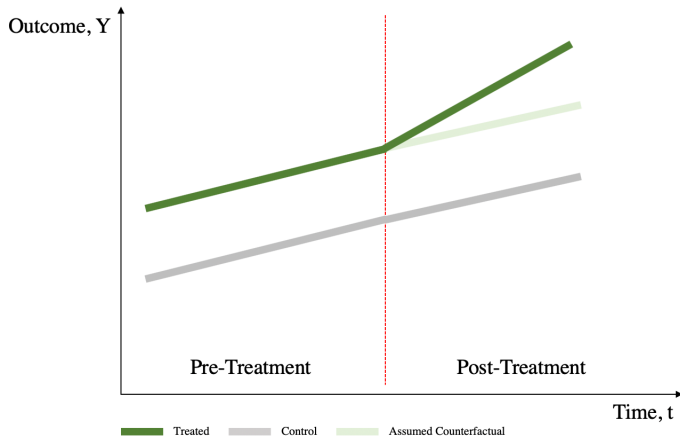


Figure: Parallel trends in sharp DiD designs.

## Motivation (II)

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But in many real-world settings, treatment choice is a **dynamic choice**. For instance, the present treatment choice may depend on:

- past treatments and observed levels
- informed expectations about the present
- informed expectations about the future.

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Key idea: **Parallel Trends constrain agent behavior**. But how?

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Key idea: **Parallel Trends constrain agent behavior**. But how?

Past outcomes can affect future expectations in various ways, called **learning mechanisms**. We'll focus on the impact of some mechanisms on PT:

$$E[Y_1(0) - Y_0(0) | D_0 = d_0, D_1 = d_1] = \tau \in \mathbb{R} \text{ for all } d_0, d_1 \in \{0, 1\}.$$

# Overview

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## 1. Introduction

- 1.1 Motivation
- 1.2 Setup
- 1.3 Model illustration
- 1.4 Selection: when and how

## 2. Learning mechanisms

- 2.1 Sufficient initial information
- 2.2 Learning on the Treatment arm
- 2.3 Learning on the Control arm

## 3. Conclusions

- 3.1 Review of findings
- 3.2 Appendix

## Setup (I)

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- Random sample of  $i = 1, \dots, N$  workers eligible for the program
- Treatment is participation in the program:  $D_{it} = 1$  if worker  $i$  enrolls in time  $t$ ,  $D_{it} = 0$  if not. **Choice is flexible**: any  $(d_{i0}, d_{i1}) = \mathbf{d}_i$  is possible
- Levels measured in  $t = 0, 1$ : wages  $Y_{it} \in \mathbb{R}_+$  (or other), where  $Y_{it} = D_{it}Y_{it}(1) + (1 - D_{it})Y_{it}(0)$ .



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- Levels measured in  $t = 0, 1$ : wages  $Y_{it} \in \mathbb{R}_+$  (or other), where  $Y_{it} = D_{it}Y_{it}(1) + (1 - D_{it})Y_{it}(0)$ .

As usual,  $Y_{it}(\mathbf{d}_1, \dots, \mathbf{d}_N) = Y_{it}(d_{it})$ : SUTVA holds, no spillovers nor dynamic effects, etc. Population variables will be used, and subscripts  $i$  ignored.

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- Utilities  $V_0(d_0) = Y_0(d_0) - K(d_0)$  and  $V_1(d_1) = Y_1(d_1) - K(d_1)$
- The *future* utility of the best possible choice in period 1, given  $d_0$ .  
Formally defined as the r.v.  $W_1(d_0) \equiv \max_{d_1 \in \{0,1\}} E[V_1(d_1) | U_1(d_0)]$

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Formally defined as the r.v.  $W_1(d_0) \equiv \max_{d_1 \in \{0,1\}} E[V_1(d_1) | U_1(d_0)]$
- Discount factor  $\beta$  reflecting the *present value* of  $W_1(d_0)$ . For example,  $\beta = 0.5$  implies 100€ in  $t = 1$  are as valuable as 50€ in  $t = 0$
- Initial information  $U_0$  with  $\beta, K(d_t) \in U_0$ , updated to  $U_1(d_0)$  once  $Y_0 = Y_0(d_0)$  is observed. Information does not decrease:  $U_0 \subseteq U_1(d_0)$ .

