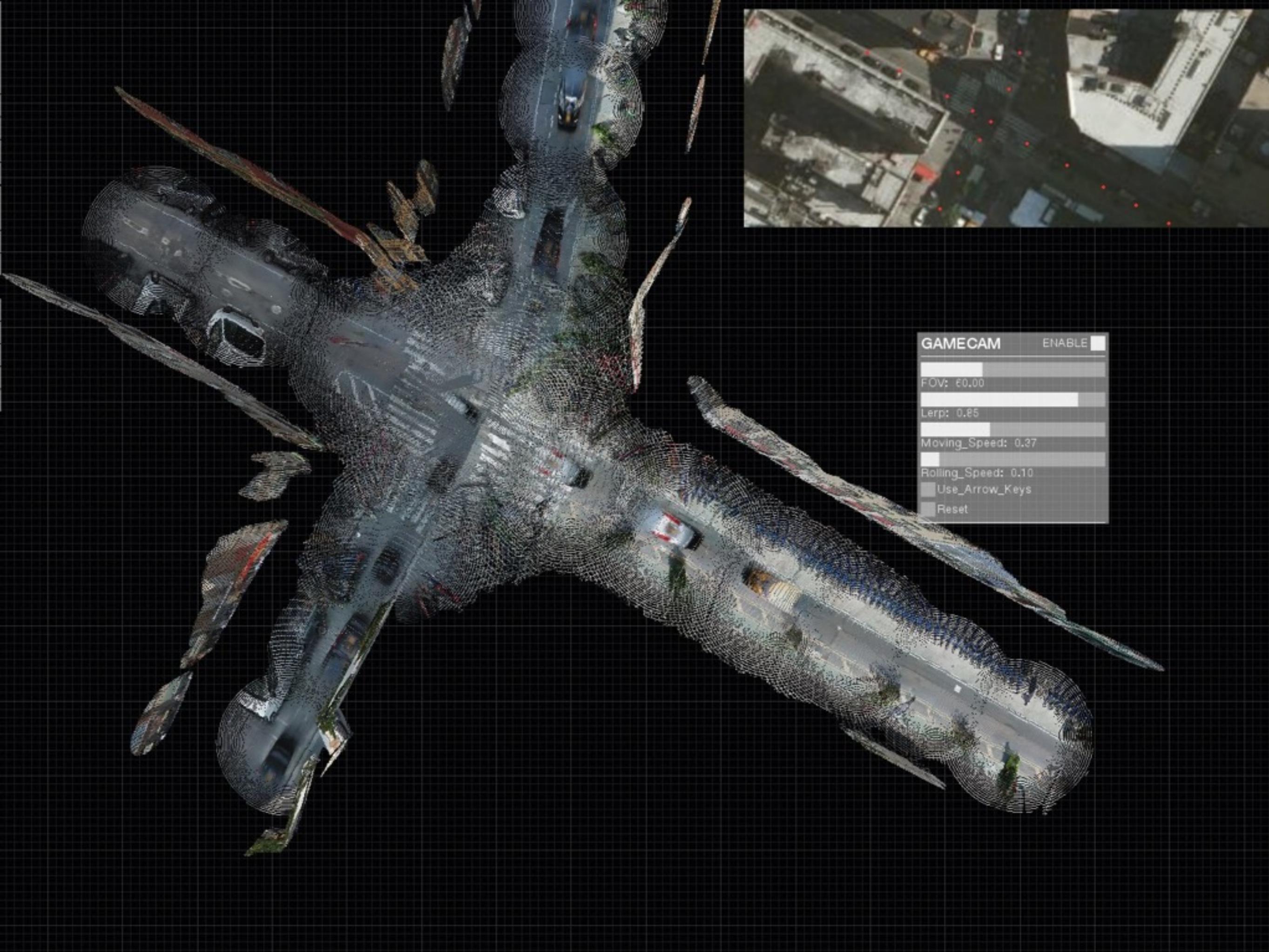




Patricio Gonzalez Vivo

@patriciogv



**GAMECAM**  **ENABLE**

FOV: 60.00

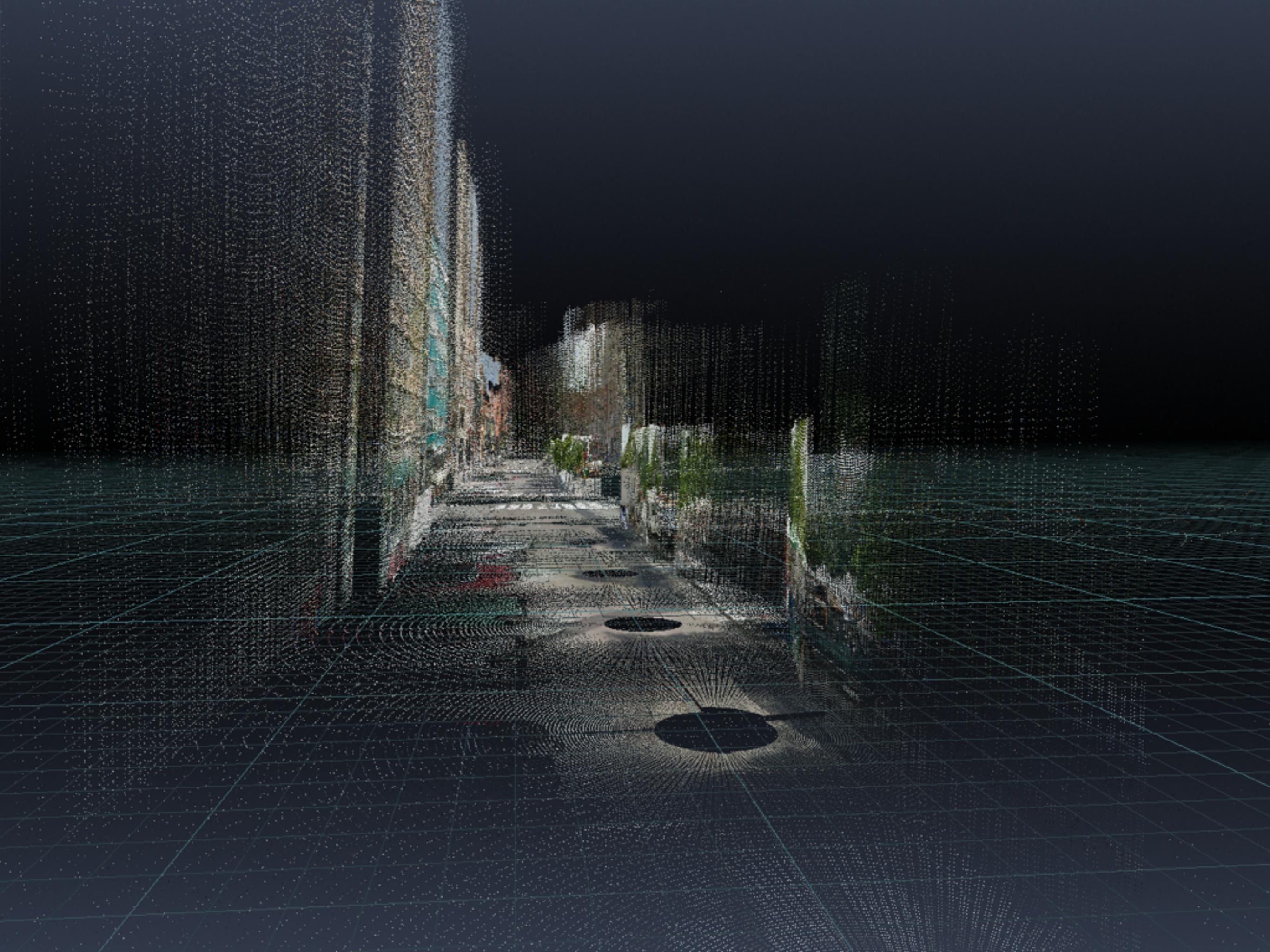
