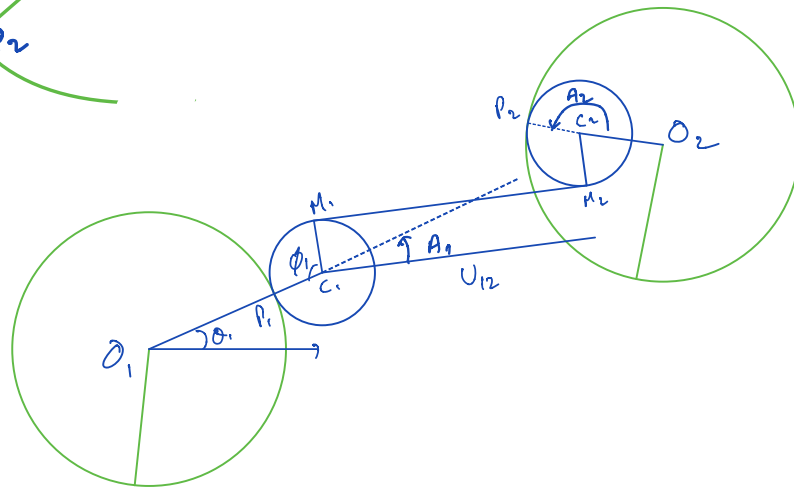
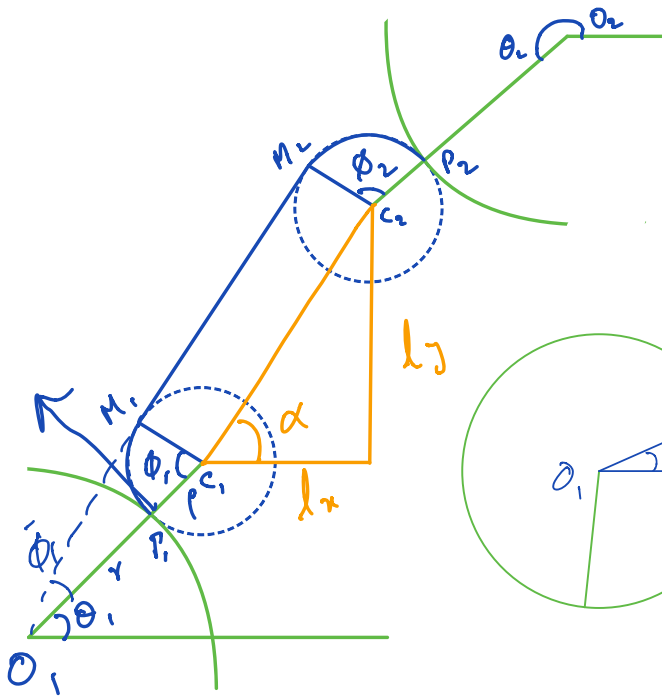


Derivative of length of the path
w.r.t θ_1 or θ_2

RSR / RSL

$\mu_{\text{start}} = +1$ if start is true
-1 if start is false

$$\begin{aligned} \sin(C_2 M_2 \rightarrow C_2 P_2) \\ = \sin(-2\pi + \phi_2) \\ = \sin \phi_2 \end{aligned}$$



$$\theta_1 + \frac{\pi}{2} - \phi_1 = \alpha$$

$$\alpha - \phi_2 = \theta_2 + \frac{\pi}{2}$$

$$\theta_1 + \frac{\pi}{2} - \phi_1 - \phi_2 = \theta_2 + \frac{\pi}{2}$$

$$\phi_1 + \phi_2 = \theta_1 - \theta_2$$

$$\frac{\partial (\phi_1 + \phi_2)}{\partial \theta_1} = 1, \quad \frac{\partial (\phi_1 + \phi_2)}{\partial \theta_2} = -1$$

$$\text{for } i=1,2 \quad \rho^2 \phi_i(\theta_1, \theta_2) = \cos^2(C_i M_i \cdot C_i P_i) \bmod 2\pi$$

$$\frac{\partial \phi_i}{\partial \theta_j} = \frac{1}{\rho^2 \sqrt{1 - (C_i M_i \cdot C_i P_i)^2}} \left(C_i M_i \cdot \frac{\partial C_i P_i}{\partial \theta_j} + \frac{\partial C_i M_i}{\partial \theta_j} \cdot C_i P_i \right)$$