## Setup (III)

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### Dynamic Utility Maximization (DUM).

Given initial information  $U_0$  at the start of period 0 and accrued information  $U_1(d_0)$  at the start of period 1, *treatment decisions maximize the sum of expected discounted utility*:

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where  $1\{\cdot\}$  denotes the indicator function and  $U_1(d_0) \equiv \{U_0, Y_0(d_0)\}$ .

# Model illustration (I)

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**Example 1.** Bob considers joining a job training program.



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**Example 1.** Bob considers joining a job training program. Initially:

- he *expects* a wage of  $300 = E[Y_0(1)|U_0]$  after enrolling in  $t = 0$ , or a wage of  $200 = E[Y_0(0)|U_0]$  if he does not enroll in  $t = 0$
- he *knows* enrolling costs  $200 = K(1)$ , while not enrolling is free, ie.  $0 = K(0)$ .

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- he *knows* enrolling costs  $200 = K(1)$ , while not enrolling is free, ie.  $0 = K(0)$ .

Thus, he expects the following utilities in  $t = 0$ :

$$E[V_0(1)|U_0] = E[Y_0(1)|U_0] - K(1) = 300 - 200 = 100,$$

$$E[V_0(0)|U_0] = E[Y_0(0)|U_0] - K(0) = 200 - 0 = 200.$$

Moreover, he *values* utilities in  $t = 1$  as half of those in  $t = 0$ , ie.  $\beta = 0.5$ .

## Model illustration (II)

---

What's the impact of his choice on period 1? Let's **pretend** he *expects* a salary of  $800 = E[Y_1(1)|U_1(d_0)]$  after enrolling in  $t = 1$ , or instead  $300 = E[Y_1(0)|U_1(d_0)]$  if he does not enroll in  $t = 1$ . We then get:

$$E[W_1(d_0)|U_0] = E[Y_1(1)|U_1(d_0)] - K(1) = 800 - 200 = 600, \text{ for any } d_0.$$

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Thus, Bob is going to choose:

$$\begin{aligned} D_0 &= 1\{E[V_0(1) - V_0(0) + \beta(W_1(1) - W_1(0))|U_0] \geq 0\} \\ &= 1\{100 - 200 + 0.5 * (600 - 600) \geq 0\} \\ &= 1\{-100 \geq 0\} = 0. \end{aligned}$$

Then he observes  $Y_0(0)$ , updates his guesses on  $Y_1$ , and chooses  $D_1$  *similarly*.

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(iii) the constant trends are all equal, *ie. no trend shift between time 0 and 1.*



## Selection: when and how (II)

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Selection in  $t = 0$  can happen on the basis of the initial  $U_0$  only (**static**), but in  $t = 1$  also on the basis of the acquired information given by  $U_1$  (**dynamic**).

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**Assumption 11.** The untreated trend is mean-independent from  $U_0$ :

$$E[Y_1(0) - Y_0(0)|U_0] = \tau \in \mathbb{R}. \quad (11)$$

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In (DUM):

assumption (11) + static selection  $\implies$  Parallel Trends,

assumption (11) + dynamic selection  $\nRightarrow$  Parallel Trends.

## Sufficient initial information (I)

---

**Example 2.** Suppose (DUM) and asm (11) hold. **If the initial information is sufficient** for mean outcomes in the following sense:

$$E[Y_1(d_1)|U_0, Y_0(d_0)] = E[Y_1(d_1)|U_0] \text{ for any } d_0, d_1 \in \{0, 1\}, \quad (12)$$

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**the Parallel trends condition is satisfied.**

*Heuristic: PT may hold if observed outcomes do not provide additional information about the future, ie. if agents do not learn anything new about potential outcomes.*

## Sufficient initial information (II)

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### Proof.

