

Descent Method :- Steepest Descent method, Newton's Method, DFP (Quasi Newton's) method.

Newton method :-

Taylor's series :- Taylor series of a real valued function $f(x)$, which is infinitely differentiable at a real number 'a' is a power series

$$f(x) \cong f(a) + \frac{1}{1!} f'(a)(x-a) + \frac{1}{2!} f''(a)(x-a)^2 + \frac{1}{3!} f'''(a)(x-a)^3 + \dots$$

where $n! = 1 \times 2 \times \dots \times n$

$f'(a)$ = first derivative of function at a

$f''(a)$ = second derivative of function at a
and so on.

$$f'(x) = f'(a) + \frac{1}{2} f''(a) \cdot 2(x-a)$$

$$0 = f'(a) + f''(a)(x-a)$$

$$x-a = \frac{-f'(a)}{f''(a)} \Rightarrow x = a - \frac{f'(a)}{f''(a)}$$

To find maxima
or minima
 $f'(x) = 0$

Algorithm

Objective function $f(x)$
initial point a_1
stopping condition $\rightarrow |f'(x)| < \epsilon$

- compute $f'(x)$ and $f''(x)$
- $f'(a_1)$ and $f''(a_1)$

- compute $f'(x)$
- compute $f'(a_1)$ and $f''(a_1)$

$$a_2 = a_1 - \left[\frac{f'(a_1)}{f''(a_1)} \right]$$

$|f'(a_2)| < \epsilon$
 a_2 is local minima

$$|f'(a_2)| \geq \epsilon$$

a_2 is your new initial point.

Example:- $\text{Min}(x^2 + 2x)$ $a = 0$ starting point
 $\epsilon = 0.1$ } \rightarrow stopping condition.
 $|f'(x)| < \epsilon$

$$f(x) = x^2 + 2x$$

$$f'(x) = 2x + 2$$

$$f''(x) = 2$$

$$(1) f'(x) = 2x + 2$$

$$(2) f'(0) = 2, f'(100) = 202$$

$$(3) a_2 = a_1 - \frac{f'(a_1)}{f''(a_1)} = 0 - \frac{2}{2} = -1$$

$$\boxed{a_2 = -1}$$

$$\boxed{a_2 = 100 - \frac{2 \cdot 2}{2} = -1}$$

$$(4) f'(-1) = (2x - 1) + 2 = 0 \quad |f'(-1)| = 0 < \underline{0.1}$$

$$\boxed{a_2 = -1}$$

is a local minima.

Newton method :-
 single variable

Multivariable function
 multivariable function
 $x = (x_1, x_2, \dots, x_n)$

Newton method :- single variable

① $f'(x)$ and $f''(x)$

② $f'(a)$ and $f''(a)$ at initial point a

③ $a_2 = a - \frac{f'(a)}{f''(a)}$

↙ ↘
stopping condition

$(a'_1, a'_2, \dots, a'_n) = (a_1, a_2, \dots, a_n) - [H_f(a_1, a_2, \dots, a_n)]^{-1} \nabla f(a_1, \dots, a_n)$

↙
 $n \times 1$
column
wise.

↙
 $n \times n$
matrix
 $n \gg 2$

↙
 $n \times 1$ column
wise

• Identity matrix $\rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ $n \times n$ matrix.

• $A \rightarrow n \times n$ matrix B is called inverse of A if
 $BA = I = AB$

• A is 2×2 matrix $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$

$A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$

Example :- Minimize

$f(x, y) = x - y + 2x^2 + 2xy + y^2$

Example:-

minimize

$$f(x, y) = x - y + 2x^2 + 2xy + y^2$$

starting point $x_1 = (0, 0)$

stopping condition $|\nabla f(x_k)| = 0$.

① $f(x, y) = x - y + 2x^2 + 2xy + y^2$

$$\nabla f = \begin{pmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{pmatrix} = \begin{pmatrix} 1 + 4x + 2y \\ -1 + 2x + 2y \end{pmatrix}$$

$$H_f = \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{pmatrix} = \begin{pmatrix} 4 & 2 \\ 2 & 2 \end{pmatrix}$$

$$\nabla f|_{(0,0)} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \quad H|_{(0,0)} = \begin{pmatrix} 4 & 2 \\ 2 & 2 \end{pmatrix}$$

$$x_2 = (0, 0) - \left(H|_{(0,0)}\right)^{-1} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$x_2 = -\frac{1}{4} \begin{bmatrix} 2 & -2 \\ -2 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = -\frac{1}{4} \begin{bmatrix} 4 \\ -6 \end{bmatrix} = \begin{bmatrix} -1 \\ 3/2 \end{bmatrix}$$

2x2 2x1

check stopping condition

$$\nabla f|_{(-1, 3/2)} = \begin{pmatrix} 1 + 4x + 2y \\ -1 + 2x + 2y \end{pmatrix} \Big|_{(-1, 3/2)} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

1-4+3
-1-2+3

• $(-1, \frac{3}{2})$ is local minima.