Lerp: 0.85

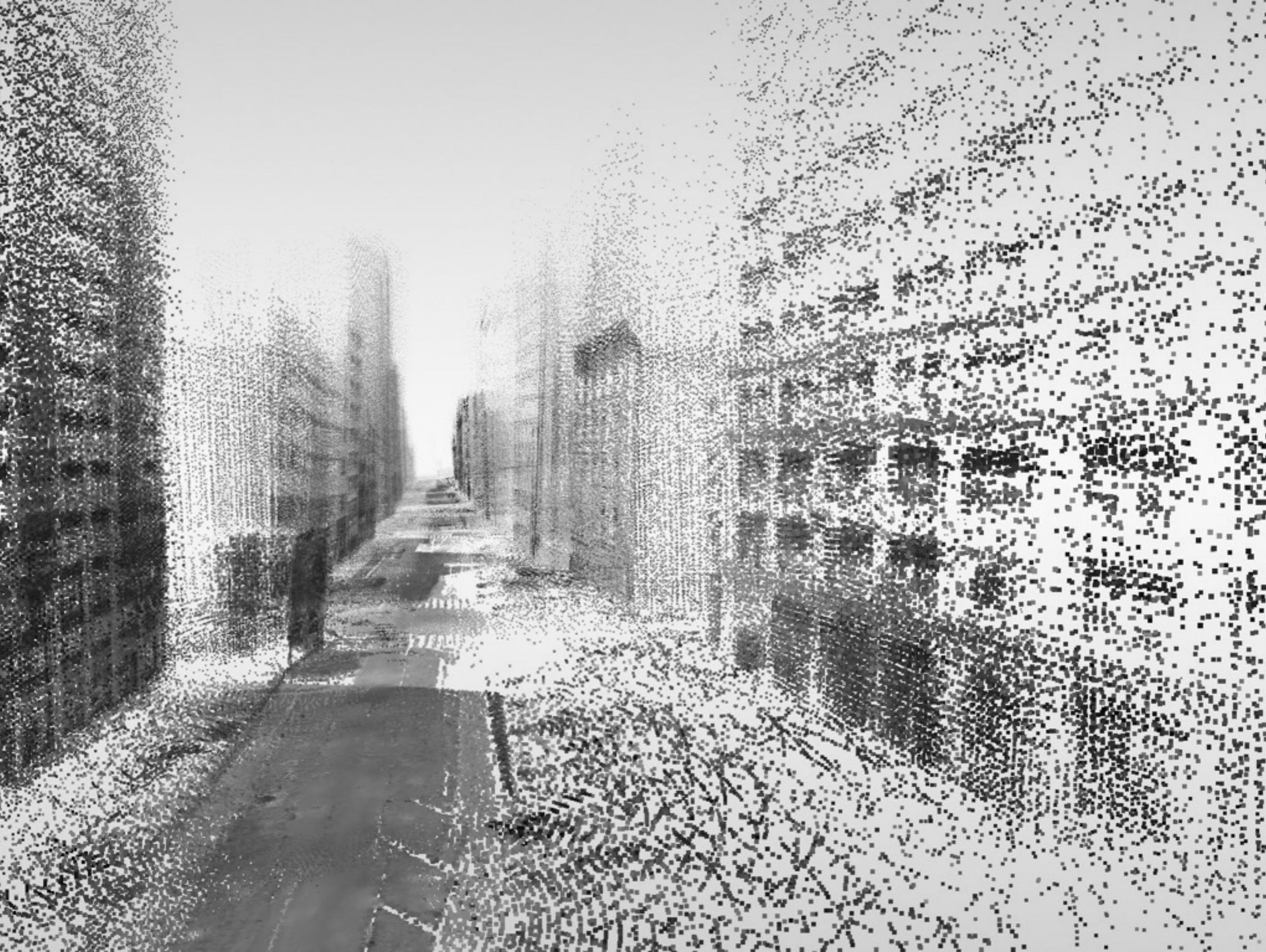
Moving\_Speed: 0.37

Rolling\_Speed: 0.10

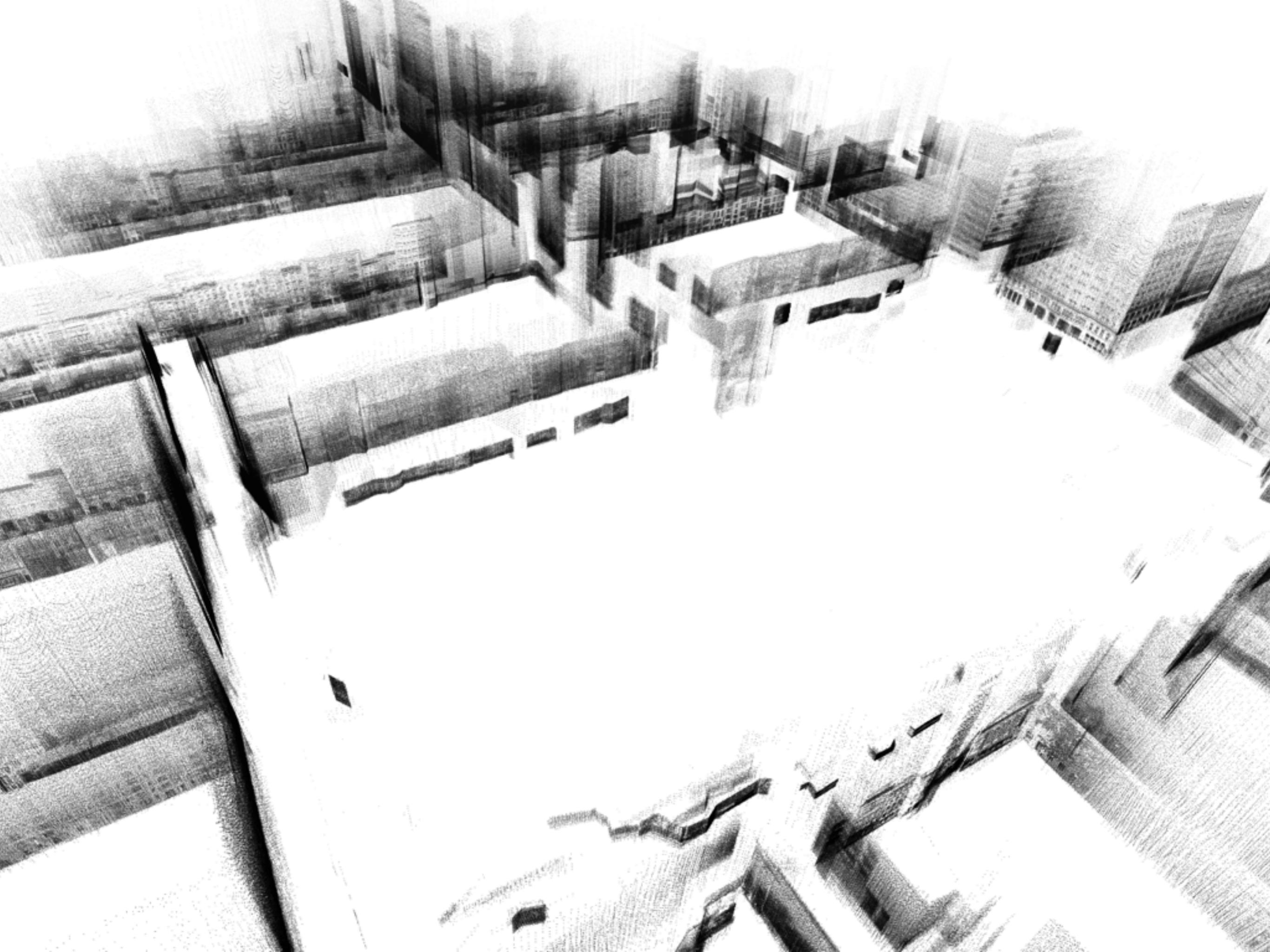
Use\_Arrow\_Keys

