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- Action Anticipation Based on an Agent's Epistemic State in Toddlers and Adults
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41 Abstract

Do toddlers and adults engage in spontaneous Theory of Mind (ToM)? Evidence from

anticipatory looking (AL) studies suggests they do. But a growing body of failed

replication studies raised questions about the paradigm's suitability, urging the need to test

the robustness of AL as a spontaneous measure of ToM. In a multi-lab collaboration we

examine whether 18- to 27-month- olds' and adults' anticipatory looks distinguish between

47 two basic forms of epistemic states: knowledge and ignorance. In toddlers [ANTICIPATED

n = 520 50% FEMALE] and adults [ANTICIPATED n = 408, 50% FEMALE], we found

⁴⁹ [SUPPORT/NO SUPPORT] for epistemic state-based action anticipation. Future research

can probe whether this conclusion extends to more complex kinds of epistemic states, such

as true and false beliefs.

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Keywords: anticipatory looking; spontaneous Theory of Mind; replication

Word count: 10243

Action Anticipation Based on an Agent's Epistemic State in Toddlers and Adults

The capacity to represent epistemic states, known as Theory of Mind (ToM) or 55 mentalizing, plays a central role in human cognition (Dennett, 1989; Frith & Frith, 2006; 56 Premack & Woodruff, 1978). Although ToM has been under intense scrutiny in the past decades, its nature and ontogeny are still the subjects of much controversy. At the heart of these debates are questions about the reliability of the tools used to measure ToM (Baillargeon, Buttelmann, & Southgate, 2018; e.g., Poulin-Dubois et al., 2018), among others, anticipatory looking (AL) paradigms. To address this issue, in a collaborative long-term project we assess the robustness of infants' and adults' tendency to spontaneously take into account different kinds of epistemic states — what they perceive, know, think, or believe — when predicting others' behaviors. This paper reports the first foundational step of this project, which focuses on the most basic epistemic state ascription: the capacity to distinguish between knowledgeable and ignorant individuals. Simple forms of knowledge attribution (such as tracking what other individuals have seen or experienced) are typically assumed to develop early and to operate spontaneously throughout the lifespan (Liszkowski, Carpenter, & Tomasello, 2007; e.g., Luo & Baillargeon, 2007; O'Neill, 1996; Phillips et al., 2021). Thus, evaluating whether ToM measures are sensitive to the knowledge-ignorance distinction is a crucial test case to assess 71 their robustness. The present paper investigates this question in an AL paradigm including 18-27-month-old infants and adults.

In the following sections we first establish the background and scientific context of
this study, namely the reliability and replicability of spontaneous ToM measures. We then
introduce a novel way to approach these issues: a large-scale collaborative project targeting
the replicability of ToM findings. Finally, we outline the rationale of the present study
which uses an AL paradigm to test whether infants and adults distinguish between two
basic forms of an agent's epistemic state: knowledge and ignorance.

Spontaneous Theory of Mind tasks

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Humans are proficient at interpreting and predicting others' intentional actions. 81 Adults as well as infants expect agents to act persistently towards the goal they pursue 82 Woodward & Sommerville (2000), and anticipate others' actions based on their goals even 83 before goals are achieved - that is, humans engage in goal-based action anticipation (for review, see Elsner & Adam, 2021; but see Ganglmayer, Attig, Daum, & Paulus, 2019). To predict others' actions, however, it is essential to consider their epistemic state: what they perceive, know, or believe. A number of seminal studies using non-verbal spontaneous measures have suggested that infants, toddlers, older children, and adults show action anticipation and action understanding not only based on other agents' goals (what they want) but also on the basis of their epistemic status (what they perceive, know, or believe). These studies suggest that from infancy onwards, humans spontaneously engage in ToM or mentalizing. For example, studies using violation of expectation methods have demonstrated that infants look longer in response to events in which an agent acts in ways that are incompatible with their (true or false) beliefs, compared to events in which they act in belief-congruent ways (Onishi & Baillargeon, 2005; Surian, Caldi, & Sperber, 2007; Träuble, Marinović, & Pauen, 2010). Other studies have employed more interactive tasks requiring the child to play, communicate, or cooperate with experimenters and, for 97 example, give an experimenter one of several objects as a function of their epistemic status. Such studies have shown that toddlers spontaneously adjust their behavior to the experimenter's beliefs (Buttelmann, Carpenter, & Tomasello, 2009; Király, Oláh, Csibra, & 100 Kovács, 2018; Knudsen & Liszkowski, 2012; Southgate, Johnson, Karoui, & Csibra, 2010). 101 The largest body of evidence for spontaneous ToM comes from studies using AL 102 tasks. In such tasks, participants see an agent who acts in pursuit of some goal (typically, 103 to collect a certain object) and has either a true or a false belief (for example, regarding 104 the location of the target object). A number of studies have shown that infants, toddlers,

older children, neurotypical adults, and even non-human primates anticipate (indicated by 106 looks to the location in question) that an agent will go where it (truly or falsely) believes 107 the object to be rather than, irrespective of the actual location of the object (Gliga, Jones, 108 Bedford, Charman, & Johnson, 2014; Grosse Wiesmann, Friederici, Singer, & Steinbeis, 109 2017; Hayashi et al., 2020; Kano, Krupenye, Hirata, Tomonaga, & Call, 2019; Krupenye, 110 Kano, Hirata, Call, & Tomasello, 2016; Meristo et al., 2012; Schneider, Lam, Bayliss, & 111 Dux, 2012; Schneider, Slaughter, Bayliss, & Dux, 2013; Senju et al., 2010; Senju, 112 Southgate, Snape, Leonard, & Csibra, 2011; Senju, Southgate, White, & Frith, 2009; 113 Surian & Franchin, 2020; Thoermer, Sodian, Vuori, Perst, & Kristen, 2012). These studies 114 have revealed converging evidence for spontaneous ToM across the human lifespan and 115 even in other primate species. 116

Across the different measures, the majority of early works on spontaneous ToM in 117 infants and toddlers have reported positive results in the second year of life, and a few 118 studies even within the first year (Kovács, Téglás, & Endress, 2010; Luo & Baillargeon, 119 2010; Southgate & Vernetti, 2014), yielding a rich body of coherent and convergent 120 evidence (for reviews see e.g., Barone, Corradi, & Gomila, 2019; Kampis & Southgate, 121 2020; Scott & Baillargeon, 2017). This growing body of literature has led to a theoretical 122 transformation of the field. In particular, findings with young infants have paved the way 123 for novel accounts of the development and cognitive foundations of ToM. The previous consensus was that full-fledged ToM emerges only at around age 4, potentially as the result 125 of developing executive functions, complex language skills and other factors (e.g., Perner, 126 1991; Wellman & Cross, 2001). In contrast, the newer accounts proposed that some basic 127 forms of ToM may be phylogenetically more ancient and may develop much earlier in 128 ontogeny (e.g., Baillargeon, Scott, & He, 2010; Carruthers, 2013; Kovács, 2016; Leslie, 129 2005). 130

Recently, however, a number of studies have raised uncertainty regarding the
empirical foundations of the early-emergence theories, as we review below. In the following

sections, we present an overview of the current empirical picture of early understanding of
epistemic states and then introduce ManyBabies2 (MB2), a large-scale collaborative
project exploring the replicability of ToM in infancy, of which the current study constitutes
the first step.

7 Replicability of Spontaneous Theory of Mind Tasks

A number of failures to replicate findings from spontaneous ToM tasks have recently 138 been published with infants, toddlers, and adults Kulke & Rakoczy (2019). Besides 139 conceptual replications, many of these studies involve more direct replication attempts 140 with the original stimuli and procedures. One of these was a two-lab replication attempt of 141 one of the most influential AL studies (Southgate, Senju, & Csibra, 2007). This failure to 142 replicate is especially notable not only because of the influence of the original finding of the 143 field, but also because of the large sample size and the involvement of some of the original 144 authors (Kampis et al., 2021). Additional unpublished replication failures have also been 145 reported. Kulke and Rakoczy (2018) examined 65 published and non-published studies 146 including 36 AL studies [replications of Schneider, Bayliss, Becker, and Dux (2012); 147 Southgate et al. (2007): Surian & Geraci, 2012; and Low & Watts, 2013, as well as studies 148 using other paradigms, and classified them as a successful, partial, or non-replication, depending on whether all, some, or none of the original main effects were found. Although 150 no formal analysis of effect size was carried out, overall, non-replications and partial 151 replications outnumbered successful replications, regardless of the method used. In 152 addition to the failure to replicate spontaneous anticipation of agents' behaviors based on their beliefs, many of the replication studies revealed an even more fundamental problem of spontaneous AL procedures: a failure to adequately anticipate an agent's action in the 155 absence of a belief. That is, researchers did not find evidence for spontaneous anticipation 156 of agents' behaviors based on their goals, even in the initial familiarization trials of the 157 experiments, where the agent's beliefs do not play any role yet (e.g., Kampis et al., 2020; 158

