Action Anticipation Based on an Agent's Epistemic State in Toddlers and Adults

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Abstract

Do toddlers and adults engage in spontaneous Theory of Mind (ToM)? Evidence from 165 anticipatory looking (AL) studies suggests they do. But a growing body of failed 166 replication studies raised questions about the paradigm's suitability, urging the need to test 167 the robustness of AL as a spontaneous measure of ToM. In a multi-lab collaboration we 168 examine whether 18- to 27-month- olds' and adults' anticipatory looks distinguish between 169 two basic forms of epistemic states: knowledge and ignorance. In adults [n = 703] included, 170 68 % FEMALE], we found clear support for epistemic state-based action anticipation: they 171 engaged in simple goal-based action anticipation in pilot studies, and clearly differentiated 172 between knowledge and ignorance conditions in the main study as predicted. In toddlers [n 173 = 521 included, 49 % FEMALE], in contrast, the results were less clear. They did engage in simple goal-based action anticipation in pilot studies, but did not show the clear differentiation between knowledge and ignorance conditions in the main study as predicted. 176 Future research with adults can now move on to probe whether their spontaneous action 177 anticipation is also sensitive to more complex kinds of epistemic states, such as true and 178 false beliefs. Future research with toddlers will first need to investigate more systematically 179 the source of the puzzling findings in the present study and clarify whether they indicate 180 competence or mere performance limitations. 181

Keywords: anticipatory looking; spontaneous Theory of Mind; replication

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Action Anticipation Based on an Agent's Epistemic State in Toddlers and Adults

The capacity to represent epistemic states, known as Theory of Mind (ToM) or 185 mentalizing, plays a central role in human cognition (Dennett, 1989; Frith & Frith, 2006; 186 Premack & Woodruff, 1978). Although ToM has been under intense scrutiny in the past 187 decades, its nature and ontogeny are still the subjects of much controversy. At the heart of 188 these debates are questions about the reliability of the tools used to measure ToM 189 (Baillargeon, Buttelmann, & Southgate, 2018; e.g., Poulin-Dubois et al., 2018), among 190 others, anticipatory looking (AL) paradigms. To address this issue, in a collaborative long-term project we assess the robustness of infants' and adults' tendency to 192 spontaneously take into account different kinds of epistemic states — what they perceive, know, think, or believe — when predicting others' behaviors. This paper reports the first foundational step of this project, which focuses on the most basic epistemic state 195 ascription: the capacity to distinguish between knowledgeable and ignorant individuals. 196 Simple forms of knowledge attribution (such as tracking what other individuals have seen 197 or experienced) are typically assumed to develop early and to operate spontaneously 198 throughout the lifespan (Liszkowski, Carpenter, & Tomasello, 2007; e.g., Luo & 190 Baillargeon, 2007; O'Neill, 1996; Phillips et al., 2021). Thus, evaluating whether ToM 200 measures are sensitive to the knowledge-ignorance distinction is a crucial test case to assess 201 their robustness. The present paper investigates this question in an AL paradigm including 202 18-27-month-old infants and adults. 203

In the following sections we first establish the background and scientific context of
this study, namely the reliability and replicability of spontaneous ToM measures. We then
introduce a novel way to approach these issues: a large-scale collaborative project targeting
the replicability of ToM findings. Finally, we outline the rationale of the present study
which uses an AL paradigm to test whether infants and adults distinguish between two
basic forms of an agent's epistemic state: knowledge and ignorance.

# Spontaneous Theory of Mind tasks

Humans are proficient at interpreting and predicting others' intentional actions. 211 Adults as well as infants expect agents to act persistently towards the goal they pursue 212 Woodward & Sommerville (2000), and anticipate others' actions based on their goals even 213 before goals are achieved - that is, humans engage in goal-based action anticipation (for 214 review, see Elsner & Adam, 2021; but see Ganglmayer, Attig, Daum, & Paulus, 2019). To 215 predict others' actions, however, it is essential to consider their epistemic state: what they 216 perceive, know, or believe. A number of seminal studies using non-verbal spontaneous 217 measures have suggested that infants, toddlers, older children, and adults show action 218 anticipation and action understanding not only based on other agents' goals (what they want) but also on the basis of their epistemic status (what they perceive, know, or believe). These studies suggest that from infancy onwards, humans spontaneously engage in ToM or 221 mentalizing. For example, studies using violation of expectation methods have 222 demonstrated that infants look longer in response to events in which an agent acts in ways 223 that are incompatible with their (true or false) beliefs, compared to events in which they 224 act in belief-congruent ways (Onishi & Baillargeon, 2005; Surian, Caldi, & Sperber, 2007; 225 Träuble, Marinović, & Pauen, 2010). Other studies have employed more interactive tasks 226 requiring the child to play, communicate, or cooperate with experimenters and, for example, 227 give an experimenter one of several objects as a function of their epistemic status. Such 228 studies have shown that toddlers spontaneously adjust their behavior to the experimenter's 220 beliefs (D. Buttelmann, Carpenter, & Tomasello, 2009; Király, Oláh, Csibra, & Kovács, 230 2018; Knudsen & Liszkowski, 2012; Southgate, Johnson, Karoui, & Csibra, 2010). 231

The largest body of evidence for spontaneous ToM comes from studies using AL
tasks. In such tasks, participants see an agent who acts in pursuit of some goal (typically,
to collect a certain object) and has either a true or a false belief (for example, regarding
the location of the target object). A number of studies have shown that infants, toddlers,

older children, neurotypical adults, and even non-human primates anticipate (indicated by looks to the location in question) that an agent will go where it (truly or falsely) believes 237 the object to be rather than, irrespective of the actual location of the object (Gliga, Jones, 238 Bedford, Charman, & Johnson, 2014; Grosse Wiesmann, Friederici, Singer, & Steinbeis, 239 2017; Hayashi et al., 2020; Kano, Krupenye, Hirata, Tomonaga, & Call, 2019; Krupenye, 240 Kano, Hirata, Call, & Tomasello, 2016; Meristo et al., 2012; Schneider, Bayliss, Becker, & 241 Dux, 2012; Schneider, Slaughter, Bayliss, & Dux, 2013; Senju et al., 2010; Senju, 242 Southgate, Snape, Leonard, & Csibra, 2011; Senju, Southgate, White, & Frith, 2009; 243 Surian & Franchin, 2020; Thoermer, Sodian, Vuori, Perst, & Kristen, 2012). These studies 244 have revealed converging evidence for spontaneous ToM across the human lifespan and 245 even in other primate species. 246

Across the different measures, the majority of early works on spontaneous ToM in 247 infants and toddlers have reported positive results in the second year of life, and a few 248 studies even within the first year (Kovács, Téglás, & Endress, 2010; Luo, 2011; Southgate 249 & Vernetti, 2014), yielding a rich body of coherent and convergent evidence (for reviews see 250 e.g., Barone, Corradi, & Gomila, 2019; Kampis, Buttelmann, & Kovács, 2020; Scott & 251 Baillargeon, 2017). This growing body of literature has led to a theoretical transformation of the field. In particular, findings with young infants have paved the way for novel 253 accounts of the development and cognitive foundations of ToM. The previous consensus was that full-fledged ToM emerges only at around age 4, potentially as the result of developing 255 executive functions, complex language skills and other factors (e.g., Perner, 1991; Wellman 256 & Cross, 2001). In contrast, the newer accounts proposed that some basic forms of ToM 257 may be phylogenetically more ancient and may develop much earlier in ontogeny (e.g., 258 Baillargeon, Scott, & He, 2010; Carruthers, 2013; Kovács, 2016; Leslie, 2005). 259

Recently, however, a number of studies have raised uncertainty regarding the
empirical foundations of the early-emergence theories, as we review below. In the following
sections, we present an overview of the current empirical picture of early understanding of

epistemic states and then introduce ManyBabies2 (MB2), a large-scale collaborative project exploring the replicability of ToM in infancy, of which the current study constitutes the first step.

# Replicability of Spontaneous Theory of Mind Tasks

A number of failures to replicate findings from spontaneous ToM tasks have recently 267 been published with infants, toddlers, and adults (e.g., Burnside, Ruel, Azar, & Poulin-Dubois, 2018; Dörrenberg, Rakoczy, & Liszkowski, 2018; Grosse Wiesmann et al., 269 2017; Kampis, Karman, Csibra, Southgate, & Hernik, 2021; Kulke, Duhn, Schneider, & 270 Rakoczy, 2018; Kulke & Hinrichs, 2021; Kulke, Johannsen, & Rakoczy, 2019; Kulke & 271 Rakoczy, 2017, 2019; Kulke, Reiß, Krist, & Rakoczy, 2018; Kulke, Wübker, & Rakoczy, 272 2019; Powell, Hobbs, Bardis, Carey, & Saxe, 2018; Priewasser, Fowles, Schweller, & Perner, 273 2020; Priewasser, Rafetseder, Gargitter, & Perner, 2018; Schuwerk, Priewasser, Sodian, & 274 Perner, 2018; Wiesmann, Friederici, Disla, Steinbeis, & Singer, 2018; for overviews, see 275 Barone et al., 2019; Kulke & Rakoczy, 2018). Besides conceptual replications, many of 276 these studies involve more direct replication attempts with the original stimuli and 277 procedures. One of these was a two-lab replication attempt of one of the most influential 278 AL studies (Southgate, Senju, & Csibra, 2007). This failure to replicate is especially 279 notable not only because of the influence of the original finding of the field, but also 280 because of the large sample size and the involvement of some of the original authors 281 (Kampis et al., 2021). Additional unpublished replication failures have also been reported. 282 Kulke and Rakoczy (2018) examined 65 published and non-published studies including 36 AL studies (replications of Schneider et al., 2012; Southgate et al., 2007; Surian & Geraci, 2012; and Low & Watts, 2013), as well as studies using other paradigms, and classified them as a successful, partial, or non-replication, depending on whether all, some, or none of the original main effects were found. Although no formal analysis of effect size was carried 287 out, overall, non-replications and partial replications outnumbered successful replications, 288

regardless of the method used. In addition to the failure to replicate spontaneous 289 anticipation of agents' behaviors based on their beliefs, many of the replication studies 290 revealed an even more fundamental problem of spontaneous AL procedures: a failure to 291 adequately anticipate an agent's action in the absence of a belief. That is, researchers did 292 not find evidence for spontaneous anticipation of agents' behaviors based on their goals, 293 even in the initial familiarization trials of the experiments, where the agent's beliefs do not 294 play any role vet (e.g., Kampis et al., 2020; Kulke, Reiß, et al., 2018; Schuwerk et al., 295 2018). The familiarization trials are designed to convey the goal of the agent, as well as the 296 general timing and structure of events, to set up participants' expectations in the test trials 297 where the agent's epistemic state is then manipulated. Typically, the last familiarization 298 trial can also be used to probe participants' spontaneous action anticipation; and test trials 299 can only be meaningfully interpreted if there is evidence of above-chance anticipation in the familiarization trials. In several AL studies many participants had to be excluded from the main analyses for failing to demonstrate robust action anticipation during the familiarization trials (e.g., Kampis et al., 2020; Kulke, Reiß, et al., 2018; Schuwerk et al., 303 2018; Southgate et al., 2007). This raises the possibility that these paradigms may not be 304 suitable for reliably eliciting spontaneous action prediction in the first place (for discussion see Baillargeon et al., 2018). In sum, in light of the complex and mixed state of the 306 evidence, it currently remains unclear whether infants, toddlers, and adults engage in 307 spontaneous ToM. This calls for systematic, large-scale, a priori designed multi-lab study 308 that stringently tests for the robustness, reliability, and replicability of spontaneous 309 measures of ToM. 310

#### General Rationale of MB2

To this end, ManyBabies 2 (MB2) was established as an international consortium
dedicated to investigating infants' and toddlers' ToM skills. The main aim is to test the
replicability and thus reliability of findings from spontaneous ToM tasks. In the long-term,

MB2 will build on the initial findings and the aim will be extended to include testing the validity of these experimental designs and addressing theoretical accounts of spontaneous 316 ToM. MB2 operates under the general umbrella of ManyBabies (MB), a large-scale 317 international research consortium founded with the aim of probing the reliability of central 318 findings from infancy research. In particular, MB projects bring together large and 319 theoretically diverse groups of researchers to tackle pressing questions of infant cognitive 320 development, by collaboratively designing and implementing methodologies and 321 pre-registered analysis plans (Frank et al., 2017). The MB2 consortium involves authors of 322 original studies as well as authors of both successful and failed replication studies, and 323 researchers from very different theoretical backgrounds. It thus presents a case of true 324 "adversarial collaboration" (Mellers, Hertwig, & Kahneman, 2001). 325

