

Lecture 6

1

Rules of differentiation:

$$\left. \begin{aligned} \text{let } \vec{a}(t) &= \langle F_1(t), F_2(t), F_3(t) \rangle \\ \vec{b}(t) &= \langle G_1(t), \dots \rangle \end{aligned} \right\} \begin{array}{l} \text{be 2 vector} \\ \text{value function of } t \end{array}$$

Then

$$\frac{d}{dt} [\vec{a}(t) \cdot \vec{b}(t)] = \vec{a}'(t) \cdot \vec{b}(t) + \vec{a}(t) \cdot \vec{b}'(t)$$

$$\frac{d}{dt} [\vec{a}(t) \times \vec{b}(t)] = \vec{a}'(t) \times \vec{b}(t) + \vec{a}(t) \times \vec{b}'(t)$$

Scaling a vector $\rightarrow \frac{d}{dt} [\lambda(t) \vec{a}(t)] = \lambda'(t) \vec{a}(t) + \lambda(t) \vec{a}'(t) \quad (\lambda(t) \text{ a scalar function})$

$$\text{Also } \frac{d}{dt} \|\vec{a}(t)\| = \frac{1}{2\|\vec{a}\|} \frac{d}{dt} \vec{a} \cdot \vec{a} \quad \begin{array}{l} \text{Assuming} \\ (\vec{a}(t) \neq 0) \end{array}$$

~~Tedious~~ Tedious, but straight forward to check!

$$\text{Exp) } \frac{d}{dt} \|\vec{a}\| = \frac{d}{dt} \sqrt{F_1^2 + F_2^2 + F_3^2} = \frac{1}{2} (F_1^2 + F_2^2 + \dots)^{1/2} (2F_1 F_1' + 2F_2 F_2' + \dots) = \frac{1}{\|\vec{a}\|} \vec{a} \cdot \vec{a}'$$

(2)

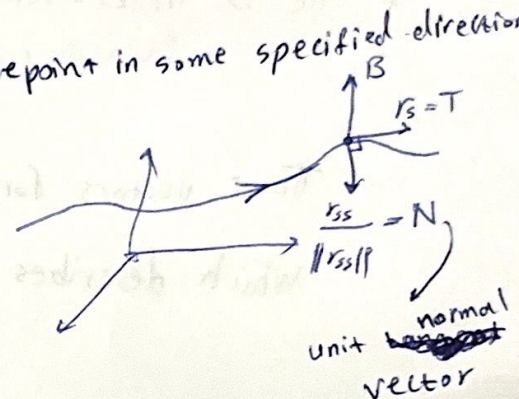
~~Frame curvature, torsion~~

let $\vec{r}(s)$ be arc. length parametrization of some C , starting from some point in some specified direction

$$\|\vec{r}_s\|^2 = \vec{r}_s \cdot \vec{r}_s = 1$$

$$0 = (\vec{r}_s \cdot \vec{r}_s)_s = \vec{r}_{ss} \cdot \vec{r}_s + \vec{r}_s \cdot \vec{r}_{ss} = 2 \vec{r}_{ss} \cdot \vec{r}_s$$

\vec{r}_s, \vec{r}_{ss} are perpendicular



Def: Assume $\vec{r}_s, \vec{r}_s \times \vec{r}_{ss}$ both nonzero for all s . let

$$\vec{T}(s) = \vec{r}_s(s)$$

$$\vec{N}(s) = \frac{\vec{r}_{ss}(s)}{\|\vec{r}_{ss}(s)\|}$$

$$\vec{B}(s) = \vec{T}(s) \times \vec{N}(s) \quad \text{serret formula}$$

$\{\vec{T}(s), \vec{N}(s), \vec{B}(s)\}$ are called Frenet (frame) of C at point $\vec{r}(s)$.

It is an orthogonal frame at $\vec{r}(s)$, consisting of unit vectors.

Note: $\vec{B}(s)$ is unit normal vector for osculating plane! It is also called ~~Binormal~~ ^{Binormal} vector.

It is orthogonal to both $\vec{T}(s)$ & $\vec{N}(s)$

(or tangent plane) plane of \vec{r}_s and \vec{r}_{ss}

$$* \frac{dT}{ds}(s) = k(s) N(s) \quad T(s) = \vec{T}(s)$$

curvature is rate of change of unit tangent ($N(s)$ is the unit vector).

Proof: $\frac{dT}{ds} = \frac{d}{ds}(r_s) = r_{ss} = \|r_s\| \left(\frac{r_{ss}}{\|r_s\|} \right) = \|r_{ss}\| N$

$$k(s) = \frac{\|r_s \times r_{ss}\|}{\|r_s\|^3} = \frac{\|r_s\| \|r_{ss}\| \sin \frac{\pi}{2}}{\|r_s\|^3} = \frac{\|r_{ss}\|}{\|r_s\|^2}$$

* Somewhat equivalent ways of stating above:

$$k(s) = \left\| \frac{dT}{ds}(s) \right\| = \|r_{ss}\|$$

$$* \frac{dB}{ds} = -\tau N$$

$T(s)$ is rate of change of unit normal of osculating plane (how the curve is deviating from osculating plane).

let's proof: $B \cdot B = 1$
 $0 = (B \cdot B)_s = 2 B_s \cdot B$
 B_s is perpendicular to B

$$\left. \begin{array}{l} B \cdot T = 0 \\ 0 = (B \cdot T)_s = B_s \cdot T + B \cdot T_s \end{array} \right\} \begin{array}{l} B \cdot T = 0 \\ B_s \text{ is perpendicular to } T \end{array} \quad \text{since } T_s = kN$$

$$\Rightarrow B_s \text{ must be parallel to } N \rightarrow B_s = \lambda \frac{N}{\|N\|} \text{ for some } \lambda$$

a vector function of s and it is a unit vector

$$\begin{aligned} \text{Multiply both side with } \cdot N &\Rightarrow \lambda = B_s \cdot N = (T \times N)_s \cdot N = (T_s \times N + T \times N_s) \cdot N = \underbrace{(kN) \times N}_0 + T \times \left(\frac{1}{\|r_{ss}\|} \right)_s r_{ss} \cdot \left(\frac{1}{\|r_{ss}\|} \right)_{ss} N \\ &= \frac{-N \cdot (T \times r_{sss})}{\|r_{ss}\|} = \frac{-r_{ss} \cdot (r_s \times r_{sss})}{\|r_{ss}\|^2} = \frac{-r_{ss} \cdot (r_s \times r_{sss})}{\|r_s \times r_{ss}\|^2} = -\tau \end{aligned}$$

becomes 0 when $\cdot N$
 since $T \times r_{ss}$ is perpend. r_{ss}
 and N parallel to r_{ss}