Kulke, Reiß, et al., 2018; Schuwerk et al., 2018). The familiarization trials are designed to convey the goal of the agent, as well as the general timing and structure of events, to set 160 up participants' expectations in the test trials where the agent's epistemic state is then 161 manipulated. Typically, the last familiarization trial can also be used to probe participants' 162 spontaneous action anticipation; and test trials can only be meaningfully interpreted if 163 there is evidence of above-chance anticipation in the familiarization trials. In several AL 164 studies many participants had to be excluded from the main analyses for failing to 165 demonstrate robust action anticipation during the familiarization trials (e.g., Kampis et al., 166 2020; Kulke, Reiß, et al., 2018; Schuwerk et al., 2018; Southgate et al., 2007). This raises 167 the possibility that these paradigms may not be suitable for reliably eliciting spontaneous 168 action prediction in the first place (for discussion see Baillargeon et al., 2018). In sum, in 169 light of the complex and mixed state of the evidence, it currently remains unclear whether infants, toddlers, and adults engage in spontaneous ToM. This calls for systematic, 171 large-scale, a priori designed multi-lab study that stringently tests for the robustness, reliability, and replicability of spontaneous measures of ToM. 173

174 General Rationale of MB2

To this end, ManyBabies 2 (MB2) was established as an international consortium 175 dedicated to investigating infants' and toddlers' ToM skills. The main aim is to test the 176 replicability and thus reliability of findings from spontaneous ToM tasks. In the long-term, 177 MB2 will build on the initial findings and the aim will be extended to include testing the 178 validity of these experimental designs and addressing theoretical accounts of spontaneous ToM. MB2 operates under the general umbrella of ManyBabies (MB), a large-scale international research consortium founded with the aim of probing the reliability of central findings from infancy research. In particular, MB projects bring together large and 182 theoretically diverse groups of researchers to tackle pressing questions of infant cognitive 183 development, by collaboratively designing and implementing methodologies and

pre-registered analysis plans (Frank et al., 2017). The MB2 consortium involves authors of original studies as well as authors of both successful and failed replication studies, and researchers from very different theoretical backgrounds. It thus presents a case of true "adversarial collaboration" (Mellers et al., 2001).

89 Rationale of the Present Study

Based on both theoretical and practical considerations, the current paper presents 190 the first foundational step in MB2, focusing on AL measures. It investigates whether 191 toddlers and adults anticipate (in their looking behavior) how other agents will act based 192 on their goals (i.e., what they want) and epistemic status (i.e., what they know or do not 193 know). From a practical perspective, we focus on AL since it is a child-friendly and widely 194 used method that is also suitable for humans across the lifespan and even other species. 195 Additionally, as AL is screen-based and standardizable, identical stimuli can be presented 196 in different labs. From a theoretical perspective, given the mixed findings with AL tasks 197 reviewed in the previous section, we take a systematic and bottom-up approach. First, we 198 probe whether AL measures are suitable for measuring spontaneous goal-directed action 199 anticipation. With the aim to improve the low overall rates of anticipatory looks in recent 200 studies, we designed new, engaging stimuli to test whether these are successful in eliciting 201 spontaneous action anticipation. Second, in case reliably elicited action anticipation can be 202 found: we probe whether toddlers and adults take into account the agent's epistemic status 203 in their spontaneous goal-based action anticipation. That is, do they track whether the 204 agent saw or did not see a crucial event, and therefore whether this agent does or does not know something? In the current study we focus on the most basic form of tracking the epistemic status of agents: considering whether they had access to relevant information, 207 and whether they are thus knowledgeable or ignorant. We reasoned that only after 208 establishing whether a context can elicit spontaneous tracking of an agent's epistemic 209 status in a more basic sense (i.e., the agent's knowledge vs. ignorance) is it eventually 210

meaningful to ask whether this context also elicits more complex epistemic state tracking 211 (i.e., the agent's beliefs). Answering these first two questions in the present study will 212 allow us, in the long run, to address a third set of questions in subsequent studies, probing 213 the nature of the representations and cognitive mechanisms involved in infant ToM. Do 214 toddlers and adults engage in full-fledged belief-ascription in their spontaneous goal-based 215 action anticipation? What kind of epistemic states do toddlers and adults spontaneously 216 attribute to others in their action anticipation (e.g., Horschler et al., 2020; Phillips et al., 217 2020)? Do the results that prove replicable really assess ToM, or can they be interpreted in 218 alternative ways such as behavioral rules, associations, or simple perceptual preferences 219 (see, e.g., Heyes, 2014; Perner & Ruffman, 2005)? The present study lays the foundation 220 for investigating these questions. Regarding the knowledge-ignorance distinction, many 221 accounts in developmental and comparative ToM research have argued for the ontogenetic 222 and evolutionary primacy of representing what agents witness and represent, relative to 223 more sophisticated ways of representing how agents represent (and potentially mis-represent) objects and situations (e.g., Apperly & Butterfill, 2009; Flavell, 1988; 225 Kaminski et al., 2008; Martin & Santos, 2016; Perner, 1991; Phillips et al., 2020). For 226 example, it is often assumed that young children and non-human primates may be capable of so-called "Level I perspective-taking" (understanding who sees what) but only human 228 children from around age 4 may finally develop capacities for "Level II perspective-taking" 229 (understanding how a given situation may appear to different agents; Flavell et al., 1981). 230 Empirically, many studies using verbal and/or interactive measures have indicated that 231 children may engage in knowledge-ignorance and related distinctions before they engage in 232 more complex forms of meta-representation (e.g., Flavell et al., 1981; Hogrefe et al., 1986; 233 Moll & Tomasello, 2006; O'Neill, 1996; though for some findings indicating Level II 234 perspective-taking at an early age see Scott & Baillargeon, 2009; Buttelmann et al., 2015; 235 Buttelmann & Kovács, 2019; Kampis et al., 2020; Scott, Richman, & Baillargeon, 2015), 236 and that non-human primates seem to master knowledge-ignorance tasks while not 237

demonstrating any more complex, meta-representational form of ToM (e.g., Hare et al., 2011; Kaminski et al., 2008; Karg et al., 2015). The knowledge-ignorance distinction thus 230 appears to be an ideal candidate for assessing epistemic status-based action anticipation in 240 a wide range of populations. To date, however, no study has probed whether or how 241 children's (and adults') spontaneous action anticipation, as indicated by AL, is sensitive to 242 ascriptions of knowledge vs. ignorance. Most studies that have addressed ToM with AL 243 measures have targeted the more sophisticated true/false belief contrast. As reviewed 244 above, the results of those studies yield a mixed picture regarding replicability of the 245 findings. It has been argued that tasks that reliably replicate are ones which can be solved 246 with the more basic knowledge-ignorance distinction, whereas tasks that do not replicate 247 require more sophisticated belief-ascription (Powell et al., 2018)¹, suggesting that only 248 some but not all findings might not be replicable. Based on these considerations, the present study tests whether toddlers and adults engage in knowledge- and ignorance-based 250 AL to probe the most basic form of spontaneous, epistemic state-based action anticipation.

Design and Predictions of the Present Study

The current study presents 18- to 27-month-old toddlers and adults with animated scenarios while measuring their gaze behavior. Testing adults (and not just toddlers) is crucial to address debates about the validity and interpretation of AL measures of ToM throughout the lifespan (e.g., Schneider et al., 2017). Following the structure of previous AL paradigms, participants are first familiarized to an agent repeatedly approaching a target (familiarization trials). AL is measured during familiarization trials to probe

¹ For example, some studies have found partial replication results, with patterns of the following kind: participants showed systematic anticipation (or appropriate interactive responses) in true belief trials but showed ooking (or interactive responses) at chance level in the false belief trials (e.g., Dörrenberg et al., 2019; Kulke, Reiß, et al., 2018; Powell et al., 2018). Such a pattern remains ambiguous since it may merely reflect a knowledge-ignorance distinction.

