Estimation and Detection (Fall 2016)

1. (100 points) Given the following system model:

$$x[n] = A + Bn + Cn^{2} + Dn^{3} + w[n], n = 0, 1, ..., N - 1$$

- (a) (30 points) Obtain the MVUEs for A, B, C and D. Indicate the minimum variance of these estimators.
- (b) (10 points) Let the noise be i.i.d and $w[n] \sim \mathcal{N}(0, 0.01)$. Let N = 20, A = 0.5, B = -0.5, C = 0.07, D = -0.005. Randomly generate N observations and calculate MVUEs for A, B, C and D using the N observations.
- (c) (20 points) Followed (b) for M=1000 realizations. Let $\mu_A=\frac{1}{M}\sum_{i=1}^{M}\hat{A}_i$, $\mu_B=\frac{1}{M}\sum_{i=1}^{M}\hat{B}_i$, $\mu_C=\frac{1}{M}\sum_{i=1}^{M}\hat{C}_i$, $\mu_D=\frac{1}{M}\sum_{i=1}^{M}\hat{D}_i$, $\sigma_A^2=\frac{1}{M}\sum_{i=1}^{M}(\hat{A}_i-\mu_A)^2$, $\sigma_B^2=\frac{1}{M}\sum_{i=1}^{M}(\hat{B}_i-\mu_B)^2$, $\sigma_C^2=\frac{1}{M}\sum_{i=1}^{M}(\hat{C}_i-\mu_C)^2$, $\sigma_D^2=\frac{1}{M}\sum_{i=1}^{M}(\hat{D}_i-\mu_D)^2$, where \hat{A}_i , \hat{B}_i , \hat{C}_i , \hat{D}_i are the MVUEs obtained at the *i*th realization. Calculate σ_A^2 , σ_B^2 , σ_C^2 , σ_D^2 and compare them to the CRLBs of A, B, C and D.
- (d) (10 points) Let N = 100, repeat (b)-(c).
- (e) (30 points) Plot the CRLBs of A, B, C, D and $\sigma_A^2, \sigma_B^2, \sigma_C^2, \sigma_D^2$ as functions of N, where N = 20:1:100.

- 2. (40 points) In Problem 1, we assume that the order of the system model is known in advance. That is, the above problem is an order 3 estimation. In this problem set, we assume that the order is NOT known in advance. Thus, the order shall be "guessed".
 - (a) (20 points) Assume that the guess is order 2. That is, we assume that only A, B and C are to be estimated but actually there exists D in the model. Please repeat 1(b)-1(e). (This is an underestimate)
 - (b) (20 points) Assume that the guess is order 4. Please repeat 1(b)-1(e). (This is an overestimate)