

Architecture of the “follow me” behavior

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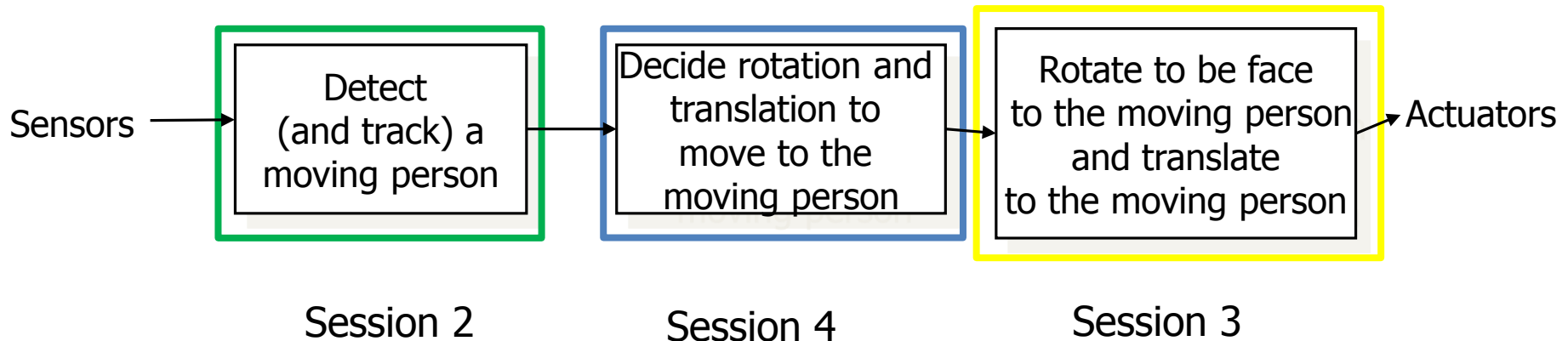
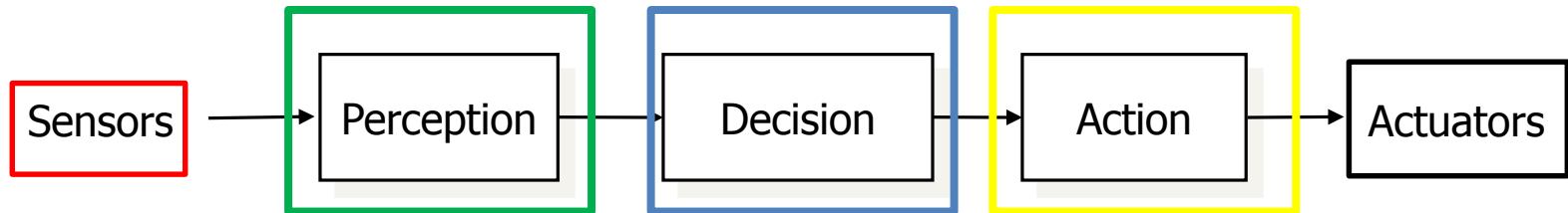
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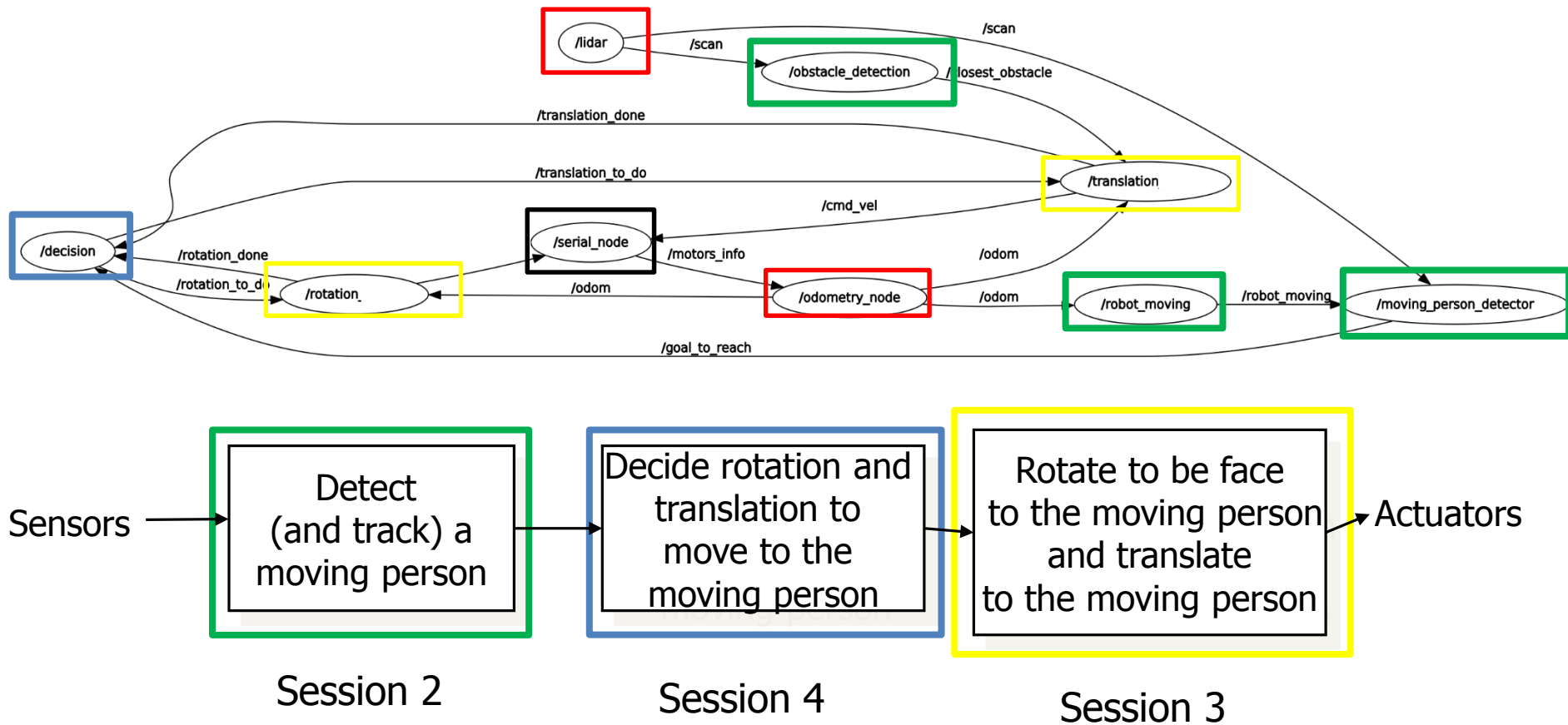
Overview of the complete architecture (1/2)



Strong assumption: a moving person can only be detected when the mobile robot doesn't move

Overview of the complete architecture (2/2)

- The complete architecture is composed of 6 nodes



Strong assumption: a moving person can only be detected when the mobile robot doesn't move