whether participants understood the agent's goal and spontaneously anticipate their 259 actions. Subsequently, during test trials the agent's visual access is manipulated, leading 260 them to be either knowledgeable or ignorant about the location of the target. Participants' 261 AL will be measured during test trials to determine whether or not they take into account 262 the agent's epistemic access and adjust their action anticipation accordingly. Participants' 263 looking patterns will be recorded using either lab-based corneal reflection eye-tracking or 264 online recording of gaze patterns. We chose to provide the online testing option to increase 265 the flexibility for data collection given the disruption caused by the Covid-19 pandemic. 266 This option will also provide the opportunity to potentially compare in-lab and online 267 testing procedures (Sheskin et al., 2020). Novel animated stimuli were collectively 268 developed within the MB2 consortium on the basis of previous work (e.g., Clements & 269 Perner, 1994) and based on input from collaborators with experience with both successful 270 and failed replication studies (e.g., Grosse Wiesmann et al., 2017; Surian & Geraci, 2012). 271 These animated 3D scenes feature a dynamic interaction aimed to optimally engage 272 participants' attention: a chasing scenario involving two agents, a chaser and a chasee (see Figures 1 and 2). As part of the chase, the chase enters from the top of an upside-down 274 Y-shaped tunnel with two boxes at its exits. The tunnel is opaque so participants cannot 275 see the chasee after it enters the tunnel, but can hear noises that indicate movement. The 276 chase eventually exits from one of the arms of the Y, and goes into the box on that side. 277 The chaser observes the chase exit the tunnel and go into a box, and then follows it 278 through the tunnel. During familiarization trials, the chaser always exits the tunnel on the 279 same side as the chasee, and approaches the box where the chasee is currently located. 280 Thus, if participants engage in spontaneous action anticipation during familiarization 281 trials, they should reliably anticipate during the period when the chaser is in the tunnel 282 that it will emerge at the exit that leads to the box containing the chasee. During test 283 trials, the chase always first hides in one of the boxes but shortly thereafter leaves its 284 initial hiding place and hides in the box at the other tunnel exit. Critically, the chaser 285

either does (knowledge condition) or does not (ignorance condition) have epistemic access 286 to the chasee's location. During knowledge trials, the chaser observes all movements of the 287 chasee. During *ignorance* trials, the chaser observes the chasee enter the tunnel, but then 288 leaves and only returns once the chase is already hidden inside the second box. The event 289 sequences in the two conditions are thus identical with the only difference between 290 conditions pertaining to what the chaser has or has not seen. They were designed in this 291 way with the long-term aim to implement, in a minimal contrast design, more complex 292 conditions of false/true belief contrasts with the very same event sequences (true belief 293 conditions will then be identical to the knowledge conditions here, but in false belief 294 conditions the chaser witnesses the chasee's placement in the first box, but then fails to 295 witness the re-location)². Participants' AL (their gaze pattern indicating where they expect 296 the chaser to appear) will be assessed during the anticipatory period - that is, the period 297 during which the chaser is going through the tunnel and is not visible. There will be two 298 main dependent measures: first looks, and a differential looking score (DLS). The first look measure will be binary, indicating which of the two tunnel exits participants fixate first: 300 the exit where the chase is actually hiding, or the other exit. DLS is a measure of the 301 proportion of time spent looking at the correct tunnel exit during the entire anticipatory 302 period. In two pilot studies (see Methods section), we addressed the foundational question

² There is thus a certain asymmetry with regard to the interpretation and the consequences of potentially positive and negative results of the present knowledge-ignorance contrast: in the case of positive results, we can conclude that subjects spontaneously engage in basic epistemic state ascription and can move on to test, with the minimal contrast comparison of knowledge-ignorance vs. false belief-true belief, whether this extends to more complex forms of epistemic state attribution. In the case of negative results, though, we cannot draw firm conclusions to the effect that subjects do not engage in spontaneous epistemic state ascription. More caution is in order since the present knowledge-ignorance contrast has been designed in order to be comparable to future belief contrasts rather than to be the simplest implementation possible. Simpler implementations would then need to be devised that involve fewer steps (i.e. the chasee just goes to one location and this is or is not witnessed by the chasee).

of the current study: whether these stimuli reveal spontaneous goal-directed action anticipation as measured by AL in the above-described familiarization trials (i.e., without a 305 change of location by the chase or manipulation of the chaser's epistemic state). We found 306 that our paradigm indeed elicited action anticipation and exclusion rates due to lack of 307 anticipation were significantly lower relative to previous (original and replication) AL 308 studies. Both toddlers and adults showed reliable anticipation of the chaser's exit at the 300 chasee's location, indicating that in contrast with many previous AL studies the current 310 paradigm successfully elicits spontaneous goal-based action anticipation. Based on these 311 pilot data we concluded that the paradigm is suitable for examining the second and critical 312 question: whether toddlers and adults, in their spontaneous goal-based action anticipation, 313 take into account the agent's epistemic state. We predict that if participants track the 314 chaser's perceptual access and resulting epistemic state (knowledge/ignorance) and 315 anticipate their actions accordingly, they should look more in anticipation to the exit at the 316 chasee's location than the other exit in the knowledge condition, but should not do so (or 317 to a lesser degree; see below) in the *ignorance* condition. We anticipate three potential 318 factors that could influence participant's gaze patterns: Keeping track of the chaser's 319 epistemic status in the *ignorance* condition might either lead to no expectations as to 320 where the chaser will look (resulting in chance level looking between the two exits) or (if 321 participants follow an "ignorance leads to mistakes"-rule, see e.g., Ruffman, 1996) to an 322 expectation that the chaser will go to the wrong location (longer looking to the exit with 323 the empty box; e.g., Fabricius et al., 2010). Either way, participants may still show a 'pull 324 of the real' even in the *ignorance* condition, i.e., reveal a default tendency to look to the 325 side where the chasee is located. But if they truly keep track of the epistemic status of the 326 chaser (knowledge vs. ignorance), they should show this tendency to look to the side where 327 the chase really is in the *ignorance* condition to a lesser degree than in the *knowledge* 328 condition. In sum, the research questions of the present study are the following: First, can 329 we observe in a large sample that toddlers and adults robustly anticipate agents' actions 330

based on their goals in this paradigm, as they did in our pilot study? Second, can we find evidence that they take into account the agent's epistemic access (knowledge vs. ignorance) 332 and adjust their action anticipation accordingly? In addressing these questions, the present 333 study will significantly contribute to our knowledge on spontaneous ToM. It will inform us 334 whether the present paradigm and stimuli can elicit spontaneous goal-based and 335 mental-state-based action anticipation in adults and toddlers, based on a large sample of 336 about 800 participants in total from over 20 labs. In the long run, the present study will 337 lay the foundation for future work to address broader questions of what kind of epistemic 338 states toddlers and adults spontaneously attribute to others in their action anticipation 339 and what cognitive mechanisms allow them to do so.

341 Methods

All materials, and later the collected de-identified data, will be provided on the Open Science Framework (OSF; https://osf.io/jmuvd/). All analysis scripts, including the pilot data analysis and simulations for the design analysis, can be found on GitHub (https://github.com/manybabies/mb2-analysis). We report how we determined our sample size and we will report all data exclusions, all manipulations, and all measures in the study. Additional methodological details can be found in the Supplemental Material.

348 Stimuli

Figures 1 and 2 provide an overview of the paradigm. For the stimuli, 3D animations were created depicting a chasing scenario between two agents (chaser and chasee) who start in the upper part of the scene. At the very top of the scene a door leads to outside the visible scene. Below this area, a horizontal fence separates the space, and thus the lower part of the space can be reached by the Y-shaped tunnel only. Additional information on the general scene setup, events, and timings in the familiarization and the test trials, as well as trial randomization can be found in the Supplemental Material.

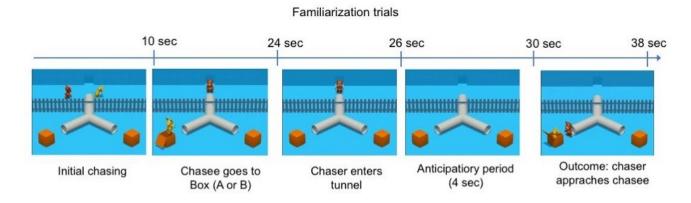


Figure 1. Timeline of the familiarization trials.

Familiarization Trials. All participants will view four familiarization trials (for an 356 overview of key events see Figure 1). During familiarization trials, after a brief chasing 357 introduction, the chase enters an upside-down Y-shaped tunnel with a box at both of its 358 exits. The chasee then leaves the tunnel through one of the exits and hides in the box on 359 the corresponding side. Subsequently, the chaser enters the tunnel (to follow the chasee), 360 and participants' AL to the tunnel exits is measured before the chaser exits on the side the 361 chase is hiding, as an index of their goal-based action anticipation. In these familiarization 362 trials, if participants engage in spontaneous action anticipation, they should reliably 363 anticipate that the chaser should emerge at the tunnel exit that leads to the box where the 364 chase is. After leaving the tunnel, the chaser approaches the box in which the chase is 365 hiding and knocks on it. Then, the chasee jumps out of the box and the two briefly interact. 366