# Rationale of the Present Study

Based on both theoretical and practical considerations, the current paper presents 327 the first foundational step in MB2, focusing on AL measures. It investigates whether 328 toddlers and adults anticipate (in their looking behavior) how other agents will act based 329 on their goals (i.e., what they want) and epistemic status (i.e., what they know or do not 330 know). From a practical perspective, we focus on AL since it is a child-friendly and widely 331 used method that is also suitable for humans across the lifespan and even other species. 332 Additionally, as AL is screen-based and standardizable, identical stimuli can be presented 333 in different labs. From a theoretical perspective, given the mixed findings with AL tasks 334 reviewed in the previous section, we take a systematic and bottom-up approach. First, we probe whether AL measures are suitable for measuring spontaneous goal-directed action anticipation. With the aim to improve the low overall rates of anticipatory looks in recent 337 studies, we designed new, engaging stimuli to test whether these are successful in eliciting 338 spontaneous action anticipation. Second, in case reliably elicited action anticipation can be 339 found: we probe whether toddlers and adults take into account the agent's epistemic status

in their spontaneous goal-based action anticipation. That is, do they track whether the 341 agent saw or did not see a crucial event, and therefore whether this agent does or does not 342 know something? In the current study we focus on the most basic form of tracking the 343 epistemic status of agents: considering whether they had access to relevant information, 344 and whether they are thus knowledgeable or ignorant. We reasoned that only after 345 establishing whether a context can elicit spontaneous tracking of an agent's epistemic 346 status in a more basic sense (i.e., the agent's knowledge vs. ignorance) is it eventually 347 meaningful to ask whether this context also elicits more complex epistemic state tracking 348 (i.e., the agent's beliefs). Answering these first two questions in the present study will 349 allow us, in the long run, to address a third set of questions in subsequent studies, probing 350 the nature of the representations and cognitive mechanisms involved in infant ToM. Do 351 toddlers and adults engage in full-fledged belief-ascription in their spontaneous goal-based 352 action anticipation? What kind of epistemic states do toddlers and adults spontaneously 353 attribute to others in their action anticipation (e.g., Horschler, MacLean, & Santos, 2020; 354 Phillips et al., 2021)? Do the results that prove replicable really assess ToM, or can they be 355 interpreted in alternative ways such as behavioral rules, associations, or simple perceptual 356 preferences (see, e.g., Heyes, 2014; Perner & Ruffman, 2005)? The present study lays the 357 foundation for investigating these questions. Regarding the knowledge-ignorance 358 distinction, many accounts in developmental and comparative ToM research have argued 359 for the ontogenetic and evolutionary primacy of representing what agents witness and 360 represent, relative to more sophisticated ways of representing how agents represent (and 361 potentially mis-represent) objects and situations (e.g., Apperly & Butterfill, 2009; Flavell, 362 1988; Kaminski, Call, & Tomasello, 2008; Martin & Santos, 2016; Perner, 1991; Phillips et 363 al., 2021). For example, it is often assumed that young children and non-human primates 364 may be capable of so-called "Level I perspective-taking" (understanding who sees what) but 365 only human children from around age 4 may finally develop capacities for "Level II 366 perspective-taking" [understanding how a given situation may appear to different agents; 367

Flavell, Everett, Croft, and Flavell (1981). Empirically, many studies using verbal and/or interactive measures have indicated that children may engage in knowledge-ignorance and 369 related distinctions before they engage in more complex forms of meta-representation (e.g., 370 Flavell et al., 1981; Hogrefe, Wimmer, & Perner, 1986; Moll & Tomasello, 2006; O'Neill, 371 1996; F. Buttelmann & Kovács, 2019; F. Buttelmann, Suhrke, & Buttelmann, 2015; 372 Kampis et al., 2020; though for some findings indicating Level II perspective-taking at an 373 early age see Scott & Baillargeon, 2009; Scott, Richman, & Baillargeon, 2015), and that 374 non-human primates seem to master knowledge-ignorance tasks while not demonstrating 375 any more complex, meta-representational form of ToM (e.g., Hare, Call, & Tomasello, 2001; 376 Kaminski et al., 2008; Karg, Schmelz, Call, & Tomasello, 2015). The knowledge-ignorance 377 distinction thus appears to be an ideal candidate for assessing epistemic status-based 378 action anticipation in a wide range of populations. To date, however, no study has probed whether or how children's (and adults') spontaneous action anticipation, as indicated by AL, is sensitive to ascriptions of knowledge vs. ignorance. Most studies that have addressed ToM with AL measures have targeted the more sophisticated true/false belief contrast. As 382 reviewed above, the results of those studies yield a mixed picture regarding replicability of 383 the findings. It has been argued that tasks that reliably replicate are ones which can be 384 solved with the more basic knowledge-ignorance distinction, whereas tasks that do not 385 replicate require more sophisticated belief-ascription (Powell et al., 2018)<sup>1</sup>, suggesting that 386 only some but not all findings might not be replicable. Based on these considerations, the 387 present study tests whether toddlers and adults engage in knowledge- and ignorance-based 388 AL to probe the most basic form of spontaneous, epistemic state-based action anticipation. 380

<sup>&</sup>lt;sup>1</sup> For example, some studies have found partial replication results, with patterns of the following kind: participants showed systematic anticipation (or appropriate interactive responses) in true belief trials but showed ooking (or interactive responses) at chance level in the false belief trials (e.g., Dörrenberg, Wenzel, Proft, Rakoczy, & Liszkowski, 2019; Kulke, Reiß, et al., 2018; Powell et al., 2018). Such a pattern remains ambiguous since it may merely reflect a knowledge-ignorance distinction.

#### Design and Predictions of the Present Study

The current study presents 18- to 27-month-old toddlers and adults with animated 391 scenarios while measuring their gaze behavior. Testing adults (and not just toddlers) is 392 crucial to address debates about the validity and interpretation of AL measures of ToM 393 throughout the lifespan (e.g., Schneider, Slaughter, & Dux, 2017). Following the structure of previous AL paradigms, participants are first familiarized to an agent repeatedly approaching a target (familiarization trials). AL is measured during familiarization trials 396 to probe whether participants understood the agent's goal and spontaneously anticipate 397 their actions. Subsequently, during test trials the agent's visual access is manipulated, 398 leading them to be either knowledgeable or ignorant about the location of the target. 399 Participants' AL will be measured during test trials to determine whether or not they take 400 into account the agent's epistemic access and adjust their action anticipation accordingly. 401 Participants' looking patterns will be recorded using either lab-based corneal reflection 402 eye-tracking or online recording of gaze patterns. We chose to provide the online testing 403 option to increase the flexibility for data collection given the disruption caused by the 404 COVID-19 pandemic. This option will also provide the opportunity to potentially compare 405 in-lab and online testing procedures (Sheskin et al., 2020). Novel animated stimuli were 406 collectively developed within the MB2 consortium on the basis of previous work (e.g., 407 Clements & Perner, 1994) and based on input from collaborators with experience with 408 both successful and failed replication studies (e.g., Grosse Wiesmann et al., 2017; Surian & 400 Geraci, 2012). These animated 3D scenes feature a dynamic interaction aimed to optimally 410 engage participants' attention: a chasing scenario involving two agents, a chaser and a chasee (see Figures 1 and 2). As part of the chase, the chasee enters from the top of an 412 upside-down Y-shaped tunnel with two boxes at its exits. The tunnel is opaque so participants cannot see the chasee after it enters the tunnel, but can hear noises that 414 indicate movement. The chase eventually exits from one of the arms of the Y, and goes 415 into the box on that side. The chaser observes the chasee exit the tunnel and go into a box,

and then follows it through the tunnel. During familiarization trials, the chaser always 417 exits the tunnel on the same side as the chasee, and approaches the box where the chasee is 418 currently located. Thus, if participants engage in spontaneous action anticipation during 419 familiarization trials, they should reliably anticipate during the period when the chaser is 420 in the tunnel that it will emerge at the exit that leads to the box containing the chasee. 421 During test trials, the chase always first hides in one of the boxes but shortly thereafter 422 leaves its initial hiding place and hides in the box at the other tunnel exit. Critically, the 423 chaser either does (knowledge condition) or does not (ignorance condition) have epistemic 424 access to the chasee's location. During knowledge trials, the chaser observes all movements 425 of the chasee. During *ignorance* trials, the chaser observes the chasee enter the tunnel, but 426 then leaves and only returns once the chase is already hidden inside the second box. The 427 event sequences in the two conditions are thus identical with the only difference between 428 conditions pertaining to what the chaser has or has not seen. They were designed in this 429 way with the long-term aim to implement, in a minimal contrast design, more complex 430 conditions of false/true belief contrasts with the very same event sequences (true belief 431 conditions will then be identical to the knowledge conditions here, but in false belief 432 conditions the chaser witnesses the chasee's placement in the first box, but then fails to 433 witness the re-location)<sup>2</sup>. Participants' AL (their gaze pattern indicating where they expect 434

<sup>&</sup>lt;sup>2</sup> There is thus a certain asymmetry with regard to the interpretation and the consequences of potentially positive and negative results of the present knowledge-ignorance contrast: in the case of positive results, we can conclude that subjects spontaneously engage in basic epistemic state ascription and can move on to test, with the minimal contrast comparison of knowledge-ignorance vs. false belief-true belief, whether this extends to more complex forms of epistemic state attribution. In the case of negative results, though, we cannot draw firm conclusions to the effect that subjects do not engage in spontaneous epistemic state ascription. More caution is in order since the present knowledge-ignorance contrast has been designed in order to be comparable to future belief contrasts rather than to be the simplest implementation possible. Simpler implementations would then need to be devised that involve fewer steps (i.e. the chasee just goes to one location and this is or is not witnessed by the chasee).

the chaser to appear) will be assessed during the anticipatory period - that is, the period 435 during which the chaser is going through the tunnel and is not visible. There will be two 436 main dependent measures: first looks, and a differential looking score (DLS). The first look 437 measure will be binary, indicating which of the two tunnel exits participants fixate first: 438 the exit where the chase is actually hiding, or the other exit. DLS is a measure of the 439 proportion of time spent looking at the correct tunnel exit during the entire anticipatory 440 period. In two pilot studies (see Methods section), we addressed the foundational question 441 of the current study: whether these stimuli reveal spontaneous goal-directed action 442 anticipation as measured by AL in the above-described familiarization trials (i.e., without a 443 change of location by the chase or manipulation of the chaser's epistemic state). We found 444 that our paradigm indeed elicited action anticipation and exclusion rates due to lack of 445 anticipation were significantly lower relative to previous (original and replication) AL studies. Both toddlers and adults showed reliable anticipation of the chaser's exit at the chasee's location, indicating that in contrast with many previous AL studies the current paradigm successfully elicits spontaneous goal-based action anticipation. Based on these pilot data we concluded that the paradigm is suitable for examining the second and critical 450 question: whether toddlers and adults, in their spontaneous goal-based action anticipation, 451 take into account the agent's epistemic state. We predict that if participants track the 452 chaser's perceptual access and resulting epistemic state (knowledge/ignorance) and 453 anticipate their actions accordingly, they should look more in anticipation to the exit at the 454 chasee's location than the other exit in the knowledge condition, but should not do so (or 455 to a lesser degree; see below) in the *ignorance* condition. We anticipate three potential 456 factors that could influence participant's gaze patterns: Keeping track of the chaser's 457 epistemic status in the *ignorance* condition might either lead to no expectations as to 458 where the chaser will look (resulting in chance level looking between the two exits) or (if 450 participants follow an "ignorance leads to mistakes"-rule, see e.g., Ruffman, 1996) to an 460 expectation that the chaser will go to the wrong location [longer looking to the exit with 461

the empty box; e.g., Fabricius, Boyer, Weimer, and Carroll (2010)]. Either way, 462 participants may still show a 'pull of the real' even in the *ignorance* condition, i.e., reveal a 463 default tendency to look to the side where the chasee is located. But if they truly keep 464 track of the epistemic status of the chaser (knowledge vs. ignorance), they should show this 465 tendency to look to the side where the chase really is in the *ignorance* condition to a lesser 466 degree than in the knowledge condition. In sum, the research questions of the present study 467 are the following: First, can we observe in a large sample that toddlers and adults robustly 468 anticipate agents' actions based on their goals in this paradigm, as they did in our pilot 460 study? Second, can we find evidence that they take into account the agent's epistemic 470 access (knowledge vs. ignorance) and adjust their action anticipation accordingly? In 471 addressing these questions, the present study will significantly contribute to our knowledge 472 on spontaneous ToM. It will inform us whether the present paradigm and stimuli can elicit spontaneous goal-based and mental-state-based action anticipation in adults and toddlers, 474 based on a large sample of about 800 participants in total from over 20 labs. In the long 475 run, the present study will lay the foundation for future work to address broader questions of what kind of epistemic states toddlers and adults spontaneously attribute to others in 477 their action anticipation and what cognitive mechanisms allow them to do so.

479 Methods

All materials, and later the collected de-identified data, will be provided on the Open Science Framework (OSF; https://osf.io/jmuvd/). All analysis scripts, including the pilot data analysis and simulations for the design analysis, can be found on GitHub (https://github.com/manybabies/mb2-analysis). We report how we determined our sample size and we will report all data exclusions, all manipulations, and all measures in the study. Additional methodological details can be found in the Supplemental Material.

#### 36 Stimuli

Figures 1 and 2 provide an overview of the paradigm. For the stimuli, 3D animations were created depicting a chasing scenario between two agents (chaser and chasee) who start in the upper part of the scene. At the very top of the scene a door leads to outside the visible scene. Below this area, a horizontal fence separates the space, and thus the lower part of the space can be reached by the Y-shaped tunnel only. Additional information on the general scene setup, events, and timings in the familiarization and the test trials, as well as trial randomization can be found in the Supplemental Material.

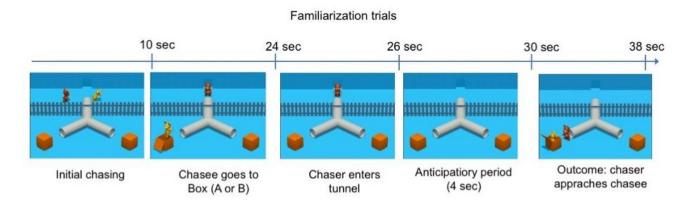


Figure 1. Timeline of the familiarization trials.