In (DUM) we have the following choice rule for  $D_1$ :

$$\begin{aligned} D_1 &= 1\{E[V_1(d_0, d_1) - V_1(d_0, 0)|U_0, U_1(d_0)] \geq 0\} \\ &= 1\{E[V_1(d_0, d_1) - V_1(d_0, 0)|U_0] \geq 0\}, \text{ per asm (12).} \end{aligned}$$

That implies  $D_1$  is conditional on  $U_0$  only, like  $D_0$ .

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$$E[Y_1(0) - Y_0(0)|D_0, D_1] = E[E[Y_1(0) - Y_0(0)|U_0]|D_0, D_1]$$

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$$\begin{aligned} E[Y_1(0) - Y_0(0)|D_0, D_1] &= E[E[Y_1(0) - Y_0(0)|U_0]|D_0, D_1] \\ &= E[\tau|D_0, D_1] = \tau, \text{ for all } (d_0, d_1). \end{aligned}$$

Since  $E[Y_1(0) - Y_0(0)|D_0, D_1] = \tau \in \mathbb{R}$ , PT is valid. □



## Sufficient initial information (III)

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### Interpretation.

- $\text{Asm (11)} \equiv \text{const. untreated trend given } U_0 \implies \text{no violation in } t = 0$
- $+ \text{asm (12)} \equiv \text{sufficient } U_0 \implies \text{no violation in } t = 1 \text{ either.}$

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Is this a special case of a more general result? What if workers accurately predicted their untreated wages (*safe arm*), but could learn something about the effect of the training program (*risky arm*)?

## Learning on the Treatment arm (I)

---

**Example 3.** Suppose (DUM) and asm (11) hold. If

- there is **no learning across treatment arms** ( $d_0 \neq d_1$ ) **nor on the untreated arm** ( $d_0 = d_1$ ):

$$E[Y_1(d_1)|U_0, Y_0(d_0)] = E[Y_1(d_1)|U_0] \text{ where } (d_0 + d_1) \in \{0, 1\}, \quad (13)$$

- and  $Y_0(1)$  is **not informative** about  $Y_0(0)$  given  $U_0$ :

$$E[Y_0(0)|Y_0(1), U_0] = E[Y_0(0)|U_0] \text{ for any } d_0, d_1 \in \{0, 1\}, \quad (14)$$

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the Parallel trends condition is **satisfied**.

Heuristic: *PT may hold if agents can learn only from and about treated outcomes, ie. if untreated outcomes are accurately expected from the start.*

## Learning on the Treatment arm (II)

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### Proof.

In (DUM) the choice rule for  $D_0$  is conditional on  $U_0$ . By asm (13), the treatment decision  $D_1(d_0 = 0)$  is also conditional on  $U_0$  since  $U_1(0) \equiv U_0$ .

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$$\begin{aligned} & E[Y_1(0) - Y_0(0) | D_0 = 0, D_1 = d_1] \\ &= E[E[Y_1(0) - Y_0(0) | U_0] | D_0 = 0, D_1(0) = d_1] \end{aligned}$$

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Thus, the untreated trend is constant *for those initially not treated*. □

## Learning on the Treatment arm (III)

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### Proof.

Choice  $D_1(d_0 = 1)$  is conditional on  $U_1(1) \equiv \{U_0, Y_0(1)\}$ . By the LIE:

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But by asm (13) and (14), untreated outcomes  $Y_1(0)$  and  $Y_0(0)$  do not actually depend on  $Y_0(1)$ .

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Thus, the untreated trend is constant *for those who are initially treated*.  $\square$

## Learning on the Treatment arm (IV)

---

### Proof.

It is proved that (i) the conditional untreated trend is constant in  $d_1$  for each  $d_0$ , ie. no violation in  $t = 1$  given  $d_0$ .

## Learning on the Treatment arm (IV)

### Proof.

It is proved that (i) the conditional untreated trend is constant in  $d_1$  for each  $d_0$ , ie. no violation in  $t = 1$  given  $d_0$ .