$$\sqrt{1 - (C_i M_i \cdot C_i P_i)^2} = \sin \phi_i$$

$$\text{if } u \cdot v = 0 \text{ or } v \cdot w = 0$$

$$u \cdot w = -\|u\| \|w\| \left[\sin(\angle uv) \sin(\angle vw) \right]$$

$\angle uv$ is the angle between \vec{u} & \vec{v} in ccw from \vec{u} to \vec{v}

$$\|C_i M_i\| = \rho$$

$$C_i P_i = O_i P_i - O_i C_i$$

$$= O_i + r [\cos \theta_i, \sin \theta_i] - O_i - (r + \rho) [\cos \theta_i, \sin \theta_i]$$

$$\|C_i P_i\| = \rho$$

$$= -\rho [\cos \theta_i, \sin \theta_i]$$

$$\left\| \frac{\partial C_i P_i}{\partial \theta_j} \right\| = \rho \delta_{ij} \left[\begin{array}{l} \delta_{ij} = 1 \text{ if } i = j \\ = 0 \text{ if } i \neq j \end{array} \right]$$

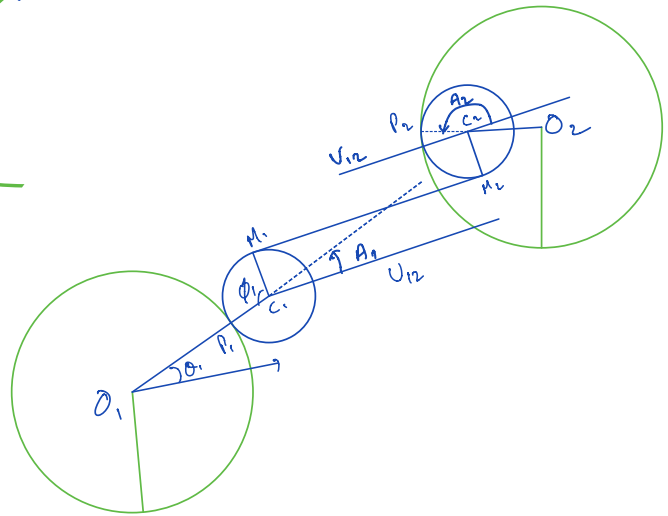
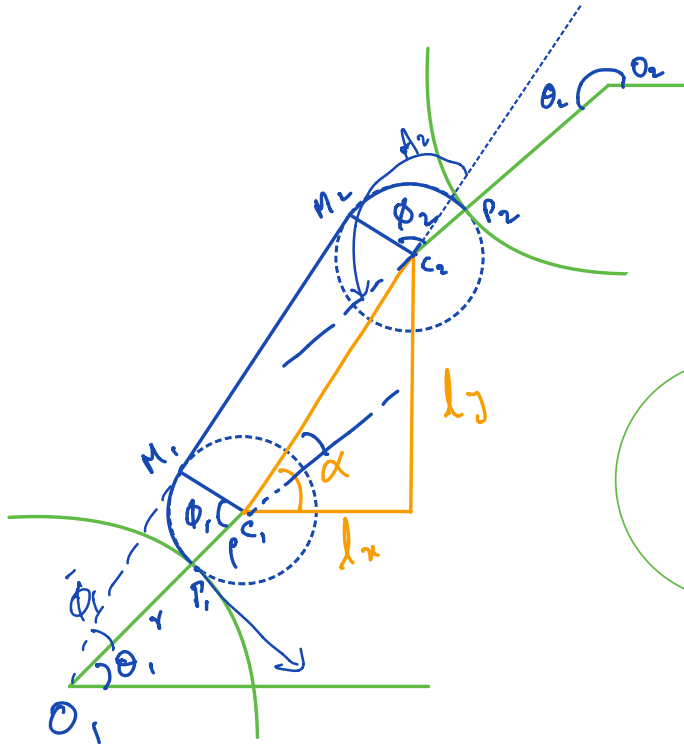
$$C_i M_i \cdot \frac{\partial C_i P_i}{\partial \theta_j} = -\rho \delta_{ij} \sin(\angle C_i M_i \rightarrow C_i P_i) \sin\left(\angle C_i P_i \rightarrow \frac{\partial C_i P_i}{\partial \theta_i}\right)$$