**Familiarization Trials.** All participants will view four familiarization trials (for an 494 overview of key events see Figure 1). During familiarization trials, after a brief chasing 495 introduction, the chase enters an upside-down Y-shaped tunnel with a box at both of its 496 exits. The chasee then leaves the tunnel through one of the exits and hides in the box on 497 the corresponding side. Subsequently, the chaser enters the tunnel (to follow the chasee), 498 and participants' AL to the tunnel exits is measured before the chaser exits on the side the 499 chase is hiding, as an index of their goal-based action anticipation. In these familiarization 500 trials, if participants engage in spontaneous action anticipation, they should reliably 501 anticipate that the chaser should emerge at the tunnel exit that leads to the box where the 502 chase is. After leaving the tunnel, the chaser approaches the box in which the chase is 503

hiding and knocks on it. Then, the chasee jumps out of the box and the two briefly interact.

Familiarization Phase Pilot Studies. In a pilot study with 18- to 505 27-month-olds (n = 65) and adults (n = 42), seven labs used in-lab corneal reflection 506 eye-tracking to collect data on gaze behavior in the familiarization phase. A key 507 desideratum of our paradigm is that it should produce sufficient AL, as a low rate of AL in previous studies has led to high exclusion rates. The goals of the pilot study were to 1) 509 estimate the level of correct goal-based action predictions in the familiarization phase, 2) 510 determine the optimal number of familiarization trials, 3) check for issues with perceptual 511 properties of stimuli (e.g., distracting visual saliencies), and 4) test the general procedure 512 including preprocessing and analyzing raw gaze data from different eye-tracking systems. 513 We found that the familiarization stimuli elicited a relatively high proportion of 514 goal-directed action anticipations, but we were concerned about the effects of some minor 515 properties of the stimulus (in particular, a small rectangular window in the tunnel tube 516 that allowed participants to see the agents at one point on their path to the tunnel exits). 517 In a second pilot study with 18- to 27-month-olds (n = 12, three participating labs), slight 518 changes of stimulus features (the removal of the window in the tube; temporal changes of 519 auditory anticipation cue) did not cause major changes in the AL rates. Sixty-eight percent 520 of toddlers' first looks in the first pilot, 69% of toddlers' first looks in the second pilot, and 521 69% of adults' first looks were toward the correct area of interest (AOI) during the 522 anticipatory period. The average proportion of looking towards the correct AOI during the 523 anticipatory period was 70.7% ( $\text{CI}_{95\%} = 67.6\%$  - 73.8%) in toddlers in the first pilot, 70.5% 524  $(\mathrm{CI}_{95\%}=62.8\%$  - 78.2%) in the second pilot for toddlers, and 75.3%  $(\mathrm{CI}_{95\%}=71.0\%$  -525 79.5%) in adults. In Bayesian analyses, we found strong evidence that toddlers and adults looked more towards the target than towards the distractor during the anticipation period. 527 Based on conceptual and practical methodological considerations while also considering 528 previous studies, we decided to include four trials in the final experiment. The pilot data 529 results of the toddlers supported this decision insofar as we observed a looking bias towards 530

the correct location already in trials 1-4, without additional benefit of trials 5-8. Further, 531 prototypical analysis pipelines were established for combining raw gaze data from different 532 eye-trackers. In short, we developed a way to resample gaze data from different 533 eye-trackers to be at a common Hz rate and to define proportionally correct AOIs for 534 different screen dimensions with the goal to merge all raw data into one data set for 535 inferential statistics. The established analysis procedure is described further in the Data 536 Preprocessing section below. In sum, we concluded that this paradigm sufficiently elicits 537 goal-directed action predictions, an important prerequisite for drawing any conclusion on 538 AL behavior in the test trials of this study. A detailed description of the two pilot studies 539 can be found in the Supplemental Material.

Test Trials. All participants will see two test trials, one knowledge and one 541 ignorance trial. However, in line with common practice in ToM studies, the main 542 comparison concerns the first test trial between-participants to avoid potential carryover 543 effects. In addition, in exploratory analyses, we plan to assess whether results remain the 544 same if both trials are taken into account and whether gaze patterns differ between the two 545 trials (see Exploratory Analyses). If the results remain largely unchanged across the two 546 trials, it may suggest that future studies could increase power by including multiple test 547 trials. In test trials, the chasee first hides in one of the boxes, but shortly thereafter the chase leaves this box and hides in the second box, at the other tunnel exit. Critically, the 540 chaser either witnesses (knowledge condition) or does not witness (ignorance condition) 550 from which tunnel exit the chase exited and thus where the chase is currently hiding (for 551 an overview, see Figure 2). In the knowledge trials, the chaser observes all movements of the chasee. The chaser leaves for a brief period of time after the chasee entered the tunnel, but it returns before the chasee exited the tunnel. Therefore, no events take place in the chaser's absence. In the *ignorance* trials, the chaser sees the chasee enter the tunnel, but 555 then leaves. Therefore, the chaser does not see the chase entering either box and only 556 returns once the chase is already hidden in the final location. Finally, the chaser enters 557

the tunnel but does not appear in either exit. Rather, the scene "freezes" for four seconds 558 and participants' AL is measured. Thus, the knowledge and ignorance conditions are 559 matched for the chaser leaving for a period of time, but they differ in whether they warrant 560 the chaser's epistemic access to the location of the chasee. No outcome is shown in either 561 test trials. When designing the knowledge and ignorance condition, we aimed at keeping all 562 events and their timings parallel, except the crucial manipulation. We show the same 563 events in both conditions. Where possible, all events also have the same duration. In the 564 case of the chaser's absence in the knowledge condition, there were two main options, both 565 with inevitable trade-offs. First, we could have increased the duration of the chaser's 566 absence in the knowledge condition to match the duration of the chaser's absence in both 567 conditions. Yet, this would potentially disrupt the flow of events, such as keeping track of 568 the chasee's actions and the general scene dynamics, since nothing would happen for a substantial amount of time. Second, the chaser can be absent for a shorter time in the 570 knowledge than in the ignorance condition, in which case the flow of events – the chasee's actions and the general scene dynamics – would remain natural. We chose the second 572 option because we reasoned that the artificial break in the knowledge condition could 573 disrupt the participant's tracking of the chaser's epistemic state, thus being a confound that would be more detrimental than the difference in the duration of absence. Further, 575 the current contrast has the advantage that the chasee's sequence and timing of actions are 576 identical in both conditions, thus minimizing the difference between conditions. Finally, 577 with the current design, the duration of the chaser's absence will be closely matched in the 578 later planned false belief - true belief contrast, because in the future false belief condition, 570 the chaser has to be absent for fewer events (because the chaser witnesses the first hiding 580 events after the chase reappeared at the other side of the tunnel). 581

Trial Randomization. We will vary the starting location of the chasee (left or right half of the upper part of the scene) and the box the chasee ended up (left or right box) in both familiarization and test trials. The presentation of the familiarization trials



Figure 2. Schematic overview of stimuli and conditions of the test trials.

Note. After the familiarization phase, participants know about the agent's goal (chaser wants to find chasee), perceptual access (chaser can see what happens on the other side of the fence), and situational constraints (boxes can be reached by walking through the forking tunnel). In the knowledge condition, the chaser witnesses the chasee walking through the tunnel and jumping in and out of the first box. While the chasee is in the box, the chaser briefly leaves the scene through the door in the back and returns shortly after. Subsequently, the chaser watches the chasee jumping out of the box again and hiding in the second box. In the ignorance condition, the chaser turns around and stands on the other side of the door in the back of the scene, thus unable to witness any of the chasee's actions. The chaser then returns and enters the tunnel to look for the chasee. During the test phase (4 seconds still frame), AL towards the end of the tunnels is measured.

will be counterbalanced in two pseudo-randomized orders (LRRL and RLLR). Each lab signs up for one or two sets of 16-trial-combinations, for each of their tested age groups.

# Lab Participation Details

Time-Frame. The contributing labs will start data collection as soon as they are
able to once our Registered Report receives an in-principle acceptance. The study will be
submitted for Stage 2 review within one year after in-principle acceptance (i.e., post-Stage
1 review). We anticipate that this time window gives the individual labs enough flexibility
to contribute the committed sample sizes; however, if this timeline needs adjusting due to
the Covid-19 pandemic this decision will be made prior to any data analysis.

Participation Criterion. The participating labs were recruited from the MB2 consortium. In July 2020, we asked via the MB2 listserv which labs planned to contribute how many participants for the respective age group (toddlers and/or adults). The Supplemental Material provides an overview of participating labs. Each lab made a commitment to collecting data from at least 16 participants (toddlers or adults), but we will not exclude any contributed data on the basis of the total sample size contributed by that lab. Labs will be allowed to test using either in-lab eye-tracking or online methods.

Ethics. All labs will be responsible for obtaining ethics approval from their
appropriate institutional review board. The labs will contribute de-identified data for
central data analysis (i.e., eye-tracking raw data/coded gaze behavior, demographic
information). Video recordings of the participants will be stored at each lab according to
the approved local data handling protocol. If allowed by the local institutional review
board, video recordings will be made available to other researchers via the video library
Databrary (https://nyu.databrary.org/).

Participants. In a preliminary expression of interest, 26 labs signed up to contribute a minimal sample size of 16 toddlers and/or adults. Based on this information,

we expect to recruit a total sample of 520 toddlers (ages 18-27 months) and 408 adults 610 (ages 18-55 years). To avoid an unbalanced age distribution in the toddlers sample, labs 611 will sign up for testing at least one of two age bins (bin 1: 18-22 months, bin 2: 23-27 612 months), and will be asked to ensure approximately equal distribution of participants' age 613 in their collected sample if possible. They will be asked to try to ensure that the mean age 614 of their sample lies in the middle of the range of the chosen bin and that participant ages 615 are distributed across their whole bin. Both for adults and toddlers, basic demographic 616 data will be collected on a voluntary basis with a brief questionnaire (see Supplemental 617 Material for details). The requested demographic information that is not used in the 618 registered confirmatory and/or exploratory analyses of this study will be collected for 619 further potential follow-up analyses in spin-off projects within the MB framework. After 620 completing the task, adult participants will be asked to fill a funneled debriefing questionnaire. This questionnaire asks what the participant thinks the purpose of the experiment was, whether the participant had any particular goal or strategy while watching 623 the videos, and whether the participant consciously tracked the chaser's epistemic state. 624 Additionally, we collect details regarding each testing session (see Supplemental Material). 625

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Our final dataset consisted of 1224 participants, with an overall exclusion rate of 24.16% (toddlers: 35.60%, adults: 12.67%). Table 1 and Table 2 show the distribution of included participants across labs, eye-tracking methods, and ages. A final sample of 521 toddlers (49.14% female) that were tested in 37 labs (mean lab sample size = 14.08, SD = 5.56, range: 2 - 32) was analyzed. The average age of toddlers in the final sample was 22.49 months (SD: 2.53, range: 18 - 27.01). The final sample size of included adults was N = 703 (68.85% female), tested in 34 labs (mean lab sample size = 20.68, SD = 12.14, range: 8 - 65). Their mean age was 24.61 years (SD: 7.36, range: 18 - 55).

# Apparatus and Procedure

Eye-tracking Methods. We expect that participating labs will use one of three
types of eye-tracker brands to track the participant's gaze patterns: Tobii, EyeLink, or
SMI. Thus, apparatus setup will slightly vary in individual labs (e.g., different sampling
rates and distances at which the participants were seated in front of the monitor).
Participating labs will report their eye-tracker specifications and study procedure alongside
the collected data. To minimize variation between labs, all labs using the same type of
eye-tracker will use the same presentation study file specific to that eye-tracker type. The
Supplemental Material will provide an overview of employed eye-trackers, stimulus
presentation softwares, sampling rates and screen dimensions.

Online Gaze Recording. To allow for the participation of labs that do not have 646 access to an eye-tracker, or are not able to invite participants to their facilities due to current restrictions regarding the COVID-19 pandemic, labs can choose to collect data via online testing. We initially anticipated for labs to flexibly choose between different methods for coding gaze direction, including manual frame-by-frame coding from video recordings or using various online platforms for virtual data collection (e.g., LookIt, 651 YouTube, Zoom, Labranced). Additionally, we considered the possibility of webcam 652 eye-tracking using tools such as WebGazer.js (Papoutsaki et al., 2016). However, we later 653 decided that all labs would conduct only supervised testing, leading to the exclusive use of 654 the MB-ManyWebcams WebGazer setup for data collection [Steffan et al. (2024); see also 655 Supplemental Material S2. This ensured a standardized approach across all participating 656 labs. 657

Testing Procedure. Toddlers were seated either on their caregiver's lap or in a
highchair. The distance from the monitor depended on the data collection method.

Caregivers were asked to refrain from interacting with their child and closed their eyes
during stimulus presentation or wore a set of opaque sunglasses. Adult participants were

seated on a chair at the appropriate distance from the monitor. Once the participant was
seated, the experimenter initiated the eye-tracker-specific calibration procedure.

Additionally, we presented another calibration stimulus before and after the presentation of
the task. This allowed for evaluating the accuracy of the calibration procedure across labs
(cf., Frank, Vul, & Saxe, 2012).

### 667 General Lab Practices

To ensure standardization of our experimental procedure, materials for testing
practices and instructions were prepared and distributed to the participating labs. Each
lab was responsible for maintaining these practices and reported all relevant details on
testing sessions (for details see the Supplemental Material).

Videos of Participants. As with all MB projects, we strongly encouraged labs to record video data of their own lab procedures and each testing session, provided that this was in line with regulations of the respective institutional ethics review board and the given informed consent. Participating labs that could not contribute participant videos were asked to provide a video walk-through of their experimental set-up and procedure instead. If no institutional ethics review board restrictions occurred, labs were encouraged to share video recordings of the test sessions via Databrary.

