

Finding Gradients: parameterized functions

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6:42 AM

Stephen Becker, 2021 [Caveat: check the original references for all technical assumptions]

Max

$$f(x) = \max_{z \in Z} \varphi(x, z)$$

want ∇f or subdifferential ∂f
 $x \in \mathbb{R}^n$, define $Z(x) = \operatorname{argmax}_z \varphi(x, z)$

Theorem "Danskin" (ref.: Prop. 4.5.1 Bertsekas "Convex Analysis + Optimization" '03)

Let Z be compact, $\varphi: \mathbb{R}^n \times Z \rightarrow \mathbb{R}$ continuous, and
 $\forall z \in Z$, $\varphi(\cdot, z): \mathbb{R}^n \rightarrow \mathbb{R}$ is convex, then

1) f is convex and its directional derivative in direction d , D_d , is

$$D_d = \max_{\substack{z \in Z(x) \\ \text{over maximizers}}} D_d \varphi(x, z) \quad \leftarrow \text{w.r.t. } x \text{ only}$$

and if $Z(x)$ is a singleton, then f is differentiable at x

2) if $\varphi(\cdot, z)$ is differentiable (in x) $\forall z \in Z$, and $\nabla_x \varphi(x, \cdot)$ is continuous in z $\forall x$, then the subdifferential is

$$\partial f(x) = \operatorname{conv} \left\{ \nabla_x \varphi(x, z) : z \in Z(x) \right\}$$

convex hull

Ex $f(x) = \max \{x, -x\} = |x| = \max_{z \in \{-1, 1\}} \varphi(x, z)$ $\varphi(x, z) = \begin{cases} x & z = 1 \\ -x & z = -1 \end{cases}$

Theorem doesn't apply since Z is discrete so φ can't be continuous in z

Then, use:

Theorem "Dubovitskii and Milyutin" (ref. Thm. 18.5 Bauschke + Combettes '17)

Let Z be a finite set and $\forall z$, $\varphi(\cdot, z)$ is convex and continuous (in x).

Then

$$\partial f(x) = \operatorname{conv} \left\{ \bigcup_{\substack{z \in Z(x) \\ \text{all maximizers}}} \partial \varphi(x, z) \right\} \quad \leftarrow \text{w.r.t. } x$$

Min

$$f(x) = \inf_{z \in Z} \varphi(x, z)$$

(allow a domain $z \in Z$ by allowing $\varphi(x, z) = +\infty$)

Analogously to before, define $Z(x) = \operatorname{argmin}_z \varphi(x, z)$

Theorem (ref. Thm 10.13 Rockafellar and Wets "Variational Analysis" '97)

Assume $\varphi \in \Gamma_0(\mathbb{R}^n \times \mathbb{R}^m)$ (ie., jointly convex, lsc, proper)

and φ is LBLU (see below), then

1) f is convex

2) $\partial f(x) = \partial \varphi(x, z_x)$ for any $z_x \in Z(x)$

LBLU = Level Bounded Locally Uniformly

(A sufficient condition is if $\varphi(x, z) = +\infty$ if $z \notin C$ for some bounded set C , hence this is similar to the assumption in Danskin's Thm)

Details:

$\text{lev}_{\leq \alpha} f := \{x : f(x) \leq \alpha\}$ are sub-level sets.

Rockafellar and Wets define a function f to be **level bounded** if all $\text{lev}_{\leq \alpha} f$ are bounded (i.e., $\forall \alpha \in \mathbb{R}$)

Note: via Bauschke, Combettes, $f: \mathcal{H} \rightarrow \bar{\mathbb{R}}$ **coercive** if $\lim_{\|x\| \rightarrow \infty} f(x) = \infty$, and this is equivalent to **level-bounded** (Prop. 11.12 Bauschke, Combettes)
In fact, if \mathcal{H} finite-dimensional and $f \in \Gamma_0(\mathcal{H})$, it's sufficient to show $\exists \alpha \in \mathbb{R}$ s.t. $\text{lev}_{\leq \alpha} f \neq \emptyset$ is bounded (Prop. 11.13)