tl always

$$\boxed{C_i M_i \cdot \frac{\partial C_i P_i}{\partial \theta_j} = -\rho \delta_{ij} \mu_{i=1} \mu_{C_i=R} \sin \phi_i}$$

$$\frac{\partial C_i M_i}{\partial \theta_j} \cdot C_i P_i = - \left\| \frac{\partial C_i M_i}{\partial \theta_j} \right\| \overbrace{\|C_i P_i\|}^{=\rho} \sin\left(\angle \frac{\partial C_i M_i}{\partial \theta_j} \rightarrow C_i M_i\right) \underbrace{\sin(\angle C_i M_i \rightarrow C_i P_i)}_{\mu_{i=1} \mu_{C_i=R} \sin \phi_i}$$

$$\frac{\partial \phi_i}{\partial \theta_j} = \prod_{i=1}^n \prod_{q=R}^n \left[\delta_{ij} + \frac{1}{r} \left\| \frac{\partial C_i M_i}{\partial \theta_j} \right\| \sin \left(\angle \frac{\partial C_i M_i}{\partial \theta_j} \rightarrow C_i M_i \right) \right]$$



$$\begin{aligned} & \sin(\angle U_{12} \rightarrow O_1 C_1) \\ &= -\sin\left(\frac{\pi}{2} - \phi_1\right) \\ &= -\cos \phi_1 \end{aligned}$$

$$\begin{aligned} \angle U_{12} \rightarrow O_2 C_2 &= \angle U_{12} \rightarrow U_{21} \\ &+ \angle U_{21} \rightarrow O_2 C_2 = \pi + \frac{\pi}{2} - \phi_2 \end{aligned}$$

$$\sin(\angle U_{12} \rightarrow O_2 C_2) = -\cos \phi_2$$

$$\begin{aligned} & \angle U_{12} \rightarrow O_1 C_1 \\ &= \frac{\pi}{2} - \pi + \phi_1 \\ &= -\frac{\pi}{2} + \phi_1 \end{aligned}$$

$$\sin(\angle U_{12} \rightarrow O_1 C_1) = -\cos \phi_1$$

$$\angle U_{12} \rightarrow O_2 C_2 = \phi_2 - \frac{\pi}{2}$$

$$\sin(\angle U_{12} \rightarrow O_2 C_2) = -\cos \phi_2$$

$$O_1 O_2 = O_1 C_1 + C_1 M_1 + M_1 M_2 + M_2 C_2 + C_2 O_2$$

$$M_1 M_2 = O_2 C_2 + C_2 M_2 - O_1 C_1 - C_1 M_1 + O_1 O_2$$

For RSR (LSL)

$$C_2 M_2 = C_1 M_1$$

$$M_1 M_2 = O_2 C_2 - O_1 C_1$$

RSI (LSR)

$$\text{or } C_2 M_2 = -C_1 M_1$$

$$M_1 M_2 = O_2 C_2 - O_1 C_1 - 2 C_1 M_1$$

$$\frac{\partial O_i C_i}{\partial \theta_j} = 0 \text{ if } i \neq j$$

$$\frac{\partial M_1 M_2}{\partial \theta_j} = -\mu_{j=1} \frac{\partial O_j C_j}{\partial \theta_j}$$

$$L_s^2 = M_1 M_2 \cdot M_1 M_2$$

$$L_s \frac{\partial L_s}{\partial \theta_j} = M_1 M_2 \cdot \frac{\partial M_1 M_2}{\partial \theta_j}$$

$$\frac{\partial L_s}{\partial \theta_j} = \mu_{12} \cdot \frac{\partial M_1 M_2}{\partial \theta_j}$$

$$\left(U_{12} = \frac{\overline{M_1 M_2}}{L_S}, \text{ unit vector} \right)$$

$$\frac{\partial L_S}{\partial \theta_j} = - \mu_{j=1} U_{12} \cdot \frac{\partial O_j C_j}{\partial \theta_j}$$