Familiarization Phase Pilot Studies. In a pilot study with 18- to
27-month-olds (n = 65) and adults (n = 42), seven labs used in-lab corneal reflection
eye-tracking to collect data on gaze behavior in the familiarization phase. A key
desideratum of our paradigm is that it should produce sufficient AL, as a low rate of AL in
previous studies has led to high exclusion rates. The goals of the pilot study were to 1)
estimate the level of correct goal-based action predictions in the familiarization phase, 2)
determine the optimal number of familiarization trials, 3) check for issues with perceptual
properties of stimuli (e.g., distracting visual saliencies), and 4) test the general procedure

including preprocessing and analyzing raw gaze data from different eye-tracking systems. 375 We found that the familiarization stimuli elicited a relatively high proportion of 376 goal-directed action anticipations, but we were concerned about the effects of some minor 377 properties of the stimulus (in particular, a small rectangular window in the tunnel tube 378 that allowed participants to see the agents at one point on their path to the tunnel exits). 379 In a second pilot study with 18- to 27-month-olds (n = 12, three participating labs), slight 380 changes of stimulus features (the removal of the window in the tube; temporal changes of 381 auditory anticipation cue) did not cause major changes in the AL rates. Sixty-eight percent 382 of toddlers' first looks in the first pilot, 69% of toddlers' first looks in the second pilot, and 383 69% of adults' first looks were toward the correct area of interest (AOI) during the 384 anticipatory period. The average proportion of looking towards the correct AOI during the 385 anticipatory period was 70.7% (CI $_{95\%}$ = 67.6% - 73.8%) in toddlers in the first pilot, 70.5% $(\mathrm{CI}_{95\%}=62.8\%$ - 78.2%) in the second pilot for tod dlers, and 75.3% (CI $_{95\%}=71.0\%$ -79.5%) in adults. In Bayesian analyses, we found strong evidence that toddlers and adults looked more towards the target than towards the distractor during the anticipation period. 389 Based on conceptual and practical methodological considerations while also considering 390 previous studies, we decided to include four trials in the final experiment. The pilot data 391 results of the toddlers supported this decision insofar as we observed a looking bias towards 392 the correct location already in trials 1-4, without additional benefit of trials 5-8. Further, 393 prototypical analysis pipelines were established for combining raw gaze data from different 394 eye-trackers. In short, we developed a way to resample gaze data from different 395 eye-trackers to be at a common Hz rate and to define proportionally correct AOIs for 396 different screen dimensions with the goal to merge all raw data into one data set for 397 inferential statistics. The established analysis procedure is described further in the Data 398 Preprocessing section below. In sum, we concluded that this paradigm sufficiently elicits 390 goal-directed action predictions, an important prerequisite for drawing any conclusion on 400 AL behavior in the test trials of this study. A detailed description of the two pilot studies 401

can be found in the Supplemental Material.

All participants will see two test trials, one knowledge and one Test Trials. 403 ignorance trial. However, in line with common practice in ToM studies, the main 404 comparison concerns the first test trial between-participants to avoid potential carryover 405 effects. In addition, in exploratory analyses, we plan to assess whether results remain the same if both trials are taken into account and whether gaze patterns differ between the two trials (see Exploratory Analyses). If the results remain largely unchanged across the two trials, it may suggest that future studies could increase power by including multiple test trials. In test trials, the chase first hides in one of the boxes, but shortly thereafter the 410 chase leaves this box and hides in the second box, at the other tunnel exit. Critically, the 411 chaser either witnesses (knowledge condition) or does not witness (ignorance condition) 412 from which tunnel exit the chase exited and thus where the chase is currently hiding (for 413 an overview, see Figure 2). In the knowledge trials, the chaser observes all movements of 414 the chasee. The chaser leaves for a brief period of time after the chasee entered the tunnel, 415 but it returns before the chasee exits the tunnel. Therefore, no events take place in the 416 chaser's absence. In the *ignorance* trials, the chaser sees the chasee enter the tunnel, but 417 then leaves. Therefore, the chaser does not see the chase entering either box and only 418 returns once the chase is already hidden in the final location. Finally, the chaser enters 419 the tunnel but does not appear in either exit. Rather, the scene "freezes" for four seconds 420 and participants' AL is measured. Thus, the knowledge and ignorance conditions are 421 matched for the chaser leaving for a period of time, but they differ in whether they warrant 422 the chaser's epistemic access to the location of the chasee. No outcome is shown in either 423 test trials. When designing the knowledge and ignorance condition, we aimed at keeping all events and their timings parallel, except the crucial manipulation. We show the same 425 events in both conditions. Where possible, all events also have the same duration. In the 426 case of the chaser's absence in the knowledge condition, there were two main options, both 427 with inevitable trade-offs. First, we could have increased the duration of the chaser's

absence in the knowledge condition to match the duration of the chaser's absence in both 429 conditions. Yet, this would potentially disrupt the flow of events, such as keeping track of 430 the chasee's actions and the general scene dynamics, since nothing would happen for a 431 substantial amount of time. Second, the chaser can be absent for a shorter time in the 432 knowledge than in the ignorance condition, in which case the flow of events – the chasee's 433 actions and the general scene dynamics – remains natural. We chose the second option 434 because we reasoned that the artificial break in the knowledge condition could disrupt the 435 participant's tracking of the chaser's epistemic state, thus being a confound that would be 436 more detrimental than the difference in the duration of absence. Further, the current 437 contrast has the advantage that the chasee's sequence and timing of actions are identical in 438 both conditions, thus minimizing the difference between conditions. Finally, with the 439 current design, the duration of the chaser's absence will be closely matched in the later planned false belief - true belief contrast, because in the future false belief condition, the chaser has to be absent for fewer events (because the chaser witnesses the first hiding events after the chase reappeared at the other side of the tunnel).

Trial Randomization. We will vary the starting location of the chasee (left or right half of the upper part of the scene) and the box the chasee ended up (left or right box) in both familiarization and test trials. The presentation of the familiarization trials will be counterbalanced in two pseudo-randomized orders. Each lab signs up for one or two sets of 16-trial-combinations, for each of their tested age groups.

49 Lab Participation Details

Time-Frame. The contributing labs will start data collection as soon as they are
able to once our Registered Report receives an in-principle acceptance. The study will be
submitted for Stage 2 review within one year after in-principle acceptance (i.e., post-Stage
1 review). We anticipate that this time window gives the individual labs enough flexibility
to contribute the committed sample sizes; however, if this timeline needs adjusting due to



Figure 2. Schematic overview of stimuli and conditions of the test trials.

Note. After the familiarization phase, participants know about the agent's goal (chaser wants to find chasee), perceptual access (chaser can see what happens on the other side of the fence), and situational constraints (boxes can be reached by walking through the forking tunnel). In the knowledge condition, the chaser witnesses the chasee walking through the tunnel and jumping in and out of the first box. While the chasee is in the box, the chaser briefly leaves the scene through the door in the back and returns shortly after. Subsequently, the chaser watches the chasee jumping out of the box again and hiding in the second box. In the ignorance condition, the chaser turns around and stands on the other side of the door in the back of the scene, thus unable to witness any of the chasee's actions. The chaser then returns and enters the tunnel to look for the chasee. During the test phase (4 seconds still frame), AL towards the end of the tunnels is measured.

the Covid-19 pandemic this decision will be made prior to any data analysis.

Participation Criterion. The participating labs were recruited from the MB2 consortium. In July 2020, we asked via the MB2 listserv which labs plan to contribute how many participants for the respective age group (toddlers and/or adults). The Supplemental Material provides an overview of participating labs. Each lab made a commitment to collecting data from at least 16 participants (toddlers or adults), but we will not exclude any contributed data on the basis of the total sample size contributed by that lab. Labs will be allowed to test using either in-lab eye-tracking or online methods.

Ethics. All labs will be responsible for obtaining ethics approval from their
appropriate institutional review board. The labs will contribute de-identified data for
central data analysis (i.e., eye-tracking raw data/coded gaze behavior, demographic
information). Video recordings of the participants will be stored at each lab according to
the approved local data handling protocol. If allowed by the local institutional review
board, video recordings will be made available to other researchers via the video library
DataBrary (https://nyu.databrary.org/).

In a preliminary expression of interest, 26 labs signed up to 470 contribute a minimal sample size of 16 toddlers and/or adults. Based on this information, 471 we expect to recruit a total sample of 520 toddlers (ages 18-27 months) and 408 adults 472 (ages 18-55 years). To avoid an unbalanced age distribution in the toddlers sample, labs 473 will sign up for testing at least one of two age bins (bin 1: 18-22 months, bin 2: 23-27 474 months), and will be asked to ensure approximately equal distribution of participants' age 475 in their collected sample if possible. They will be asked to try to ensure that the mean age of their sample lies in the middle of the range of the chosen bin and that participant ages 477 are distributed across their whole bin. Both for adults and toddlers, basic demographic data will be collected on a voluntary basis with a brief questionnaire (see Supplemental Material for details). The requested demographic information that is not used in the 480 registered confirmatory and/or exploratory analyses of this study will be collected for

further potential follow-up analyses in spin-off projects within the MB framework. After
completing the task, adult participants will be asked to fill a funneled debriefing
questionnaire. This questionnaire asks what the participant thinks the purpose of the
experiment was, whether the participant had any particular goal or strategy while watching
the videos, and whether the participant consciously tracked the chaser's epistemic state.
Additionally, we collect details regarding each testing session (see Supplemental Material).

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Our final dataset consisted of 1224 participants, with an overall exclusion rate of 490 24.16% (toddlers: 35.60%, adults: 12.67%). Tables 1 A. and B. show the distribution of 491 included participants across labs, eye-tracking methods, and ages. A final sample of 521 492 toddlers (49.14% female) that were tested in 37 labs (mean lab sample size = 14.08, SD =493 5.56, range: 2 - 32) was analyzed. The average age of toddlers in the final sample was 22.49 494 months (SD: 2.53, range: 18 - 27.01). The final sample size of included adults was N = 703495 (68.85% female), tested in 34 labs (mean lab sample size = 20.68, SD = 12.14, range: 8 -496 65). Their mean age was 24.61 years (SD: 7.36, range: 18 - 55). 497

498 Apparatus and Procedure

Eye-tracking Methods. We expect that participating labs will use one of three
types of eye-tracker brands to track the participant's gaze patterns: Tobii, EyeLink, or
SMI. Thus, apparatus setup will slightly vary in individual labs (e.g., different sampling
rates and distances at which the participants are seated in front of the monitor).
Participating labs will report their eye-tracker specifications and study procedure alongside
the collected data. To minimize variation between labs, all labs using the same type of
eye-tracker will use the same presentation study file specific to that eye-tracker type. The

Supplemental Material will provide an overview of employed eye-trackers, stimulus presentation softwares, sampling rates and screen dimensions.