Example $\text{Min } f(x) = 100(y - x^2)^2 + (1-x)^2$

starting point $(0,0)$

$$|\nabla f| \Big|_{x_k} = (0,0)$$

$$\cdot \quad \nabla f = \begin{pmatrix} df/dx \\ df/dy \end{pmatrix} = \begin{pmatrix} 100 \cdot 2 \underbrace{(y-x^2)}_{(-2x)} + 2(1-x)(-1) \\ 100 \cdot 2(y-x^2) \end{pmatrix}$$

$$H_f = \begin{pmatrix} -400(y-x^2) - 400(x)(-2x) + 2 & -400x \\ -400x & 200 \\ -400 & 200 \end{pmatrix}$$

$$\bullet \quad \nabla f|_{(0,0)} = \begin{pmatrix} -2 \\ 0 \end{pmatrix} \quad H_f|_{(0,0)} = \begin{pmatrix} 2 & 0 \\ 0 & 200 \end{pmatrix}$$

$$\left(H_f|_{(0,0)} \right)^{-1} = \frac{1}{400} \begin{pmatrix} 200 & 0 \\ 0 & 2 \end{pmatrix}$$

$$X_2 = \overset{(0,0)}{X_1} - \begin{pmatrix} 1/2 & 0 \\ 0 & \frac{1}{2^{100}} \end{pmatrix} \begin{pmatrix} -2 \\ 0 \end{pmatrix} = - \begin{pmatrix} -1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$x_2 = (1, 0)$$

$$\nabla f|_{(1,0)} = (400, -200) \neq (0,0)$$

$X_2 = (1, 0)$ is new initial point.

$$1 \text{ m}^2 = 100 \text{ dm}^2$$

Second iteration:-

$$\nabla f(1,0) = (400, -200)$$

$$H_f(1,0) = \begin{pmatrix} 1202 & -400 \\ -400 & 200 \end{pmatrix}$$

$$(H_f(1,0))^{-1} = \frac{1}{80400} \begin{pmatrix} 200 & 400 \\ 400 & 1202 \end{pmatrix}$$

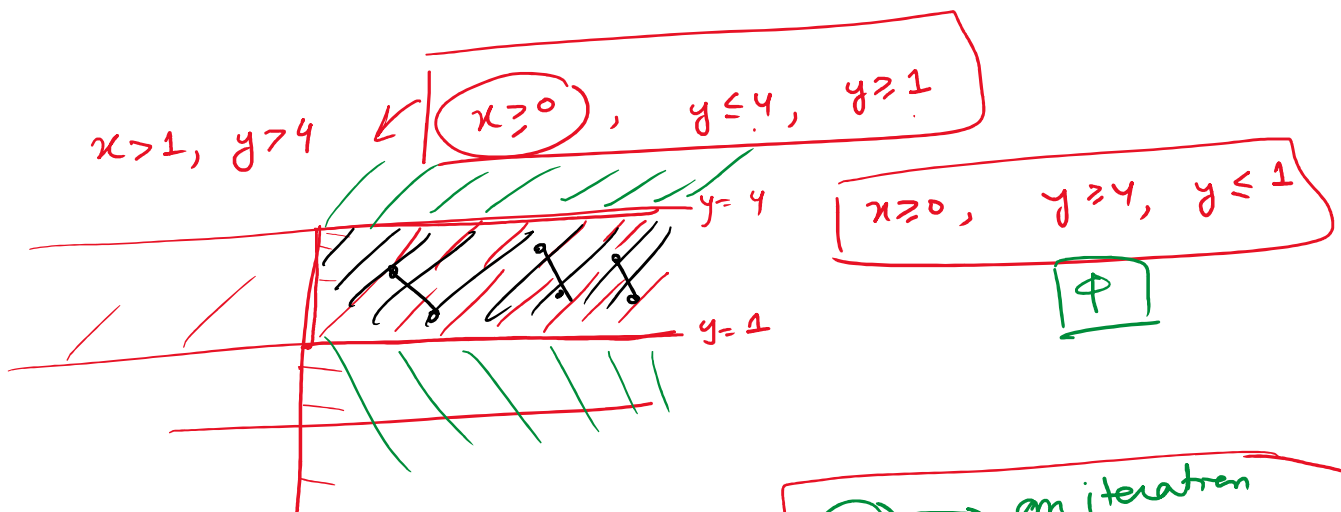
$$X_3 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} - \frac{1}{80400} \begin{pmatrix} 200 & 400 \\ 400 & 1202 \end{pmatrix} \begin{pmatrix} 400 \\ -200 \end{pmatrix}$$

$$X_3 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} - \frac{1}{80400} \begin{pmatrix} 8000 & -80000 \\ 160000 & -240400 \end{pmatrix}$$

$$X_3 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} - \frac{1}{80400} \begin{pmatrix} 0 \\ -80400 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\nabla f|_{(1,1)} = (0,0)$$

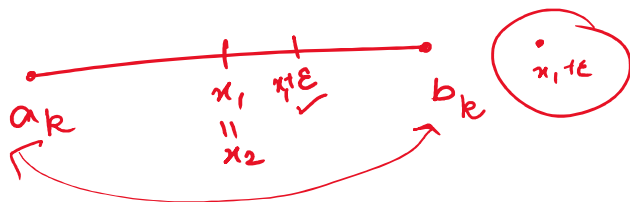
$(1,1)$ is local minimum.



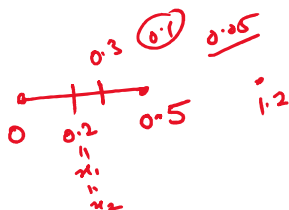
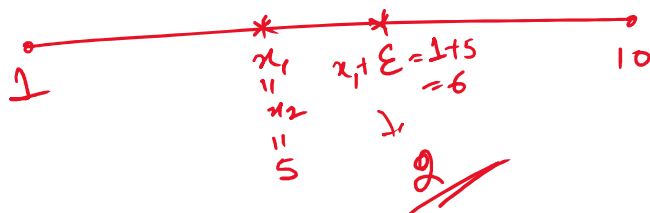
$\epsilon \rightarrow$ an iteration $x_1 = x_2$ will happen at $(n-1)^{th}$ iteration.



How to choose ε



for Example



will happen in
($n-1$)th iteration.

Not $\varepsilon \rightarrow \varphi(x_1) = \varphi(x_2)$

$\varphi(x_1) \geq \varphi(x_2)$
↓

$\varphi(x_1) \leq \varphi(x_2)$
↓



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