$$= \mu_{j=1} \left\| \frac{\partial O_j C_j}{\partial \theta_j} \right\| \sin(\angle U_{12} \rightarrow O_j C_j)$$

$$\underbrace{\sin(\angle O_j C_j \rightarrow \frac{\partial O_j C_j}{\partial \theta_j})}_{+1}$$

$$= \mu_{j=1} (r + p) \sin(\angle U_{12} \rightarrow O_j C_j)$$

for RSR

$$\frac{\partial L_S}{\partial \theta_j} = - \mu_{j=1} (r + p) \cos \phi_j$$

$$\frac{\partial \phi_i}{\partial \theta_j} = \mu_{i=1} \mu_{Q=2} \left[\delta_{ij} + \frac{1}{\rho} \left\| \frac{\partial C_i M_i}{\partial \theta_j} \right\| \sin \left(\angle \frac{\partial C_i M_i}{\partial \theta_j} \rightarrow C_i M_i \right) \right]$$

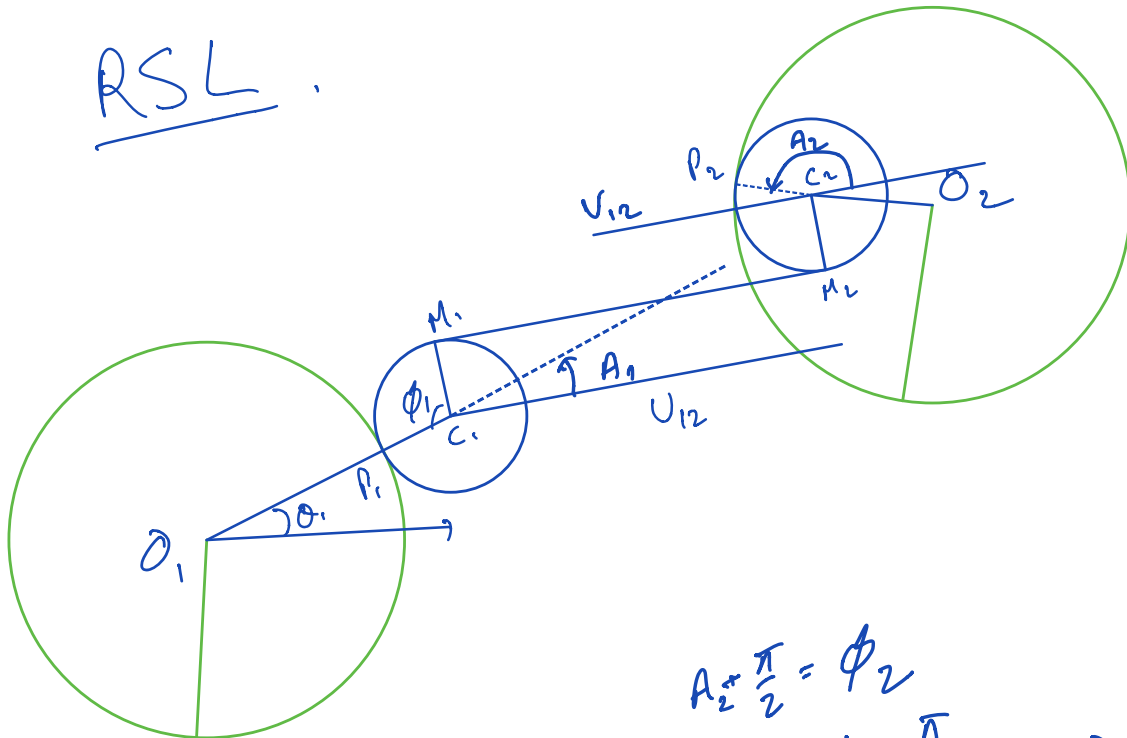
$$\frac{\partial \phi_1}{\partial \theta_j} = \delta_{1j} + \frac{1}{\rho} \left\| \frac{\partial C_1 M_1}{\partial \theta_j} \right\| \sin \left(\angle \frac{\partial C_1 M_1}{\partial \theta_j} \rightarrow C_1 M_1 \right)$$

$$\frac{\partial \phi_2}{\partial \theta_j} = - \delta_{2j} - \frac{1}{\rho} \left\| \frac{\partial C_1 M_1}{\partial \theta_j} \right\| \sin \left(\angle \frac{\partial C_1 M_1}{\partial \theta_j} \rightarrow C_1 M_1 \right)$$

$$\frac{\partial (\phi_1 + \phi_2)}{\partial \theta_j} = (\delta_{1j} - \delta_{2j}) = \mu_{j=1}$$

$$\frac{\partial L_{RSR}}{\partial \theta_j} = \mu_{j=1} \left[\rho - (\gamma + \rho) \cos \phi_j \right]$$