Online Gaze Recording. To allow for the participation of labs that do not have 508 access to an eye-tracker, or are not able to invite participants to their facilities due to 509 current restrictions regarding the COVID-19 pandemic, labs can choose to collect data via 510 online testing. Specifically, labs may choose to manually code gaze direction during 511 stimulus presentation on a frame-by-frame basis from video recordings of a camera facing 512 the participant (e.g., a webcam). Labs that choose to collect data virtually will utilize the 513 platform of their choice (e.g., LookIt, YouTube, Zoom, Labvanced, etc.). Further, labs may 514 also choose to use webcam eye-tracking with tools like WebGazer.js (Papoutsaki et al., 515 2016). In our analyses, we control for and quantify potential sources of variability due to 516 these different methods. 517

Testing Procedure. Toddlers will be seated either on their caregiver's lap or in a 518 highchair. The distance from the monitor will depend on the data collection method. 519 Caregivers will be asked to refrain from interacting with their child and close their eyes 520 during stimulus presentation or wear a set of opaque sunglasses. Adult participants will be 521 seated on a chair within the respective appropriate distance from the monitor. Once the 522 participant is seated, the experimenter will initiate the eye-tracker-specific calibration 523 procedure. Additionally, we will present another calibration stimulus before and after the 524 presentation of the task. This allows for evaluating the accuracy of the calibration 525 procedure across labs (cf., Frank et al., 2012).

27 General Lab Practices

To ensure standardization of procedure, materials for testing practices and instructions will be prepared and distributed to the participating labs. Each lab will be responsible for maintaining these practices and report all relevant details on testing sessions (for details see the Supplemental Material).

Videos of Participants. As with all MB projects, we strongly encourage labs to record video data of their own lab procedures and each testing session, provided that this is in line with regulations of the respective institutional ethics review board and the given informed consent. Participating labs that cannot contribute participant videos will be asked to provide a video walk-through of their experimental set-up and procedure instead.

If no institutional ethics review board restrictions occur, labs are encouraged to share video recordings of the test sessions via DataBrary.

Design Analysis

Here we provide a simulation of the predicted findings because a traditional 540 frequentist power analysis is not applicable for our project for two reasons. First, we use 541 Bayesian methods to quantify the strength of our evidence for or against our hypotheses, 542 rather than assessing the probability of rejecting the null hypothesis. In particular, we 543 compute a Bayes factor (BF; a likelihood ratio comparing two competing hypotheses), 544 which allows us to compare models. Second, because of the many-labs nature of the study, 545 the sample size will not be determined by power analysis, but by the amount of data that 546 participating labs are able to contribute within the pre-established timeframe. Even if the 547 effect size is much smaller than what we anticipate (e.g., less than Cohen's d = 0.20), the results would be informative as our study is expected to be dramatically larger than any 549 previous study in this area. If, due to unforeseen reasons, the participating labs will not be 550 able to collect a minimum number of 300 participants per age group within the proposed 551 time period, we plan to extend the time for data collection until this minimum number is reached. Or in contrast, if the effect size is large (e.g., more than Cohen's d = 0.80), the resulting increased precision of our model will allow us to test a number of other 554 theoretically and methodologically important hypotheses (see Results section). Although 555 we did not determine our sample size based on power analysis, here we provide a 556 simulation-based design analysis to demonstrate the range of BFs we might expect to see, 557

given a plausible range of effect sizes and parameters. We focus this analysis on our key 558 analysis of the test trials (as specified below), namely the difference in AL on the first test 559 trial that participants saw. We describe below the simulation for the child sample, but 560 based on our specifications, we expect that a design analysis for adult data would produce 561 similar results. We first ran a simulation for the first look analysis. In each iteration of our 562 simulation, we used a set of parameters to simulate an experiment, using a first look 563 (described below) as the key measure. For the key effect size parameter for condition 564 (knowledge vs. ignorance), we sampled a range of effect sizes in logit space spanning from 565 small to large effects (Cohen's d = 0.20 - 0.80; log odds from 0.36 - 1.45). For each 566 experiment, the betas for age and the age x condition interaction were sampled uniformly 567 between -0.20 and 0.20. The age of each participant was sampled uniformly between 18 568 and 27 months and then centered. The intercept was sampled from a normal distribution (1, 0.25), corresponding to an average looking proportion of 0.73. Lab intercepts and the 570 lab slope by condition were set to 0.1, and other lab random effects were set to 0 as we do 571 not expect them to be meaningfully non-zero. These values were chosen based on pilot 572 data (average looking proportion), but also to have a large range of possible outcomes (lab 573 intercept, age and age x condition interaction). We are confident that the results would be 574 robust to different choices. We then used these simulated data to simulate an experiment 575 with 22 labs and 440 toddlers and computed the resulting BFs, as specified in the analysis 576 plan below. We adopted all of the priors specified in the results section below³. We ran 349 577 simulations and, in 72% of them, the BF showed strong evidence in favor of the full model 578 (BF > 10); in 6% the BF showed substantial evidence (10 > BF > 3); it was inconclusive 579 14% of the time (1/10 > BF > 3), and in 8% of cases the null model was substantially

³ After the design analysis, additional labs expressed their interest in contributing data, which is why the anticipated sample sizes and the numbers this design analysis is based on differ. Given the uncertainty in determining the final sample size in this project, we kept the design analysis as is to have a more conservative estimate of the study's power.

favored (see Figure 3). In none of the simulations the BF was < 1/10. Thus, under the 581 parameters chosen here for our simulations, it is likely that the planned experiment is of 582 sufficient size to detect the expected effect. We also ran a design analysis for the 583 proportional looking analysis. We used the same experimental parameters (number of labs, 584 participants, ages, etc.). For generating simulated data, we drew the condition effect from 585 a uniform distribution between .05 and .20 (in proportion space). The age and 586 age:condition effects were drawn from uniform distributions between -.05 and .05. Sigma, 587 the overall noise in the experiment, was drawn from a uniform distribution between .05 and 588 .1. The intercept was drawn from a normal distribution with mean .65 and a standard 580 deviation of .05. The by-lab standard deviation for the intercept and condition slope was 590 set to .01. Priors were as described in the main text. We ran 119 simulations, and in all 591 119 we obtained a BF greater than 10, suggesting that, under our assumptions, the study is well-powered.

Data Preprocessing

Eye-tracking. Raw gaze position data (x- and y-coordinates) will be extracted in 595 the time window starting from the first frame at which the chaser enters the tunnel until 596 the last frame before it exits the tunnel in the last familiarisation trial and in the test trial. 597 For data collected from labs using a binocular eye-tracker, gaze positions of the left and the 598 right eye will be averaged. We will use the peekds R package 599 (http://github.com/langcog/peekds) to convert eye-tracking data from disparate trackers 600 into a common format. Because not all eye-trackers record data with the same frequency or regularity, we will resample all data to be at a common rate of 40 Hz (samples per second). We will exclude individual trials if more than 50% of the gaze data is missing (defined as off-screen or unavailable point of gaze during the whole trial, not just the anticipatory 604 period). Applying this criterion would have caused us to exclude 4\% of the trials in our 605 pilot data, which inspection of our pilot data suggested was an appropriate trade-off

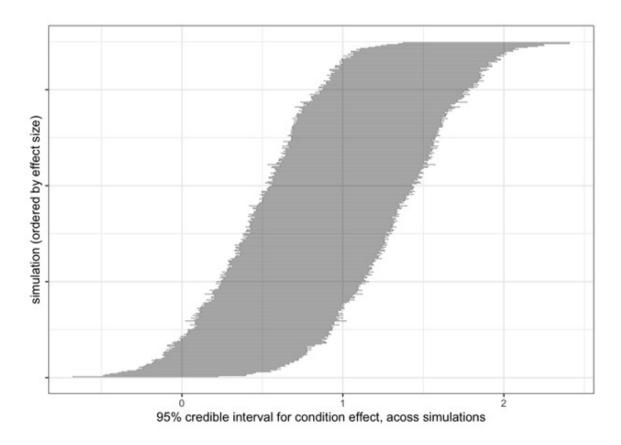


Figure 3. Effect sizes of simulated experiments.