#### 679 Design Analysis

Here we provide a simulation of the predicted findings because a traditional
frequentist power analysis was not applicable for our project for two reasons. First, we used
Bayesian methods to quantify the strength of our evidence for or against our hypotheses,
rather than assessing the probability of rejecting the null hypothesis. In particular, we
computed a Bayes factor (BF; a likelihood ratio comparing two competing hypotheses),
which allowed us to compare models. Second, because of the many-labs nature of the

study, the sample size was not determined by power analysis, but by the amount of data 686 that participating labs were able to contribute within the pre-established timeframe. Even 687 if the effect size was much smaller than what we anticipated (e.g., less than Cohen's d =688 0.20), the results would have been informative as our study was expected to be 689 dramatically larger than any previous study in this area. If, due to unforeseen reasons, the 690 participating labs were not able to collect a minimum number of 300 participants per age 691 group within the proposed time period, we planned to extend the time for data collection 692 until this minimum number was reached. Conversely, if the effect size was large (e.g., more 693 than Cohen's d = 0.80), the resulting increased precision of our model would allow us to 694 test a number of other theoretically and methodologically important hypotheses (see 695 Results section). Although we did not determine our sample size based on power analysis, 696 here we provide a simulation-based design analysis to demonstrate the range of BFs we might expect to see, given a plausible range of effect sizes and parameters. We focus this analysis on our key analysis of the test trials (as specified below), namely the difference in AL on the first test trial that participants saw. We describe below the simulation for the 700 child sample, but based on our specifications, we expected that a design analysis for adult 701 data would produce similar results. We first ran a simulation for the first look analysis. In 702 each iteration of our simulation, we used a set of parameters to simulate an experiment, 703 using a first look (described below) as the key measure. For the key effect size parameter 704 for condition (knowledge vs. ignorance), we sampled a range of effect sizes in logit space 705 spanning from small to large effects (Cohen's d = 0.20 - 0.80; log odds from 0.36 - 1.45). 706 For each experiment, the betas for age and the age x condition interaction were sampled 707 uniformly between -0.20 and 0.20. The age of each participant was sampled uniformly 708 between 18 and 27 months and then centered. The intercept was sampled from a normal 700 distribution (1, 0.25), corresponding to an average looking proportion of 0.73. Lab 710 intercepts and the lab slope by condition were set to 0.1, and other lab random effects were 711 set to 0 as we do not expect them to be meaningfully non-zero. These values were chosen 712

based on pilot data (average looking proportion), but also to have a large range of possible 713 outcomes (lab intercept, age and age x condition interaction). We are confident that the 714 results would be robust to different choices. We then used these simulated data to simulate 715 an experiment with 22 labs and 440 toddlers and computed the resulting BFs, as specified 716 in the analysis plan below. We adopted all of the priors specified in the results section 717 below<sup>3</sup>. We ran 349 simulations and, in 72% of them, the BF showed strong evidence in 718 favor of the full model (BF > 10); in 6% the BF showed substantial evidence (10 > BF >719 3); it was inconclusive 14% of the time (1/10 < BF < 3), and in 8% of cases the null model 720 was substantially favored (see Supplement). The BF was not < 1/10 in any of the 721 simulations. Thus, under the parameters chosen here for our simulations, it was likely that 722 the planned experiment was of sufficient size to detect the expected effect. We also ran a 723 design analysis for the proportional looking analysis. We used the same experimental 724 parameters (number of labs, participants, ages, etc.). For generating simulated data, we 725 drew the condition effect from a uniform distribution between .05 and .20 (in proportion 726 space). The age and age x condition interaction effects were drawn from uniform 727 distributions between -.05 and .05. Sigma, the overall noise in the experiment, was drawn 728 from a uniform distribution between .05 and .1. The intercept was drawn from a normal 729 distribution with mean .65 and a standard deviation of .05. The by-lab standard deviation 730 for the intercept and condition slope was set to .01. Priors were as described in the main 731 text. We ran 119 simulations, and in all 119 we obtained a BF greater than 10, suggesting 732 that, under our assumptions, the study was well-powered. 733

<sup>&</sup>lt;sup>3</sup> After the design analysis, additional labs expressed their interest in contributing data, which is why the anticipated sample sizes and the numbers this design analysis is based on differ. Given the uncertainty in determining the final sample size in this project, we kept the design analysis as is to have a more conservative estimate of the study's power.

#### Data Preprocessing

**Eve-tracking.** Raw gaze position data (x- and y-coordinates) was extracted in the 735 time window starting from the first frame at which the chaser entered the tunnel until the 736 last frame before it exited the tunnel in the familiarization and in test trials. For data 737 collected from labs using a binocular eye-tracker, gaze positions of the left and the right 738 eye were averaged. We will use the peekds R package 739 (https://github.com/peekbank/peekbankr) to convert eye-tracking data from disparate trackers into a common format. Because not all eye-trackers record data with the same 741 frequency or regularity, we will resample all data to be at a common rate of 40 Hz (samples 742 per second). We will exclude individual trials if more than 50% of the gaze data is missing 743 (defined as off-screen or unavailable point of gaze during the whole trial, not just the 744 anticipatory period). Applying this criterion would have caused us to exclude 4\% of the 745 trials in our pilot data, which inspection of our pilot data suggested was an appropriate 746 trade-off between not excluding too much usable data and not analyzing trials which were 747 uninformative. For each monitor size, we will determine the specific AOIs and compute 748 whether the specific x- and y-position for each participant, trial, and time point fall within 749 their screen resolution-specific AOIs. Our goal is to determine whether participants are 750 anticipating the emergence of the chaser from one of the two tunnel exits. Thus, we defined 751 AOIs on the stimulus by creating a rectangular region around the tunnel exit that is D 752 units from the top, bottom, left, and right of the boundary of the tunnel exit, where D is 753 the diameter of the tunnel exits. We then expanded the sides of the AOI rectangles by 25%754 in all directions to account for tracker calibration error. Our rationale was that, if we made the AOI too small, we might fail to capture anticipations by participants with poor calibrations. In contrast, if we made the regions too large, we might capture some fixations by participants looking at the box where the chase actually is. On the other hand, these 758 chasee looks would not be expected to vary between conditions and so would only affect our 759 baseline level of looking. Thus, the chosen AOIs aim at maximizing our ability to capture

between-condition differences. For an illustration of the tunnel exit AOIs see Figure 3. We are not analyzing looks to the boxes, since they can less unambiguously be interpreted as epistemic state-based action predictions and because we observed few anticipatory looks to the boxes in the pilot studies. For more detailed information about the AOI definition process see the description of the pilot study results in the Supplemental Material.

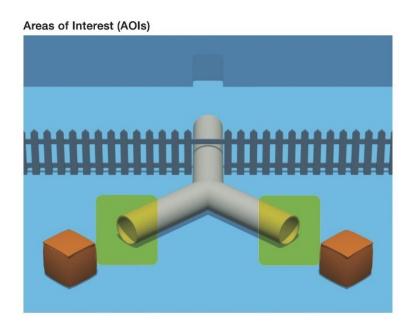


Figure 3. Illustration of Areas of Interest (AOIs) for gaze data analysis during the anticipatory period.

Note. The light green rectangles show the dimensions of the AOIs used for the analysis of AL during the test period.

Manual Coding. For data gathered without an eye-tracker (e.g., videos of
participants gathered from online administration), precise estimation of looks to specific
AOIs will not be possible. Instead, videos will be coded for whether participants are looking
to the left or the right side of the screen (or "other/off screen"). In our main analysis,
during the critical anticipatory window, we will treat these looks identically to looks to the
corresponding AOI. See exploratory analyses for analysis of data collected online.

Temporal Region of Interest. For familiarization trials, we define the start of
the anticipatory period (total length = 4000 ms) as starting 120 ms after the first frame
after which the chaser has completely entered the tunnel and lasting until 120 ms after the
first frame at which the chaser is visible again [we chose 120 ms as a conservative value for
cutting off reactive saccades; cf., Yang, Bucci, and Kapoula (2002)]. For test trials, we
define the start of the anticipatory period in the same way, with a total duration of 4000
ms.

Dependent Variables. We define two primary dependent variables: 1. First look. 779 First saccades will be determined as the first change in gaze occurring within the 780 anticipatory time window that is directed towards one of the AOIs. The first look is then 781 the binary variable denoting the target of this first saccade (i.e., either the correct or 782 incorrect AOI) and is defined as the first AOI where participants fixated at for at least 150 783 ms, as in Rayner, Smith, Malcolm, and Henderson (2009). The rationale for this definition 784 was that, if participants are looking at a location within the tunnel exit AOIs before the 785 anticipation period, they might have been looking there for other reasons than action 786 prediction. We therefore count only looks that start within the anticipation period because 787 they more unambiguously reflect action predictions. This further prevents us from running 788 into a situation where we would include a lot of fixations on regions other than the tunnel exit AOIs because participants are looking somewhere else before the anticipation period begins. 2. Proportion DLS [also referred to as total relative looking time; Senju et al. (2009)]. We compute the proportion looking (p) to the correct AOI during the full 4000 ms 792 anticipatory window (correct looking time / (correct looking time + incorrect looking 793 time)), excluding looks outside of either AOI.

795 Results

### <sup>96</sup> Confirmatory Analyses

As discussed in the Methods section, we adopted a Bayesian analysis 797 strategy so as to maximize our ability to make inferences about the presence or absence of 798 a condition effect (i.e., our key effect of interest). In particular, we fit Bayesian mixed effects regressions using the package brms in R (Bürkner, 2017). This framework allows us to estimate key effects of interest while controlling for variability across grouping units (in 801 our case, labs). To facilitate interpretation of individual coefficients, we report means and 802 credible intervals. For key inferences in our confirmatory analysis, we use the bridge 803 sampling approach (Gronau et al., 2017) to compute BFs comparing different models. As 804 the ratio of the likelihood of the observed data under two different models, BFs allow us to 805 quantify the evidence that our data provide with respect to key comparisons. For example, 806 by comparing models with and without condition effects, we can quantify the strength of 807 the evidence for or against such effects. Bayesian model comparisons require the 808 specification of proper priors on the coefficients of individual models. Here, for our first 800 look analysis, we use a set of weakly informative priors that capture the expectation that 810 the effects that we observe (of condition and, in some cases, trial order) are modest. For 811 coefficients, we choose a normal distribution with mean of 0 and SD of 2. Based on our 812 pilot testing and the results of MB1, we assume that lab and participant-level variation will 813 be relatively small, and so for the standard deviation of random effects (i.e., variation in 814 effects across labs and, in the case of the familiarization trials, participants) we set a Normal prior with mean of 0 and SD of 0.1. We set an LKJ(2) prior on the correlation 816 matrix in the random effect structure, a prior that is commonly used in Bayesian analyses of this type (Bürkner, 2017). Because the BF is sensitive to the choice of prior, we also ran 818 a secondary analysis with a less informative prior: fixed effect coefficients chosen from a 819 normal distribution with mean 0 and SD of 3, and random effect standard deviations

drawn from a normal prior with a mean of 0 and SD of 0.5 (see Supplement S3). With respect to the specification of random effects, we followed the approach advocated by Barr 822 (2013), that is, specifying the maximal random effect structure justified by our design. 823 Since we are interested in lab-level variation, we fitted random effect coefficients for fixed 824 effects of interest within labs (e.g., condition within lab). Further, where there were 825 participant-level repeated measure data (e.g., familiarization trials), we fitted random 826 effects of participants. For the proportional looking score analysis, we used a uniform prior 827 on the intercept between -0.5 and 0.5 (corresponding to proportional looking scores 828 between 0 and 1: the full possible range). For the priors on the fixed effect coefficients, we 820 used a normal prior with a mean of 0 and an SD of 0.1. Because these regressions are in 830 proportion space, 0.10 corresponds to a change in proportion of 10%. For the random effect 831 priors, we used a normal distribution with mean 0 and standard deviation .05. The LKJ 832 prior was specified as above. All preregistered confirmatory models converged, with no 833 divergent transitions, all Rhat values < 1.1, and an effective sample size greater than 20% of the total sample size.

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Familiarization Trials. Figure 4 shows the proportion of first looks and the
proportion of target looking (non-logit transformed) for toddlers and adults plotted across
familiarization trials and test trials. Our first set of analyses examined data from the four
familiarization trials and asked whether participants anticipated the chaser's reappearance
at one of the tunnel exits. In our first analysis, we were interested in whether participants
engaged in AL during the familiarization trials. To quantify the level of familiarization, we
fitted Bayesian mixed effect models predicting target looks based on trial number (1-4)
with random effects for lab and participants and random slopes for trial number for each.

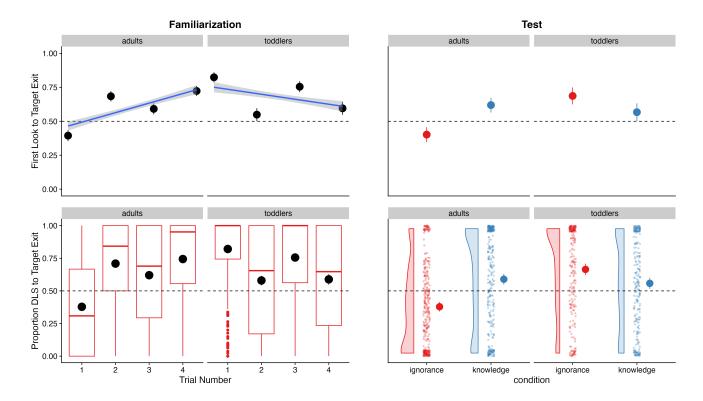


Figure 4. Proportional target looking and proportion of first looks for toddlers and adults during familiarization and test. Error bars and error bands represent 95% CIs.