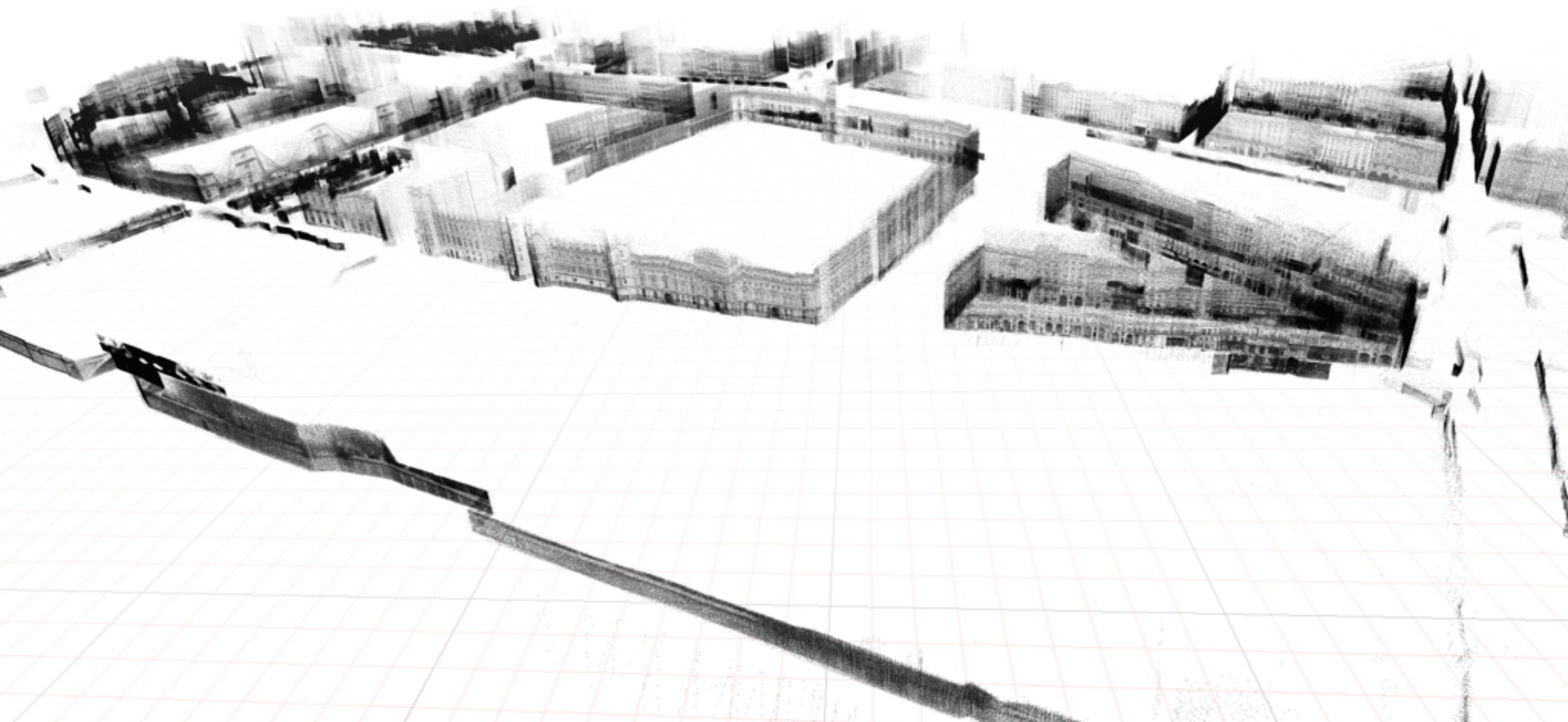
Reset

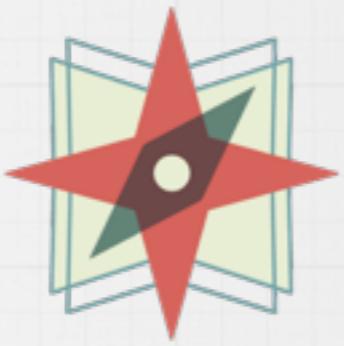




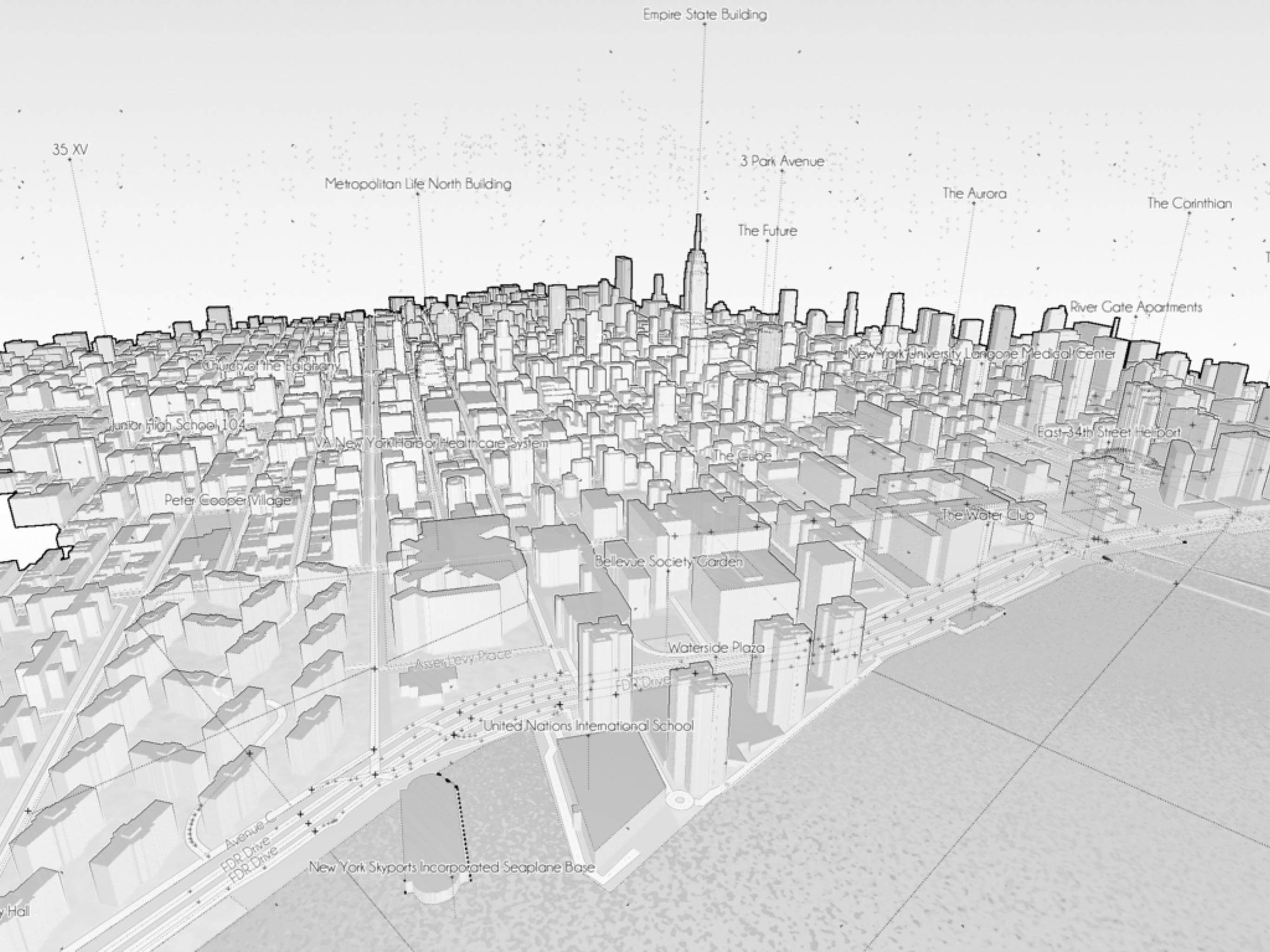


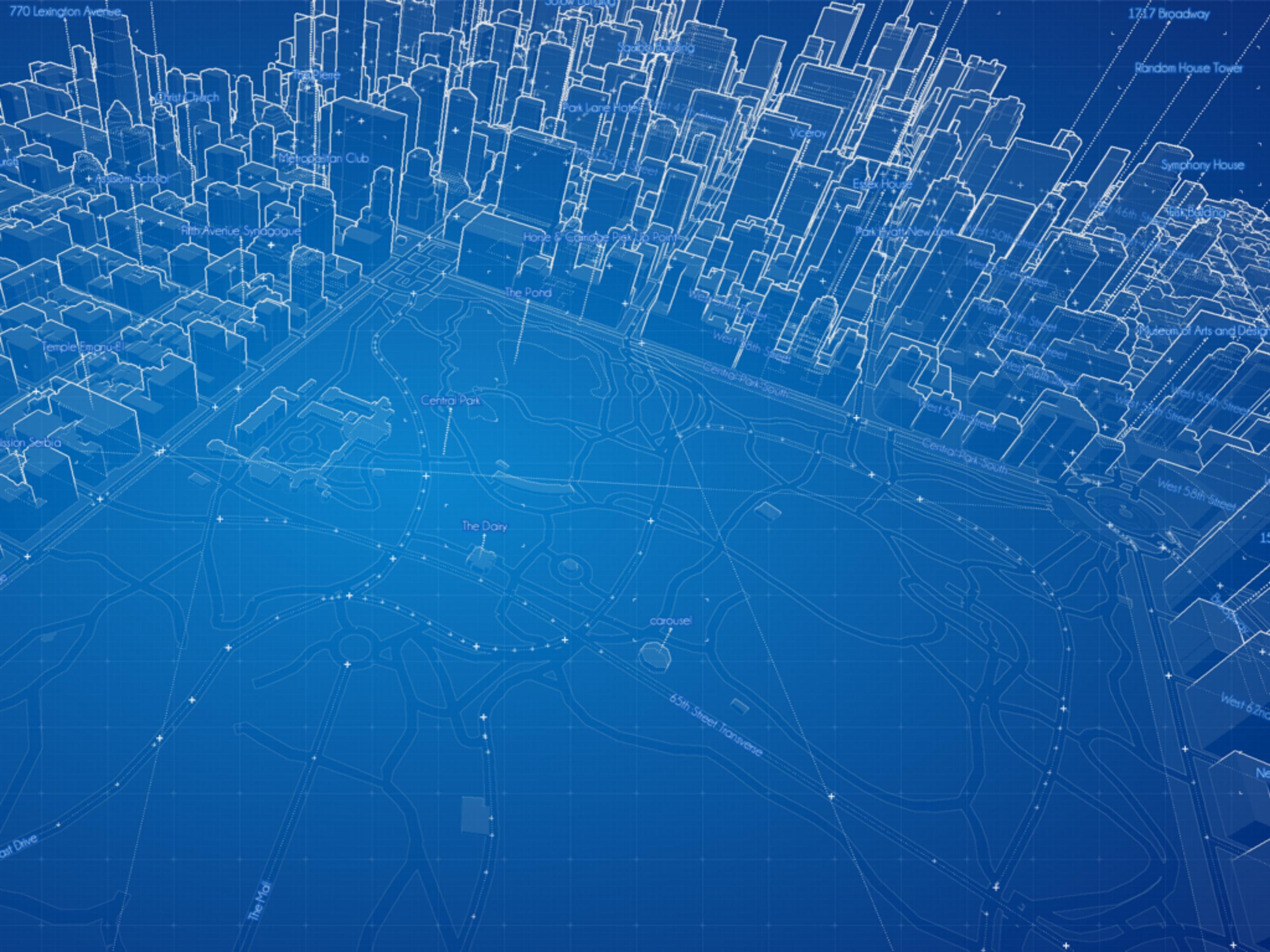