As asm (11) implies, (ii) the conditional untreated trend is also constant in  $d_0$  and (iii) with the same value:

$$\begin{aligned} & E[Y_1(0) - Y_0(0) | D_0 = d_0] \\ &= E[E[Y_1(0) - Y_0(0) | U_0] | D_0 = d_0] \\ &= \tau, \text{ for all } d_0 \in \{0, 1\}, \end{aligned}$$

ie. no violation in  $t = 0$  and there is no trend shift in between.

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### Proof.

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ie. no violation in  $t = 0$  and there is no trend shift in between.

Since (i), (ii) and (iii) from (Observation 1) are equivalent to PT, the condition is valid. □

## Learning on the Control arm (I)

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**Example 4.** Suppose (DUM) and asm (11) hold. Let  $\Omega_{vl}$  be the set of *valuable learners*, ie. agents whose optimal  $D_1$  is decisively influenced by  $Y_0$ . If  $Y_0(0)$  is informative about  $Y_1(0)$  but no other form of learning is possible, then PT is satisfied if and only if:

## Learning on the Control arm (I)

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**Example 4.** Suppose (DUM) and asm (11) hold. Let  $\Omega_{vl}$  be the set of *valuable learners*, ie. agents whose optimal  $D_1$  is decisively influenced by  $Y_0$ . If  $Y_0(0)$  is informative about  $Y_1(0)$  but no other form of learning is possible, then PT is satisfied if and only if:

- valuable learning is impossible (ie.  $P(\Omega_{vl}) = 0$ ), or
- valuable learning occurs only where untreated outcomes are constant almost surely (ie.  $P(Y_0(0) = Y_1(0)|\Omega_{vl}) = 1$ ) and  $\tau = 0$ .

*Heuristic: PT may not hold if valuable information can be learned from and about untreated outcomes, unless said outcomes are stable over time.*



## Learning on the Control arm (II)

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**Interpretation.** Since  $D_1(0)$  is not conditional on  $U_0$  alone in this case, PT is generally violated in  $t = 1$  by the untreated in  $t = 0$ . Typically:

$$E[Y_1(0) - Y_0(0)|D_0 = 0] \neq E[Y_1(0) - Y_0(0)|D_0 = 1].$$

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$$E[Y_1(0) - Y_0(0)|D_0 = 0] \neq E[Y_1(0) - Y_0(0)|D_0 = 1].$$

But PT is valid if:

- $Y_0(0)$  does not determine  $D_1 = D_1(0)$ , ie.  $U_0$  is practically sufficient, or
- $Y_0(0) \equiv Y_1(0)$  in  $\Omega_v$ , implying that the untreated trend is zero among all valuable learners, regardless of their treatment choices.

## Review of findings

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Since PT *constrains agent behavior*, it's not compatible with every kind of dynamic choice mechanism. Our examples specifically deal with **learning**:

**Example 2.** PT may hold if observed outcomes do not provide additional information about the future, i.e., if agents do not learn anything new about potential outcomes. *No dynamic selection in this case.*

**Example 3.** PT may hold if agents can learn only from and about treated outcomes, i.e., if untreated outcomes are accurately expected from the start. *Learning on treated outcomes does not affect untreated trends.*

**Example 4.** PT may not hold if valuable information can be learned from and about untreated outcomes, unless said outcomes are stable over time. *Learning on untreated outcomes may lead to differences in conditional untreated trends.*

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**Thank you**

## Appendix (Alternative identification strategies)

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From the last example, we can see that the causal effect of treatment is still identified for the always-treated and the switchers out-of-treatment since:

$$E[Y_1(0) - Y_0(0)|D_0 = 1, D_1(0) = d_1] = \tau \text{ for all } d_1 \in \{0, 1\}.$$

This would be an instance of **partial identification**, but is it meaningful?

The last example also suggests another approach, **mean stationarity** of untreated outcomes:  $E[Y_1(0) - Y_0(0)] = 0$ . It implies, for  $D_0 = 0$ :

$$E[Y_1(1) - Y_1(0)|D_1 = 1] = \frac{E[Y_1] - E[Y_0]}{P(D_1 = 1)},$$

ie. the ATT is identified in sharp designs if the untreated trend is zero.