Note. Ordered by effect size (from left to right), 95% credible intervals for the key effect (in logit space) for our simulated experiments that use first look as the dependent variable.

between not excluding too much usable data and not analyzing trials which were uninformative. For each monitor size, we will determine the specific AOIs and compute 608 whether the specific x- and y-position for each participant, trial, and time point fall within 609 their screen resolution-specific AOIs. Our goal is to determine whether participants are 610 anticipating the emergence of the chaser from one of the two tunnel exits. Thus, we defined AOIs on the stimulus by creating a rectangular region around the tunnel exit that is D units from the top, bottom, left, and right of the boundary of the tunnel exit, where D is 613 the diameter of the tunnel exits. We then expanded the sides of the AOI rectangles by 25%614 in all directions to account for tracker calibration error. Our rationale was that, if we made 615 the AOI too small, we might fail to capture anticipations by participants with poor

calibrations. In contrast, if we made the regions too large, we might capture some fixations 617 by participants looking at the box where the chase actually is. On the other hand, these 618 chasee looks would not be expected to vary between conditions and so would only affect our 619 baseline level of looking. Thus, the chosen AOIs aim at maximizing our ability to capture 620 between-condition differences. For an illustration of the tunnel exit AOIs see Figure 4. We 621 are not analyzing looks to the boxes, since they can less unambiguously be interpreted as 622 epistemic state-based action predictions and because we observed few anticipatory looks to 623 the boxes in the pilot studies. For more detailed information about the AOI definition 624 process see the description of the pilot study results in the Supplemental Material. 625

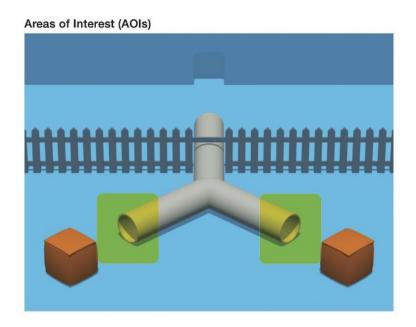


Figure 4. Illustration of Areas of Interest (AOIs) for gaze data analysis during the anticipatory period.

Note. The light green rectangles show the dimensions of the AOIs used for the analysis of AL during the test period.

Manual Coding. For data gathered without an eye-tracker (e.g., videos of participants gathered from online administration), precise estimation of looks to specific AOIs will not be possible. Instead, videos will be coded for whether participants are looking

to the left or the right side of the screen (or "other/off screen"). In our main analysis, during the critical anticipatory window, we will treat these looks identically to looks to the corresponding AOI. See exploratory analyses for analysis of data collected online.

Temporal Region of Interest. For familiarization trials, we define the start of
the anticipatory period (total length = 4000 ms) as starting 120 ms after the first frame
after which the chaser has completely entered the tunnel and lasting until 120 ms after the
first frame at which the chaser is visible again (we chose 120 ms as a conservative value for
cutting off reactive saccades; cf., Yang et al., 2002). For test trials, we define the start of
the anticipatory period in the same way, with a total duration of 4000 ms.

Dependent Variables. We define two primary dependent variables: 1. First look. 638 First saccades will be determined as the first change in gaze occurring within the 639 anticipatory time window that is directed towards one of the AOIs. The first look is then 640 the binary variable denoting the target of this first saccade (i.e., either the correct or 641 incorrect AOI) and is defined as the first AOI where participants fixated at for at least 150 642 ms, as in Rayner et al. (2009). The rationale for this definition was that, if participants are 643 looking at a location within the tunnel exit AOIs before the anticipation period, they might have been looking there for other reasons than action prediction. We therefore count 645 only looks that start within the anticipation period because they more unambiguously 646 reflect action predictions. This further prevents us from running into a situation where we would include a lot of fixations on regions other than the tunnel exit AOIs because participants are looking somewhere else before the anticipation period begins. 2. Proportion DLS (also referred to as total relative looking time; Senju et al., 2009). We compute the proportion looking (p) to the correct AOI during the full 4000 ms anticipatory 651 window (correct looking time / (correct looking time + incorrect looking time)), excluding 652 looks outside of either AOI. 653

Results

55 Confirmatory Analyses

As discussed in the Methods section, we adopted a Bayesian analysis 656 strategy so as to maximize our ability to make inferences about the presence or absence of a condition effect (i.e., our key effect of interest). In particular, we fit Bayesian mixed 658 effects regressions using the package brms in R (Bürkner, 2017). This framework allows us 659 to estimate key effects of interest while controlling for variability across grouping units (in 660 our case, labs). To facilitate interpretation of individual coefficients, we report means and 661 credible intervals. For key inferences in our confirmatory analysis, we use the bridge 662 sampling approach (Gronau et al., 2017) to compute BFs comparing different models. As 663 the ratio of the likelihood of the observed data under two different models, BFs allow us to 664 quantify the evidence that our data provide with respect to key comparisons. For example, 665 by comparing models with and without condition effects, we can quantify the strength of 666 the evidence for or against such effects. Bayesian model comparisons require the 667 specification of proper priors on the coefficients of individual models. Here, for our first 668 look analysis, we use a set of weakly informative priors that capture the expectation that 669 the effects that we observe (of condition and, in some cases, trial order) are modest. For 670 coefficients, we choose a normal distribution with mean of 0 and SD of 2. Based on our 671 pilot testing and the results of MB1, we assume that lab and participant-level variation will 672 be relatively small, and so for the standard deviation of random effects (i.e., variation in 673 effects across labs and, in the case of the familiarization trials, participants) we set a Normal prior with mean of 0 and SD of 0.1. We set an LKJ(2) prior on the correlation matrix in the random effect structure, a prior that is commonly used in Bayesian analyses of this type (Bürkner, 2017). Because the BF is sensitive to the choice of prior, we also ran a secondary analysis with a less informative prior: fixed effect coefficients chosen from a 678 normal distribution with mean 0 and SD of 3, and random effect standard deviations

drawn from a normal prior with a mean of 0 and SD of 0.5. With respect to the 680 specification of random effects, we followed the approach advocated by Barr et al. (2013), 681 that is, specifying the maximal random effect structure justified by our design. Since we 682 are interested in lab-level variation, we will fit random effect coefficients for fixed effects of 683 interest within labs (e.g., condition within lab). Further, where there were participant-level 684 repeated measure data (e.g., familiarization trials), we fitted random effects of participants. 685 For the proportional looking score analysis, we used a uniform prior on the intercept 686 between -0.5 and 0.5 (corresponding to proportional looking scores between 0 and 1: the 687 full possible range). For the priors on the fixed effect coefficients, we used a normal prior 688 with a mean of 0 and an SD of 0.1. Because these regressions are in proportion space, 0.10 689 corresponds to a change in proportion of 10%. For the random effect priors, we used a 690 normal distribution with mean 0 and standard deviation .05. The LKJ prior was specified 691 as above.

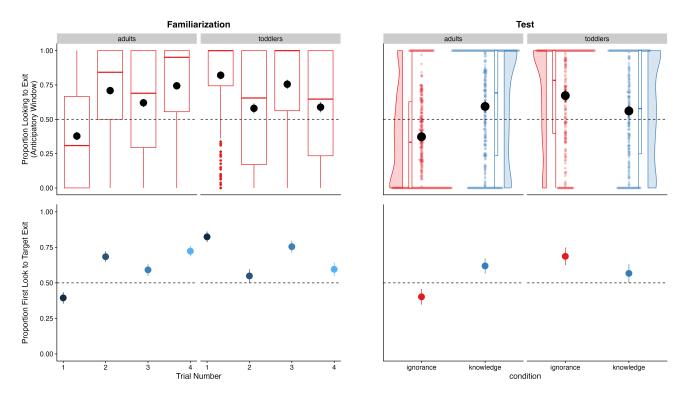


Figure 5. Proportional target looking and proportion of first looks for toddlers and adults during familiarization and test.

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Familiarization Trials. Figure 5 shows the proportion of total relative looking 695 time (non-logit transformed) and proportion of first looks for toddlers and adults plotted 696 across familiarization trials and test trials. Our first set of analyses examined data from 697 the four familiarization trials and asked whether participants anticipated the chaser's 698 reappearance at one of the tunnel exits. In our first analysis, we were interested in whether 699 participants engage in AL during the familiarization trials. To quantify the level of 700 familiarization, we fitted Bayesian mixed effect models predicting target looks based on 701 trial number (1-4) with random effects for lab and participants and random slopes for trial 702 number for each. In R formula notation (which we adopt here because of its relative 703 concision compared with standard mathematical notation), our base model was as follows: 704 $measure \sim 1 + trial \quad number + (trial \quad number | lab) + (trial \quad number | participant)$ We 705 fitted a total of four instances of this model, one for each age group (toddlers vs. adults) 706 and dependent measure (proportion looking score vs. first look). First look models were 707 fitted using a logistic link function. The proportion looking score models were Gaussian. 708 Our key question of interest was whether overall anticipation is higher than chance levels 709 on the familiarization trial immediately before the test trials, in service of evaluating the 710 evidence that participants are attentive and making predictive looks immediately prior to 711 test. To evaluate this question across the four models, we coded trial number so that the 712 last trial before the test trials (trial 4) was set to the intercept, allowing the model 713 intercept to encode an estimate of the proportion of correct anticipation immediately 714 before test. We then fitted a simpler model for comparison $measure \sim 0 + trial \quad number + (trial \quad number | lab) + (trial \quad number | participant),$ which 716 included no intercept term. We then computed the BF comparing this model to the full 717 model. This BF quantified the evidence for an anticipation effect for each group and 718

measure.