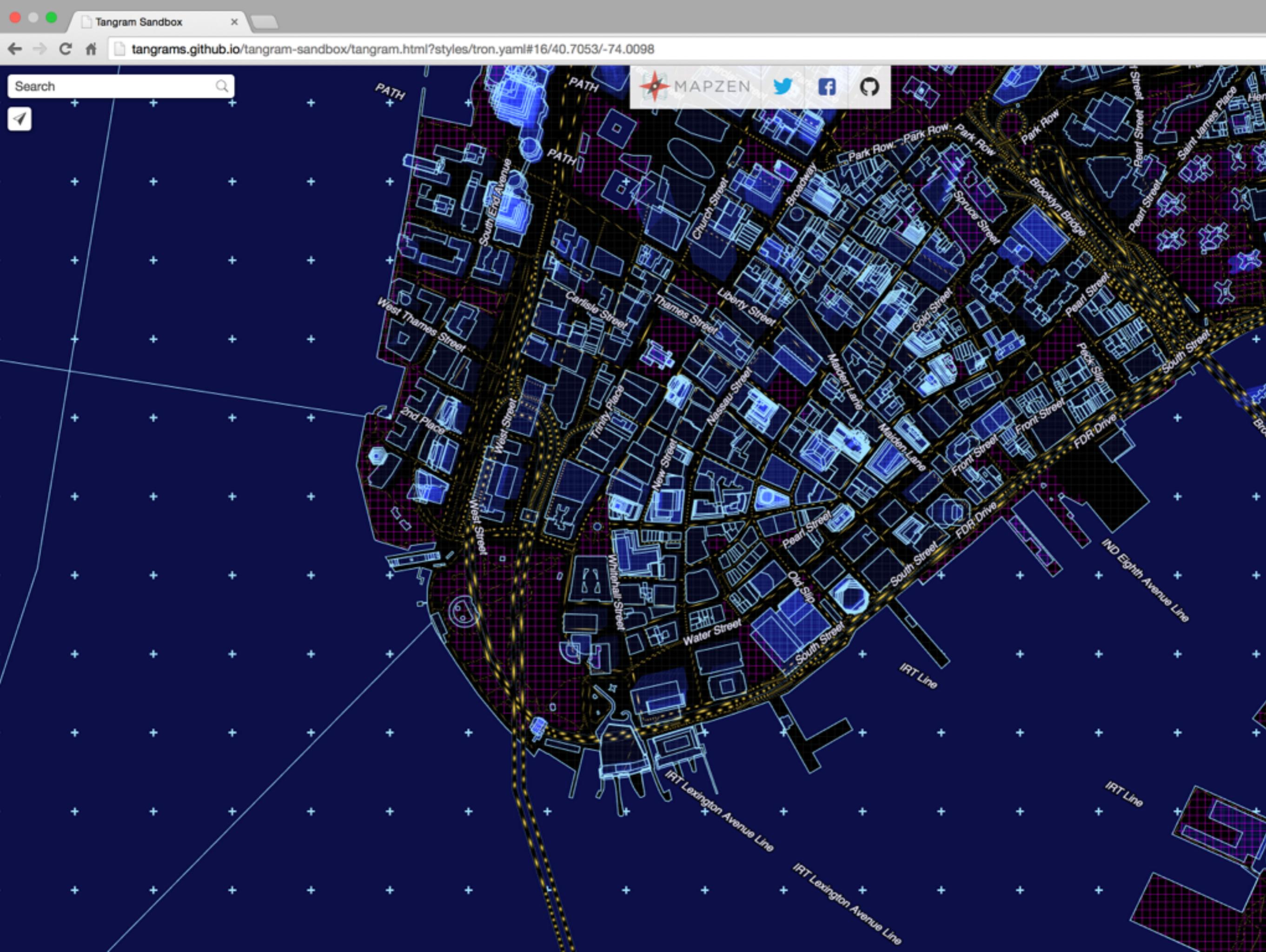


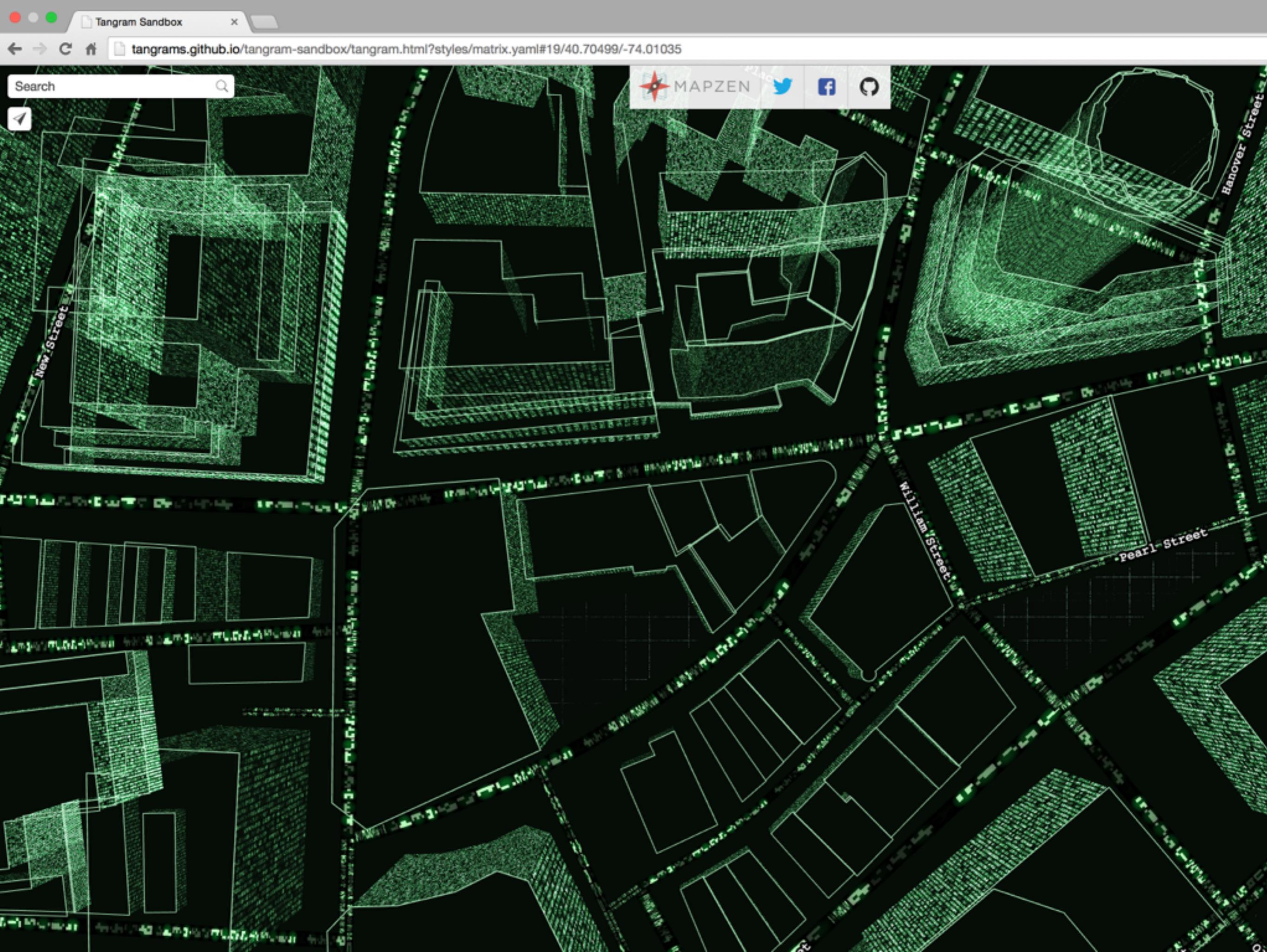


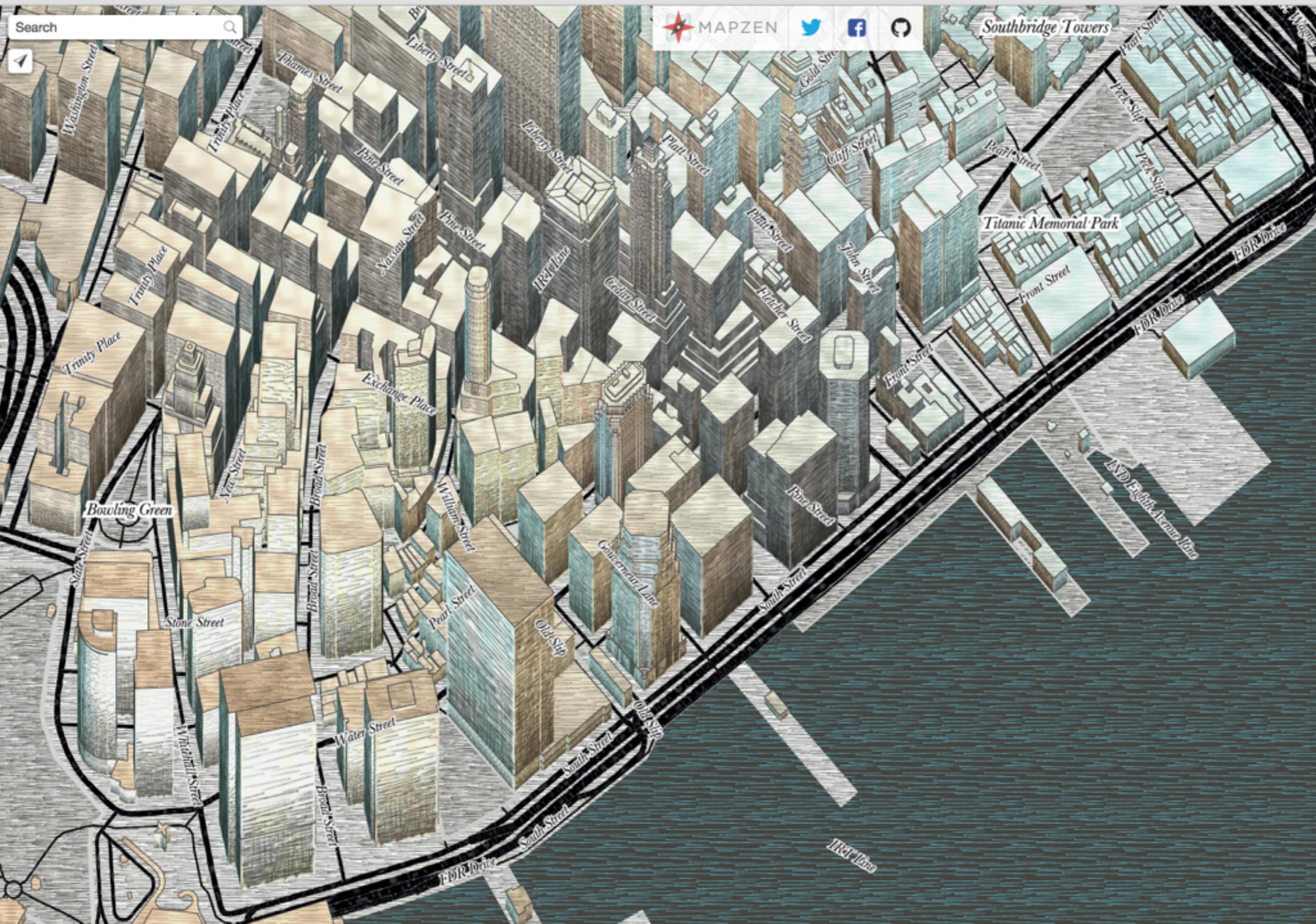
MAPZEN