In R formula notation (which we adopt here because of its relative concision compared 846 with standard mathematical notation), our base model was as follows: 847  $measure \sim 1 + trial\_number + (trial\_number|lab) + (trial\_number|participant)$ . We fitted a total of four instances of this model, one for each age group (toddlers vs. adults) 849 and dependent measure (proportion looking score vs. first look). First look models were 850 fitted using Bernoulli family with a logit link function. The proportion looking score 851 models were Gaussian and the dependent variable was centered by subtracting 0.5, such that 0 corresponded to chance-level performance. Our key question of interest was whether 853 overall anticipation was higher than chance levels on the familiarization trial immediately 854 before the test trials, in service of evaluating the evidence that participants were attentive 855 and making predictive looks immediately prior to test. To evaluate this question across the 856 four models, we coded trial number so that the last trial before the test trials (trial 4) was 857

set to the intercept, allowing the model intercept to encode an estimate of the proportion of correct anticipation immediately before test. We then fitted a simpler model for comparison  $measure \sim 0 + trial\_number + (trial\_number|lab) + (trial\_number|participant)$ , which included no intercept term. We then computed the BF comparing this model to the full model. This BF quantified the evidence for an anticipation effect for each group and measure.

## First look.

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Investigating proportion of first looks to the target location for toddlers, 865 we again used a Bayesian mixed effects model to predict whether toddlers' first look was to 866 the target exit based on trial number (1-4), with random effects for lab and participants 867 and random slopes for trial number for each. The Bayes factor comparing the full model to 868 the simpler model was estimated to be BF > 1000, favoring the full model over the null 869 model. This confirmed that toddlers showed above-chance looking to the target location 870 during the anticipatory window of the last familiarization trial. The model also provided 871 support for an effect of trial number on proportion of first looks, with the negative 872 coefficient indicating a decrease in target looks across the familiarization trials.

Adults. Comparing the Bayesian mixed effects model of adults predicting proportion of first looks based on trial number (1-4), with random effects for lab and participants and random slopes for trial number for each with the simpler model without an intercept, we computed a Bayes factor of BF > 1000, strongly favoring the full model over the null model. Again, this suggested that also adults' anticipation was higher than chance levels on the last familiarization trial. In addition, there was support for an effect of trial number on proportion of first looks, with the positive coefficient indicating an increase in proportion of first target looks across the familiarization trials.

## $Proportion\ DLS.$

Toddlers. We used a Bayesian mixed effects models to predict proportional target looking based on trial number (1-4) for toddlers, with random effects for lab and participants and random slopes for trial number for each. The Bayes factor comparing this model to the simpler null model without the intercept was estimated to be BF > 1000, strongly favoring the full model over the null model. See also Table 3 for regression coefficients for the full model. These results suggest a significant effect of trial number on PTL, with the negative coefficient indicating a decrease in PTL across the familiarization trials.

Adults. Next, we used a Bayesian mixed effects model to predict PTL based on trial number (1-4) for adults, again with random effects for lab and participants and random slopes for trial number for each. The Bayes factor for the full model against the null model was BF > 1000, suggesting strong evidence for the full model. These results suggest a significant effect of trial number on PTL, with the positive coefficient indicating an increase in target looks across the familiarization trials.

We focused our confirmatory analysis on the first test trial (see 897 Exploratory Analysis section for an analysis of both trials). Our primary question of 898 interest was whether AL differs between conditions (knowledge vs. ignorance, coded as -.5/.5) and by age (in months, centered). For child participants, we fitted models with the specification: 901  $measure \sim 1 + condition + aqe + condition : aqe + (1 + condition + aqe + condition : aqe | lab).$ 902 For adult participants, we fitted models with the specification 903  $measure \sim 1 + condition + (1 + condition | lab)$ . Again, we fitted models with a logistic link for first look analyses and with a standard linear link for DLS. In each case, our key BF was a comparison of this model with a simpler "null" model that did not include the fixed effect of condition but still included other terms. We took a BF > 3 in favor of a particular model as substantial evidence and a BF > 10 in favor of strong evidence. A BF 908 < 1/3 was taken as substantial evidence in favor of the simpler model, and a BF < 1/10 as strong evidence in favor of the simpler model. For the model of data from toddlers, we
additionally were interested in whether the model showed changes in AL with age. We
assessed evidence for this by computing BFs related to the comparison with a model that
did not include an interaction between age and condition as fixed effects

 $measure \sim 1 + condition + age + (1 + condition + age + condition : age | lab).$ 

These BFs captured the evidence for age-related changes in the difference in action anticipation between the two conditions. It is important to note that in the case of a null 915 effect, there are two main explanations: (1) toddlers and adults in our study do not 916 distinguish between knowledgeable and ignorant agents when predicting their actions. (2) 917 The method used is not appropriate to reveal knowledge/ignorance understanding. By 918 using Bayesian analyses, we are able to better evaluate the first of these two possibilities: 919 The BF provides a measure of our statistical confidence in the null hypothesis, i.e., no 920 difference between experimental conditions, given the data in ways that standard null 921 hypothesis significance testing does not. In other words, instead of merely concluding that 922 we did not find a difference between conditions, we would be able to find 923 no/anecdotal/moderate/strong/very strong/extreme evidence for the null hypothesis that 924 our participants did not distinguish between knowledgeable and ignorant agents when 925 predicting their actions (Schönbrodt & Wagenmakers, 2018). We therefore consider this 926 analysis an important addition to our overall analysis strategy. Yet, even our Bayesian 927 analyses are not able to rule out the second possibility that participants may well show 928 such knowledge/ignorance understanding with different methods, or that this ability may not be measurable with any methods available at the current time. Addressing this alternative explanation warrants follow up experiments.

#### First look.

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Toddlers. Investigating proportion of first looks for toddlers, we again used a
Bayesian mixed effects model to predict target looks based on condition, with random

effects for lab. The Bayes factor comparing the full model to the simpler model was
estimated to be BF = 2.4, providing only anecdotal evidence in favor of the full model over
the null model.

Again, we examined whether age influenced the difference in action anticipation
between knowledge and ignorance trials. To do this, we compared the full model, which
included an interaction between age and condition, with a simpler model without this
interaction. The computed Bayes factor, BF = 0.0, extremely supports the simpler model,
suggesting that the interaction term does not substantially improve the model's fit. This
implies that age does not appear to significantly affect the difference in action anticipation
between the two trial types.

Adults. We compared a Bayesian mixed-effects model predicting the proportion of first looks based on condition, including random effects for lab to a simpler model without the main effect of condition. The analysis yielded a Bayes factor of BF > 1000, providing strong evidence in favor of the full model over the null model. Results indicated that first looks to the target were significantly more frequent in the knowledge condition compared to the ignorance condition.

Proportion DLS. Figure 5 depicts mean proportion of looking to target and distractor during the anticipation window. The timecourse plot displays mean proportional looking for both conditions, knowledge and ignorance, both age cohorts, toddlers and adults, as wells as both test trials, first and second.

Toddlers. As first model, we used a Bayesian mixed effects models to predict toddlers' PTL based on condition, age, and the interaction of condition and age, while accounting for variability across labs. The Bayes factor comparing this model to the simpler null model without the interaction of condition was estimated to be BF = 21.2, favoring the full model over the null model. Table 4 shows the statistics for regression coefficients of the full model. These results suggest a significant effect of condition on PTL, with the

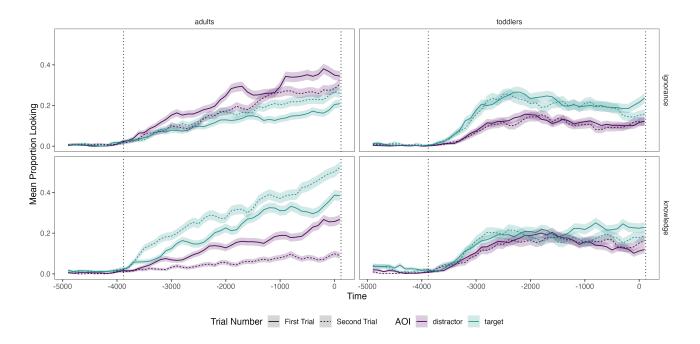


Figure 5. Timecourse of mean proportional looking for the first and second test trial for toddlers and adults in the ignorance and knowledge condition. The dotted vertical lines represent the onset and offset of the 4s anticipatory period. Time is centered such that 0 represents the moment the bear re-remerges from the tunnel. Error bands represent +1/-1 SEs.

positive coefficient indicating higher PTL for ignorance trials compared to knowledge trials.

An exploratory test of above-chance looking in the knowledge condition, however, revealed
that toddlers looked significantly above chance to the target, t(255) = 2.64, p = 0.009.

Additionally, we assessed whether toddlers' AL changed with age. Comparing our full model, which included an interaction between age and condition, with a simpler model without this interaction yielded a Bayes factor, BF = 0.4, providing only anecdotal evidence supporting the simpler model. This result suggests that the interaction between age and condition might not be a necessary predictor, as it doesn't provide substantial additional explanatory power. Hence, our results do not provide sufficient evidence to determine whether age-related changes in AL are consistent across conditions or differ between them.

Adults. Next, we used a Bayesian mixed effects model to predict PTL based on condition for adults, again with random effects for lab. The Bayes factor comparing this model to the simpler null model without the main effect of condition was estimated to be BF > 1000, strongly favoring the full model over the null model. These results suggest a significant main effect of condition on PTL, with the negative coefficient indicating a higher number of target looks for knowledge than for ignorance trials.

# 77 Exploratory Analyses

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Spill-over. We will analyze within-participants data from the second test trial that participants saw, using exploratory models to assess whether (1) findings are consistent when both trials are included (overall condition effect), (2) whether effects are magnified or diminished on the second trial (order main effect), and (3) whether there is evidence of "spillover" - dependency in anticipation on the second trial depending on what the first trial is (condition x order interaction effect; see Figure 6).

Analyzing condition-effects of within-participants data for both test trials, we fitted a
Bayesian mixed-effects model with the dependent variable of PTL and main effects of
condition and age and their interaction for toddlers. Comparing this full model to a null
model that did not include the fixed effect of condition, we obtained a Bayes Factor of BF
= 147.1, providing strong evidence in favor of the null model.

For adults, we also fitted a Bayesian mixed-effects model to predict their PTL for both test trials with the main effect of condition and random effects for participant and lab. Again, the data provided very strong evidence for the inclusion of the main effect of condition with a Bayes Factor of BF > 1000. The effect of condition was negative and credible, suggesting that PTL was significantly lower in the ignorance condition compared to the knowledge condition.

In order to investigate whether there was an interaction of condition and test trial

number, we fitted Bayesian mixed-effects models to predict PTL with fixed effects for 996 condition, test trial number, and their interaction, along with random intercepts and slopes 997 for these variables across labs, for toddlers and adults separately. For toddlers, the Bayes 998 factor, BF = 0.4, provided anecdotal evidence for the simpler null model without the 999 interaction term, indicating that the interaction between condition and test trial number 1000 does not add substantial explanatory power to the model. These results suggest that 1001 neither condition nor its interaction with test trial number significantly impacts PTL in 1002 this sample. 1003

For adults, the Bayes Factor, BF = 19.7, provided strong evidence for including the interaction of condition and test trial number as a fixed effect. These results indicate that while PTL increased over trials, this effect was moderated by condition, with the ignorance condition showing a slower rate of increase compared to the knowledge condition.

To examine whether anticipatory looking during the second test trial was influenced 1008 by condition and anticipatory looking during the first test trial, we fitted a Bayesian 1000 mixed-effects model for each age cohort separately. This model included fixed effects for 1010 condition, proportion of target looking during the first test trial, and their interaction. 1011 Random intercepts and slopes for these predictors were modeled at the lab level. We 1012 compared the full model including condition, first trial anticipatory looking, and their 1013 interaction to a null model with only the intercept. For toddlers, the Bayes factor, BF = 1014 1.1, suggests anecdotal evidence in favor of including these predictors compared to the null 1015 model. In addition, we compared the full model to a model excluding the main effect of 1016 condition. The Bayes factor was BF = 2.3, again providing only anecdotal evidence in 1017 favor of the full model that included condition. Taken together, these results suggest that 1018 condition and its interaction with first trial anticipatory looking were not strong predictors 1019 of second trial anticipatory looking behavior in toddlers. 1020

For adults, the Bayes factor comparing the full model including condition, first trial

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anticipatory looking, and their interaction to the null model with only the intercept was  $_{1023}$  BF > 1000 providing extreme evidence for the full model. Comparing the full model with a  $_{1024}$  model that excluded condition, the Bayes factor, BF > 1000, provided again extreme  $_{1025}$  evidence in favor of the full model. Hence, the extremely large Bayes factors underscore the  $_{1026}$  importance of considering these predictors in explaining second test trial anticipatory  $_{1027}$  looking behavior.

## Relationship between familiarization and test.

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We will explore whether condition differences vary for participants who show higher rates of anticipation during the four familiarization trials. For example, we might group participants according to whether they did or did not show correct AL at the end of the familiarization phase, defined as overall longer looking at the correct AOI than the incorrect AOI on average in trials 3 and 4 of the familiarization phase.