RSL.



$$\frac{\pi}{2} - A_1 = \pi - \phi_1$$

$$A_1 = \phi_1 - \frac{\pi}{2}$$

$$\sin A_1 = -\cos \phi_1$$

$$M_1 M_2 = O_2 C_2 - O_1 C_1 - 2 C_1 M_1$$

$$\frac{\partial M_1 M_2}{\partial \theta_j} = -r_{j=1} \frac{\partial O_j C_j}{\partial \theta_j} - 2 \frac{\partial C_1 M_1}{\partial \theta_j}$$

$$\frac{\partial L_s}{\partial \theta_j} = v_{12} \cdot \frac{\partial M_1 M_2}{\partial \theta_j}$$

$$A_2 = \frac{\pi}{2} = \phi_2$$

$$A_2 = \phi_2 - \frac{\pi}{2}$$

$$\sin A_2 = \sin \left(\phi_2 - \frac{\pi}{2} \right)$$

$$= -\cos \phi_2$$

$$U_{12} \cdot \frac{\partial O_j C_j}{\partial \theta_j} = - \overbrace{\left\| \frac{\partial O_j C_j}{\partial \theta_j} \right\|}^{(r + \mu_{C_j} = R \cdot P)} \overbrace{\left(\sin(U_{12} \rightarrow O_j C_j) \right.}^{-\cos(\phi_j)} \\ \left. \sin(O_j C_j \rightarrow \frac{\partial O_j C_j}{\partial \theta_j}) \right)_{+1}$$

$$U_{12} \cdot \frac{\partial O_j C_j}{\partial \theta_j} = (r + \mu_{C_j} = R \cdot P) \cos \phi_j$$

$$U_{12} \cdot \frac{\partial C_1 M_1}{\partial \theta_j} = - \overbrace{\left\| \frac{\partial C_1 M_1}{\partial \theta_j} \right\|}^{+1} \overbrace{\left(\sin(U_{12} \rightarrow C_1 M_1) \right.}^{+1} \\ \left. \sin(C_1 M_1 \rightarrow \frac{\partial C_1 M_1}{\partial \theta_j}) \right)$$

$$= - \left\| \frac{\partial C_1 M_1}{\partial \theta_j} \right\| \sin(C_1 M_1 \rightarrow \frac{\partial C_1 M_1}{\partial \theta_j})$$

$$\frac{\partial L_s}{\partial \theta_j} = - \mu_{j=1} U_{12} \cdot \frac{\partial \theta_j c_j}{\partial \theta_j} - 2 U_{12} \cdot \frac{\partial C_{M1}}{\partial \theta_j}$$

$$= - \mu_{j=1} (V + \mu_{c_j=R} \rho) \cos \phi_j$$

$$+ 2 \left\| \frac{\partial C_{M1}}{\partial \theta_j} \right\| \sin(C_{M1} \rightarrow \frac{\partial C_{M1}}{\partial \theta_j})$$

$$\frac{\partial (\phi_1 + \phi_2)}{\partial \theta_j} = \overbrace{(\delta_{1j} + \delta_{2j})}^{\varepsilon_1} +$$

$$\frac{2}{\rho} \left\| \frac{\partial C_{M1}}{\partial \theta_j} \right\| \sin \left(\angle \frac{\partial C_{M1}}{\partial \theta_j} \rightarrow C_{M1} \right)$$

$$\frac{\partial L_{RSL}}{\partial \theta_j} = \rho - \sum_{j=1}^n (r + \mu_{Cj} R \rho) \cos \phi_j$$

The first derivatives w.r.t $\theta_1, \theta_2, \theta_3$ vanish when the straight line segment is collinear with center of the arc₁ or arc₂, respectively.