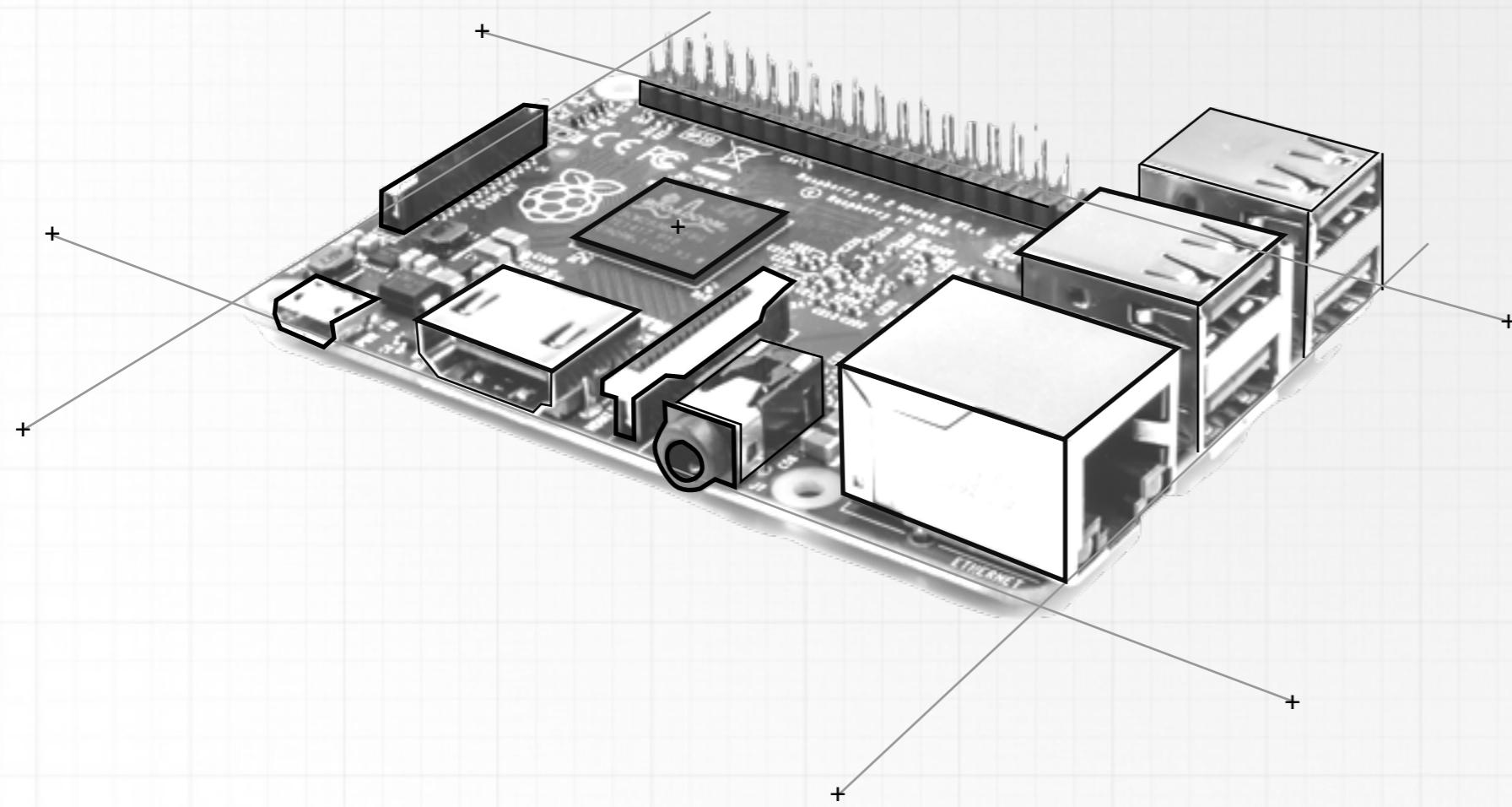








# RaspberryPi



# RaspberryPi

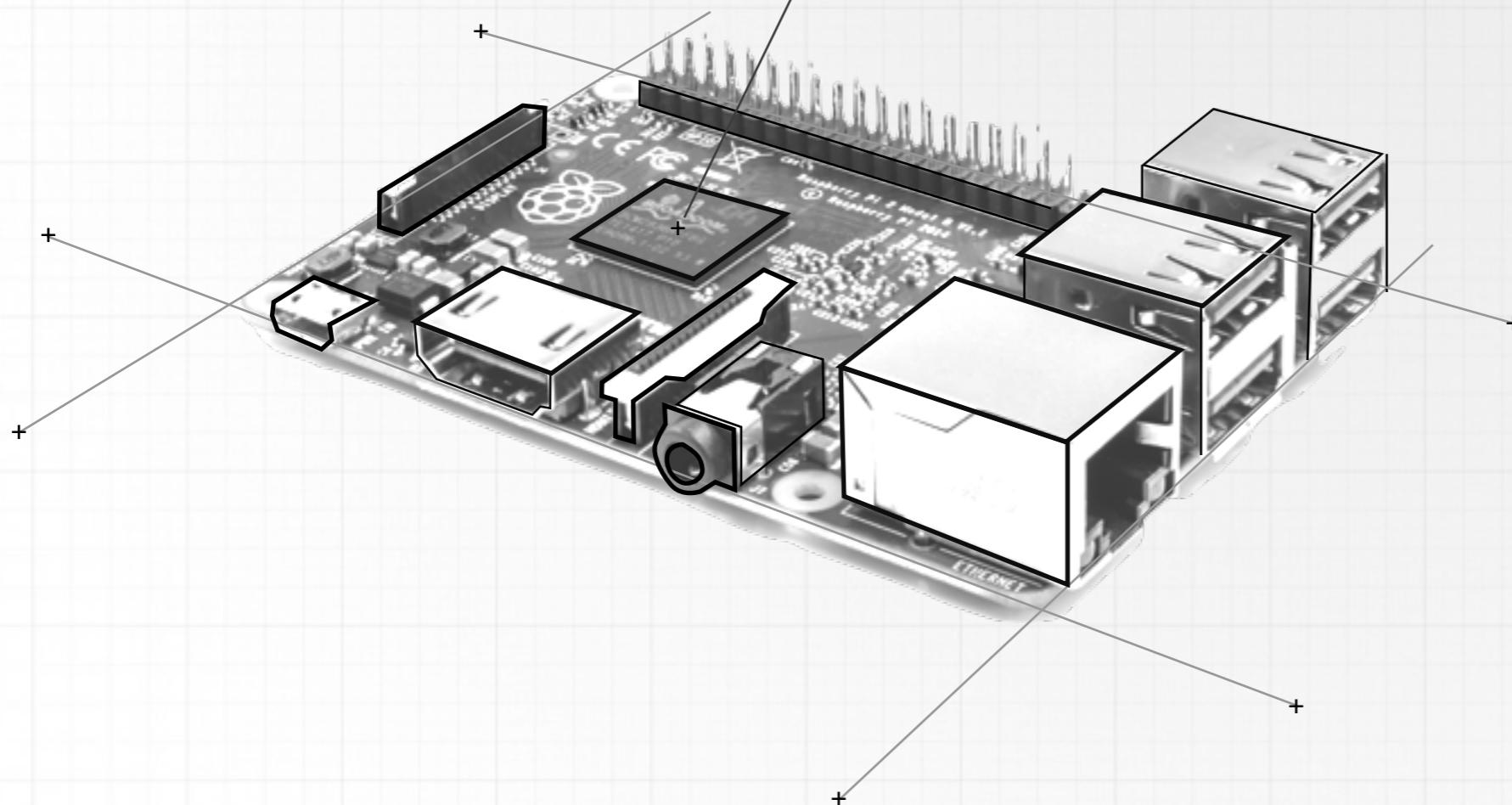
**CPU:** 700 MHz single-core ARM1176JZF-S (Model 