To investigate whether participants who show anticipatory looking during the 1035 familiarization phase also exhibit anticipatory looking during the test phase, we explored 1036 three different measures. First, we assessed anticipatory looking in participants who 1037 successfully anticipated during the final familiarization trial, defined as those whose first 1038 fixation was on the target. Second, we examined anticipatory looking in participants who 1039 consistently demonstrated anticipatory behavior across all familiarization trials, 1040 operationalized as having a PTL greater than 0.5 in each trial. Finally, we computed 1041 correlations to explore whether performance in the familiarization phase was related to 1042 performance in the test trials. 1043

Relationship between anticipatory looking during the first test trial and
first look during final familiarization trial. We fitted a main Bayesian hierarchical
model testing the fixed effects of condition (ignorance vs. knowledge), first look during the
final familiarization trial (target vs. distractor), and their interaction on first-trial

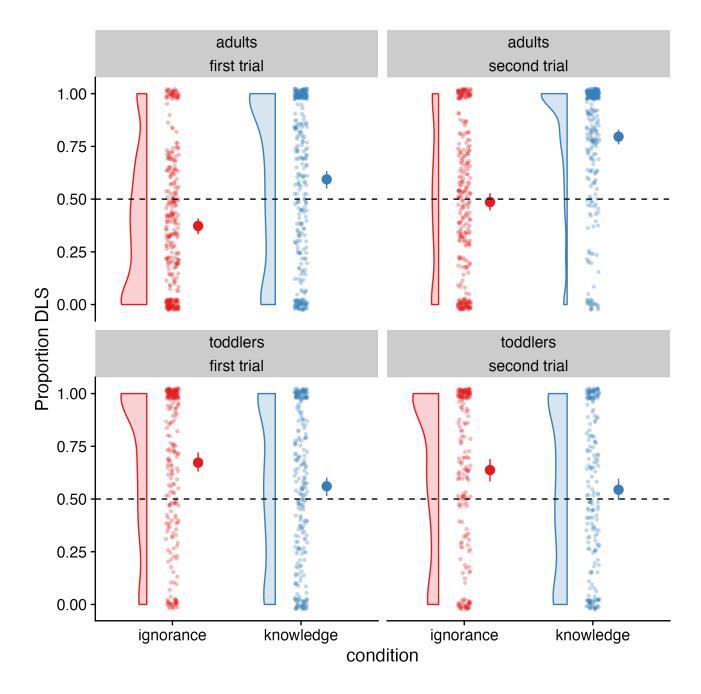


Figure 6. Proportional target looking for the first and second test trial for toddlers and adults in the ignorance and knowledge condition. Error bars represent 95% CIs.

proportion target looking during the anticipatory window for toddlers and adults 1048 separately. Random intercepts and slopes for all fixed effects and their interaction were 1049 included at the lab level, accounting for variability across different experimental settings. 1050 For toddlers, the Bayes factor comparing this model to the simpler null model without the 1051 interaction of condition and first look during the final familiarization trial indicated that 1052 the data slightly favored the simpler null model over the full model, BF = 0.7. The effect 1053 of condition was positive, but its confidence interval narrowly included zero, suggesting 1054 weak evidence for a condition effect (see Table 5). The effect of performance during the 1055 final familiarization trial was close to zero, indicating no substantial main effect of prior 1056 performance. Similarly, the interaction between condition and performance in the final 1057 familiarization trial was small and non-significant. These results suggest that while there 1058 was some weak evidence for a main effect of condition on anticipatory looking, neither 1059 performance during the final familiarization trial nor its interaction with condition 1060 substantially predicted anticipatory looking during the test trial. This result indicates that 1063 the relation between anticipatory looking during the first test trial and condition did not 1062 depend significantly on prior familiarization performance. 1063

For adults, the Bayes factor comparing this model to the simpler null model without 1064 the main effect of condition was estimated to be BF > 1000, strongly favoring the base 1065 model over the null model. The regression coefficients showed a significant negative effect 1066 of condition, indicating that anticipatory looking was lower in ignorance trials compared to 1067 knowledge trials. The decisive Bayes factor strongly favors the inclusion of condition and 1068 familiarization trial performance in the model, suggesting that these predictors are relevant 1069 for understanding anticipatory looking in adults. However, the small and non-significant 1070 estimates for the effects of familiarization trial performance and its interaction with 107 condition imply that condition is the primary driver of anticipatory looking differences, 1072 with performance in familiarization trials contributing minimally. 1073

Only > 50% looking to target during familiarization trials. To examine the 1074 effect of condition and successful anticipatory looking during familiarization (above 50%) 1075 target looking during the last two familiarization trials before test) on anticipatory looking 1076 during the first test trial, we fitted Bayesian mixed-effects models for each age group 1077 separately. The models included fixed effects for condition, anticipatory looking during 1078 familiarization trials, and their interaction. Random intercepts and slopes for these 1079 predictors were included at the lab level. Comparing the full model to the null model of 1080 toddlers revealed a Bayes Factor of BF = 17.9, providing strong evidence favoring the full 1081 model over a null model that excludes these predictors, suggesting that these factors 1082 contribute meaningfully to explaining the variance in test trial anticipatory looking. The 1083 regression analysis showed a positive main effect of condition, indicating higher 1084 anticipatory looking in one condition compared to the other (see Table 5). There was a 1085 small positive, but non-significant, effect of successful anticipatory looking during 1086 familiarization. The interaction between condition and successful anticipatory looking 1087 during familiarization was also small and non-significant. These results indicate that 1088 condition is a meaningful predictor of anticipatory looking during test trials in toddlers, 1089 with participants showing different levels of anticipatory looking based on condition. 1090 However, the successful anticipatory looking during familiarization trials and its interaction 1091 with condition appear to have minimal additional impact. The strong Bayes factor further 1092 supports the importance of including these predictors in the model but highlights that 1093 condition remains the primary driver of test trial differences. 1094

The estimated Bayes factor in favor of the full model of adults over the null model
was BF > 1000, indicating that the predictors substantially contribute to explaining test
trial anticipatory looking. The regression coefficients revealed a significant main effect of
condition, with participants showing lower anticipatory looking in the ignorance condition
compared to the knowledge condition. There was a small, positive, and non-significant
effect of successful anticipatory looking during familiarization and the interaction between

condition and successful successful anticipatory looking during familiarization was negligible. These results indicate that condition has a substantial and meaningful impact on anticipatory looking during the first test trial in adults, while successful anticipatory looking in familiarization trials and its interaction with condition have limited additional influence. The extremely large Bayes factor highlights the strong explanatory power of including these predictors in the model, although condition remains the primary driver of the observed differences.

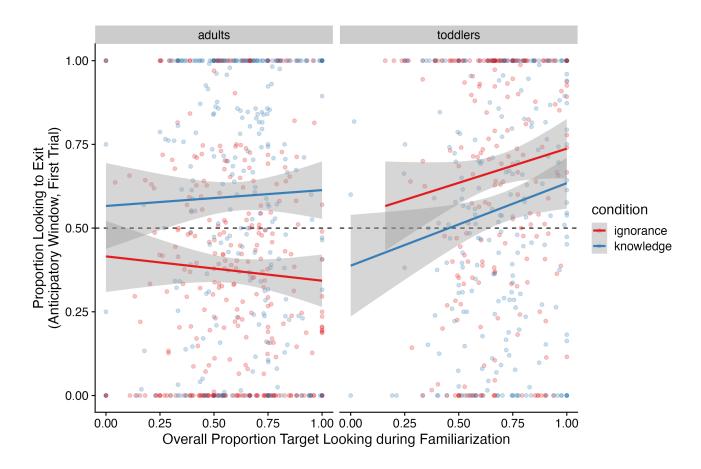


Figure 7. Relationship of anticipatory looking during familiarization and test for both age cohorts and conditions. Error bands represent 95% CIs.

Correlation between familiarization and test. We also examined the
correlation between familiarization and test performance across the two age cohorts and
conditions (see Figure 7). While no significant correlations were found for adults in either

condition, toddlers in the knowledge condition exhibited a significant positive correlation of anticipatory looking in familiarization and test, r=0.15, t(254)=2.35, p=0.02, suggesting that toddlers, who showed higher proportional target looking overall during familiarization, also showed higher proportional target looking in the first test trial. No such significant correlation was found for toddlers in the ignorance condition, r=0.11, t(234)=1.68, p=0.09. However, there was also no significant interaction between condition and the correlation in anticipatory looking between familiarization and test for toddlers (p=0.79).

Looking patterns during mouse's change of location. To examine whether 1118 participants monitored both the bear and the mouse during the mouse's location change, 1119 and whether this influenced AL in the test phase, we defined new time windows of interest 1120 (TOIs) corresponding to the mouse's location change in each condition and new AOIs for 1121 both the mouse and bear. We hypothesized that participants who attended to both AOIs 1122 would exhibit greater AL compared to those who predominantly tracked the mouse during 1123 its location change. Specifically, we analyzed the frequency of gaze shifts between the mouse and bear mouse's location change. An additional exploratory analysis of differential 1125 gaze duration directed toward mouse and bear during the mouse's location change is 1126 provided in the Supplement S3. 1127

1128

Comparing the number of shifts of toddlers and adults during the 1129 location change of the mouse. We fitted a Bayesian mixed-effects model using the 1130 Poisson family to examine the relationship between the number of shifts between mouse 1131 and bear and age cohort during location change of the mouse, while accounting for random 1132 effects by lab. The effect of condition was negative and approached significance, suggesting 1133 a potential reduction in the number of shifts for the ignorance condition compared to the 1134 knowledge condition. The main effect of age cohort was positive and credible, 1135 Estimate=0.56, indicating that the number of shifts was higher for adults than for 1136

toddlers. Importantly, the interaction between condition and age cohort was negative and credible, indicating that the negative effect of condition was more pronounced in the adult cohort (see Figure 8 and Table 6 for the results of Bayesian mixed effects models).

Comparing this model to a simpler model without the interaction of condition and age cohort, a Bayes Factor of BF > 1000 was computed. This provides strong evidence in favor of including the interaction of condition and age cohort in the model. In order to interpret this interaction, we conducted follow-up analyses separately for toddlers and adults.

For toddlers, there was extreme evidence in favor of the null model compared to the full model that included condition as fixed effect, BF < 0.01, suggesting little to no reliable difference in the number of gaze shifts between the knowledge and ignorance condition.

In contrast, for adults, the Bayes Factor of BF > 1000 provided extreme evidence in favor of the full model that included condition as fixed effect. In the knowledge condition, adults showed more gaze shifts than in the ignorance condition. These findings demonstrate a robust condition effect in adults but not in toddlers.

AL as a function of number of gaze shifts between mouse and bear during location change.

In order to examine the effect of condition and the number of shifts between mouse and bear during location change of the mouse on anticipatory looking, we fitted Bayesian mixed-effects models for each age cohort separately (see Figure 9 and Table 7 for the results of Bayesian mixed effects models). The dependent variable was PTL in the anticipation period. The fixed effects included the main effects of condition, the number of shifts, and their interaction. We also included random intercepts and slopes for number of shifts within each participant and within each lab, allowing us to account for the hierarchical structure of the data and potential variability between labs and participants.

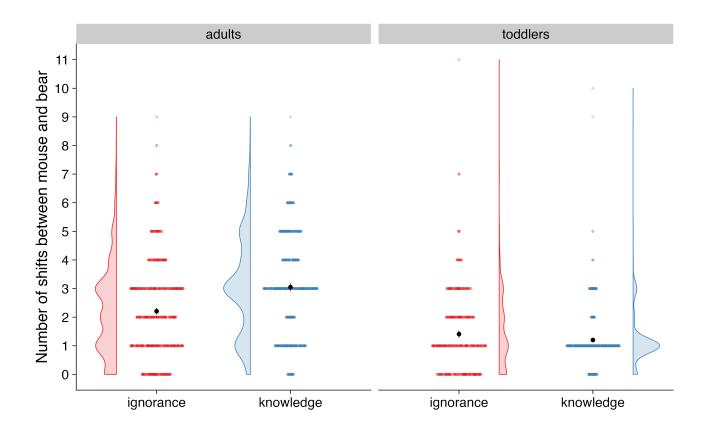


Figure 8. Number of shifts between mouse and bear during location change of mouse in the test phase for toddlers and adults in the ignorance and knowledge condition. Error bars represent 95% CIs.

For toddlers, comparing this model to a simpler model without the interaction of condition and number of shifts, a Bayes Factor of BF < 0.01 was computed, indicating that the data extremely favored the null model over the full model. A Bayes Factor comparison also provided extreme evidence against including the fixed effect of number of shifts, BF < 0.01. These results suggest that, for toddlers, condition influenced proportional DLS, but the number of location shifts—either alone or in interaction with condition—did not meaningfully contribute to explaining variation in their looking behavior.