Then

Def **LBLU** (def. 1.16 Rockafellar + Wets)

$\varphi: \mathbb{R}^n \times \mathbb{R}^m \rightarrow \bar{\mathbb{R}}$ is **Level Bounded** (in z) **Locally Uniformly** (in x)

if $\forall x_0 \in \mathbb{R}^n \forall \alpha \in \mathbb{R}, \exists$ a neighborhood V of x_0 and a bounded set $B \subseteq \mathbb{R}^m$ s.t. $\forall x \in V, \{z : \varphi(x, z) \leq \alpha\} \subseteq B$
↑ uniformly ↑ locally bounded

(special case: Fenchel-Legendre conjugates)

$$f^*(y) = \sup_x \underbrace{\langle x, y \rangle - f(x)}_{\varphi(y, x)} \dots \text{but think of as negative } \underline{\text{infimum}}$$

Since want to exploit convexity of f

Unique minimizer guaranteed if f is strictly convex (Prop. 18.9 Bauschke + Combettes '17)

* fundamental theorem

Theorem (Thm. 18.15 Bauschke + C.)

f is differentiable and has a L-Lipschitz gradient

iff

f^* is $\mu = 1/L$ strongly convex

(and can swap f, f^*)

cf. Goebel + Rockafellar '07
"Local strong convexity of..." for local results

Integrals

$$f(x) = \int_{\Omega} \varphi(x, z) dz$$

c.f. Kim Border's notes for Ma 3 '20 at Caltech
"Supplement 4: Differentiating under an integral sign"

Theorem (informal) (refs: Border, or Aliprantis + Burkinshaw)
"Principles of Real Analysis" '98 3rd ed.

Assume $\forall x, \varphi(x, \cdot) \in L^1(\Omega)$, $\frac{\partial}{\partial x} \varphi(x, \cdot)$ exists and is also in L^1
i.e., $\int_{\Omega} |\varphi(x, z)| dz < \infty$

and assume a **uniform local integrability condition**

(sufficient: Ω is bounded, $\frac{\partial}{\partial x} \varphi$ is jointly continuous)

then f is differentiable and

$$\frac{d}{dx} f(x) = \int \frac{\partial}{\partial x} \varphi(x, z) dz$$

refs: Aliprantis + Burkinshaw
p. 193-194

or
Dudley, Appendix A
p. 417-423
"Uniform CLTs" 2nd ed.

refs: Dieudonné p. 177
Thm 8.11.2, 1969
"Foundations of Modern Analysis"

Counterexamples (when assumptions not met)

in Gelbaum + Olmsted, p. 123 Ex. 9.15

"Counterexamples in Analysis" 2003, 1965

variant

$$f(x) = \int_{a(x)}^{b(x)} \varphi(x, z) dz$$

Theorem Leibniz Integral Rule (refs: wikipedia)

$x \in \mathbb{R}^1, z \in \mathbb{R}^1$

Assume φ and $\frac{\partial}{\partial x} \varphi$ are jointly continuous in (x, z) and
 $a(x), b(x)$ continuously differentiable, then

$$\frac{d}{dx} f(x) = \int_{a(x)}^{b(x)} \frac{\partial}{\partial x} \varphi(x, z) dz + f(x, b(x)) \cdot b'(x) - f(x, a(x)) \cdot a'(x)$$

i.e., Fundamental Theorem of Calculus

Generally, use Lebesgue's Dominated Convergence Theorem to prove these results

Kim Border's notes are cached here:

<https://healy.econ.ohio-state.edu/kcb/Ma103/Notes/DifferentiatingAnIntegral.pdf>

Bauschke and Combettes '17 is this book:

"Convex Analysis and Monotone Operator Theory in Hilbert Spaces" 2017, Springer