1)  
900 MHz quad-core ARM Cortex-A7 (Model 2)

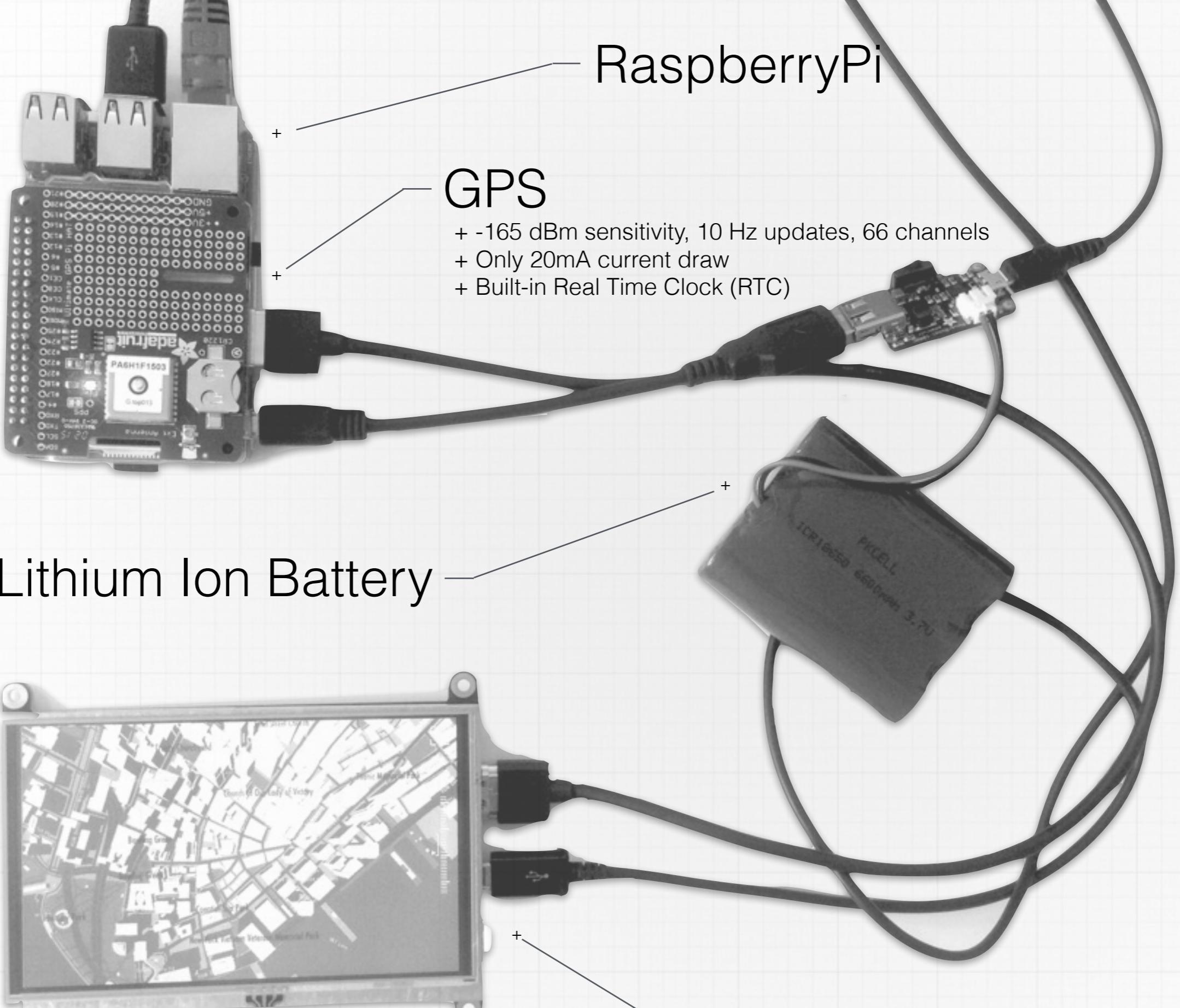
**GPU:** Broadcom VideoCore IV @ 250 MHz  
OpenGL ES 2.0 (24 GFLOPS)