For adults, the number of shifts showed a small but credible positive effect, suggesting that more shifts were associated with an increase in PTL. The interaction

between condition and the number of shifts was negative and credible, indicating that the 1171 effect of number of shifts on proportion looking at test was larger in the knowledge 1172 condition than in the ignorance condition. Due to limitations with bridge sampling, Bayes 1173 factors were computed using the Savage-Dickey density ratio method. The Bayesian 1174 analysis of the interaction effect produced an extremely high Bayes Factor of BF > 1000, 1175 strongly supporting the presence of this interaction. The effect of the number of shifts also 1176 received very strong evidence, BF = 35.5, indicating a meaningful contribution of this 1177 predictor to the model. 1178

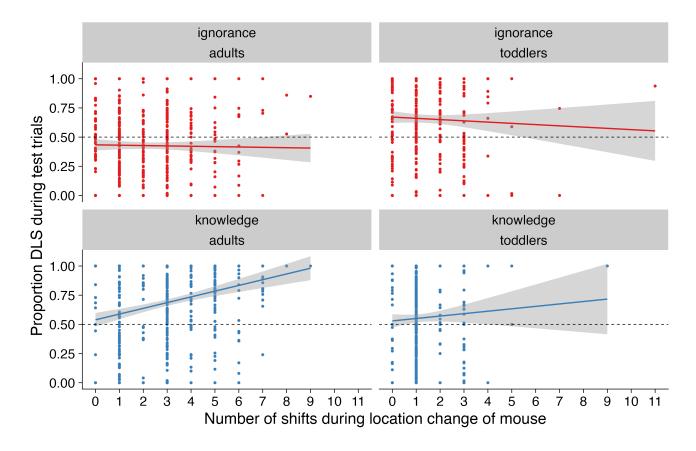


Figure 9. AL as a function of number of shifts between mouse and bear during location change of mouse in the test phase for toddlers and adults. Error bands represent 95% CIs.

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### General Discussion

The overarching aim of the ManyBabies 2 consortium is to investigate the robustness 1180 and replicability of studies showing spontaneous Theory of Mind from infancy across the 1181 lifespan. The first project, the initial steps of which are reported here, takes a systematic, 1182 sequential bottom-up approach to address anticipatory looking as a measure of spontaneous 1183 Theory of Mind and pursues three objectives. First, we aim to develop stimulus material 1184 (i.e., videos) that reliably and generally elicits spontaneous, goal-based action anticipation 1185 - such that young children and adults look where an agent will go as a function of their 1186 goal. In this way, the problem of very high exclusion rates in previous studies (of children 1187 who did not spontaneously anticipate) could be overcome (e.g., Kampis et al., 2020; Kulke, 1188 Reiß, et al., 2018; Schuwerk et al., 2018; Southgate et al., 2007). If the first goal can be 1189 met, the second goal is to examine whether young children and adults demonstrate action 1190 anticipation that is sensitive to basic epistemic states of agents: do they anticipate as a 1191 function of whether the agent has or has not seen crucial events and is thus knowledgeable 1192 or ignorant of them? If the second goal can be fully met, the third goal, to be addressed in 1193 future work, is to test the replicability of the original findings of the false belief/true belief 1194 contrast. In this paper, we focused on the first two steps and laid the foundation for future 1195 work on the third. ## Summary and evaluation of main findings Concerning our first 1196 goal, the present work was successful. In two pilot studies (see Supplement S1) and the 1197 main study reported here, toddlers and adults reliably engaged in spontaneous goal-based 1198 action anticipation: they looked ahead of time towards the location where an agent would 1199 go, given their goal. This licensed the conclusion that the present stimulus material is 1200 suitable for studying spontaneous action anticipation and laid the foundation for 1201 addressing the second goal in the main study: is spontaneous action anticipation sensitive 1202 to the agent's epistemic status? The results of this study were mixed, even with the large 1203 sample size of more than 500 toddlers and 700 adults tested in over 30 labs around the 1204 world. By accounting for random effects due to lab, our modeling approach allows us to 1205

generalize our findings to toddlers and adults across diverse socio-cultural and lab contexts. 1206 Adults showed clear evidence of the anticipatory looking patterns that one would expect if 1207 they engaged in action anticipation that is sensitive to the agent's epistemic status. When 1208 the agent (chaser) witnessed the crucial events in the Knowledge condition and thus knew 1209 where the target (chasee) was, adults looked in anticipation towards the corresponding 1210 location. This anticipation was indicated by both first looks and proportional looking time. 1211 When the chaser did not witness the crucial event in the Ignorance condition and thus did 1212 not know where the chasee was, they did not show such a pattern of anticipatory looking 1213 and rather looked at the tunnel exit opposite of the chasee's actual location. Supporting 1214 this interpretation, there were clear condition differences in both the first-looks measure 1215 and proportion of anticipatory looking. For toddlers, the findings were different and 1216 puzzling. They tended to show qualitatively the same anticipatory looking (both in first 1217 looks and in proportional looking time) towards the target location in both Knowledge and 1218 Ignorance trials. The qualitative result in the Knowledge condition is consistent with adult 1219 behavior. Yet quantitatively, children anticipated substantially more in the Ignorance 1220 compared to the Knowledge condition in their proportion of anticipatory looking-precisely 1221 the reverse effect of what one would expect if children tracked the agent's epistemic status. 1222 The overall picture that the present study presents is thus the following: The findings with 1223 adults were straightforward and in line with our predictions. In their anticipatory looking, 1224 adults engaged in spontaneous goal-based action anticipation (pilot studies and main 1225 study), and in doing so, they took into account the agent's epistemic status (main study). 1226 Based on this, the next step would be to pursue the third goal: testing whether adults take 1227 into account true/false beliefs of an agent in their spontaneous action anticipation. 1228 Specifically, adults are expected to anticipate that the agent will go to the actual location 1229 of the target in the true belief condition but to the location where the agent falsely believes 1230 the target to be in the false belief condition (e.g., Schneider et al., 2012; Senju et al., 2009). 1231 In contrast, the findings with the toddlers are puzzling and not in line with our predictions. 1232

Although toddlers did engage in spontaneous goal-based action anticipation (pilot studies 1233 and main study), they did not show clear evidence of taking into account the agent's 1234 epistemic status (main study) in the way adults did. ## Big open question: How can the 1235 puzzling looking patterns in toddlers be explained? The puzzle is what to make of these 1236 findings with children. How did the surprising anticipatory looking pattern of children 1237 come about? Why did toddlers not anticipate more clearly the chaser's action in the 1238 Knowledge condition? And why did they show anticipatory looking to the box with the 1239 chase in the Ignorance condition (where they should not do so, or at least to a lesser 1240 degree)? A number of initially plausible explanations could be ruled out via exploratory 1241 analyses. One such explanation was that behind the grouped data, more nuanced 1242 sub-group patterns were hidden. For example, older children could be performing as 1243 expected, while younger children were not; or children who anticipated strongly in the familiarization trials could be performing as expected, while children who showed little or 1245 no anticipation were not. However, corresponding exploratory analyses along these lines 1246 did not find compelling evidence for such sub-group patterns. Neither toddlers' age nor 1247 anticipatory looking in the familiarization trials had an effect on the pattern of test trial 1248 results. Another explanation was that perseveration from the last familiarization trial to 1249 the first test trials (such that children persevere in looking in anticipation to the location 1250 they have previously looked to) differentially affected Knowledge and Ignorance conditions 1251 and could thus account for at least parts of the puzzling pattern. But the relevant 1252 exploratory control analyses (for details see Supplemental Material) did not find any 1253 convincing evidence for such a possibility. How then can these puzzling anticipatory 1254 looking patterns in the Knowledge vs. Ignorance conditions in toddlers be explained? More 1255 specifically, how can we explain why toddlers in the Ignorance condition engaged in strong 1256 anticipatory looking towards the unpredicted location (where the chasee currently is, 1257 unbeknownst to the chaser)? And how can we explain why they showed only very weak 1258 correct action predictions in the Knowledge condition – weaker than in the Ignorance 1259

condition, and weaker than in the familiarization trials? We discuss several possibilities 1260 below. These are currently all, needless to say, post hoc speculations. But they may lay the 1261 foundation for testing them in future studies. ### Timing differences between conditions 1262 One possibility regarding the Ignorance condition is that slight differences in timing 1263 between the conditions may have posed challenges for toddlers. Specifically, in the 1264 Ignorance condition, the chaser hides at the back and fails to witness the key events where 1265 the chase moves first to one box and then to another. In contrast, in the Knowledge 1266 condition, the chaser observes the chase going to one box, then leaves, returns and 1267 witnesses how the chasee moves between the boxes (see Figure 2). As a result, the 1268 conditions differed subtly in timing. In the Ignorance condition, there was a slightly longer 1269 interval between the initial hiding event at location 1 and the anticipatory looking phase. 1270 This extended interval may have impaired children's memory of the event, making location 1271 1 less salient and leading them to focus more on location 2 during the anticipation phase. 1272 Although the lack of an age effect between 18- and 27-month-olds slightly undermines the 1273 memory-capacity explanation (because increasing memory capacity in this age interval 1274 should have produced an effect of age), future studies could address this issue by equating 1275 the temporal structures of both conditions. ### Attentional and other processing 1276 demands A second possible explanation for the obtained pattern of results, and in 1277 particular, why toddlers did not anticipate more clearly and strongly in the Knowledge 1278 condition, may relate to attentional and other processing demands of the Knowledge and 1279 Ignorance conditions. Regarding attention, the Knowledge condition raises particular 1280 demands of distributing and coordinating attentional focus. In the familiarization trials, 1281 children show clear and strong goal-based action anticipation. However, in these trials, the 1282 chaser remains present in the scene all the time (it never goes towards the back), and the 1283 chase goes to one box in the chaser's presence but does not change to the other box. In 1284 the Knowledge test trials, in contrast, there is much more going on: the chaser leaves 1285 towards the back and then returns, and the chase first goes to one box, and then relocates 1286

to the other. Perhaps dividing attention between the relevant events (chaser is at the back, 1287 chase at the same time in one box) and coordinating it over time (keeping track of what 1288 the chaser has witnessed when) was too demanding for toddlers, and as a result they lost 1289 track of the narrative structure of the events. Exploratory analyses of gaze shifts between 1290 chaser and chasee in toddlers vs. adults may be seen as an indication that there is 1291 something to this explanation: Adults seemed to track the chaser's perceptual access, as 1292 indicated by many gaze shifts between chaser and chase during the location change. In 1293 contrast, toddlers' attention remained largely on the moving chasee with fewer gaze shifts 1294 towards the chaser who was witnessing the relocation in the Knowledge condition. Future 1295 studies could test more directly whether attentional demands made the present Knowledge 1296 condition particularly demanding. The chaser could be continuously present all the time, 1297 for example, and never leave towards the back (which was introduced to keep the 1298 Knowledge condition as similar as possible to the Ignorance condition) – thus reducing the 1299 need to divide and coordinate attention between chaser and chasee. The corresponding 1300 Ignorance condition could then be realized differently, not such that the chaser leaves, but, 130 for example, such that their view becomes blocked by an occluder, or they falls asleep or is 1302 otherwise blindfolded. Relatedly and more generally, the complexity of the event sequences 1303 to be followed and tracked in both conditions may pose excessive performance demands 1304 that mask children's competence to understand the agent's epistemic status. Overburdened 1305 by such processing demands, toddlers may revert to simpler cognitive strategies influenced 1306 by dynamic visual salience, for example. Future research should aim to address these 1307 cognitive constraints by further simplifying task demands and optimizing event timing. 1308 ### Challenges of understanding the implementation of the Ignorance condition A third 1300 possibility is that toddlers' (and adults') anticipation is related to their differing conceptual 1310 understanding of the scenes in the Ignorance trials. In the Ignorance condition, the chaser 1311 leaves but its back is visible. This requires monitoring and understanding that this does 1312 not give the chaser epistemic access to the events, which may overburden toddlers. 1313

Additionally, the Ignorance condition presents a challenge regarding what to anticipate: 1314 should participants expect that the chaser will come out at one of the two exits at random? 1315 Or that the chaser will go to the location where the chase is not? Interestingly, adults' 1316 looking behavior in the Ignorance condition suggests that they expected the chaser to go to 1317 the incorrect location, similar to what might be predicted in a False-Belief scenario or an 1318 ignorance-leads-to-error heuristic (e.g., Ruffman, 1996; but see Friedman & Petrashek, 1319 2009). Adults and toddlers looked comparably in Knowledge trials with slightly above 1320 chance anticipation (albeit stronger in adults), whereas the two groups showed entirely 1321 opposite patterns in the Ignorance condition. This raises important questions about how 1322 toddlers interpreted the Ignorance condition. Did they entirely lose track of the chaser's 1323 epistemic state? Did they show a 'pull of the real', focusing on the actual location of the 1324 chasee? If so, why did this not occur in the Knowledge condition? Alternatively, they may 1325 have been governed by altogether different assumptions about the events in the scene. This 1326 raises the possibility that the Ignorance condition may not be the most optimal comparison 1327 to the Knowledge condition for toddlers. These concerns could be addressed by exploring 1328 alternative implementations of the Ignorance condition, such as those proposed above. 1320 ### Differential habituation and task construal across trials between the conditions A 1330 fourth possibility, finally, is that toddlers habituated to and construed the events over time 1331 differently in the Knowledge and Ignorance conditions. In the Knowledge condition, from 1332 toddlers' perspective the first test trial was the fifth trial (after the four familiarization 1333 trials) that was similar in the sense that the chaser went to look for the chasee after 1334 watching it hide. So they might have simply begun to lose interest in the task. In contrast, 1335 no such habituation may have taken place in the Ignorance condition in which the first test 1336 trial did differ from the last familiarization trial in that the chaser did not witness the 1337 chasee hiding. In addition, this may have been gone along with a different and very rich 1338 construal by toddlers of the events in the first Ignorance test trial: For the first time, in 1339 this trial the chaser did not know where to go, and the chasee knew that. Rather than not 1340

keeping track of the agents' perspectives on the scene (under-thinking), toddlers may have 1341 engaged in very complex reasoning (over-thinking) about such perspectives along the 1342 following lines: They may have looked toward the chasee's box because they expected the 1343 chase to signal its hiding location in some way, to help the chaser find it and allow their 1344 cooperative game to continue. From this perspective, toddlers thus not only understood 1345 the chaser's ignorance, but they expected the chasee to understand it too and to act 1346 accordingly. This made the chasee, rather than the chaser, the focus of toddlers' 1347 anticipation: They anticipated that the chase would somehow signal its location, to help 1348 the chaser find it. This interpretation of the task also indicates that it may measure 1349 something different in toddlers and adults and that anticipatory looking in toddlers can 1350 have a different meaning than it has in adults – i.e. a lack of measurement invariance 1351 (Meredith, 1964). While such a very rich interpretation does not receive any direct support 1352 from the present data, it could be put to systematic test in future studies (for example, by 1353 having the two agents interact in less cooperative ways). 1354