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Proportion of total relative looking time.

As first model, we used a Bayesian mixed effects models to predict PTL Toddlers. 721 based on trial number (1-4) for toddlers, with random effects for lab and participants and 722 random slopes for trial number for each. The Bayes factor comparing this model to the 723 simpler null model without the intercept was estimated to be 0.00, strongly favoring the 724 base model over the null model. See also Table 3 for regression coefficients for the base 725 model. These results suggest a significant effect of trial number on PTL, with the negative 726 coefficient indicating a decrease in PTL across the familiarization trials. The strong Bayes 727 factor provides substantial evidence in support of the base model, highlighting its 728 robustness in explaining the data compared to the null model. In addition, toddlers' mean 720 PTL of 0.69 significantly differed from chance, t(519) = 21.03, p < .001, suggesting that 730 toddlers successfully anticipated during the familiarization trials. 731

Next, we used a Bayesian mixed effects model to predict PTL based on trial 732 number (1-4) for adults, again with random effects for lab and participants and random 733 slopes for trial number for each. The Bayes factor comparing this model to the simpler null 734 model without the intercept was estimated to be 286,393.36, strongly favoring the base 735 model over the null model. These results suggest a significant effect of trial number on PTL, with the positive coefficient indicating an increase in target looks across the familiarization trials. The strong Bayes factor provides substantial evidence in support of the base model, highlighting its robustness in explaining the data compared to the null model. In addition, adults' mean PTL of 0.60 significantly differed from chance, t(696) =12.19, p < .001, suggesting that adults successfully anticipated during the familiarization trials. 742

Proportion of first looks.

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Investigating proportion of first looks for toddlers, we again used a 744 Bayesian mixed effects model to predict target looks based on trial number (1-4), with 745 random effects for lab and participants and random slopes for trial number for each. The 746 Bayes factor comparing the base model to the simpler model was estimated to be 747 286,393.36, strongly favoring the base model over the null model. There was a significant 748 effect of trial number on proportion of first looks, with the negative coefficient indicating a 749 decrease in target looks across the familiarization trials. The strong Bayes factor provides 750 substantial evidence in support of the base model, highlighting its robustness in explaining 751 the data compared to the null model. Using binomal test, the proportion of first looks of 752 0.69 significantly differed from chance, t(519) = 21.03, p < .001, suggesting that toddlers 753 successfully anticipated during the familiarization trials. 754

Comparing the Bayesian mixed effects model of adults predicting proportion 755 of first looks based on trial number (1-4), with random effects for lab and participants and 756 random slopes for trial number for each with the simpler model without an intercept, we 757 computed a Bayes factor of 286,393.36, strongly favoring the base model over the null 758 model. There was a significant effect of trial number on proportion of first looks, with the 759 positive coefficient indicating an increase in proportion of first target looks across the familiarization trials. The strong Bayes factor provides substantial evidence in support of the base model, highlighting its robustness in explaining the data compared to the null 762 model. Using binomal test, the proportion of first looks of 0.69 significantly differed from 763 chance, t(519) = 21.03, p < .001, suggesting that toddlers successfully anticipated during 764 the familiarization trials. 765

Test Trials. We focused our confirmatory analysis on the first test trial (see
Exploratory Analysis section for an analysis of both trials). Our primary question of
interest was whether AL differs between conditions (knowledge vs. ignorance, coded as
-.5/.5) and by age (in months, centered). For child participants, we fitted models with the
specification:

 $measure\ 1 + condition + age + condition : age + (1 + condition + age + condition : age | lab).$ 771 For adult participants, we fitted models with the specification 772 measure 1 + condition + (1 + condition | lab). Again, we fitted models with a logistic link 773 for first look analyses and with a standard linear link for DLS. In each case, our key BF 774 was a comparison of this model with a simpler "null" model that did not include the fixed 775 effect of condition but still included other terms. We take a BF > 3 in favor of a particular 776 model as substantial evidence and a BF > 10 in favor of strong evidence. A BF < 1/3 is 777 taken as substantial evidence in favor of the simpler model, and a BF < 1/10 as strong 778 evidence in favor of the simpler model. For the model of data from toddlers, we 779 additionally were interested in whether the model shows changes in AL with age. We 780 assessed evidence for this by computing BFs related to the comparison with a model that 781 did not include an interaction between age and condition as fixed effects

 $measure\ 1 + condition + age + (1 + condition + age + condition : age | lab).$

These BFs captured the evidence for age-related changes in the difference in action 783 anticipation between the two conditions. It is important to note that in the case of a null 784 effect, there are two main explanations: (1) toddlers and adults in our study do not 785 distinguish between knowledgeable and ignorant agents when predicting their actions. (2) 786 The method used is not appropriate to reveal knowledge/ignorance understanding. By 787 using Bayesian analyses, we are able to better evaluate the first of these two possibilities: 788 The BF provides a measure of our statistical confidence in the null hypothesis, i.e., no 789 difference between experimental conditions, given the data in ways that standard null 790 hypothesis significance testing does not. In other words, instead of merely concluding that we did not find a difference between conditions, we would be able to find no/anecdotal/moderate/strong/very strong/extreme evidence for the null hypothesis that 793 our participants did not distinguish between knowledgeable and ignorant agents when predicting their actions (Schönbrodt & Wagenmakers, 2018). We therefore consider this 795 analysis an important addition to our overall analysis strategy. Yet, even our Bayesian 796

analyses are not able to rule out the second possibility that participants may well show
such knowledge/ignorance understanding with different methods, or that this ability may
not be measurable with any methods available at the current time. Addressing this
alternative explanation warrants follow up experiments.

Proportion of total relative looking time.

801

As first model, we used a Bayesian mixed effects models to predict PTL 802 based on condition for toddlers, with random effects for lab and participants and random 803 slopes for trial number for each. The Bayes factor comparing this model to the simpler null 804 model without the intercept was estimated to be 0.00, strongly favoring the base model 805 over the null model. Table 4 shows the statistics for regression coefficients of the base 806 model. These results suggest a significant effect of trial number on PTL, with the negative 807 coefficient indicating a decrease in PTL across the familiarization trials. The strong Bayes 808 factor provides substantial evidence in support of the base model, highlighting its 800 robustness in explaining the data compared to the null model. In addition, toddlers' mean 810 PTL of 0.69 significantly differed from chance, t(519) = 21.03, p < .001, suggesting that 811 toddlers successfully anticipated during the familiarization trials. 812

Next, we used a Bayesian mixed effects model to predict PTL based on trial 813 number (1-4) for adults, again with random effects for lab and participants and random 814 slopes for trial number for each. The Bayes factor comparing this model to the simpler null 815 model without the intercept was estimated to be 286,393.36, strongly favoring the base 816 model over the null model. These results suggest a significant effect of trial number on 817 PTL, with the positive coefficient indicating an increase in target looks across the familiarization trials. The strong Bayes factor provides substantial evidence in support of 819 the base model, highlighting its robustness in explaining the data compared to the null model. In addition, adults' mean PTL of 0.60 significantly differed from chance, t(696) =821 12.19, p < .001, suggesting that adults successfully anticipated during the familiarization 822 trials. 823

Proportion of first looks.

824

Toddlers. Investigating proportion of first looks for toddlers, we again used a 825 Bayesian mixed effects model to predict target looks based on trial number (1-4), with random effects for lab and participants and random slopes for trial number for each. The Bayes factor comparing the base model to the simpler model was estimated to be 828 286,393.36, strongly favoring the base model over the null model. There was a significant 820 effect of trial number on proportion of first looks, with the negative coefficient indicating a 830 decrease in target looks across the familiarization trials. The strong Bayes factor provides 831 substantial evidence in support of the base model, highlighting its robustness in explaining 832 the data compared to the null model. Using binomal test, the proportion of first looks of 833 0.69 significantly differed from chance, t(519) = 21.03, p < .001, suggesting that toddlers 834 successfully anticipated during the familiarization trials. 835

Comparing the Bayesian mixed effects model of adults predicting proportion Adults. 836 of first looks based on trial number (1-4), with random effects for lab and participants and 837 random slopes for trial number for each with the simpler model without an intercept, we 838 computed a Bayes factor of 286,393.36, strongly favoring the base model over the null 839 model. There was a significant effect of trial number on proportion of first looks, with the 840 positive coefficient indicating an increase in proportion of first target looks across the 841 familiarization trials. The strong Bayes factor provides substantial evidence in support of 842 the base model, highlighting its robustness in explaining the data compared to the null model. Using binomal test, the proportion of first looks of 0.69 significantly differed from chance, t(519) = 21.03, p < .001, suggesting that toddlers successfully anticipated during 845 the familiarization trials.