**Memory:** 1 GB

**GPIOs:** 17x GPIO plus the same specific functions, and HAT ID bus

**Power:** 700 mA (3.5 W)





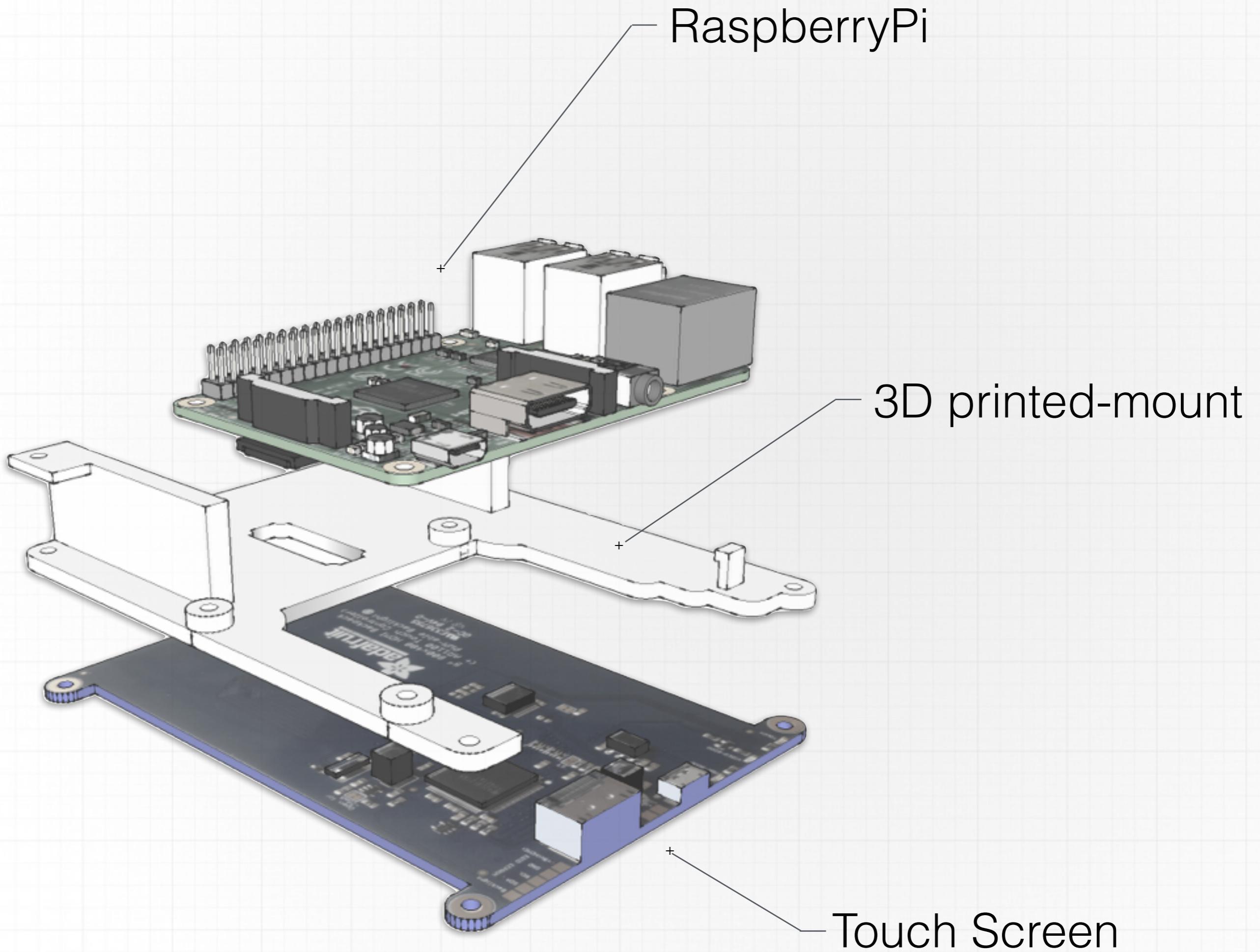
# RaspberryPi

GPS

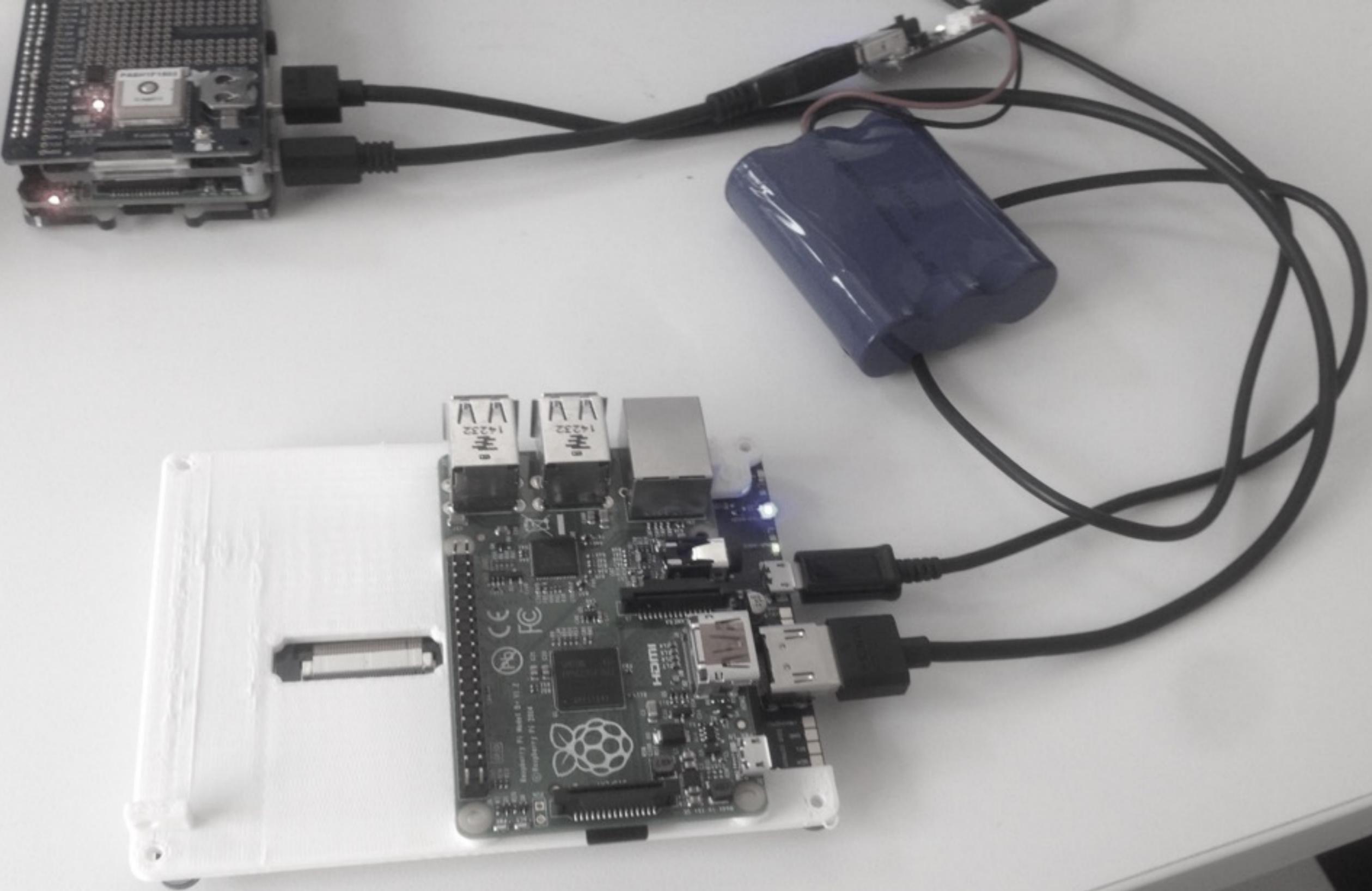
- + -165 dBm sensitivity, 10 Hz updates, 66 channels
- + Only 20mA current draw
- + Built-in Real Time Clock (RTC)