### 1355 Conclusion and future directions

The current large-scale study examined the robustness and reliability of studies using 1356 anticipatory looking as a measure of spontaneous Theory of Mind in toddlers and adults. 1357 The novel stimuli designed for this study reliably elicited spontaneous goal-based action 1358 anticipation, as shown in two pilot studies and in the main study. Spontaneous 1359 anticipatory looking occurred to a higher degree and resulted in lower exclusion rates than 1360 in previous studies - confirming the importance of the baseline checks, especially in 1361 replication studies. In this sense, the current study provides robust stimulus material 1362 suitable to elicit goal-based AL in both toddlers and adults. The main study tested 1363 whether toddlers and adults, in their spontaneous action anticipation, take into account 1364 the epistemic status of an agent who witnesses relevant events and knows where the target 1365 is (Knowledge condition) or fails to do so (Ignorance condition). Adults clearly did take 1366

into account the agent's epistemic status and distinguished between the Knowledge and the 1367 Ignorance condition: they anticipated that the agent would go to the target in the 1368 Knowledge, but expected the opposite in the Ignorance condition. In contrast, toddlers 1369 showed anticipatory looking to the target location in both conditions, but did so in 1370 quantitatively stronger ways in the Ignorance than in the Knowledge condition, which is 1371 the reverse as expected. Future research with adults could build on the present findings, 1372 for example, by testing whether adults engage in belief-based action anticipation and thus 1373 whether original findings of implicit Theory of Mind in adults can be replicated. Future 1374 research with children, in contrast, should first sort out the sources of the unexpected 1375 results found here. This will require systematic follow-up studies along several lines: First, 1376 the Knowledge-Ignorance condition contrast could be implemented in alternative, ideally 1377 simpler, ways as suggested in the above discussion. Second, an interesting extension would 1378 be to test whether young children do indicate some understanding of the present 1379 Knowledge-Ignorance contrasts in other measures. Anticipatory looking itself may be a 1380 demanding measure due to its predictive nature (cf. Johnson, Posner, & Rothbart, 1991). 1383 Postdictive measures, in contrast, such as looking behavior and pupil dilation in response 1382 to events that are/are not expected given the agent's Knowledge/Ignorance may be more 1383 sensitive to uncover early competence (e.g., Daum, Attig, Gunawan, Prinz, & Gredebäck, 1384 2012). Currently, a spin-off project (https://manybabies.org/MB2P/) is running the first 1385 follow-up studies in this direction. Finally, looking at children at different ages, for 1386 example, older children approaching an age of verbal Theory of Mind reasoning, could shed 1387 light on whether their behavior in this task may be related to an underlying conceptual 1388 understanding (e.g., Wiesmann et al., 2018). Taken together, these future studies will 1389 hopefully shed more light on the reality and robustness of implicit Theory of Mind from 1390 infancy to adulthood. To conclude, this study represents a critical step forward in 1391 understanding the development and robustness of spontaneous Theory of Mind across the 1392 lifespan. By developing novel, reliable stimuli and implementing a large-scale, multi-lab 1393

approach, it has laid the groundwork for replicable research in this domain. The findings
demonstrate that adults' anticipatory looking aligns with epistemic sensitivity, while the
unexpected, puzzling patterns in toddlers challenge existing assumptions and thus open up
exciting new avenues for future research. By addressing these puzzles, this work paves the
way for deeper insights into the developmental trajectory of Theory of Mind and the
cognitive mechanisms underlying its expression in infancy, childhood, and beyond.

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Lab	N collected	N included	Sex (N Female)	Mean Age (years)	Method
CogConcordia	21	16	11	22.12	In-lab
CorbitLab	16	15	14	19.87	In-lab
DevlabAU	20	20	15	25.15	In-lab
MEyeLab	53	53	39	24.47	In-lab
MiniDundee	15	13	10	30.23	In-lab
PKUSu	39	32	19	22.66	In-lab
${\bf SkidLSDLab}$	11	8	3	21.62	In-lab
ToMcdlSalzburg	33	31	22	27.23	In-lab
UIUCinfantlab	36	32	25	19.06	In-lab
WSUMARCS	18	13	8	29.85	In-lab
${\rm affcog} {\rm UTSC}$	23	8	5	20.88	web-based
babyLeidenEdu	20	16	12	23.31	In-lab
babylab Amsterdam	17	16	13	24.00	In-lab
babylabBrookes	67	65	49	21.78	In-lab
babylabINCC	18	18	12	31.00	In-lab
babylabMPIB	16	16	11	27.44	In-lab
babylabNijmegen	19	15	13	22.13	In-lab
babylabTrento	16	16	9	21.69	In-lab
babylabUmassb	33	11	10	19.00	In-lab
babyuniHeidelberg	16	16	14	22.06	In-lab
beinghumanWroclaw	19	16	9	32.75	web-based
careylabHarvard	18	15	12	19.80	In-lab
cclUNIRI	32	32	17	30.53	In-lab
childdevlabAshoka	16	16	8	30.88	In-lab
collabUIOWA	16	16	10	19.19	In-lab
gaugGöttingen	30	28	18	31.71	In-lab
jmuCDL	32	32	22	18.81	In-lab
${\bf kids dev Uniof New castle}$	15	14	7	33.57	In-lab
labUNAM	20	11	8	22.45	In-lab

Table 2 continued

Lab	N collected	N included	Sex (N Female)	Mean Age (years)	Method
lmuMunich	31	30	23	22.53	In-lab
mecdmpihcbs	19	19	10	27.79	In-lab
social cog Umiami	16	15	9	19.27	In-lab
sociocognitive lab	17	17	11	32.12	In-lab
tauccd	15	12	6	24.50	In-lab
Total	803	703	484	24.75	

 $\begin{tabular}{ll} Table 2 \\ Lab \ and \ Participant \ information. \end{tabular}$ 

Lab	N collected	N included	Sex (N Female)	Mean Age (months)	Method
CogConcordia	21	8	4	22.92	web-based
CorbitLab	11	10	5	22.77	In-lab
DevlabAU	18	17	8	19.00	In-lab
PKUSu	50	32	13	20.84	In-lab
SkidLSDLab	8	2	0	20.11	In-lab
${\bf ToMcdlSalzburg}$	17	12	6	22.20	In-lab
UIUCinfantlab	18	15	9	21.96	In-lab
babyLeidenEdu	18	12	8	22.59	In-lab
babylabAmsterdam	28	12	6	23.19	In-lab
${\it babylabBrookes}$	17	12	7	22.15	In-lab
babylabChicago	17	13	4	20.10	In-lab
babylabINCC	16	9	6	23.40	In-lab
babylabNijmegen	19	10	3	23.52	In-lab
${\it babylabOxford}$	25	19	8	23.42	In-lab
babylabPrinceton	17	11	7	22.15	In-lab
babylabTrento	18	17	10	22.72	In-lab
babylabUmassb	7	6	2	20.35	In-lab
babylingOslo	17	14	7	21.99	In-lab
babyuniHeidelberg	16	12	4	22.69	In-lab
${\it beinghuman Wroclaw}$	24	14	7	23.77	web-based
careylabHarvard	17	12	5	21.99	In-lab
cecBYU	16	14	4	22.39	In-lab
child devlab Ashoka	16	10	6	22.44	In-lab
gaugGöttingen	28	15	9	23.06	In-lab
gertlabLancaster	21	17	8	23.03	In-lab
in fant cog UBC	26	19	8	24.39	In-lab
irlConcordia	19	12	5	22.47	In-lab
${\bf kids dev Uniof New castle}$	16	14	9	22.36	In-lab
kokuHamburg	19	14	7	25.99	In-lab

Table 2 continued

Lab	N collected	N included	Sex (N Female)	Mean Age (months)	Method
labUNAM	18	12	7	22.68	In-lab
lmuMunich	48	24	16	22.68	In-lab
mecdmpihcbs	25	12	8	23.58	In-lab
mpievaCCP	22	18	10	23.33	In-lab
saxelab	31	15	2	23.13	web-based
${\it socallabUCSD}$	47	15	4	22.09	web-based
tauccd	15	12	8	22.99	In-lab
unicph	43	29	16	21.50	In-lab
Total	809	521	256	22.48	

Table 3  $Results\ of\ the\ Bayesian\ mixed\ effects\ models\ for\ the\ familiarization$  trials.

model	term	estimate	est_error	lower_ci	upper_ci	rhat
fl toddlers	Intercept	0.44	0.09	0.27	0.61	1.00
	Trial Number	-0.22	0.05	-0.32	-0.12	1.00
fl adults	Intercept	1.03	0.09	0.86	1.20	1.00
	Trial Number	0.38	0.04	0.30	0.47	1.00
aoi toddlers	Intercept	0.12	0.02	0.09	0.15	1.00
	Trial Number	-0.05	0.01	-0.06	-0.03	1.00
aoi adults	Intercept	0.26	0.02	0.23	0.29	1.00
	Trial Number	0.10	0.01	0.09	0.11	1.00

 $\label{eq:Results} \begin{tabular}{ll} Table 4 \\ Results of the Bayesian mixed effects models for the test trials. \\ \end{tabular}$ 

model	term	estimate	est_error	lower_ci	upper_ci	rhat
fl toddlers	Intercept	0.53	0.11	0.32	0.74	1.00
	Condition	0.53	0.21	0.13	0.93	1.00
	Age	0.06	0.05	-0.03	0.15	1.00
	Condition:Age	-0.13	0.09	-0.30	0.04	1.00
fl adults	Intercept	0.05	0.09	-0.12	0.22	1.00
	Condition	-0.89	0.17	-1.22	-0.56	1.00
aoi toddlers	Intercept	0.61	0.02	0.58	0.65	1.00
	Condition	0.10	0.03	0.03	0.17	1.00
	Age	0.01	0.01	-0.01	0.02	1.00
	Condition:Age	-0.01	0.02	-0.04	0.02	1.00
aoi adults	Intercept	0.48	0.02	0.45	0.51	1.00
	Condition	-0.20	0.03	-0.26	-0.15	1.00

Table 5

Results of the Bayesian mixed effects models for the relationship between familiarization and test.

model	term	estimate	est_error	lower_ci	upper_ci	rhat
correct adults	Intercept	0.48	0.02	0.45	0.52	1.00
	Condition	-0.20	0.03	-0.26	-0.13	1.00
	Correct First Look Final Fam	-0.04	0.03	-0.10	0.03	1.00
	Condition:Correct First Look Final Fam	-0.08	0.06	-0.19	0.04	1.00
correct toddlers	Intercept	0.62	0.02	0.58	0.65	1.00
	Condition	0.07	0.04	0.00	0.15	1.00
	Correct First Look Final Fam	0.00	0.04	-0.07	0.07	1.00
	Condition:Correct First Look Final Fam	-0.05	0.06	-0.17	0.07	1.00
sufficient adults	Intercept	0.48	0.02	0.45	0.51	1.00
	Condition	-0.21	0.03	-0.26	-0.15	1.00
	Successful Fam Anticipation	0.00	0.03	-0.06	0.05	1.00
	Condition:Successful Fam Anticipation	-0.01	0.05	-0.11	0.09	1.00
sufficient toddlers	Intercept	0.62	0.02	0.59	0.66	1.00
	Condition	0.10	0.03	0.03	0.17	1.00
	Successful Fam Anticipation	0.05	0.03	-0.02	0.11	1.00
	Condition:Successful Fam Anticipation	-0.03	0.06	-0.14	0.08	1.00

Table 6

Results of the Bayesian mixed effects models for the number of shifts during location change of the mouse.

model	term	estimate	est_error	lower_ci	upper_ci	rhat
shifts age	Intercept	0.59	0.02	0.55	0.64	1.00
	Condition	-0.10	0.03	-0.16	-0.04	1.00
	Age Cohort	0.57	0.04	0.48	0.65	1.00
	Condition:Age Cohort	-0.33	0.06	-0.44	-0.22	1.00
shifts toddlers	Intercept	0.26	0.03	0.20	0.32	1.00
	Condition	0.12	0.05	0.02	0.22	1.00
shifts adults	Intercept	0.92	0.03	0.86	0.97	1.00
	Condition	-0.28	0.04	-0.35	-0.20	1.00

Table 7

Results of the Bayesian mixed effects models for anticipatory looking as a function of the number of shifts during location change of the mouse.

model	term	estimate	est_error	lower_ci	upper_ci	rhat
toddlers shifts	Intercept	0.60	0.02	0.56	0.64	1.00
	Condition	0.12	0.04	0.04	0.19	1.00
	Number Shifts	0.00	0.01	-0.02	0.03	1.00
	Condition:Number Shifts	-0.02	0.02	-0.06	0.03	1.00
adults shifts	Intercept	0.49	0.02	0.45	0.52	1.00
	Condition	-0.09	0.04	-0.16	-0.02	1.00
	Number Shifts	0.02	0.01	0.01	0.04	1.00
	Condition:Number Shifts	-0.06	0.01	-0.08	-0.03	1.00