Exploratory Analyses

[WE LIST POTENTIAL EXPLORATORY ANALYSES HERE TO SIGNAL OUR INTEREST AND INTENTIONS BUT DO NOT COMMIT TO THEIR INCLUSION,

DUE TO LENGTH AND OTHER CONSIDERATIONS 1. Spill-over: we will analyze 850 within-participants data from the second test trial that participants saw, using exploratory 851 models to assess whether (1) findings are consistent when both trials are included (overall 852 condition effect). (2) whether effects are magnified or diminished on the second trial (order 853 main effect), and (3) whether there is evidence of "spillover" - dependency in anticipation 854 on the second trial depending on what the first trial is (condition x order interaction 855 effect). 2. We will explore whether condition differences vary for participants who show 856 higher rates of anticipation during the four familiarization trials. For example, we might 857 group participants according to whether they did or did not show correct AL at the end of 858 the familiarization phase, defined as overall longer looking at the correct AOI than the 859 incorrect AOI on average in trials 3 and 4 of the familiarization phase. 3. In analyses 860 introducing model terms for certain measurement characteristics (e.g., types of eye-tracker manufacturers, screen dimensions), we will quantify potential variability between different in-lab data acquisition methods (cf., ManyBabies Consortium, 2020). If we have a sufficiently large sample of participants tested with online sources (e.g., contributions of at 864 least 32 participants), we will conduct a separate analysis with a model term for online 865 participants that estimates whether condition effects are different in this population. We 866 will further report whether exclusion rates are different for this population. 4. If we 867 observe substantial looking (defined post hoc by evaluating scatter plot videos of gaze data) 868 to the boxes as well as the tunnel exit AOIs, we will conduct an exploratory analysis using 869 tighter AOIs around tunnel exits and boxes, asking whether box and tunnel looking vary 870 separately by age or by condition. In particular, we expect that the difference in AL 871 between the two conditions will be bigger for the tunnel exits than for the box (as looks to 872 the correct box might indicate looks to the target, which is in the same box for both 873 conditions, rather than action anticipation).

General Discussion

The current large-scale, multi-lab study set out to examine whether toddlers and 876 adults engage in spontaneous ToM. In particular, we used an anticipatory looking 877 paradigm to explore whether 18- to 27-month-old toddlers and adults distinguish between 878 two basic forms of epistemic states: knowledge and ignorance. Our call for participation 879 resulted in contributions from 47 labs, representing a total of 809 toddlers from xyz 880 countries and 805 adults from xyz countries, of which 1224 were included in the final 881 sample used for analysis (see Table 1). We begin our discussion by summarizing the 882 principal results of the study with respect to confirmatory analysis and then discuss limitations of the study as well as future directions.

55 Conclusion

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Lab	N collected	N included	Sex (N Female)	Mean Age (years)	Method
CogConcordia	21	16	11	22.12	In-lab
CorbitLab	16	15	14	19.87	In-lab
DevlabAU	20	20	15	25.15	In-lab
MEyeLab	53	53	39	24.47	In-lab
MiniDundee	15	13	10	30.23	In-lab
PKUSu	39	32	19	22.66	In-lab
SkidLSDLab	11	8	3	21.62	In-lab
ToMcdlSalzburg	33	31	22	27.23	In-lab
UIUCinfantlab	36	32	25	19.06	In-lab
WSUMARCS	18	13	8	29.85	In-lab
$\operatorname{affcogUTSC}$	23	8	5	20.88	web-based
babyLeidenEdu	20	16	12	23.31	In-lab
${\it babylabAmsterdam}$	17	16	13	24.00	In-lab
babylabBrookes	67	65	49	21.78	In-lab
babylabINCC	18	18	12	31.00	In-lab
babylabMPIB	16	16	11	27.44	In-lab
babylabNijmegen	19	15	13	22.13	In-lab
babylabTrento	16	16	9	21.69	In-lab
babylab Umassb	33	11	10	19.00	In-lab
babyuniHeidelberg	16	16	14	22.06	In-lab
beinghumanWroclaw	19	16	9	32.75	web-based
careylabHarvard	18	15	12	19.80	In-lab
$\operatorname{cclUNIRI}$	32	32	17	30.53	In-lab
${\it child devlab Ashoka}$	16	16	8	30.88	In-lab
collabUIOWA	16	16	10	19.19	In-lab
gaugGöttingen	30	28	18	31.71	In-lab
jmuCDL	32	32	22	18.81	In-lab
${\bf kids dev Uniof New castle}$	15	14	7	33.57	In-lab
labUNAM	20	11	8	22.45	In-lab

Table 2 continued

Lab	N collected	N included	Sex (N Female)	Mean Age (years)	Method
lmuMunich	31	30	23	22.53	In-lab
mecdmpihcbs	19	19	10	27.79	In-lab
social cog Umiami	16	15	9	19.27	In-lab
sociocognitivelab	17	17	11	32.12	In-lab
tauccd	15	12	6	24.50	In-lab
Total	803	703	484	24.75	

 $\label{eq:labeleq:la$

Lab	N collected	N included	Sex (N Female)	Mean Age (months)	Method
CogConcordia	21	8	4	22.92	web-based
CorbitLab	11	10	5	22.77	In-lab
DevlabAU	18	17	8	19.00	In-lab
PKUSu	50	32	13	20.84	In-lab
${\bf SkidLSDLab}$	8	2	0	20.11	In-lab
${\bf ToMcdlSalzburg}$	17	12	6	22.20	In-lab
UIUCinfantlab	18	15	9	21.96	In-lab
babyLeidenEdu	18	12	8	22.59	In-lab
${\it babylabAmsterdam}$	28	12	6	23.19	In-lab
${\it babylabBrookes}$	17	12	7	22.15	In-lab
babylabChicago	17	13	4	20.10	In-lab
babylabINCC	16	9	6	23.40	In-lab
babylabNijmegen	19	10	3	23.52	In-lab
${\it babylabOxford}$	25	19	8	23.42	In-lab
${\it babylabPrinceton}$	17	11	7	22.15	In-lab
babylab Trento	18	17	10	22.72	In-lab
babylab Umassb	7	6	2	20.35	In-lab
babylingOslo	17	14	7	21.99	In-lab
babyuniHeidelberg	16	12	4	22.69	In-lab
beinghumanWroclaw	24	14	7	23.77	web-based
careylabHarvard	17	12	5	21.99	In-lab
cecBYU	16	14	4	22.39	In-lab
child devlab A shoka	16	10	6	22.44	In-lab
${\rm gaug} G\"{\rm o}ttingen$	28	15	9	23.06	In-lab
gertlabLancaster	21	17	8	23.03	In-lab
in fant cog UBC	26	19	8	24.39	In-lab
irlConcordia	19	12	5	22.47	In-lab
${\bf kids dev Uniof New castle}$	16	14	9	22.36	In-lab
kokuHamburg	19	14	7	25.99	In-lab

Table 2 continued

Lab	N collected	N included	Sex (N Female)	Mean Age (months)	Method
labUNAM	18	12	7	22.68	In-lab
lmuMunich	48	24	16	22.68	In-lab
mecdmpihcbs	25	12	8	23.58	In-lab
mpievaCCP	22	18	10	23.33	In-lab
saxelab	31	15	2	23.13	web-based
socallabUCSD	47	15	4	22.09	web-based
tauccd	15	12	8	22.99	In-lab
unicph	43	29	16	21.50	In-lab
Total	809	521	256	22.48	

Table 3 $Results\ of\ the\ Bayesian\ mixed\ effects\ models\ for\ the\ familiarization$ trials.

model	term	estimate	std.error	conf.low	conf.high
PTL toddlers	Intercept	0.12	0.02	0.09	0.15
PTL toddlers	Trial number	-0.05	0.01	-0.06	-0.03
PTL adults	Intercept	0.26	0.02	0.23	0.29
PTL adults	Trial number	0.10	0.01	0.09	0.11
First Look toddlers	Intercept	0.44	0.09	0.27	0.62
First Look toddlers	Trial number	-0.22	0.05	-0.32	-0.12
First Look adults	Intercept	1.03	0.09	0.86	1.20
First Look adults	Trial number	0.38	0.04	0.30	0.47

 $\label{eq:Results} \begin{tabular}{ll} Table 4 \\ Results of the Bayesian mixed effects models for the test trials. \\ \end{tabular}$

model	term	estimate	std.error	conf.low	conf.high
PTL toddlers	Intercept	0.61	0.02	0.58	0.65
PTL toddlers	Condition	0.10	0.03	0.03	0.16
PTL toddlers	Age	0.01	0.01	-0.01	0.02
PTL toddlers	Condition x Age	-0.01	0.02	-0.04	0.02
PTL adults	Intercept	0.48	0.02	0.45	0.51
PTL adults	Condition	-0.20	0.03	-0.26	-0.15
First Look toddlers	Intercept	0.52	0.11	0.32	0.72
First Look toddlers	Condition	0.53	0.21	0.11	0.93
First Look toddlers	Age	0.06	0.04	-0.03	0.14
First Look toddlers	Condition x Age	-0.13	0.09	-0.31	0.05
First Look adults	Intercept	0.05	0.09	-0.13	0.22
First Look adults	Condition	-0.89	0.17	-1.21	-0.56