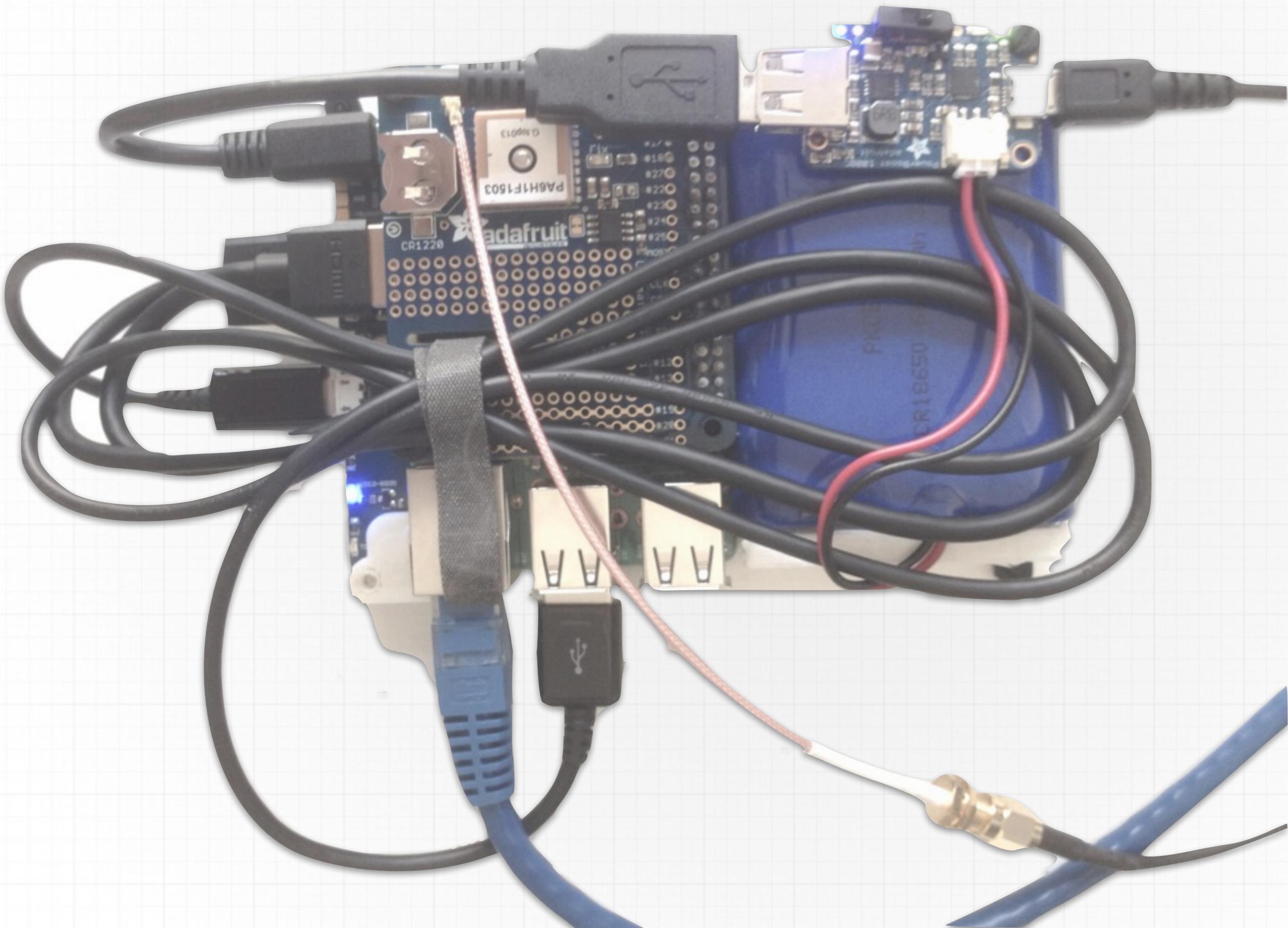
Lithium Ion Battery

Touch Screen







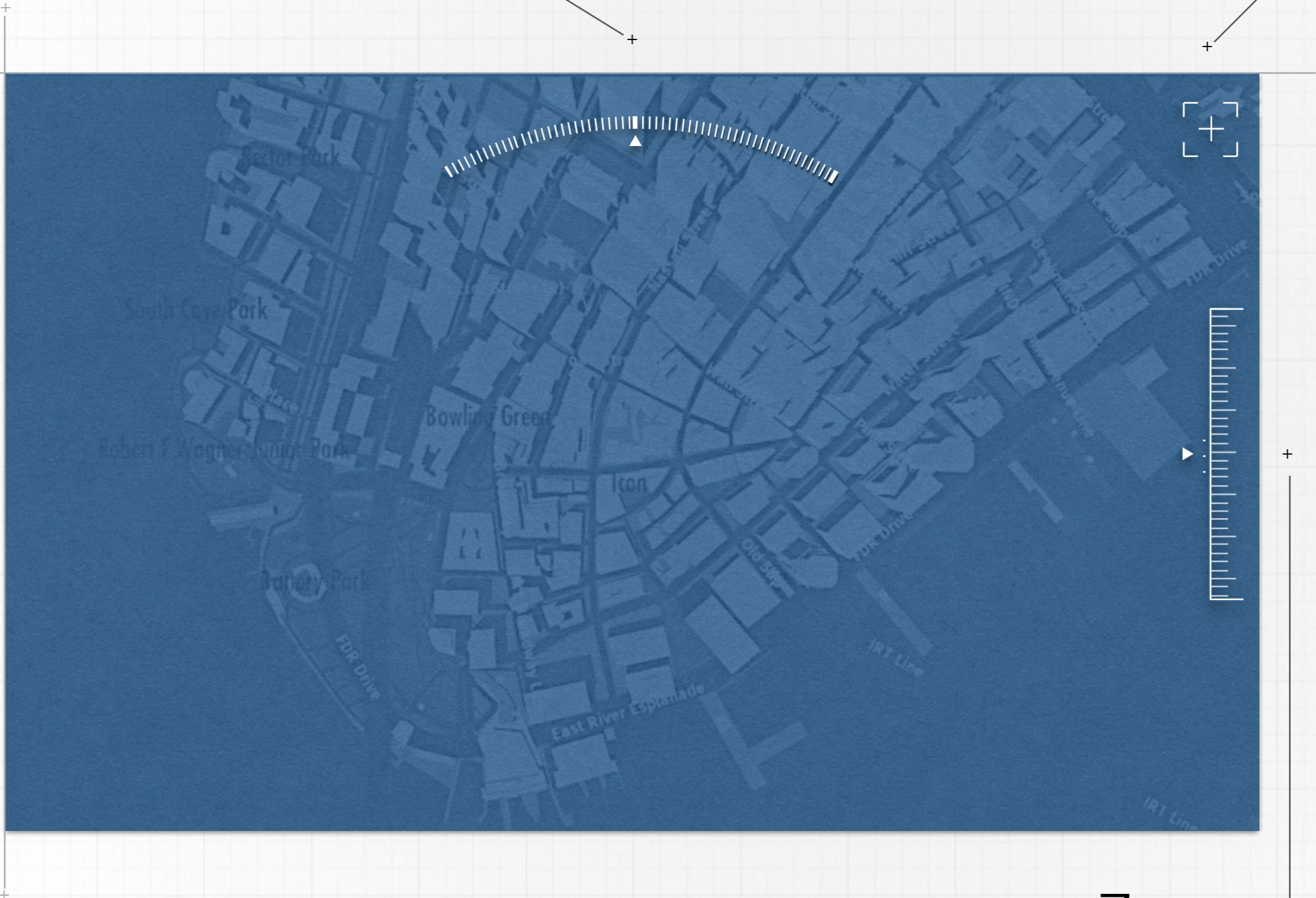




GPS

Zoom

Orientation



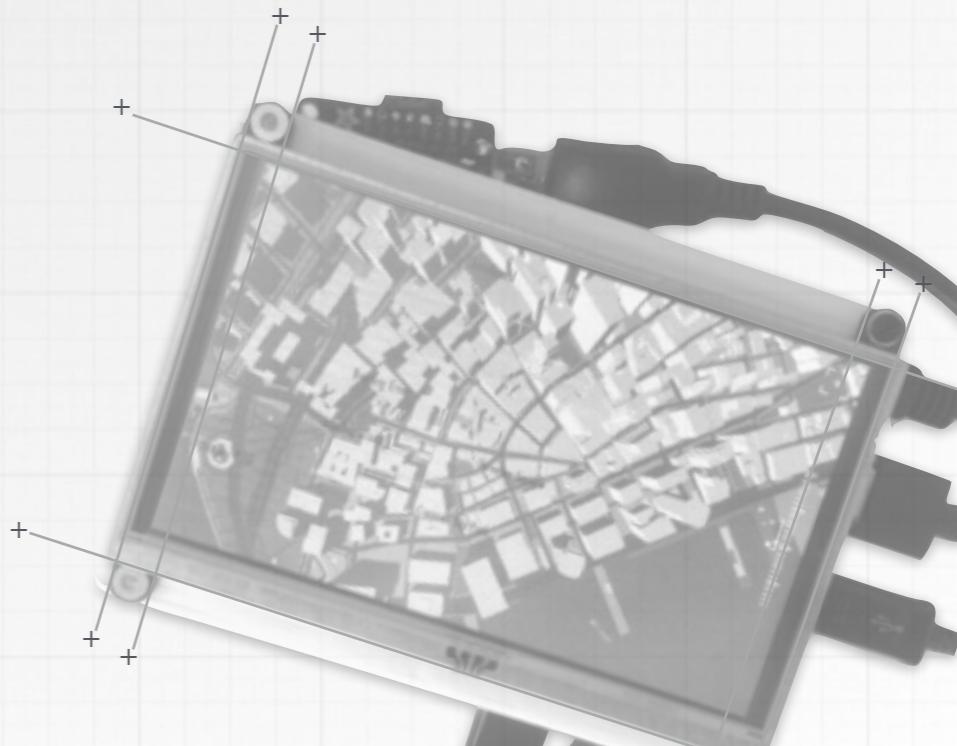
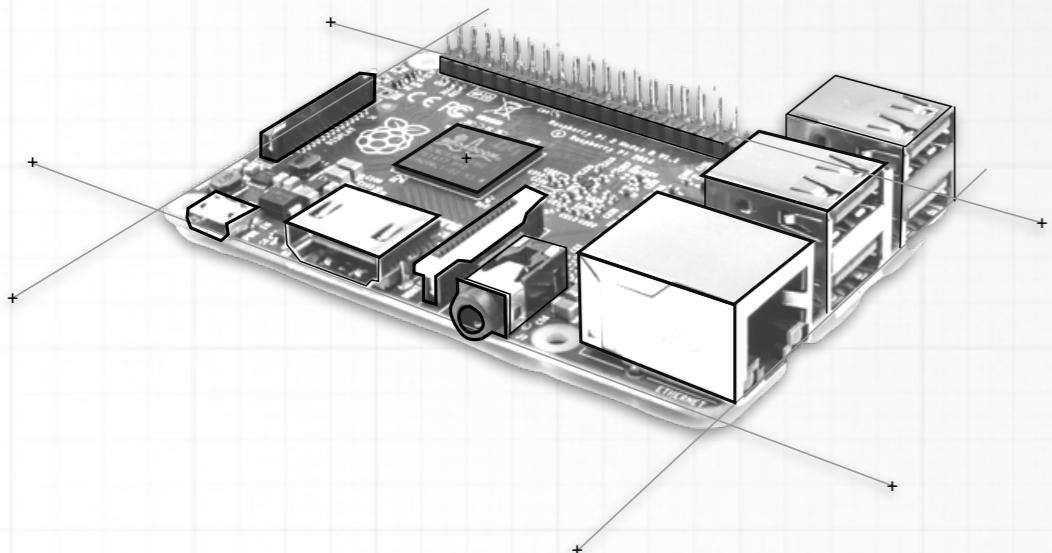






[github.com / tangrams / PI-GPS](https://github.com/tangrams/PI-GPS)

[mapzen.com / blog](http://mapzen.com/blog)



# THANK YOU



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