

UNIVERSITY NAME

DOCTORAL THESIS

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# Thesis Title

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*A thesis submitted in fulfillment of the requirements  
for the degree of Doctor of Philosophy  
in the*

Research Group Name  
Department or School Name

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## Declaration of Authorship

I, John SMITH, declare that this thesis titled, "Thesis Title" and the work presented in it are my own. I confirm that:

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- I have acknowledged all main sources of help.
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*“Thanks to my solid academic training, today I can write hundreds of words on virtually any topic without possessing a shred of information, which is how I got a good job in journalism.”*

Dave Barry



UNIVERSITY NAME

*Abstract*Faculty Name  
Department or School Name

Doctor of Philosophy

**Thesis Title**

by John SMITH

The landscape of deep learning compiler frameworks has evolved rapidly with the development of various tools, such as TVM, deeptools, TensorFlow, DLVM, nGraph, and Glow. These frameworks offer unique optimizations to address computation and data movement challenges in deep learning accelerators (DLAs). These approaches include graph or IR level optimizations related to intra node memory access optimizations, operator fusion, and various tiling techniques. Despite their unique approaches, these frameworks primarily concentrate on node level optimizations that focus on increasing the performance of executing a scheduled operation in the graph and overlook the potential for inter-node data reuse optimizations within on-chip memory resources.

OnSRAM, a scratchpad management framework build to work with deep learning compilers, addresses this gap by focusing on internode scratchpad management in DLAs. OnSRAM exploits the static graph representations of deep learning models by identifying data structures that can be pinned to on-chip memory based on their reuse rate and cost of transfer from main host memory. OnSRAM has been implemented and evaluated on single DLA that contains a monolithic scratchpad and is integrated as part of a custom deep learning compiler framework.

In this work, we extend the capabilities of OnSRAM by introducing dynamic scratchpad allocation for static graph execution models using any number of scratchpads and allowing the implementation to be interfaced as a compiler extension rather than a core part of a bespoke compiler. This enhancement allows for more fine-grained control over on-chip memory resources, providing increased flexibility and adaptability to better accommodate diverse deep learning accelerators and memory access patterns. By optimizing inter-node data movement and storage across multiple scratchpads, our approach further reduces energy consumption and latency associated with inter-node communication.





## *Acknowledgements*

The acknowledgments and the people to thank go here, don't forget to include your project advisor...



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*For/Dedicated to/To my...*



## Chapter 1

# Deep Learning

### 1.1 Deep Learning Architectures

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#### 1.1.3 RNN

#### 1.1.4 LSTM

### 1.2 Main Section 2



## Chapter 2

# Deep Learning Compilers

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#### 2.1.1 TVM

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